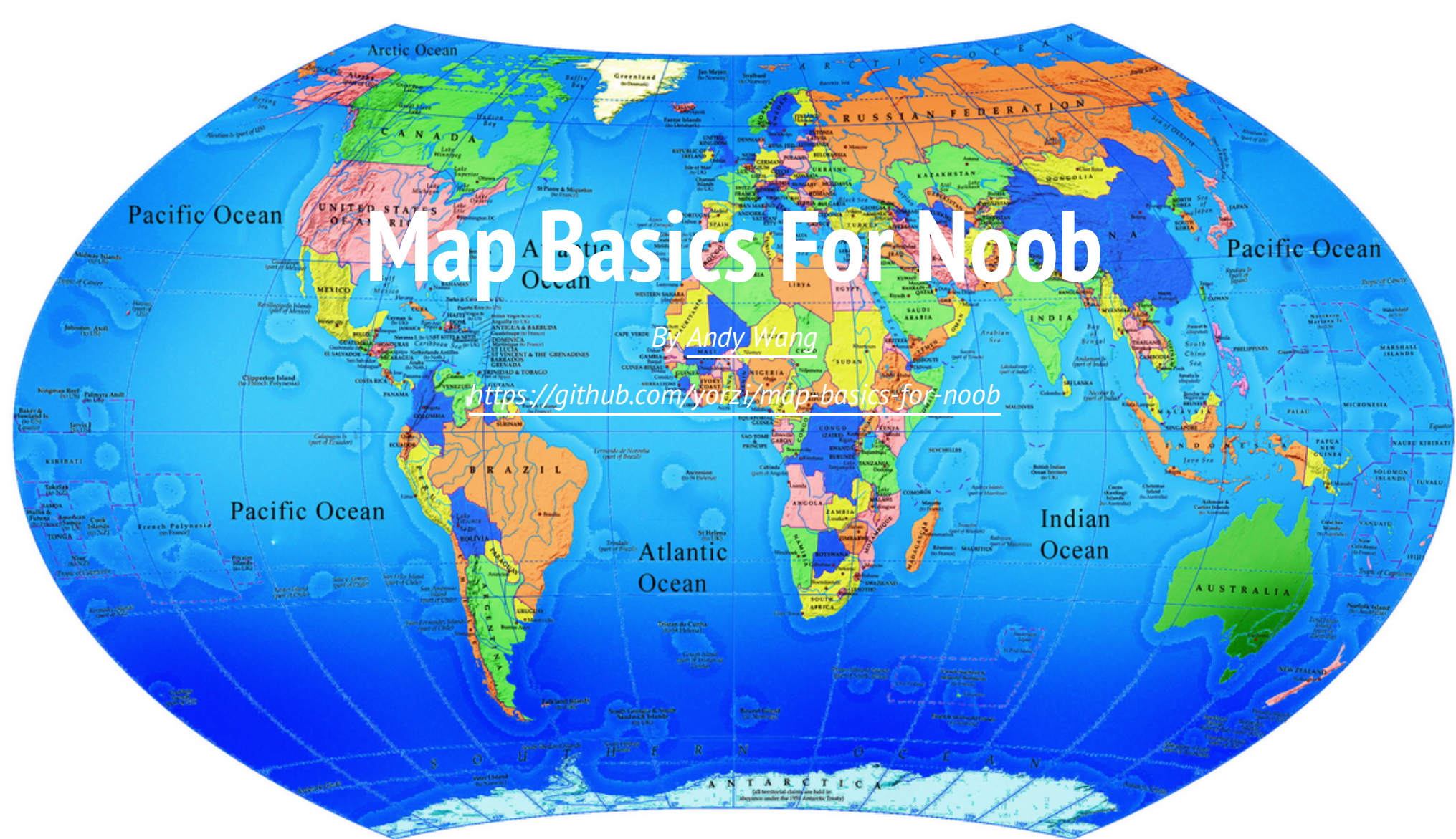


# Map Basics For Noob

By Andy Wang

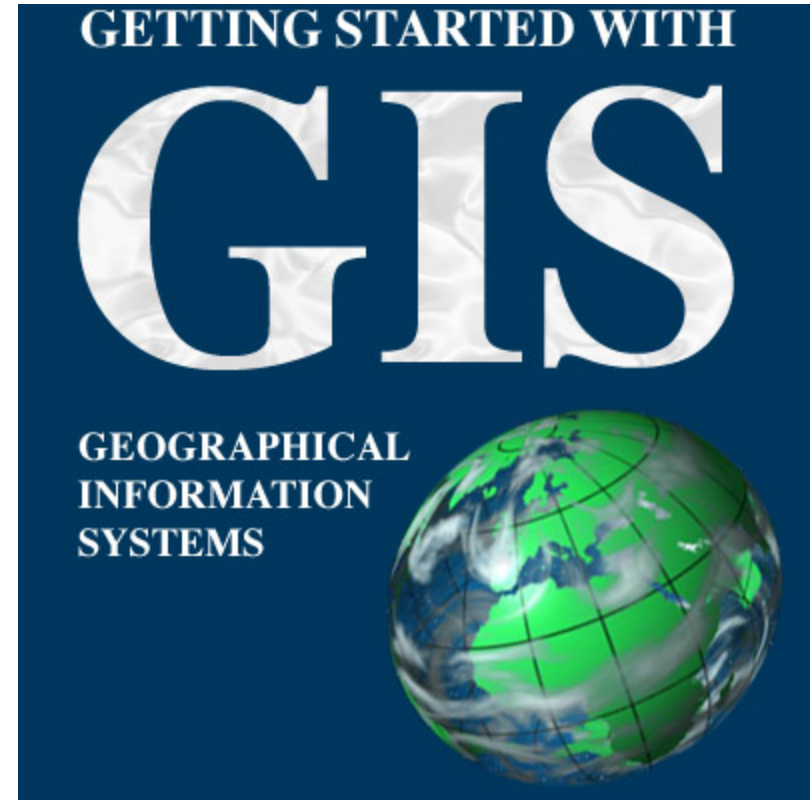
<https://github.com/yorzi/map-basics-for-noob>



**Newbie?**

# Core Concepts

1. GIS
2. Map projections
3. Coordinate systems
4. Zoom levels
5. Layers
6. Spatial databases



# 1. Geographic Information System

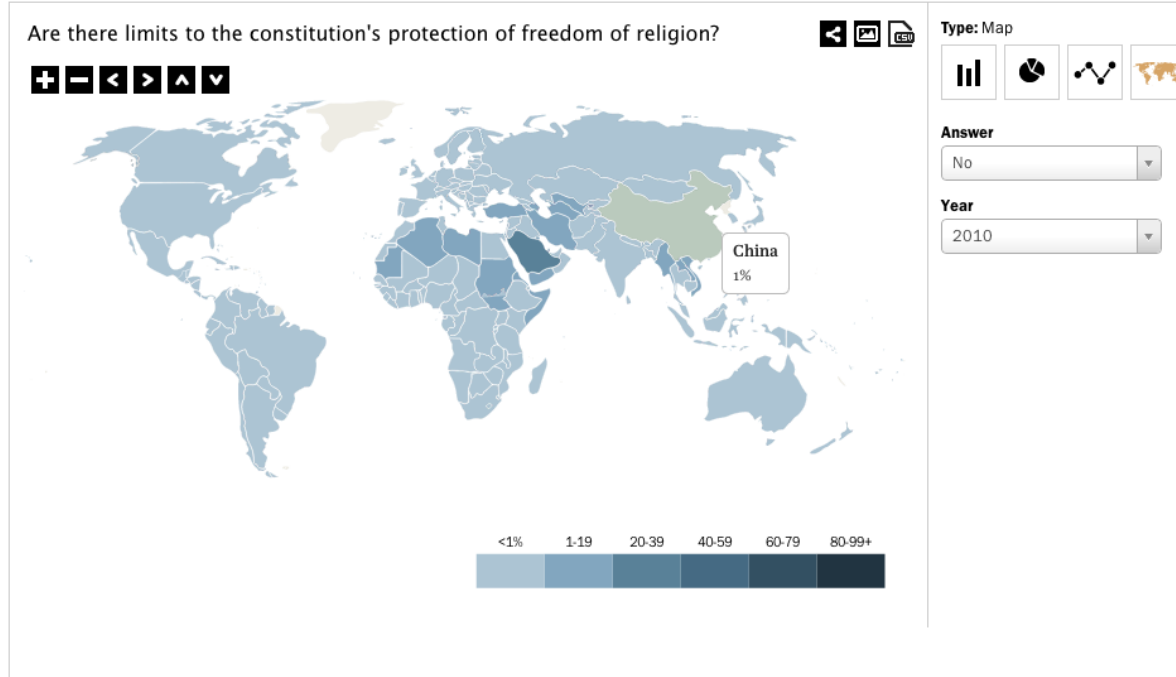


“GIS refers to any system dealing with the recording, analysis, or display of data that is related to a location.”

<http://www.esri.com/what-is-gis>

[http://www.uwyo.edu/smtc/edparc/\\_docs/\\_arcview\\_tips/basicgisconcepts.pdf](http://www.uwyo.edu/smtc/edparc/_docs/_arcview_tips/basicgisconcepts.pdf)

# Sample project:



<http://globalreligiousfutures.org/>

## 2. Map projections

“Projections refer to the method used for representing a three-dimensional object like the Earth on a two-dimensional surface like a sheet of paper or a computer screen.”

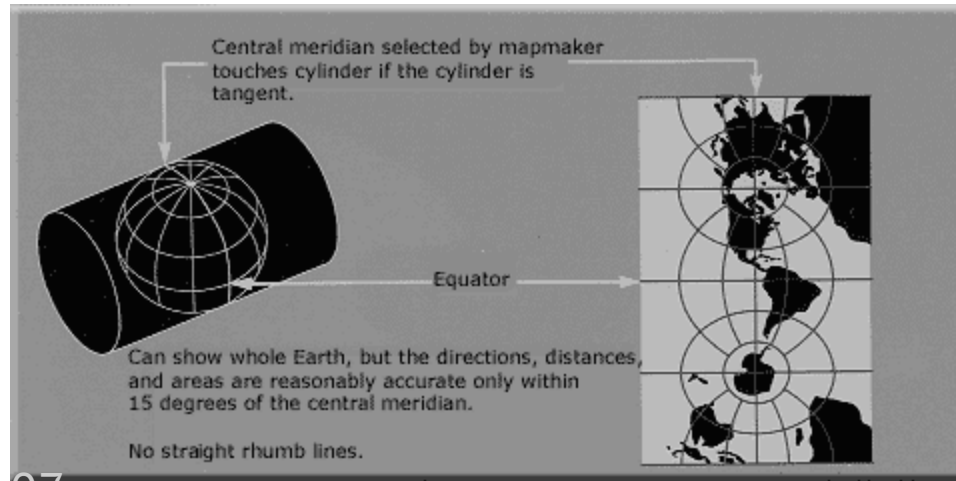
<https://github.com/mbostock/d3/wiki/Geo-Projections>

[http://en.wikipedia.org/wiki/Map\\_projection](http://en.wikipedia.org/wiki/Map_projection)

<http://www.jasondavies.com/maps/transition/>

# Mercator projection

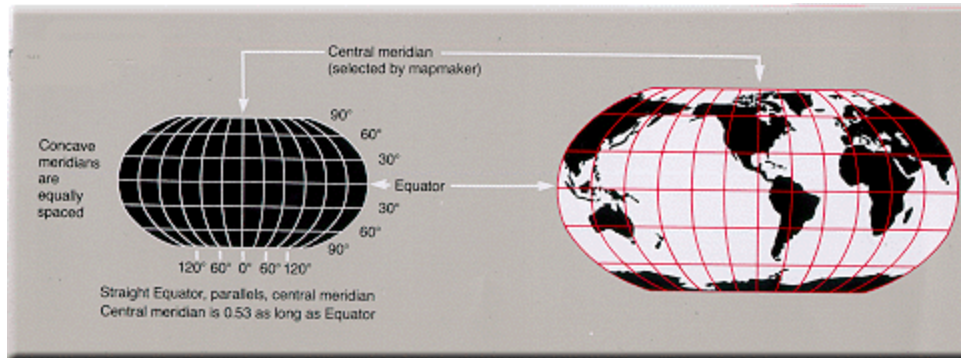
“A transverse Mercator projection is mathematically the same as a standard Mercator, but oriented around a different axis.”





# Robinson projection

“adopted by [National Geographic Magazine](#) in 1988 but abandoned by them in about 1997 for the [Winkel Tripel](#).”



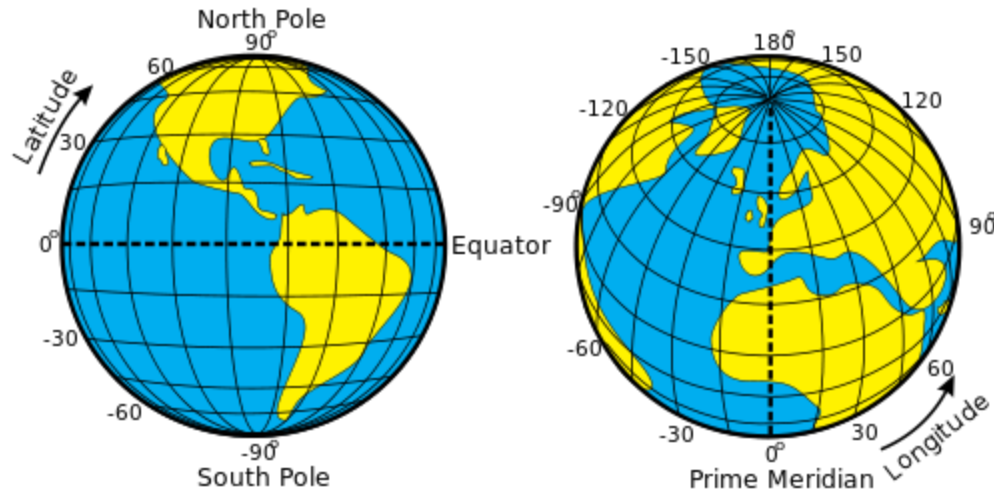


# 3. Coordinate systems

Projections refer to the method used for representing a three-dimensional object like the Earth on a two-dimensional surface like a sheet of paper or a computer screen.

[http://en.wikipedia.org/wiki/Geographic\\_coordinate\\_system](http://en.wikipedia.org/wiki/Geographic_coordinate_system)

# Latitude and Longitude of the Earth



## 4. Zoom levels

“A zoom level is a predefined scale at which a map is rendered.

OpenStreetMap, Google Maps, and most other online maps zoom levels are scaled such that the entire world fills a 256x256 pixel tile at zoom level 0, and doubles in width & height at each subsequent zoom level.”

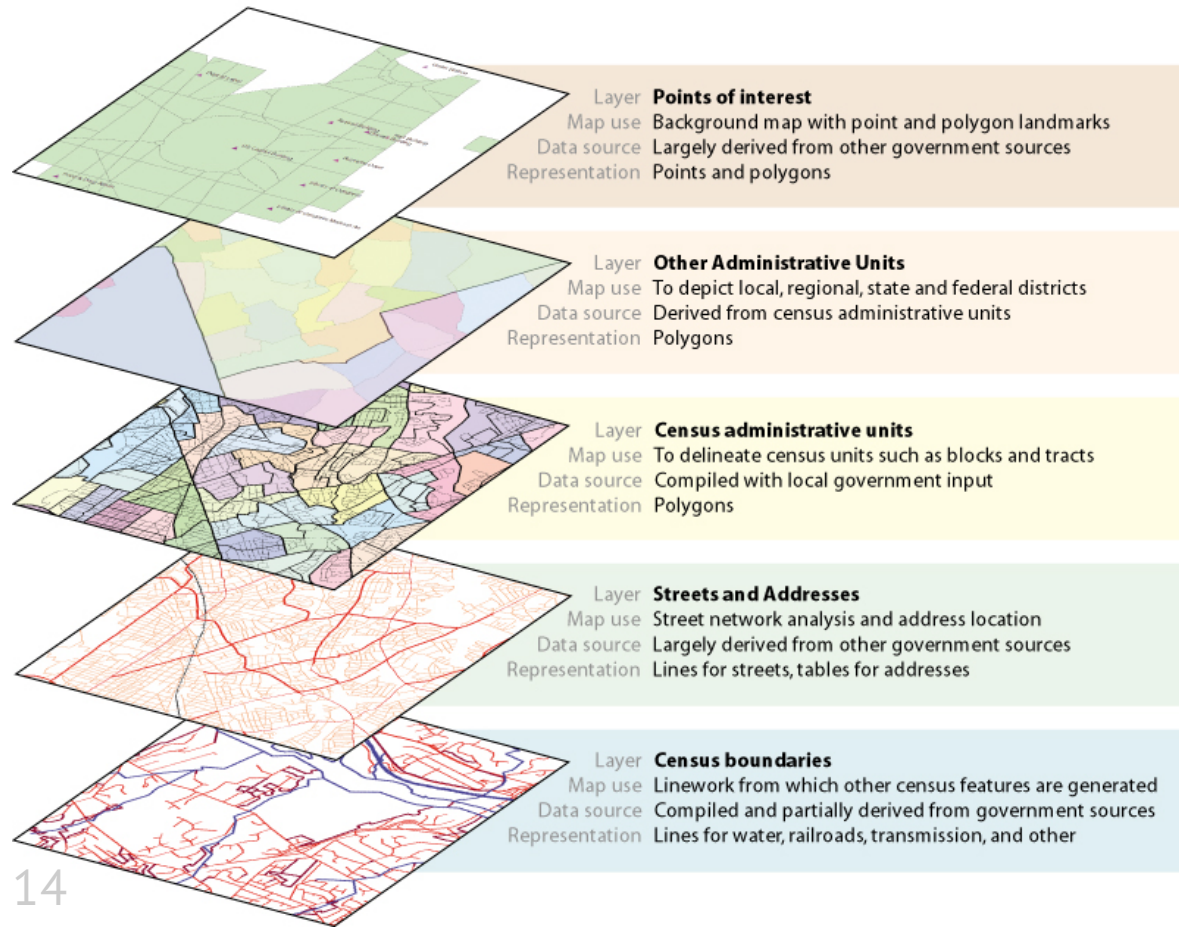
[http://wiki.openstreetmap.org/wiki/Zoom\\_levels](http://wiki.openstreetmap.org/wiki/Zoom_levels)

Level	Degree	Area	m / pixel	~Scale
0	360	whole world	156,412	1:500 Mio
1	180		78,206	1:250 Mio
2	90		39,103	1:150 Mio
3	45		19,551	1:70 Mio
4	22.5		9,776	1:35 Mio
5	11.25		4,888	1:15 Mio
6	5.625		2,444	1:10 Mio
7	2.813		1,222	1:4 Mio
8	1.406		610.984	1:2 Mio
9	0.703	wide area	305.492	1:1 Mio
10	0.352		152.746	1:500,000
11	0.176	area	76.373	1:250,000
12	0.088		38.187	1:150,000
13	0.044	village or town	19.093	1:70,000
14	0.022	largest editable area on the applet	9.547	1:35,000
15	0.011		4.773	1:15,000
16	0.005	small road	2.387	1:8,000
17	0.003		1.193	1:4,000
18	0.001		0.596	1:2,000

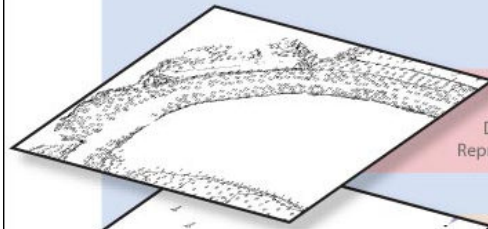
## 5. Layers

“Data on different themes are stored in separate “layers”. As each layer is geo-referenced layers from different sources can easily be integrated using location. Layer can be used to build up complex models of the real world from widely disparate sources.”

[see some layer related charts.](#)



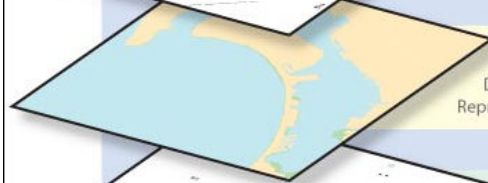
## Thematic map layers



Layer **Bathymetry**  
Map use To depict soundings and depth contours  
Data source Primarily hydrographic survey data  
Representation Points, lines, and polygons



Layer **NAVAIDS**  
Map use To depict aids to navigation features for mariners  
Data source Largely derived from hydrographic office sources  
Representation Points, lines, and polygons



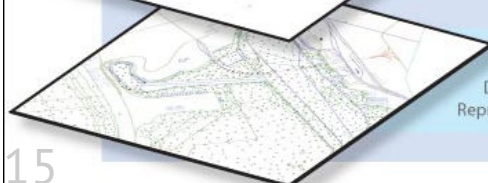
Layer **Skin of the Earth**  
Map use Contiguous, nonoverlapping areal coverage  
Data source Largely derived from hydrographic office sources  
Representation Polygons



Layer **Cautions**  
Map use Potential navigation hazards  
Data source Largely derived from hydrographic office sources  
Representation Points, lines, and polygons



Layer **Harbour Installations**  
Map use Port facilities  
Data source Largely derived from hydrographic office sources  
Representation Points, lines, and polygons



Layer **Vector Primitives**  
Map use Vector representation of all geodatabase features  
Data source Conflated representation of all feature classes  
Representation Points, lines, and polygons



## 6. Spatial databases

“A spatial database is a database that is optimized to store and query data that is related to objects in space, including points, lines and polygons.”

[http://en.wikipedia.org/wiki/Spatial\\_database](http://en.wikipedia.org/wiki/Spatial_database)

<http://www.spatial.cs.umn.edu/Book/slides/ch1revised.ppt>

# Postgres + Postgis

connect to postgres `psql -h localhost`

create database `CREATE DATABASE mydatabase;`


switch to your database `\connect mydatabase`

add postgis extension `CREATE EXTENSION postgis;`

<https://gist.github.com/yorzi/4345022>

**Quick Show-offs**

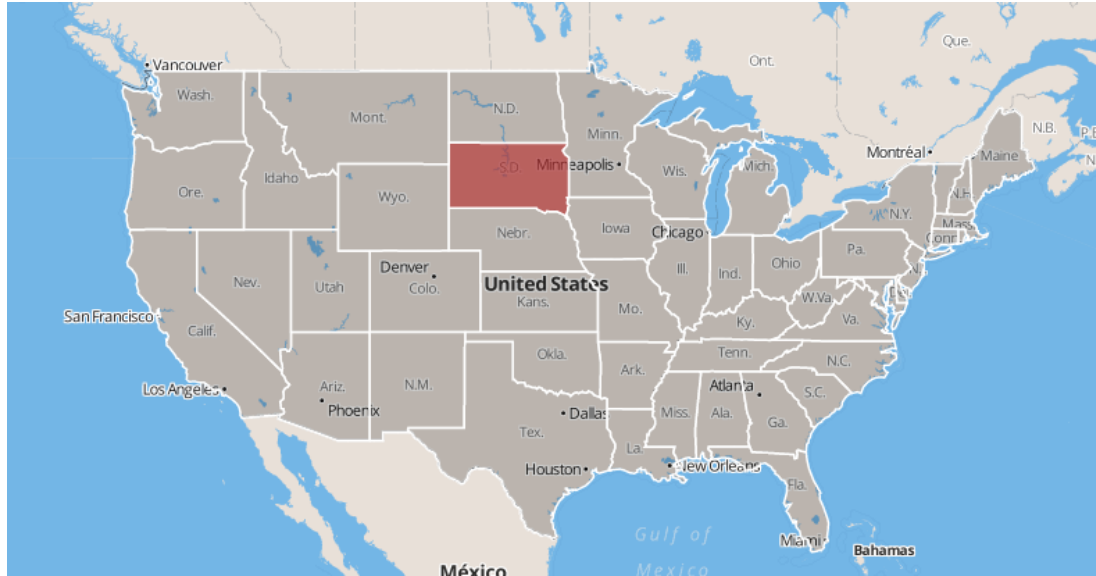
# Mapbox/TileJson + Wax + OpenLayer

Afghanistan  Comp



<http://mapbox.com/wax/connector-ol.html>

# Mapbox + D3



<https://gist.github.com/yorzi/5433125>

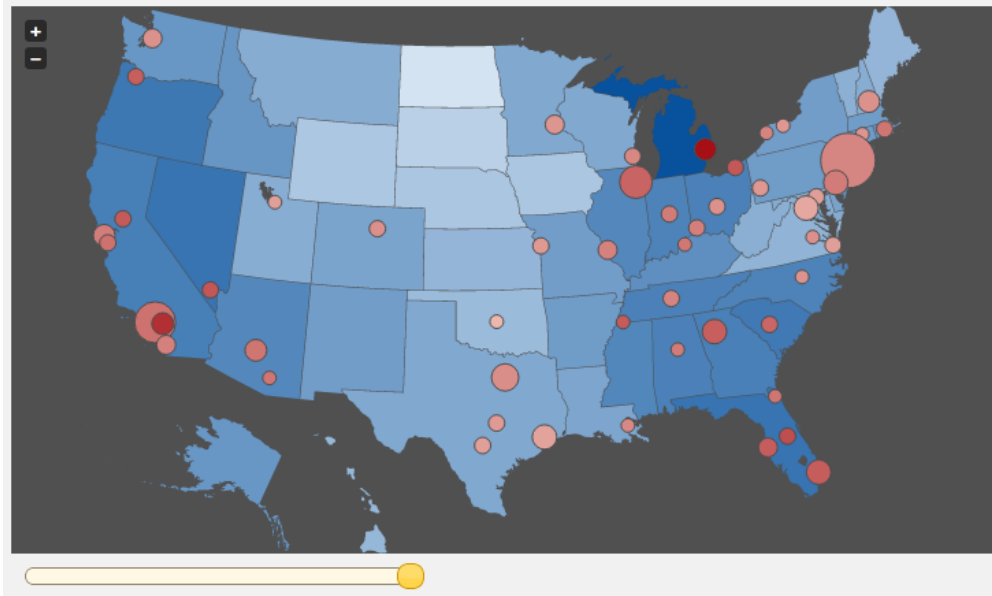
# D3 + SVG

```
var length = 300;  
var width = 350;  
  
var svg = d3.select('body').append('svg')  
  .attr('width', width)  
  .attr('height', height);  
var group = svg.append('g');  
  
var NYPath = "M7.0371 120.844l-0.6373 11.9674 ... -1.0232  
0.1923z";  
  
var ny = group.append('path')  
  .attr('d', NYPath)  
  .style('fill', 'grey')  
  .style('stroke', 'black')  
  .style('stroke-width', 1);
```



<http://www.schneidy.com/Tutorials/MapsTutorial.html>

# jVectorMap



<http://jvectormap.com/examples/usa-unemployment/>



# Resources on Maps



<http://mapbox.com/mapbox.js/api/v1.0.0/>

<http://mapbox.com/wax/>

<http://modestmaps.com/>

<http://leafletjs.com/>

<http://jvectormap.com/tutorials/getting-started/>

<https://github.com/mapbox/tilestream>

<http://openlayers.org/>

# Resources on GIS

<http://www.esri.com/>

<http://lib.stanford.edu/gis/>

<http://www.gislounge.com/gis-essentials/>

# **Thank You!**

