

view_frames Result
Recorded at time: 1768446984.8252788

robot_1/odom

Broadcaster: default authority
Average rate: 50.2
Buffer length: 5.0
Most recent transform: 136.445
Oldest transform: 131.445

robot_1/base_footprint

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/base_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bump_front_center

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bump_front_left

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bump_front_right

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bump_left

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bump_right

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/bumper

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_caster_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_left_bottom_weight_block

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_left_top_weight_block

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_right_bottom_weight_block

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_right_top_weight_block

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/left_wheel

Broadcaster: default authority
Average rate: 20.202
Buffer length: 4.95
Most recent transform: 136.425
Oldest transform: 131.475

robot_1/right_wheel

Broadcaster: default authority
Average rate: 20.202
Buffer length: 4.95
Most recent transform: 136.425
Oldest transform: 131.475

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_left_tower_standoff

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/front_right_tower_standoff

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/rear_left_tower_standoff

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/rear_right_tower_standoff

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/rplidar_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_1/tower_sensor_plate