POSCAT Seminar 9 : Graph 1

yougatup @ POSCAT



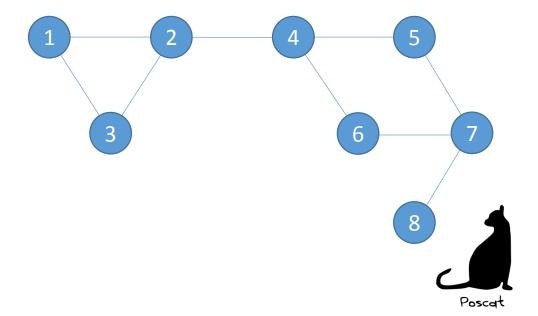
Topic

Topic today

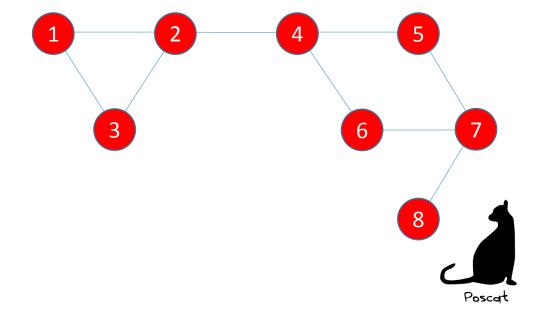
- Basic concept
- Graph representation
 - Adjacency matrix
 - Adjacency list
 - Tradeoffs
- Graph Traversal
 - Depth First Search
 - Breadth First Search
 - Flood Fill
 - Connected Component
 - Strongly Connected Component



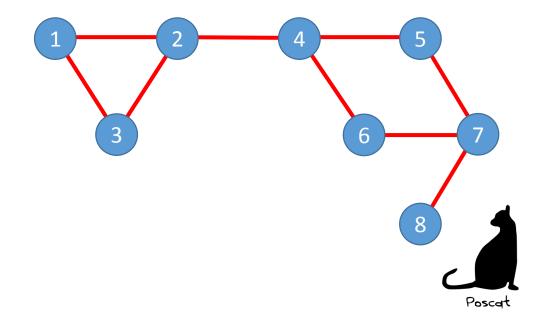
- Basic Concept
 - -G = (V, E)
 - A set of vertices and edges



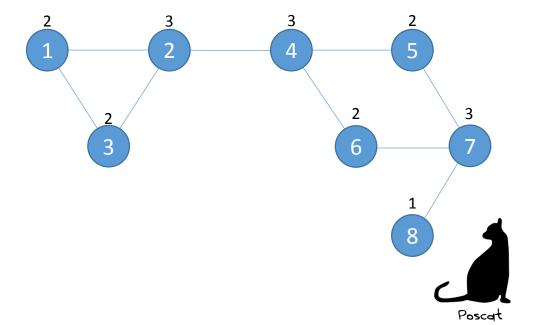
- Terminology
 - Nodes



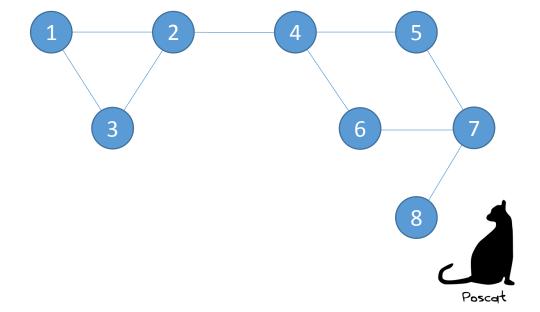
- Terminology
 - Edges



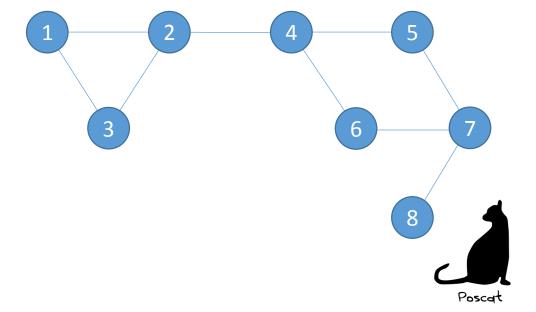
- Basic Concept
 - Degree(v): the number of adjacent edges for a vertex v



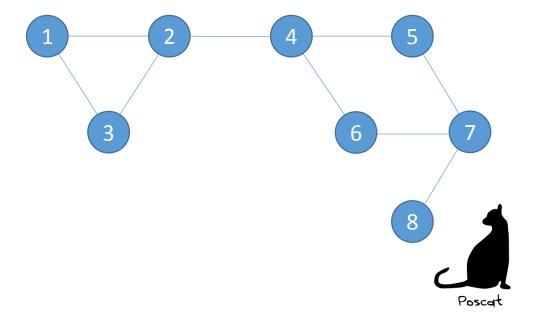
- Basic Concept
 - Connectedness: a graph is connected if there exist always a path which connects v and w for all v, w



- Representation
 - How can we represent a graph in the computer ?
 - Adjacency matrix & list

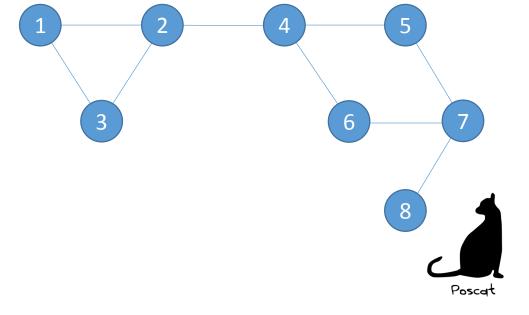


- Adjacency Matrix
 - Use matrix! (you may already know this)
 - $-G_{ij} = 1$ if there is a edge between vertex i and j
 - 0 otherwise



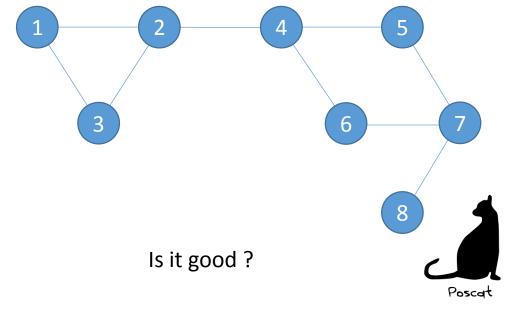
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	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	0	0	0	0
3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



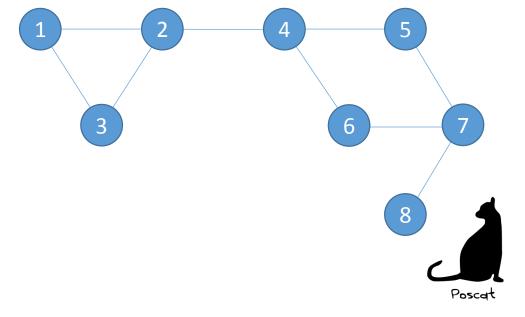
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4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



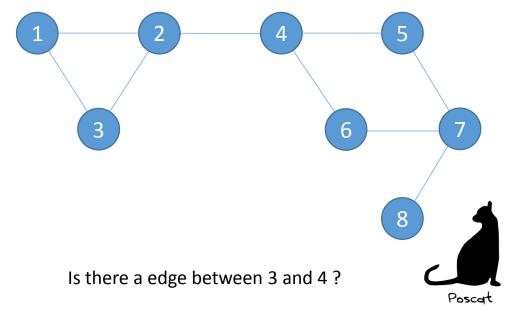
- Adjacency Matrix
 - We can determine whether there is a edge between i and j directly

	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	0	0	0	0
3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



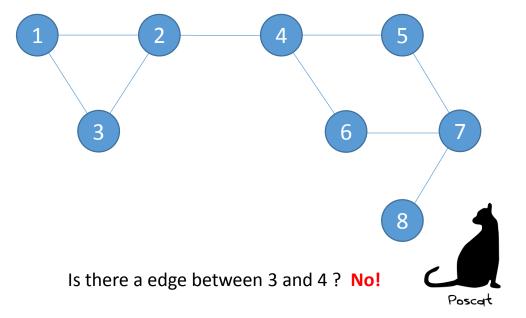
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3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



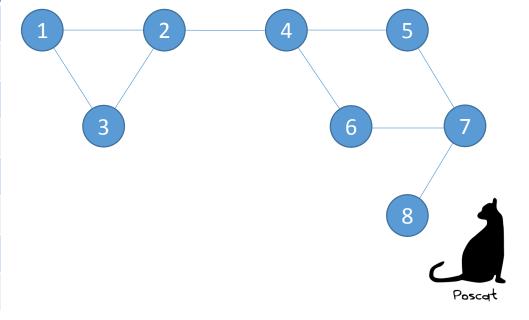
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1	0	1	1	0	0	0	0	0
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3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



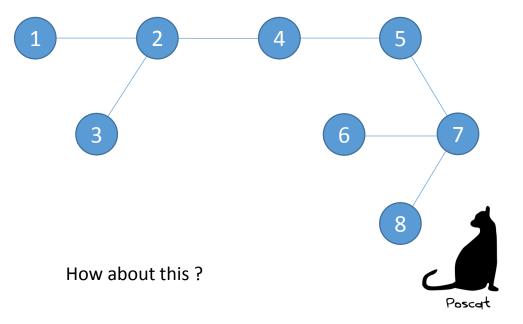
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- We have to maintain whole matrix to save a graph

	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	0	0	0	0
3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



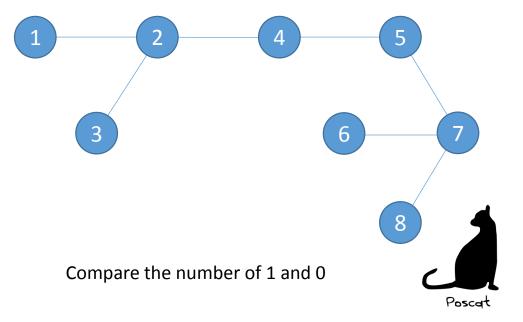
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2	1	0	1	1	0	0	0	0
3	0	1	0	0	0	0	0	0
4	0	1	0	0	1	0	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	0	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



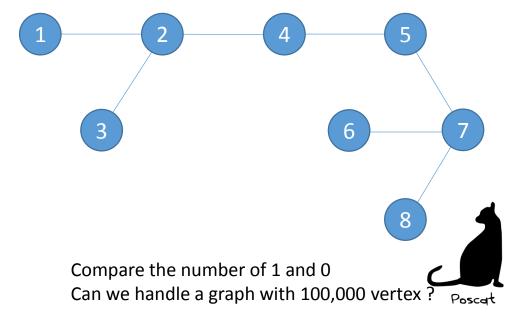
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3	0	1	0	0	0	0	0	0
4	0	1	0	0	1	0	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	0	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



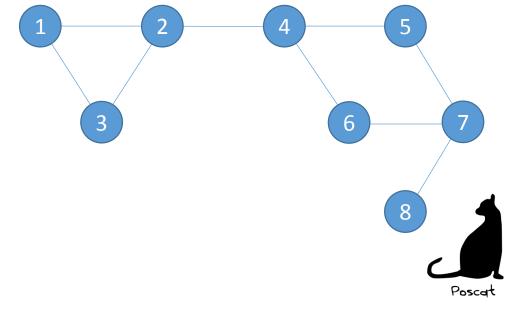
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4	0	1	0	0	1	0	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	0	0	0	1	0
7	0	0	0	0	1	1	0	1
8	0	0	0	0	0	0	1	0



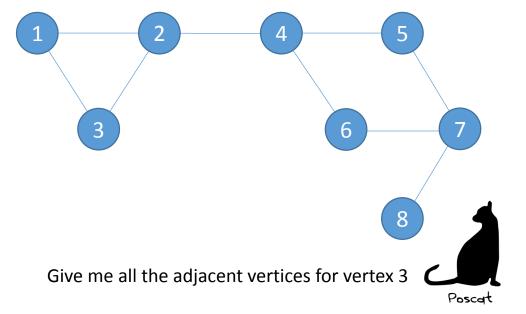
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- We have to maintain whole matrix to save a graph
- It takes O(V) to find all the adjacent vertices for a vertex v

	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	0	0	0	0
3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
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8	0	0	0	0	0	0	1	0



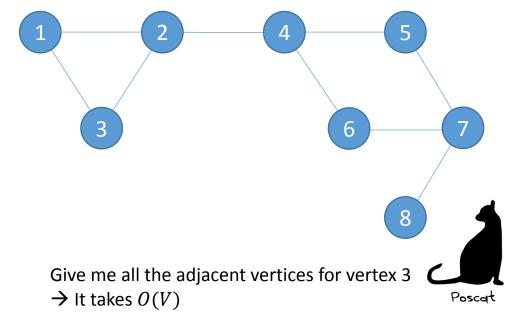
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3	1	1	0	0	0	0	0	0
4	0	1	0	0	1	1	0	0
5	0	0	0	1	0	0	1	0
6	0	0	0	1	0	0	1	0
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8	0	0	0	0	0	0	1	0

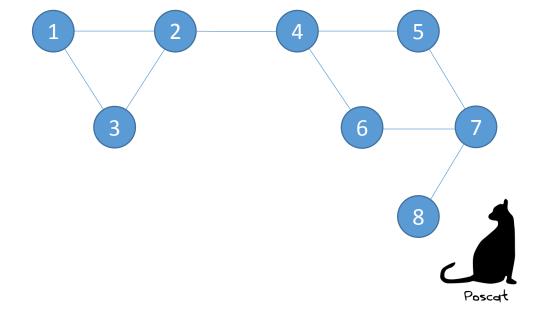


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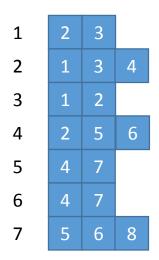
	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	0	0	0	0
3	1	1	0	0	0	0	0	0
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5	0	0	0	1	0	0	1	0
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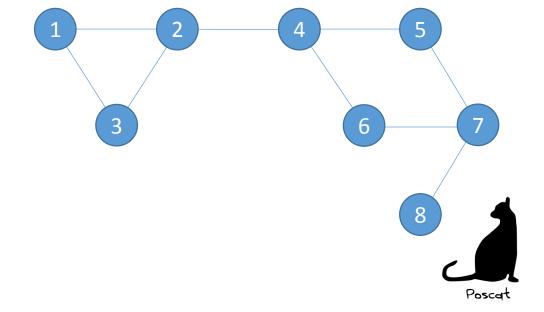


- Adjacency List
 - Handle just adjacent vertices for all vertices

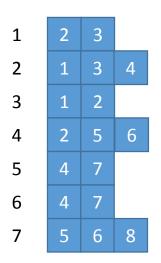


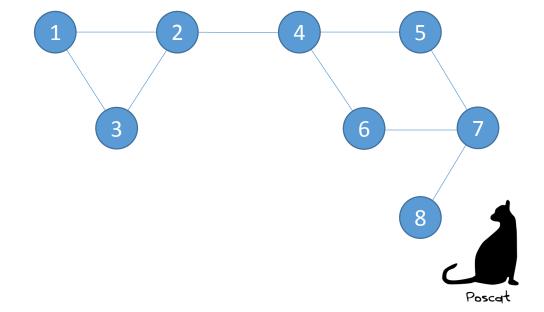
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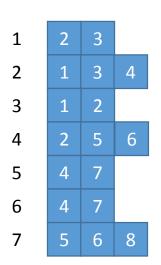


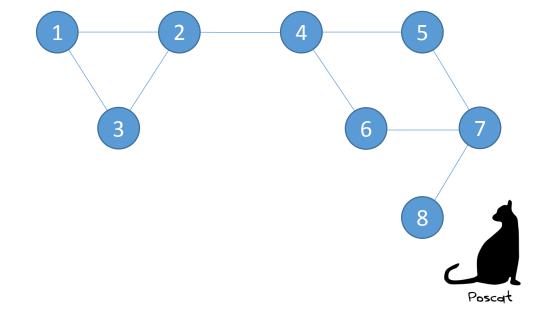
- Adjacency List
 - Handle just adjacent vertices for all vertices
 - Optimal space complexity (i.e. no redundant space)



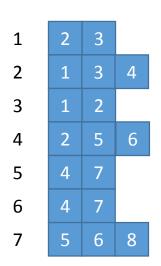


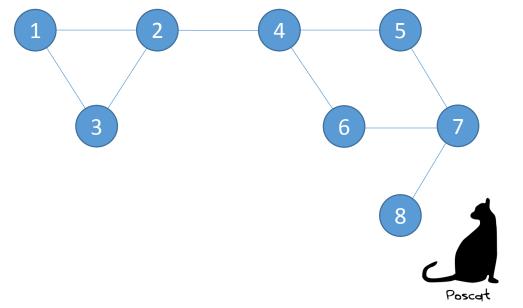
- Handle just adjacent vertices for all vertices
- Optimal space complexity (i.e. no redundant space)
- It takes O(degree(v)) to find all the adjacent vertices for vertex v



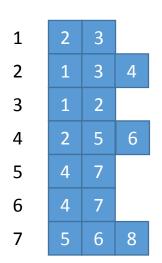


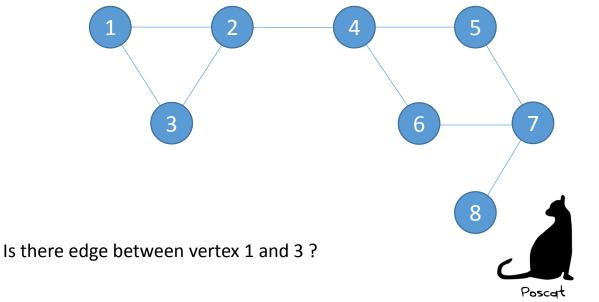
- Handle just adjacent vertices for all vertices
- Optimal space complexity (i.e. no redundant space)
- It takes O(degree(v)) to find all the adjacent vertices for vertex v
- It take also O(degree(v)) to determine the existence of edge



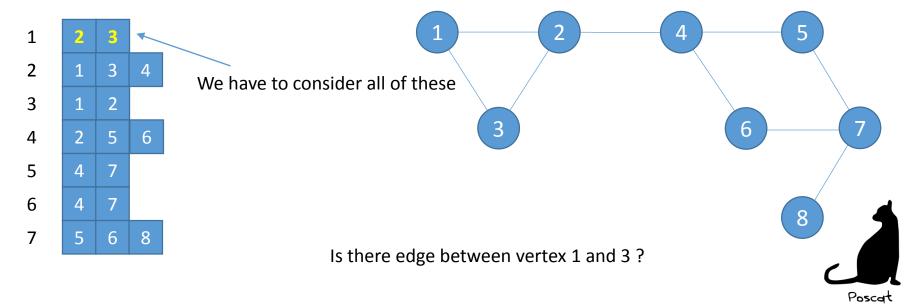


- Handle just adjacent vertices for all vertices
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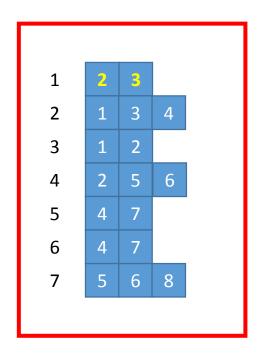


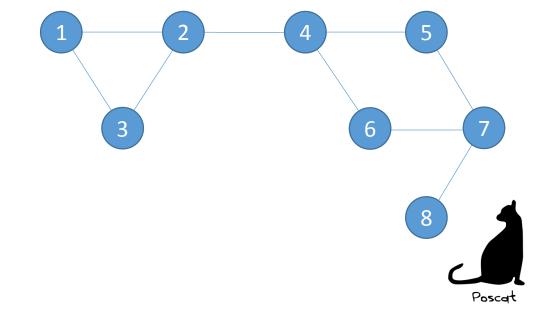
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Adjacency List

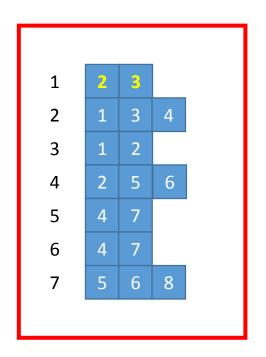
By the way, is it possible to manage this kind of structure?

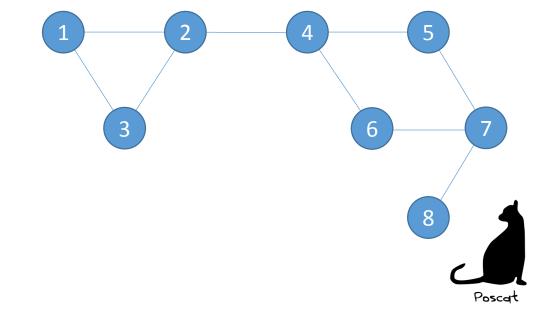




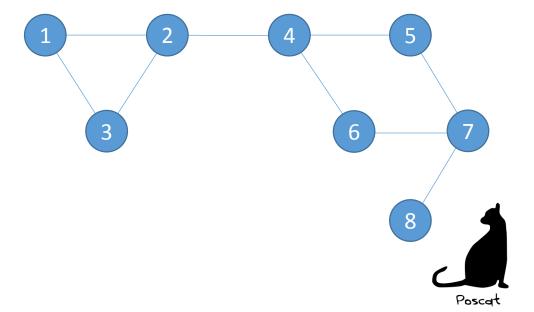
Adjacency List

By the way, is it possible to manage this kind of structure ? Yes we can! Use STL vector (I'll give some simple lecture for you today)

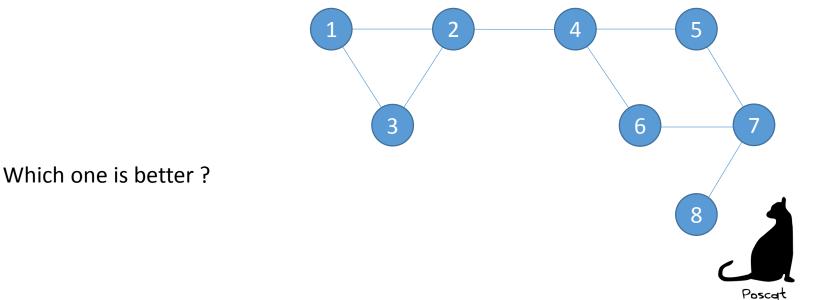




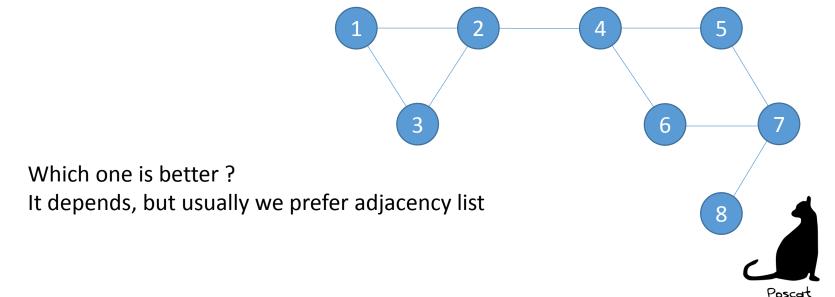
- Adjacency matrix VS Adjacency list
- Existence of edge ?
- Find all the neighboring vertices ?
- Space ?



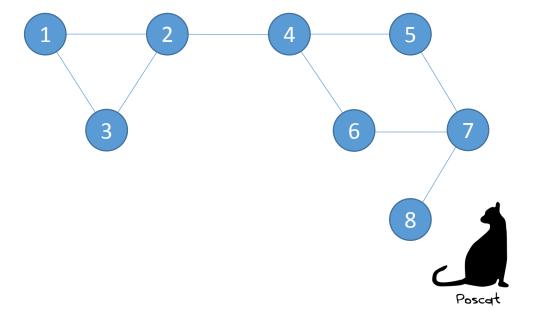
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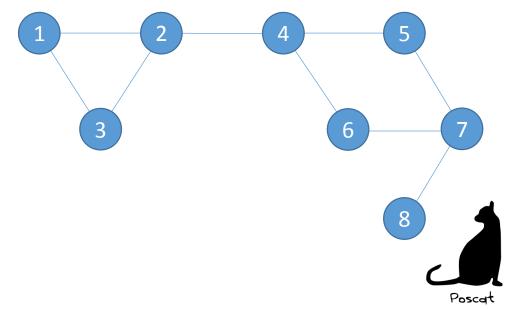
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Graph Traversal

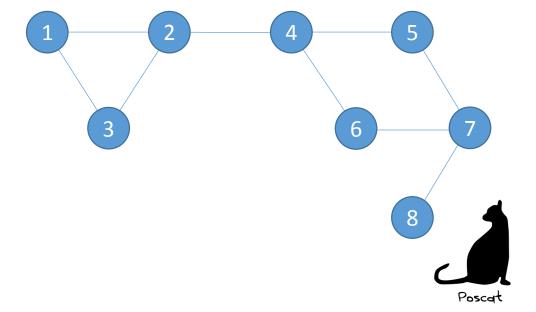
Traversal paradigm

- Basically, graph is also data structure
- In other words, we want to contain some information into a graph
- Therefore, we have to be able to traverse whole graph to find datas
- Depth First Search VS Breadth First Search

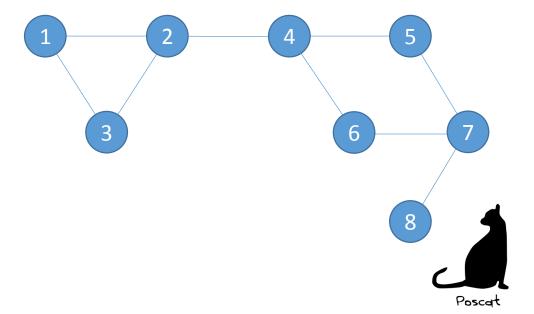


Graph Traversal

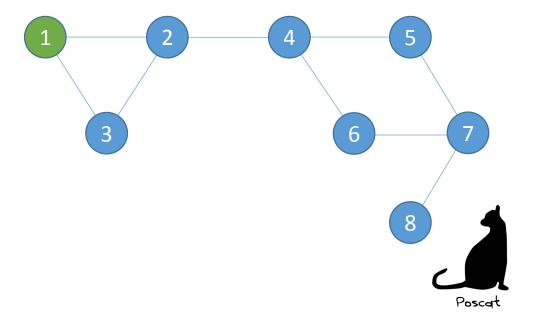
- Depth First Search
 - Use stack to traverse
 - Invarient: The current vertex is pointed by the top of the stack
 (Discuss it later. Forget it)



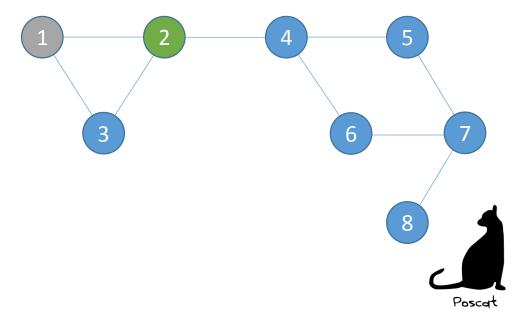
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



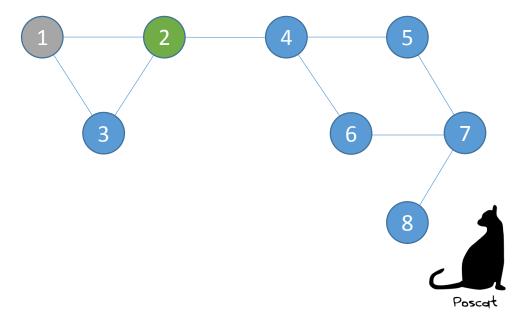
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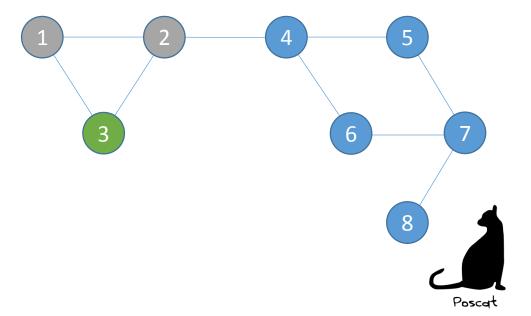
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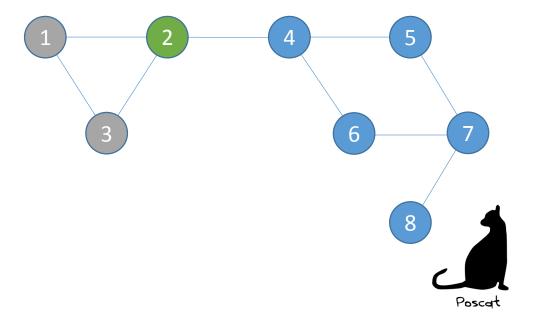
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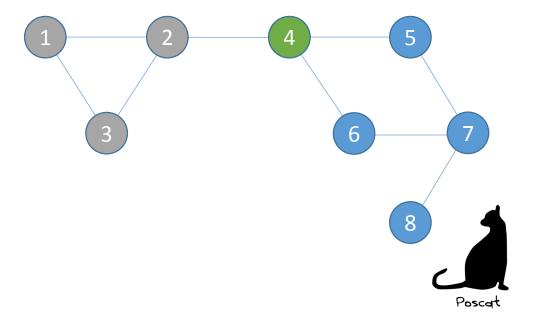
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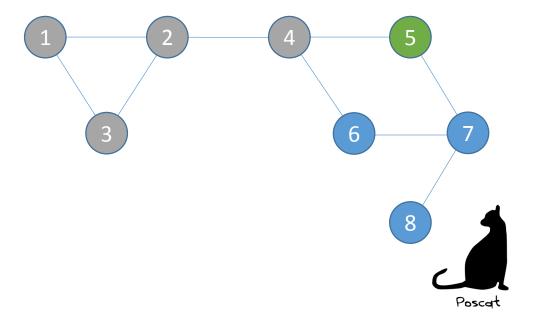
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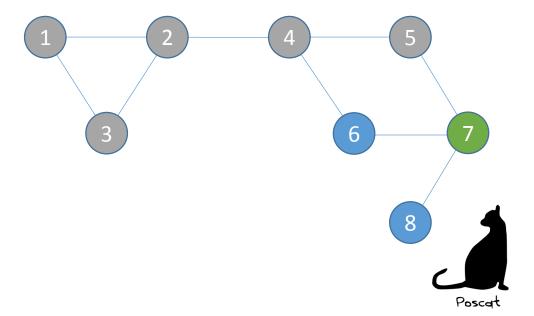
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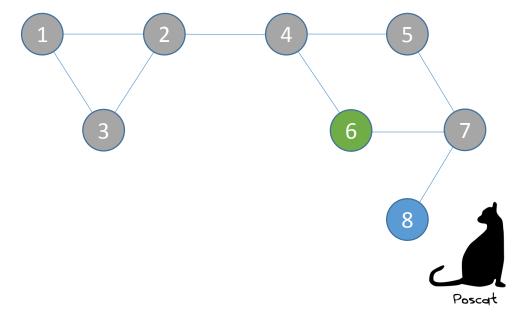
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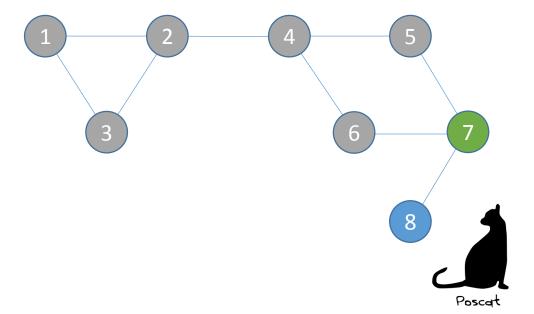
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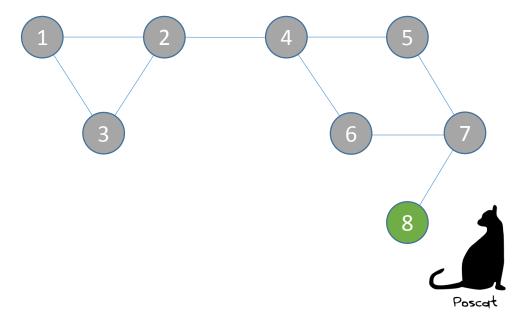
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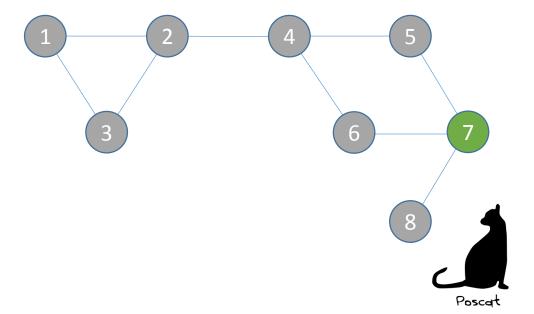
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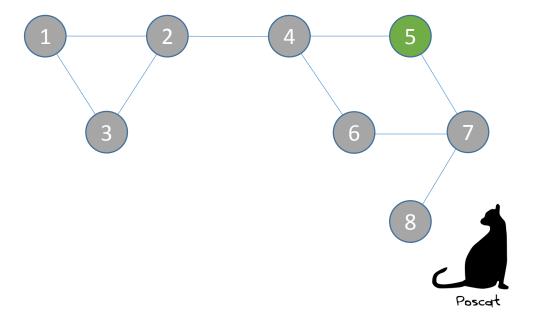
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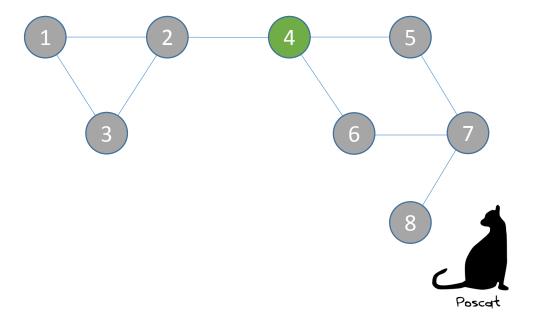
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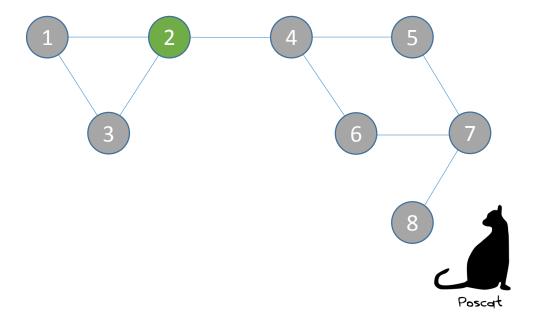
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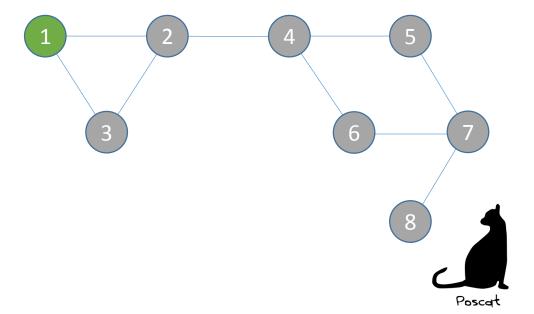
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



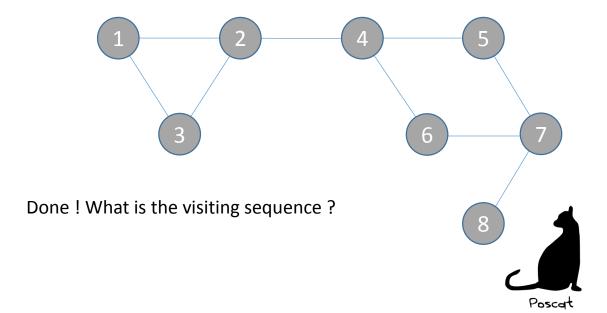
- Procedure
 - 1. Select a start vertex
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 - 3. If there is no such a vertex, move backward
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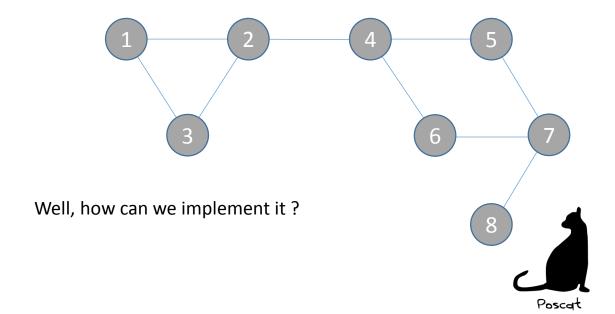
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
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 - 4. Go to step 2.



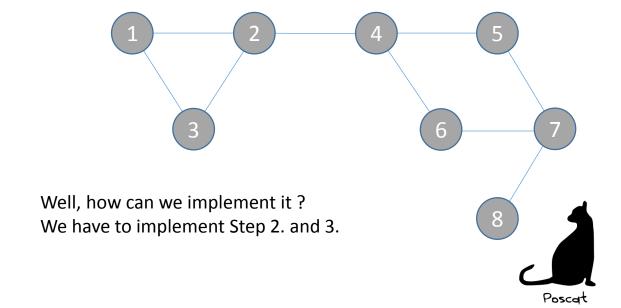
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
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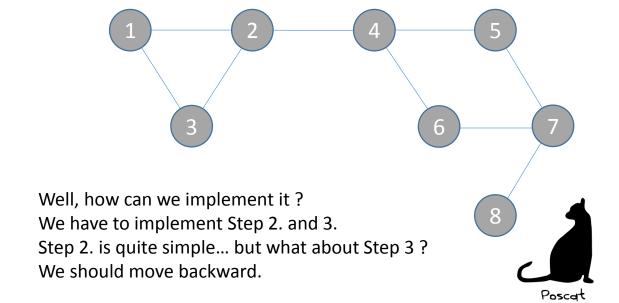
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



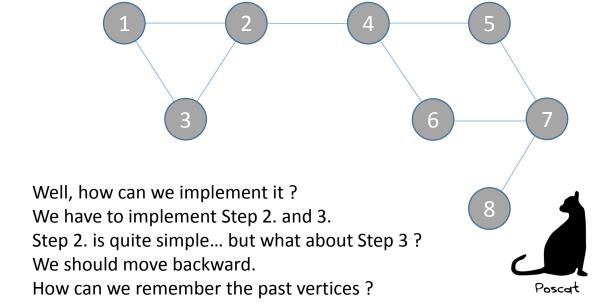
- Procedure
 - Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



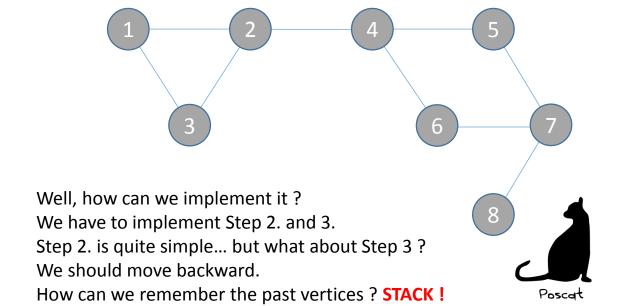
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



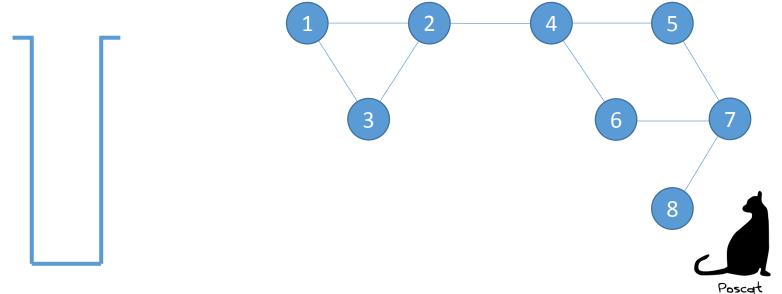
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



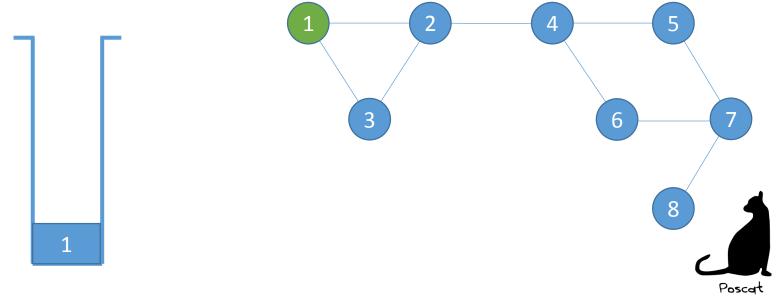
- Procedure
 - Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



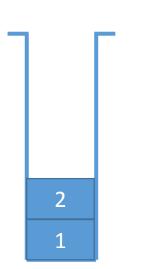
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.

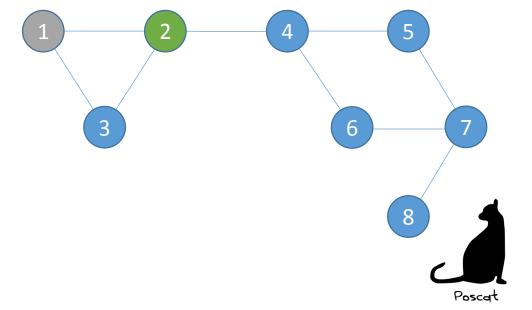


- Procedure
 - Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.

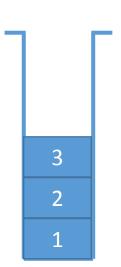


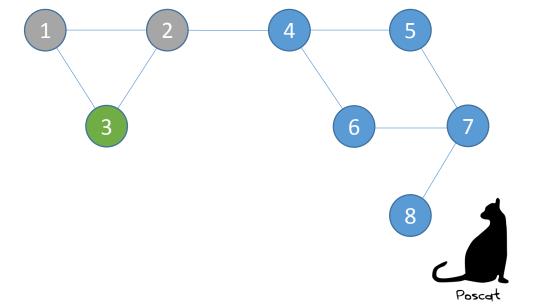
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



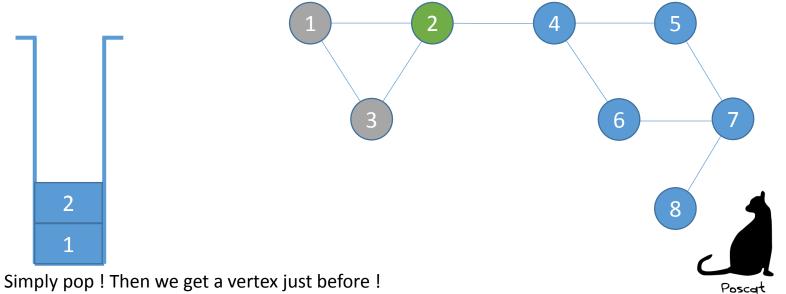


- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.

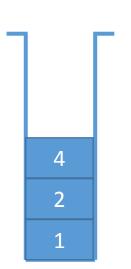


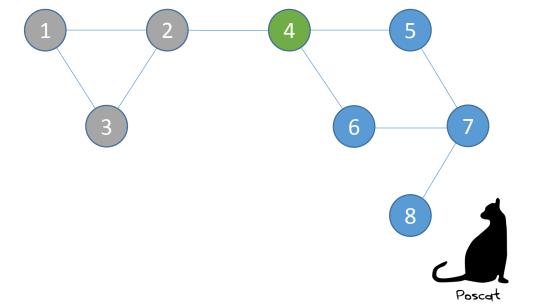


- Procedure
 - Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.

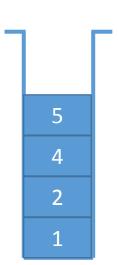


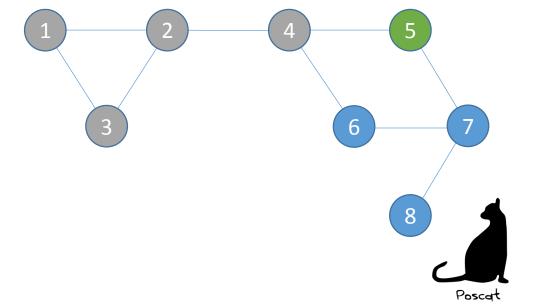
- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



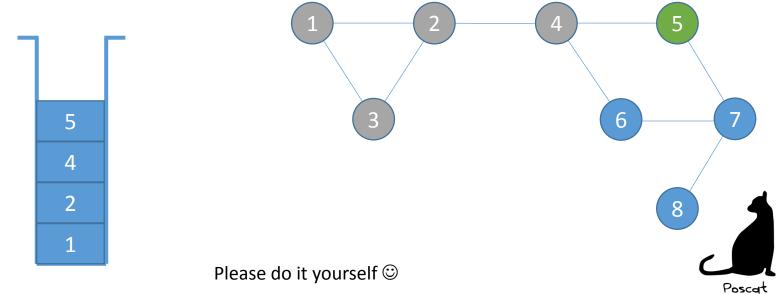


- Procedure
 - 1. Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.

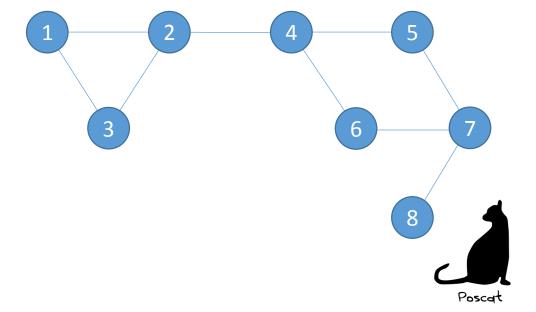




- Procedure
 - Select a start vertex
 - 2. Move to adjacent vertex we don't visit yet
 - 3. If there is no such a vertex, move backward
 - 4. Go to step 2.



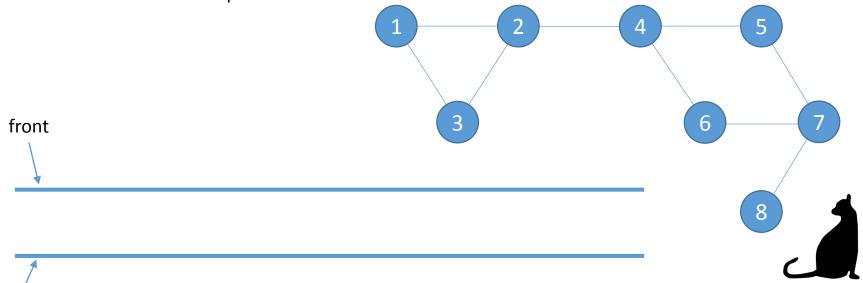
- Breadth First Search
 - Use queue to traverse
 - Invarient: The current vertex is pointed by front pointer



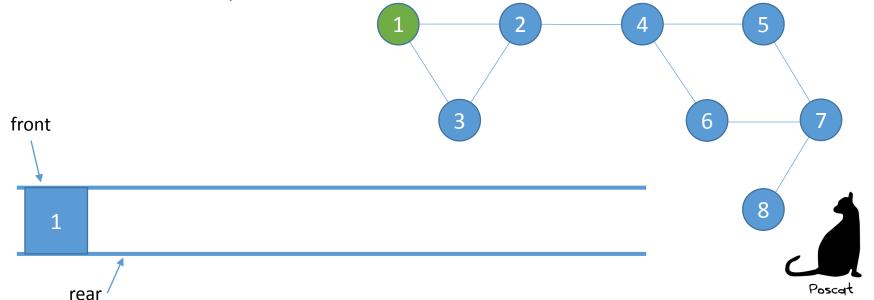
Poscat

Graph Traversal

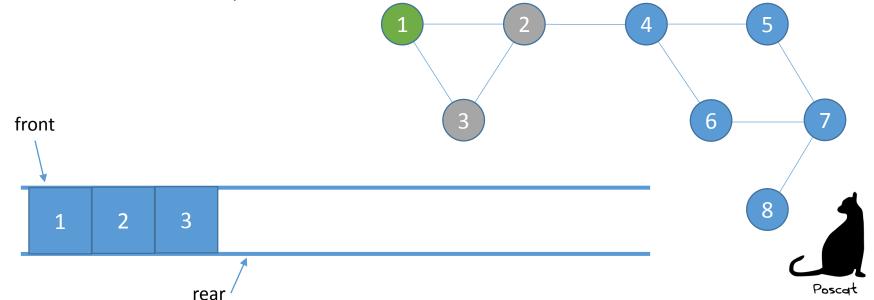
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



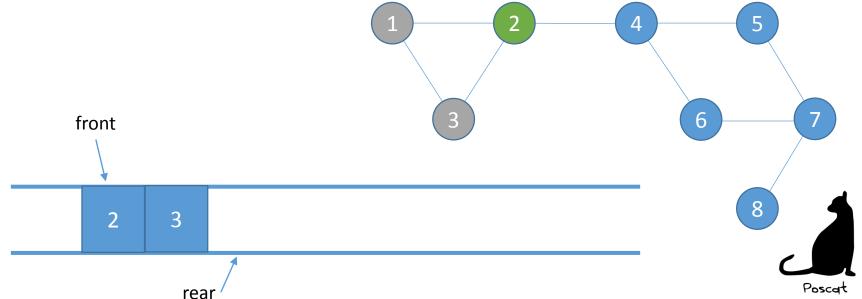
- Procedure
 - Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



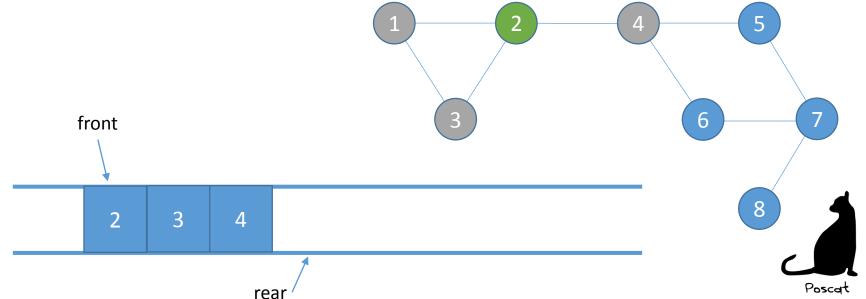
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



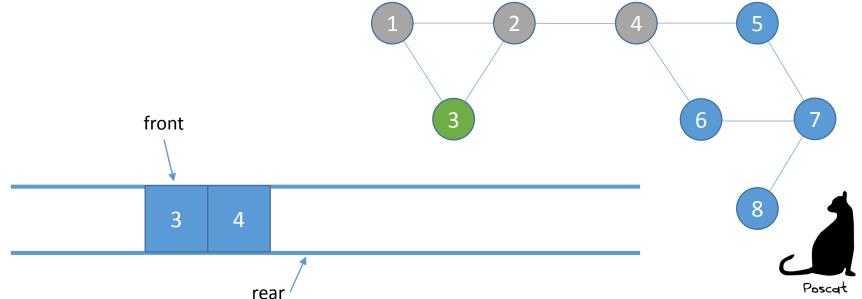
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



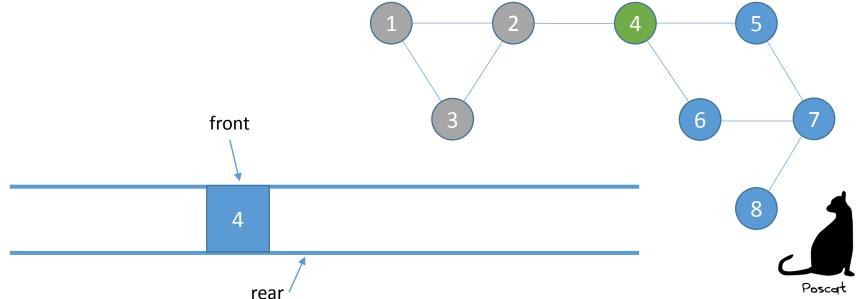
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



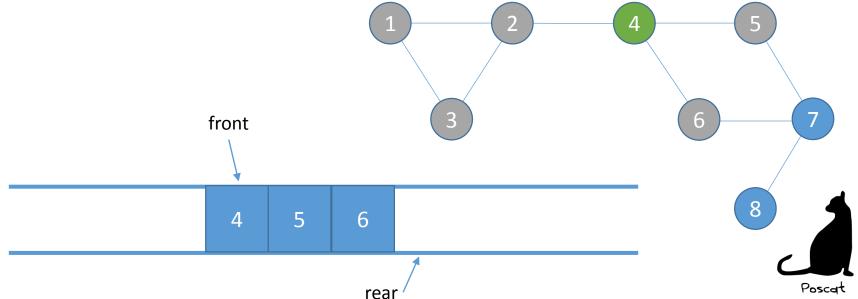
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



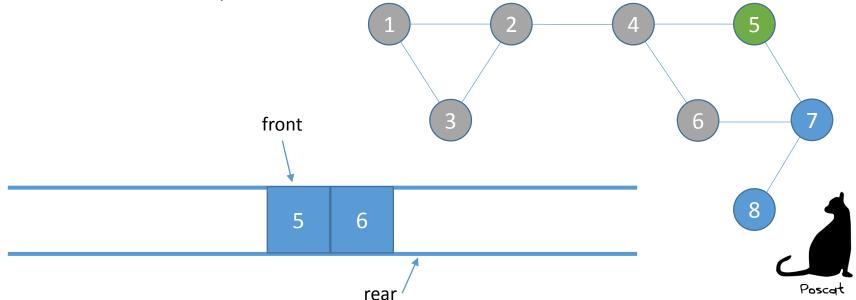
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



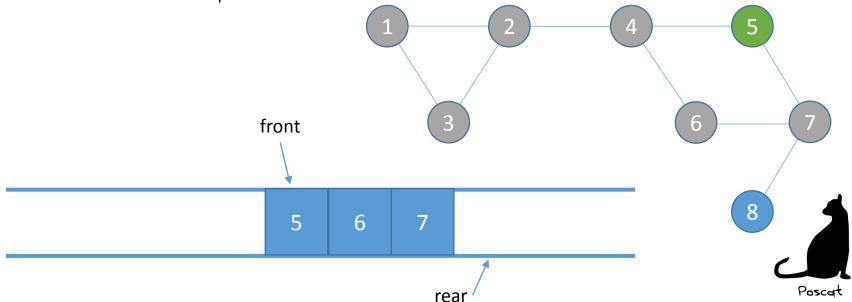
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



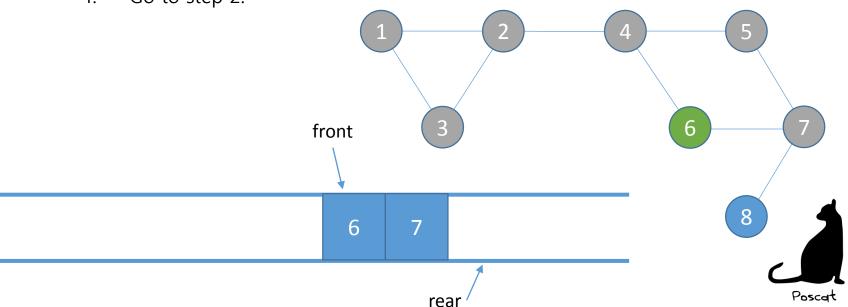
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



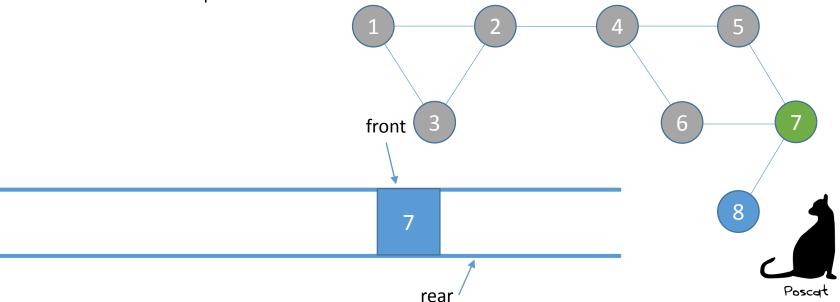
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



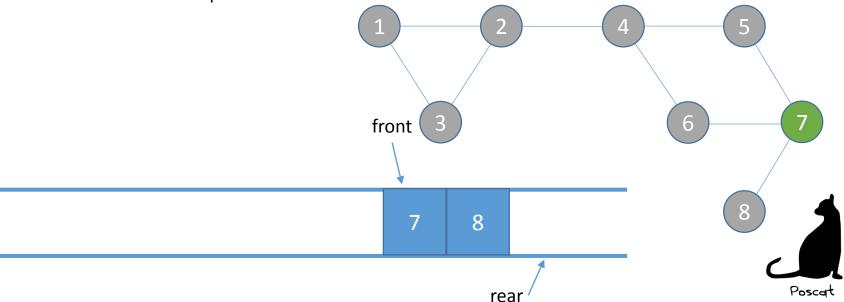
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



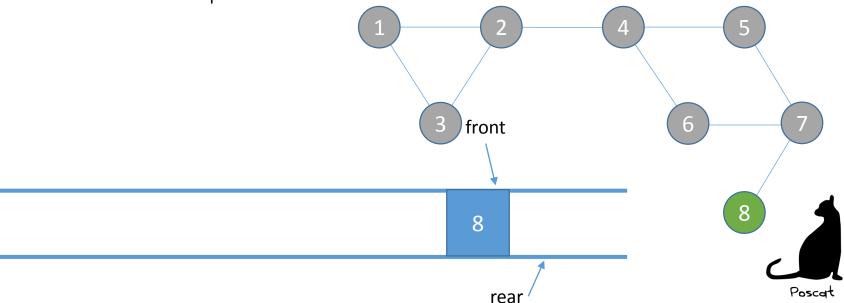
- Procedure
 - Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



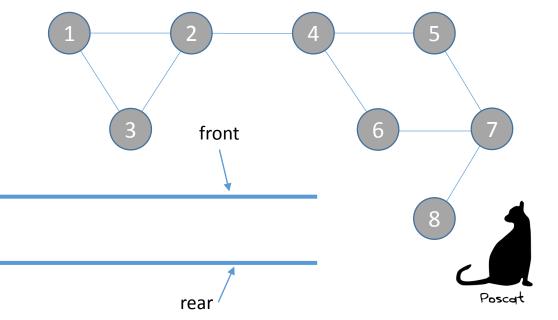
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



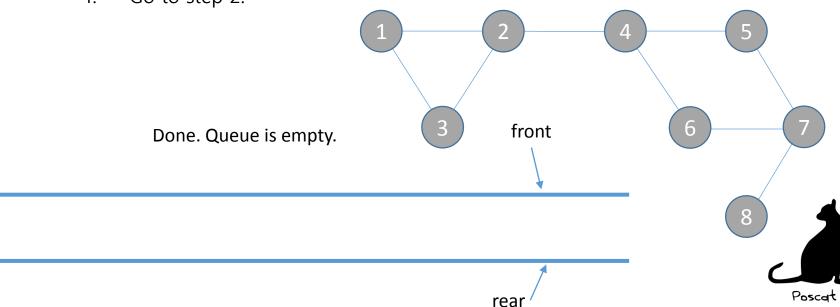
- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



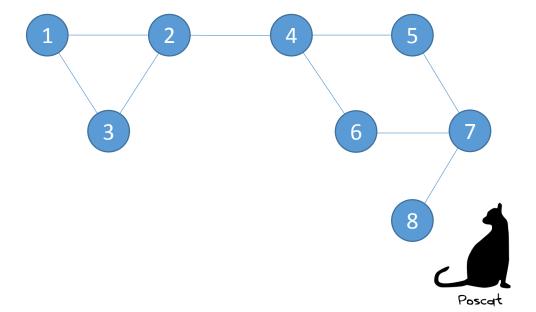
- Procedure
 - 1. Select a start vertex
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 - 4. Go to step 2.



- Procedure
 - 1. Select a start vertex
 - 2. Push all the adjacent vertices into queue
 - 3. Pop to get a new vertex
 - 4. Go to step 2.



- DFS vs BFS
 - We have to choose what search technique to use
 - Example ?



Problem

Given a map, categorize each cell as inner or outer cell Suppose that the outer-most cell is always 0

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Given a map, categorize each cell as inner or outer cell Suppose that the outer-most cell is always 0

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Any idea ?

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Any idea? Modeling it as a graph!

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Any idea? Modeling it as a graph!

Each cell is considered as a vertex. How about edge?

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Any idea? Modeling it as a graph! there is a edge if two vertices are adjacent in the map

0	0	P	0	0	0	0	0	0	0
0	G	- o-	- 0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Perform DFS or BFS starting from the outermost cell! However, we never move to the '1' cell

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
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0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
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0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



0	0	0	0	0	0	0	0	0	0
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0	0	1	1	1	1	0	0	0	0
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0	0	1	0	0	0	0	1	0	0
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0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



0	0	0	0	0	0	0	0	0	0
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0	0	0	0	1	0	1	1	1	0
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0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Can we apply this flood fill algorithm to solve a problem?

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	0	0
0	0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0	1	0
0	0	1	0	0	0	0	0	1	0
0	0	0	1	0	1	0	0	1	0
0	0	0	0	1	0	1	1	1	0
0	0	0	0	0	0	0	0	0	0



Problem

Find the minimum length from the start cell and the end cell

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

Find the minimum length from the start cell and the end cell Here!

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

Find the minimum length from the start cell and the end cell However, there is another path which is longer!

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

Which traversal is better? DFS or BFS?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

Which traversal is better? DFS or BFS ?

Definitely, BFS is better in this time. Think about the reason

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
0	1	1	0	1	0	1	1	1	0
0	0	0	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
0	1	0	0	1	0	1	0	0	0
1	1	1	0	1	0	1	1	1	0
0	1	0	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
0	1	1	0	1	0	1	0	1	0
2	1	0	0	1	0	1	0	0	0
1	1	1	0	1	0	1	1	1	0
0	1	2	0	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
0	1	1	0	1	0	0	0	1	0
3	1	1	0	1	0	1	0	1	0
2	1	0	0	1	0	1	0	0	0
1	1	1	0	1	0	1	1	1	0
0	1	2	3	0	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
0	1	1	0	0	0	1	1	0	0
4	1	1	0	1	0	0	0	1	0
3	1	1	0	1	0	1	0	1	0
2	1	0	0	1	0	1	0	0	0
1	1	1	4	1	0	1	1	1	0
0	1	2	3	4	0	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
0	1	1	0	0	0	1	0	1	0
5	1	1	0	0	0	1	1	0	0
4	1	1	0	1	0	0	0	1	0
3	1	1	0	1	0	1	0	1	0
2	1	0	5	1	0	1	0	0	0
1	1	1	4	1	0	1	1	1	0
0	1	2	3	4	5	0	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
0	1	1	1	1	0	0	0	1	0
6	1	1	0	0	0	1	0	1	0
5	1	1	0	0	0	1	1	0	0
4	1	1	0	1	0	0	0	1	0
3	1	1	6	1	0	1	0	1	0
2	1	6	5	1	0	1	0	0	0
1	1	1	4	1	6	1	1	1	0
0	1	2	3	4	5	6	1	0	0



Problem

How can we find the optimal path?

0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
7	1	1	1	1	0	0	0	1	0
6	1	1	0	0	0	1	0	1	0
5	1	1	8	0	0	1	1	0	0
4	1	1	7	1	0	0	0	1	0
3	1	1	6	1	8	1	0	1	0
2	1	6	5	1	7	1	0	0	0
1	1	1	4	1	6	1	1	1	0
0	1	2	3	4	5	6	1	0	0



Problem

How can we find the optimal path?

Let P(i,j) = the shortest length to (i,j), and fill it by using flood fill

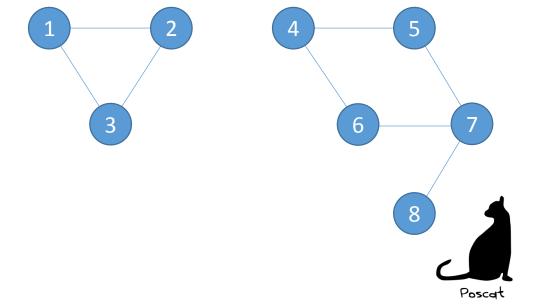
0	0	0	0	0	0	0	0	0	0
1	1	0	0	0	1	0	0	0	0
7	1	1	1	1	0	0	0	1	0
6	1	1	9	0	0	1	0	1	0
5	1	1	8	9	0	1	1	0	0
4	1	1	7	1	9	0	0	1	0
3	1	1	6	1	8	1	0	1	0
2	1	6	5	1	7	1	0	0	0
1	1	1	4	1	6	1	1	1	0
0	1	2	3	4	5	6	1	0	0

Fill it yourself ©



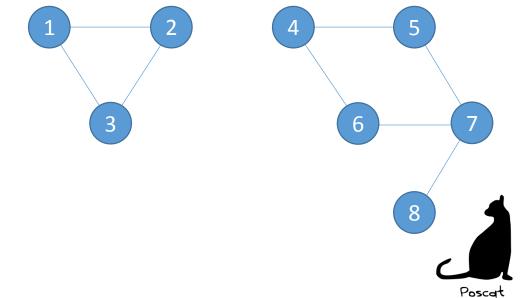
Problem

Given a graph, determine whether this graph is connected or not



Problem

Given a graph, determine whether this graph is connected or not



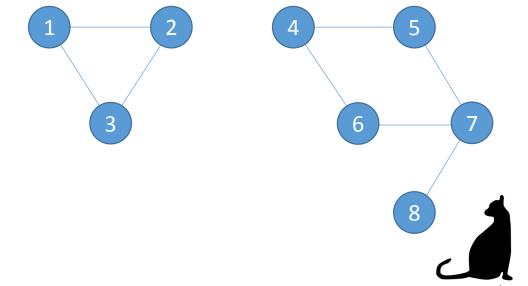
Is it connected?

Poscat

Connected Component

Problem

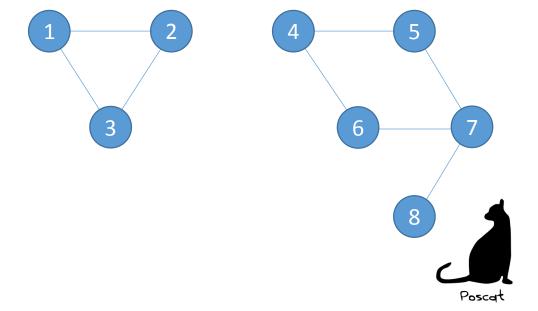
Given a graph, determine whether this graph is connected or not



Is it connected? NO!

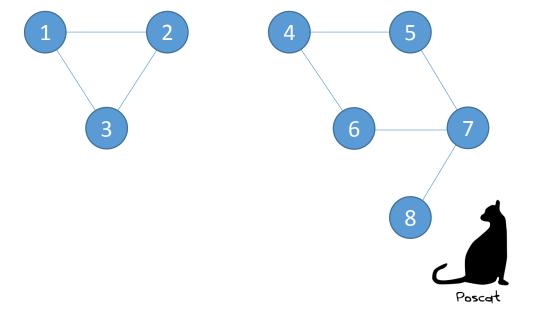
Problem

Given a graph, determine whether this graph is connected or not One traversal from any start vertex is enough. Easy.



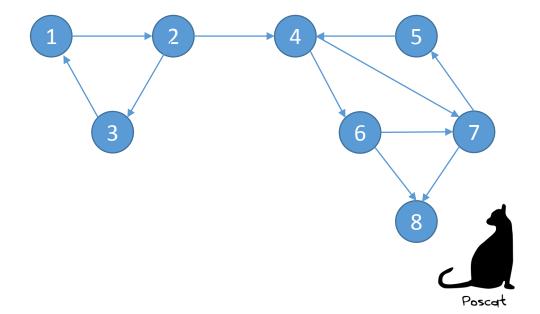
Problem

Given a graph, determine whether this graph is connected or not One traversal from any start vertex is enough. Easy. What if this graph is directed graph?



Problem

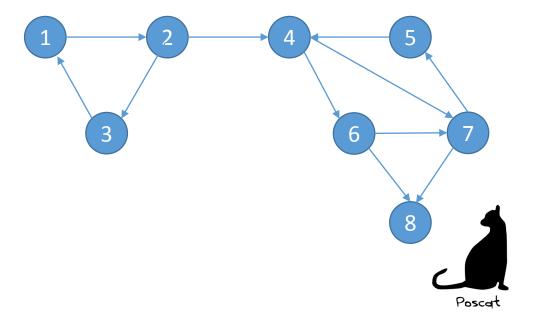
Given a graph, determine whether this graph is connected or not One traversal from any start vertex is enough. Easy. What if this graph is directed graph?



Problem

Given a direct graph, Find Strongly Connected Component

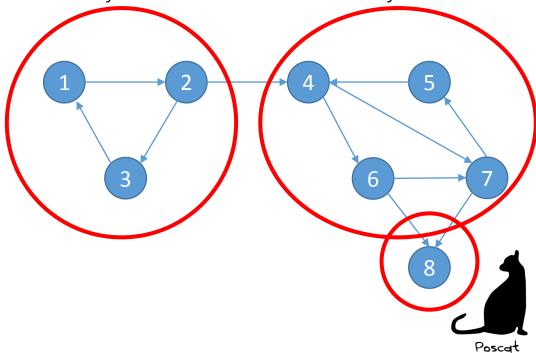
SCC: a graph is strongly connected if every vertex is reachable from every other vertex



Problem

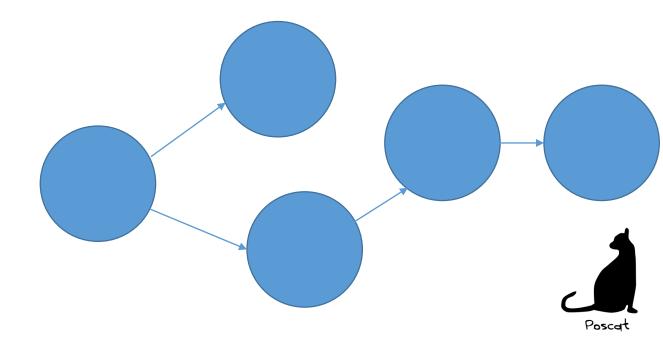
Given a direct graph, Find Strongly Connected Component

SCC: a graph is strongly connected if every vertex is reachable from every other vertex



Problem

Suppose that there is strongly connected component. (just imagine)



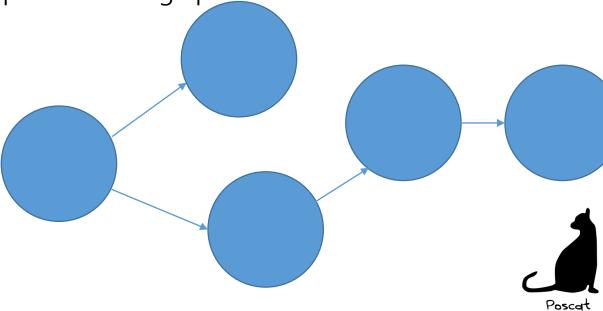
Problem

Suppose that there is strongly connected component. (just imagine)

Then we can make a graph consisting of "big" vertex

(big vertex makes a strongly connected component)

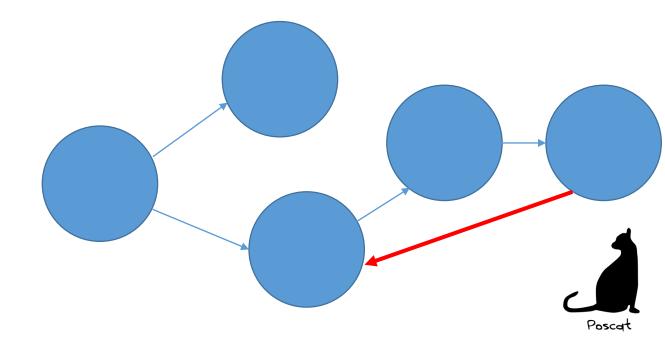
Let me call this graph as a meta graph



Problem

Trivially, this meta graph has no cycle.

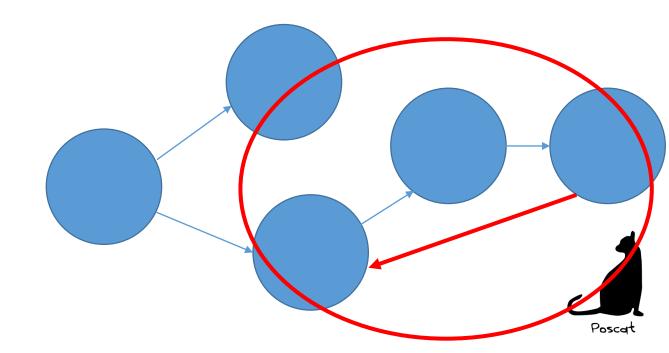
If not, they had to shrink into a vertex



Problem

Trivially, this meta graph has no cycle.

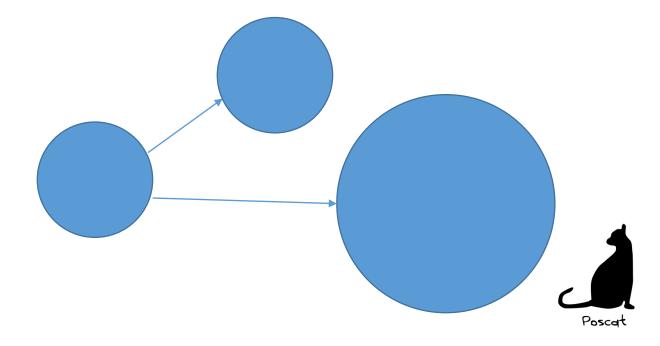
If not, they had to shrink into a vertex



Problem

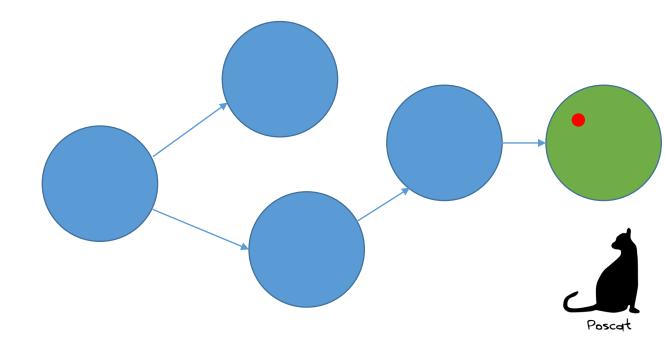
Trivially, this meta graph has no cycle.

If not, they had to shrink into a vertex



Problem

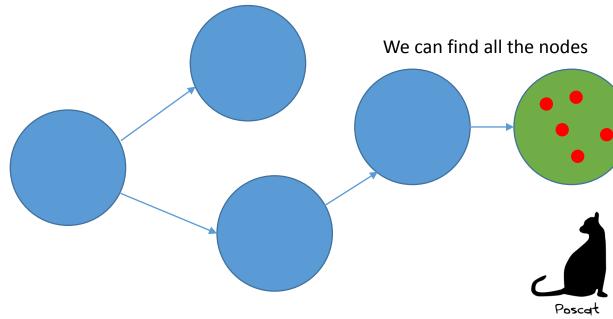
Think about the leaf big node. (a big node which has no outer edge) Choose one vertex from the leaf big node.



Problem

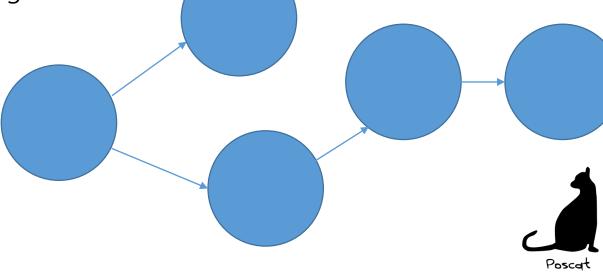
If we perform traverse started from the vertex, then it will traverse whole big node because the big node is SCC

If not, contradiction.



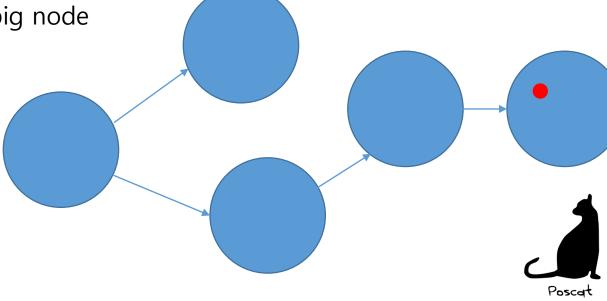
Problem

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex \rightarrow we get a SCC
- 3. Remove that big node
- 4. Repeat it



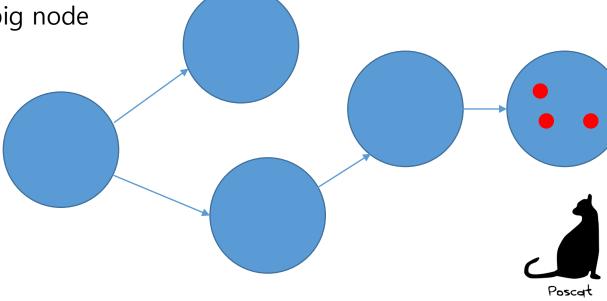
Problem

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it



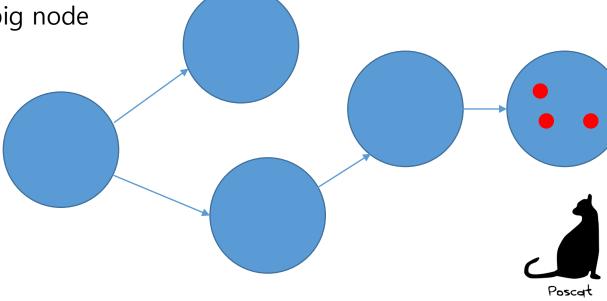
Problem

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it



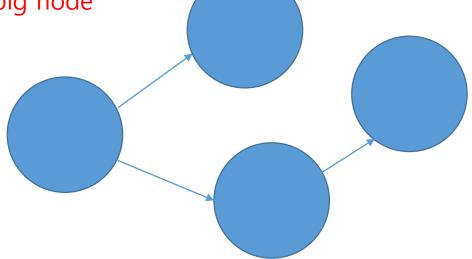
Problem

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it



Problem

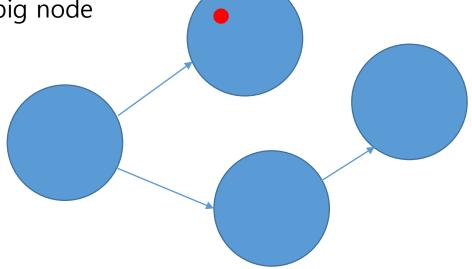
- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it





Problem

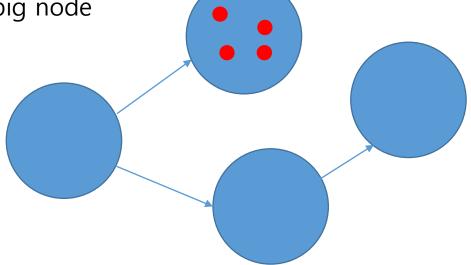
- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it





Problem

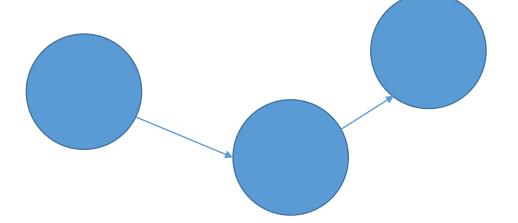
- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it





Problem

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it

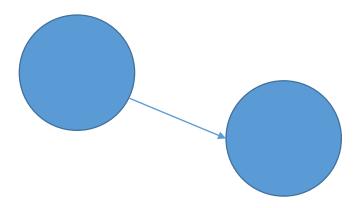




Problem

Therefore, we can derive a beautiful algorithm!

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it





Problem

Therefore, we can derive a beautiful algorithm!

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it





Problem

Therefore, we can derive a beautiful algorithm!

- 1. Find a vertex within the leaf big node
- Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it



Problem

Therefore, we can derive a beautiful algorithm!

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it

Is it correct?



Problem

Therefore, we can derive a beautiful algorithm!

- 1. Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it

Is it correct? Sure ☺



Problem

Therefore, we can derive a beautiful algorithm!

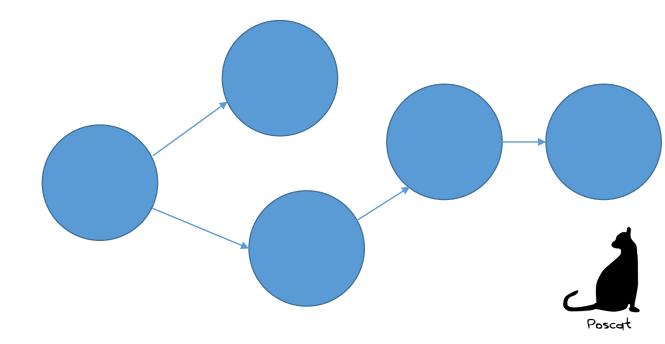
- Find a vertex within the leaf big node
- 2. Traverse started from the vertex
- 3. Remove that big node
- 4. Repeat it

However, how can we find a vertex in step 1?

We don't know whether a vertex is contained in the leaf big node or not

Actually, it is impossible

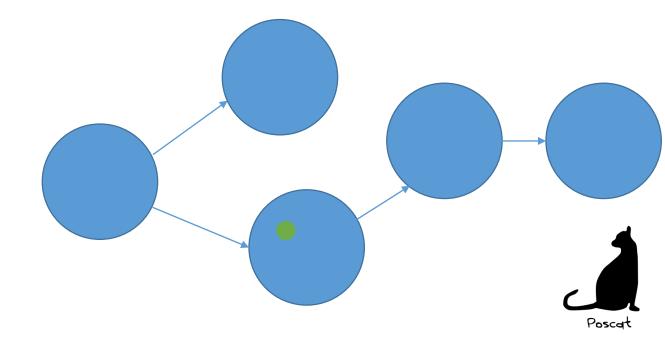
ProblemOTL ...



Problem

OTL ...

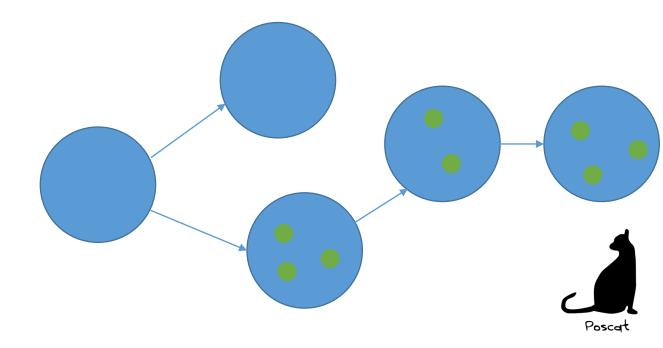
We can choose a vertex, but we don't know whether it is contained in the leaf big node



Problem

OTL ...

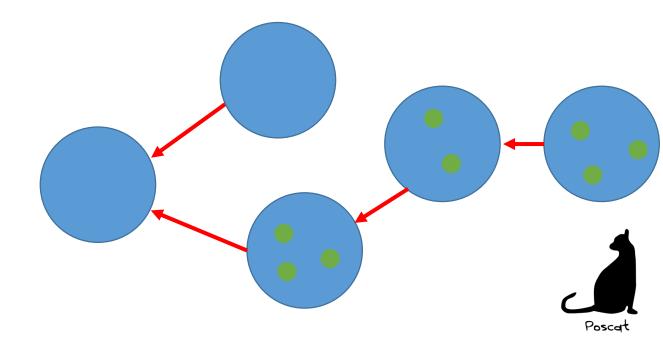
Then, just traverse it! Then it will traverse all the big node reached from the vertex



Problem

OTL ...

And reverse the whole graph!

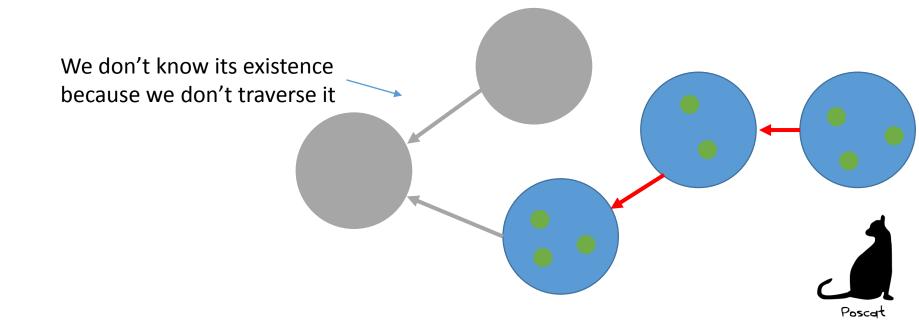


Problem

OTL ...

And reverse the whole graph!

Then our start vertex becomes the vertex contained in the leaf node!



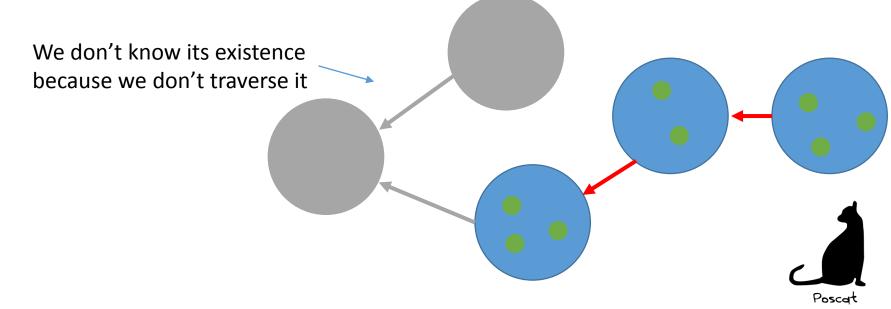
Problem

OTL ...

And reverse the whole graph!

Then our start vertex becomes the vertex contained in the leaf node!

It is strong evidence that we can perform our algorithm

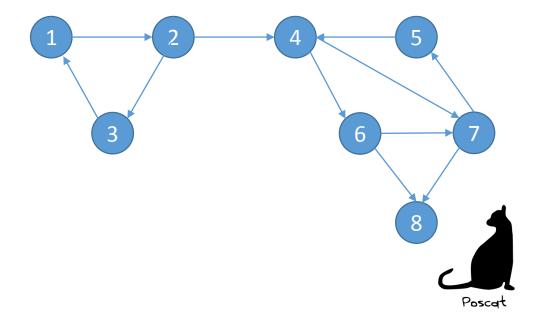


Overall procedure

- 1. Choose a start vertex
- 2. Perform DFS, and write the **exit time** for all the vertices
- 3. After doing DFS, reverse whole graph
- 4. Perform DFS or BFS starting from a vertex whose exit time is the largest
- 5. All the vertices gathering in step 4 performs a SCC

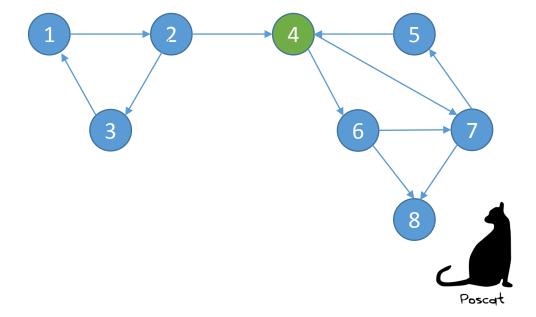


Overall procedure



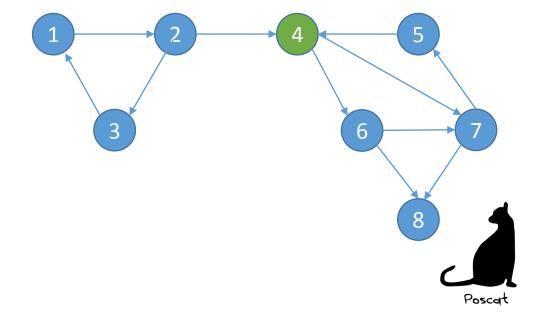
Overall procedure

Pick a start vertex



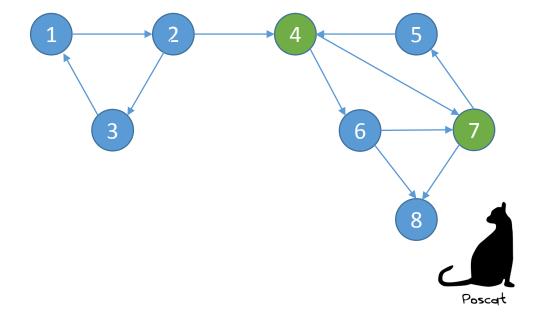
Overall procedure

Pick a start vertex



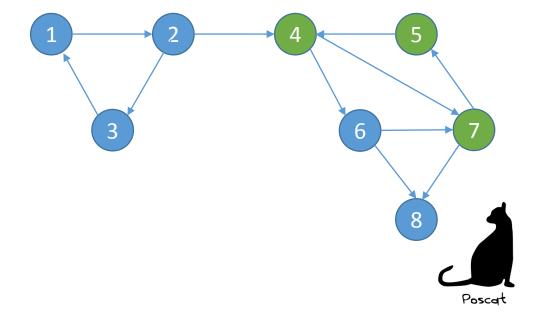
Overall procedure

Pick a start vertex



Overall procedure

Pick a start vertex

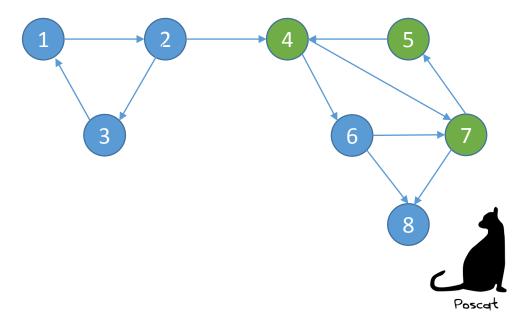


Overall procedure

Pick a start vertex

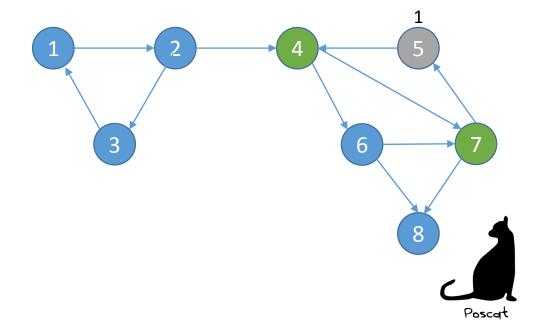
Perform DFS and write the exit time

I can't traverse further. Exit!



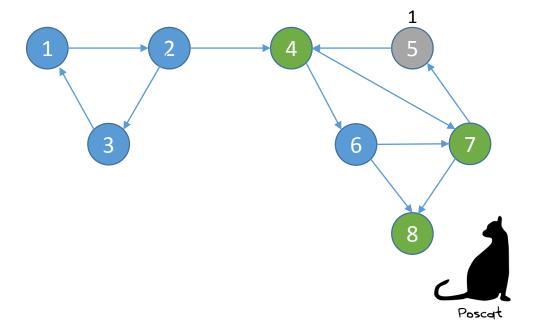
Overall procedure

Pick a start vertex



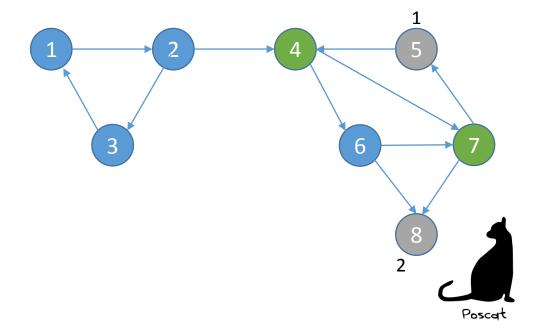
Overall procedure

Pick a start vertex



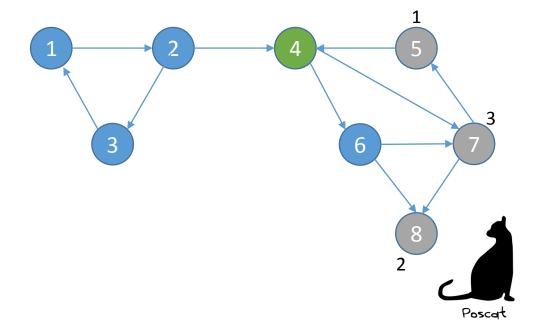
Overall procedure

Pick a start vertex



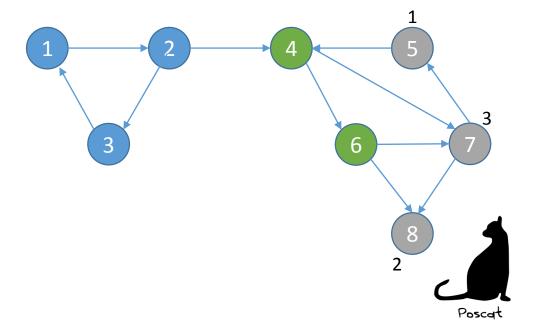
Overall procedure

Pick a start vertex



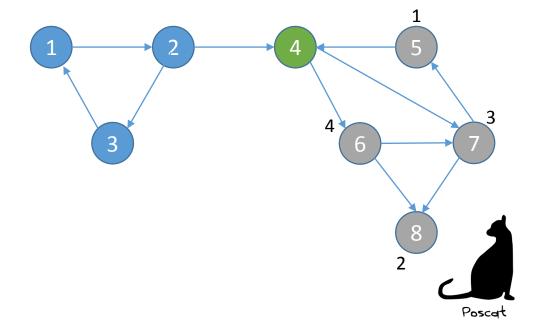
Overall procedure

Pick a start vertex



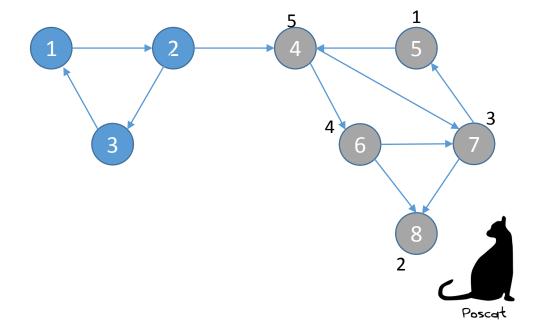
Overall procedure

Pick a start vertex



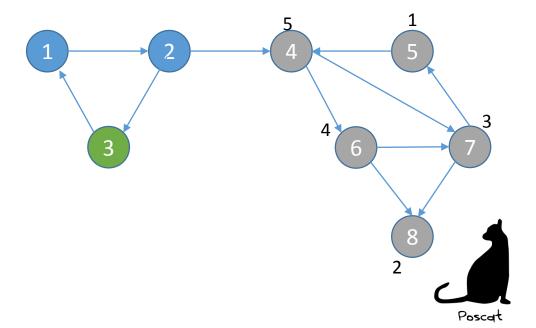
Overall procedure

Pick a start vertex



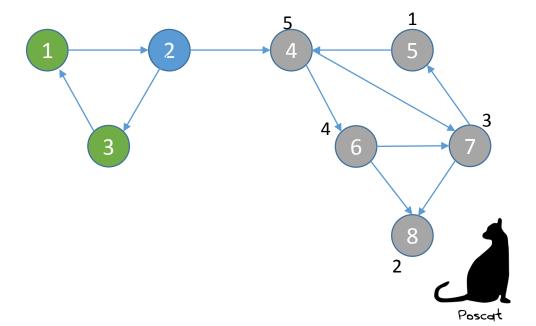
Overall procedure

Pick a start vertex



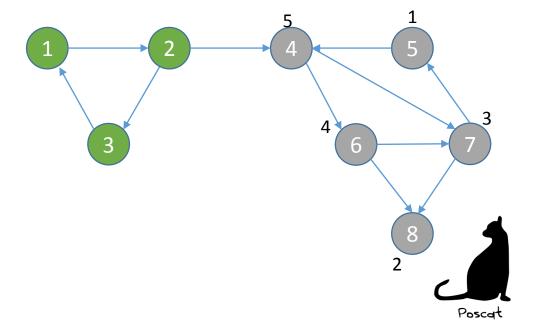
Overall procedure

Pick a start vertex



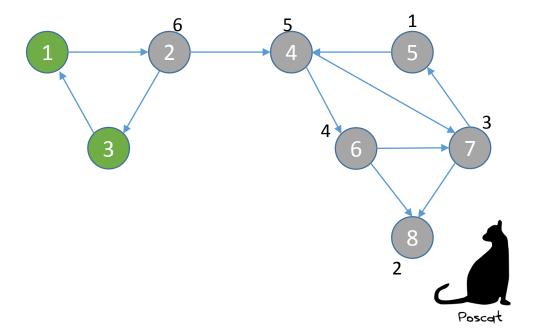
Overall procedure

Pick a start vertex



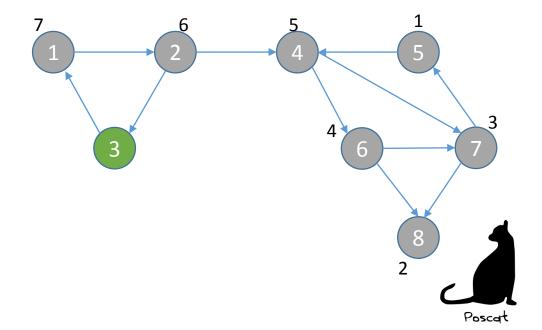
Overall procedure

Pick a start vertex



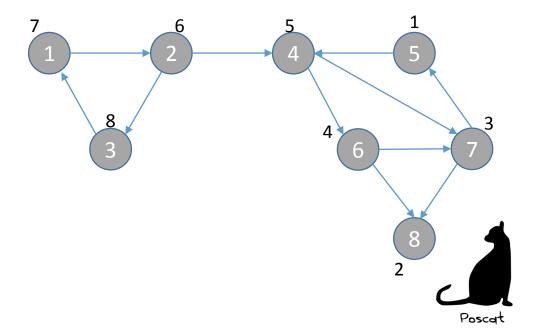
Overall procedure

Pick a start vertex



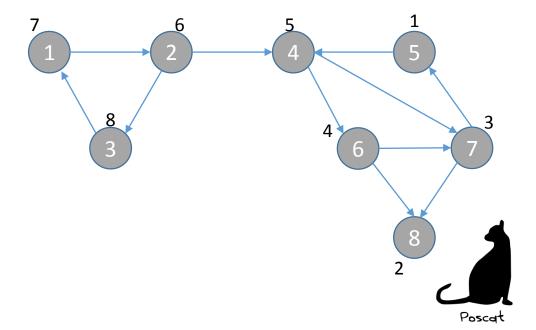
Overall procedure

Pick a start vertex



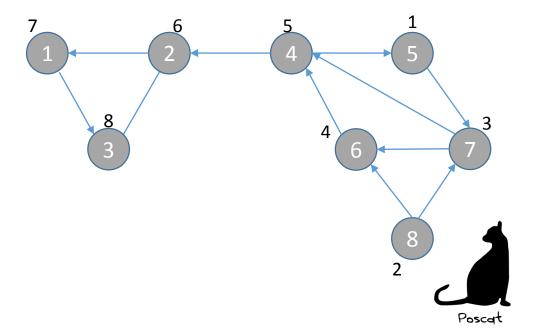
Overall procedure

After writing all the exit time, reverse whole graph

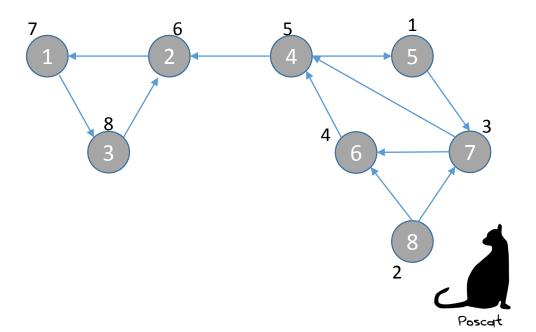


Overall procedure

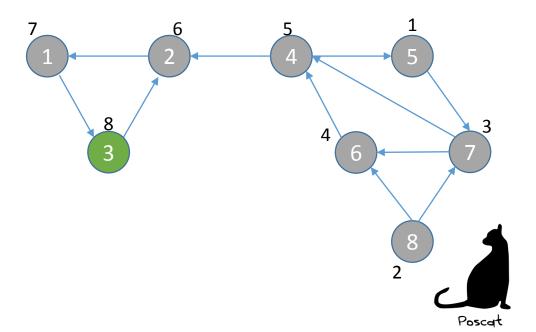
After writing all the exit time, reverse whole graph



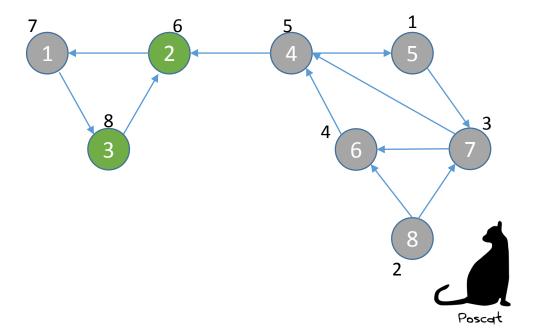
Overall procedure



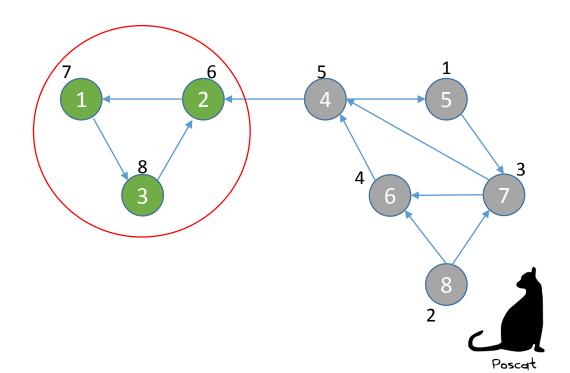
Overall procedure



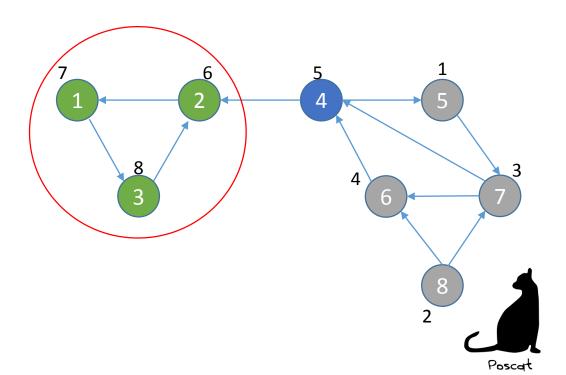
Overall procedure



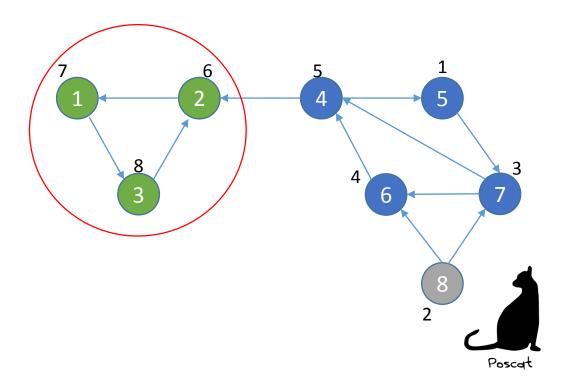
Overall procedure



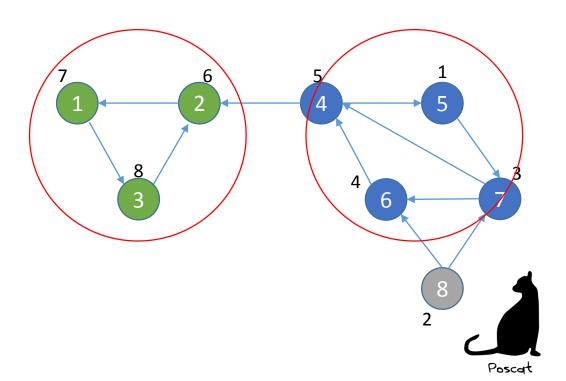
Overall procedure



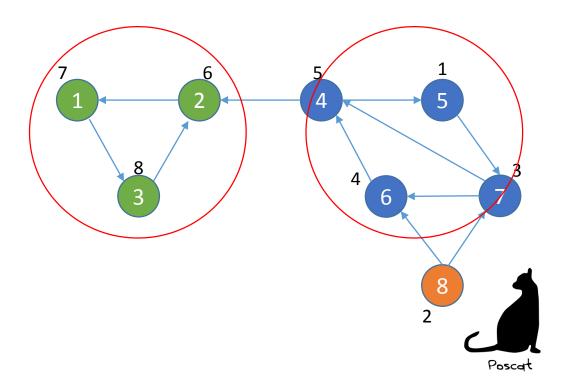
Overall procedure



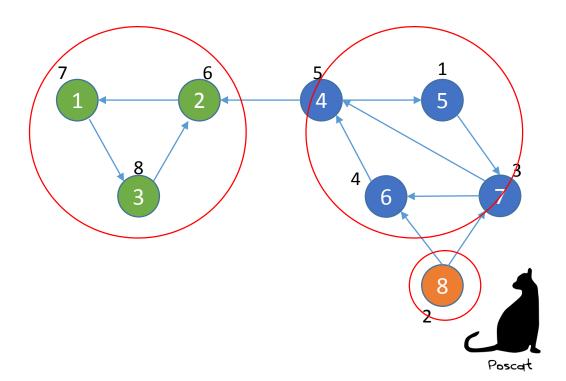
Overall procedure



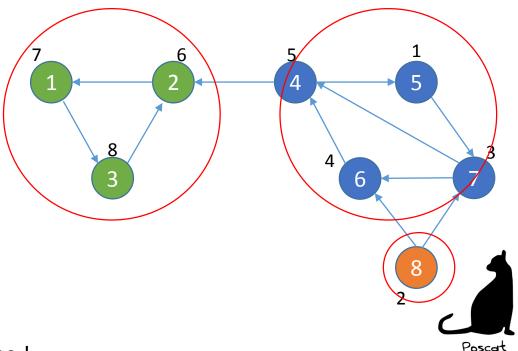
Overall procedure



Overall procedure



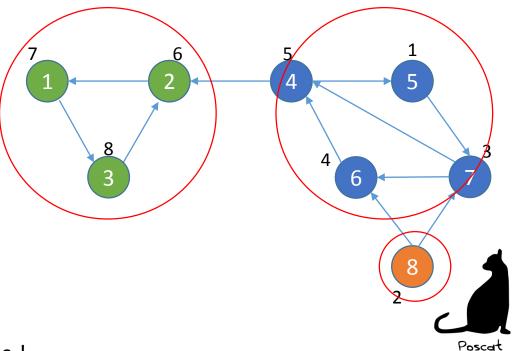
Overall procedure



Analysis

It is correct?

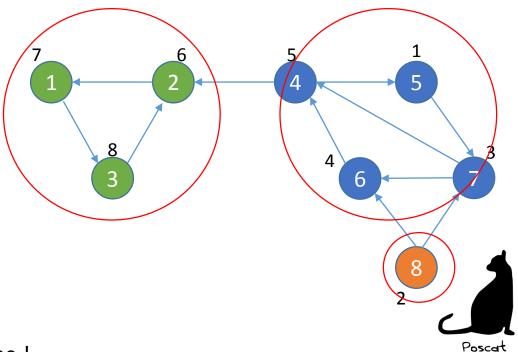
How long does it takes?



Analysis

It is correct?
How long does it takes?

We need some detail proof
We need 2 DFS (or 1 DFS + 1 BFS)



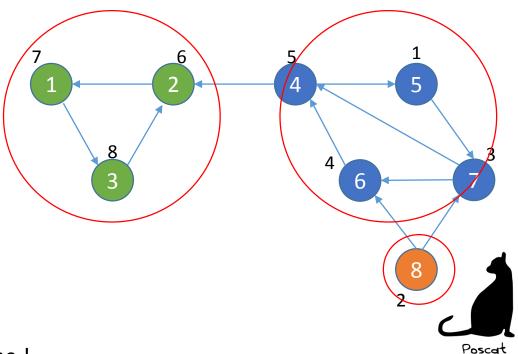
Analysis

It is correct?

How long does it takes?

We need some detail proof

$$O(V + E)$$



Done!