view_frames Result Recorded at time: 12.162 map Broadcaster: /turtlebot3 slam gmapping Average rate: 20.270 Hz Most recent transform: 12.200 (-0.038 sec old) Buffer length: 3.700 sec odom Broadcaster: /movement publisher Average rate: 10.278 Hz Most recent transform: 12.100 (0.062 sec old) Buffer length: 3.600 sec base_footprint Broadcaster: /base link broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (12.162 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{0}00$ Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (12.162 sec old) Most recent transform: 0.000 (12.162 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec chassis base scan Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (12.162 sec old) Most recent transform: 0.000 (12.162 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec cylinder connector left cylinder connector right Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 10.278 Hz Average rate: 10.278 Hz Most recent transform: 12.100 (0.062 sec old) Most recent transform: 12.100 (0.062 sec old) Buffer length: 3.600 sec Buffer length: 3.600 sec rocker_right rocker left Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10.278 Hz Average rate: 10.278 Hz Average rate: 10.278 Hz Average rate: 10.278 Hz Most recent transform: 12.100 (0.062 sec old) Buffer length: 3.600 sec Buffer length: 3.600 sec Buffer length: 3.600 sec Buffer length: 3.600 sec bogie_left wheel_back_left bogie_right wheel_back_right Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.278 Hz Average rate: 10.278 Hz Average rate: 10.278 Hz Average rate: 10.278 Hz Most recent transform: 12.100 (0.062 sec old) Buffer length: 3.600 sec Buffer length: 3.600 sec Buffer length: 3.600 sec Buffer length: 3.600 sec wheel_middle_right wheel_front_left wheel_middle_left wheel_front_right