view frames Result Recorded at time: 73.790 map Broadcaster: /turtlebot3 slam gmapping Average rate: 20.317 Hz Most recent transform: 73.800 (-0.010 sec old) Buffer length: 3.150 sec odom Broadcaster: /movement publisher Average rate: 10.323 Hz Most recent transform: 73.700 (0.090 sec old) Buffer length: 3.100 sec base_footprint Broadcaster: /base link broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (73.790 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (73.790 sec old) Most recent transform: 0.000 (73.790 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec chassis lidar link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (73.790 sec old) Most recent transform: 0.000 (73.790 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec cylinder connector left cylinder connector right Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.323 Hz Average rate: 10.323 Hz Most recent transform: 73.700 (0.090 sec old) Most recent transform: 73.700 (0.090 sec old) Buffer length: 3.100 sec Buffer length: 3.100 sec rocker_right rocker left Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10.323 Hz Average rate: 10.323 Hz Average rate: 10.323 Hz Average rate: 10.323 Hz Most recent transform: 73.700 (0.090 sec old) Buffer length: 3.100 sec Buffer length: 3.100 sec Buffer length: 3.100 sec Buffer length: 3.100 sec bogie_left wheel_back_left bogie_right wheel_back_right Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.323 Hz Average rate: 10.323 Hz Average rate: 10.323 Hz Average rate: 10.323 Hz Most recent transform: 73.700 (0.090 sec old) Most recent transform: 73.700 (0.090 sec old) Most recent transform: 73.700 (0.090 sec old) \Most recent transform: 73.700 (0.090 sec old) Buffer length: 3.100 sec Buffer length: 3.100 sec Buffer length: 3.100 sec Buffer length: 3.100 sec wheel_front_left wheel_middle_left wheel_front_right wheel_middle_right