POSCAT Seminar 10 : Graph 2

yougatup @ POSCAT



Topic

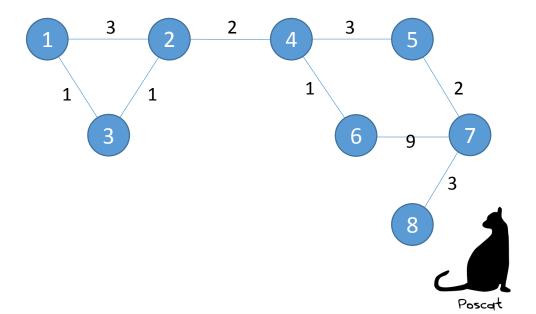
- Topic today
 - Shortest Path
 - Dijkstra Algorithm
 - Floyd Algorithm
 - Bellman-Ford Algorithm
 - Disjoint Set
 - Union & Find
 - Path Compression



Shortest Path

Problem

Given a graph, find a shortest path from start vertex to end vertex

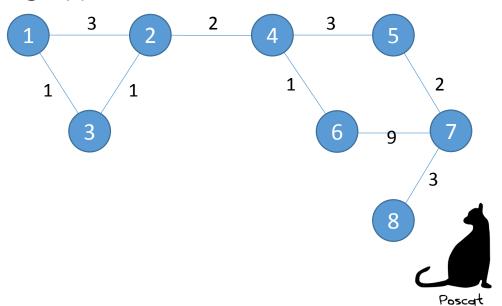


Shortest Path

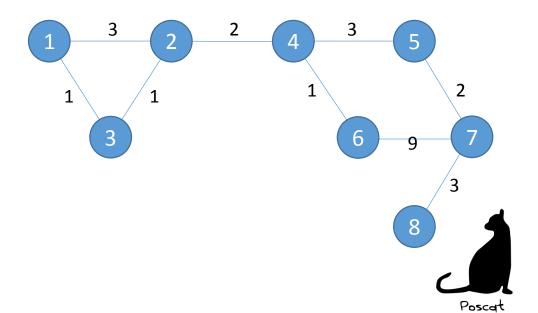
Problem

Given a graph, find a shortest path from start vertex to end vertex

- 1. Greedy Approach
- 2. Iterative Approach
- 3. Dynamic Programming Approach

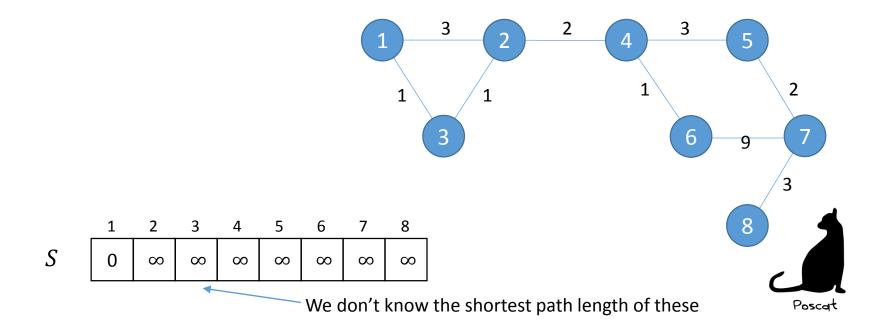


- Approach
 - Greedy approach
 - Let $S(i) = the \ length \ of \ shortest \ path \ from \ the \ start \ vertex \ to \ vertex \ i$



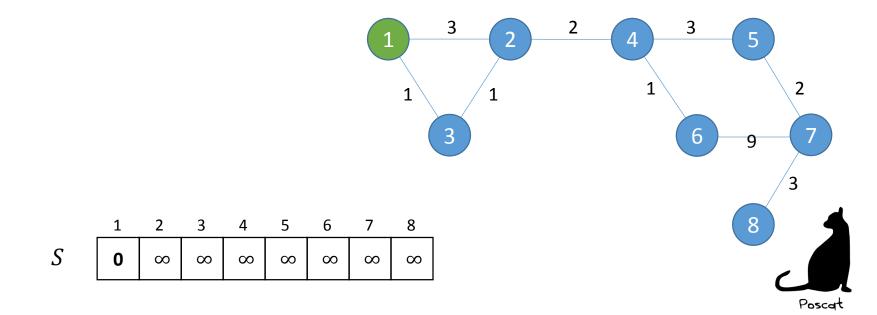
Approach

- Greedy approach
- Let S(i) = the length of shortest path from the start vertex to vertex i



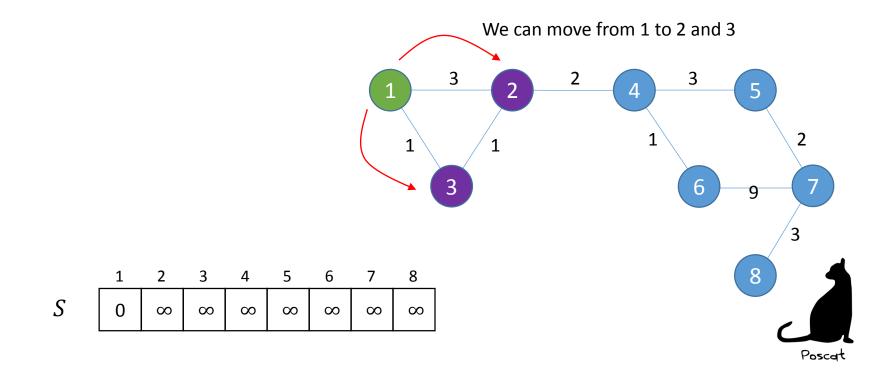
Approach

Currently, we only know that the shortest path length from the start vertex to start vertex \rightarrow 0



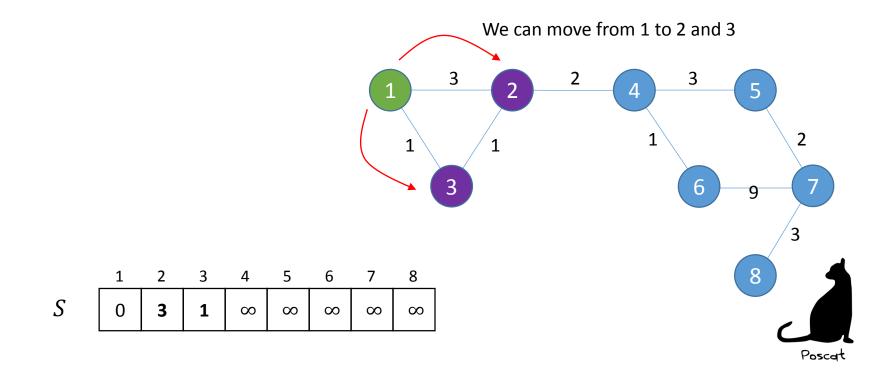
Approach

Also, we can fill another cell of S by using this information!



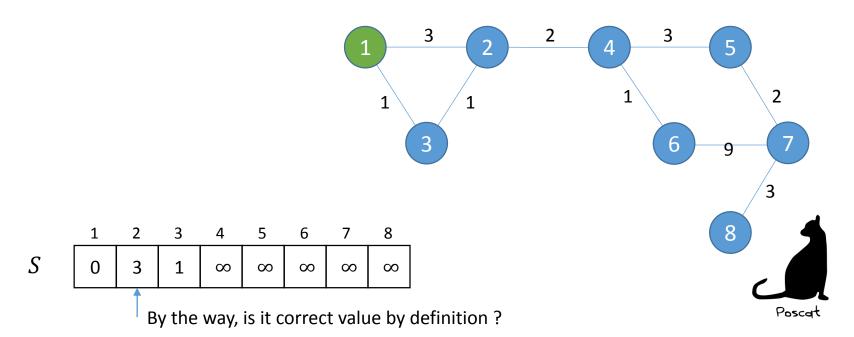
Approach

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Approach

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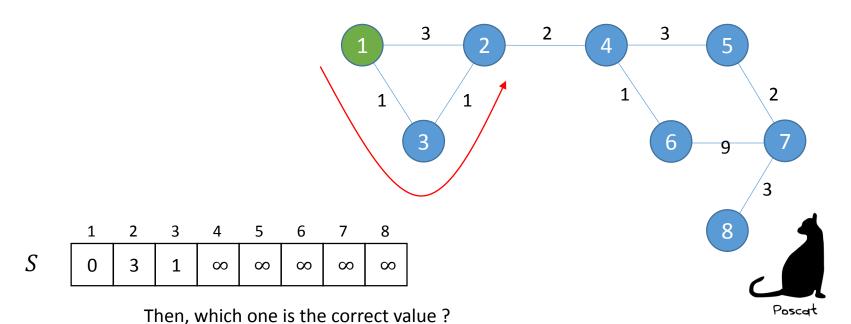
Approach

Also, we can fill another cell of S by using this information!

We can move from 1 to 2 and 3 9 8 3 1 5 8 S 3 0 1 ∞ ∞ ∞ ∞ ∞ Poscat By the way, is it correct value by definition? NO!

Approach

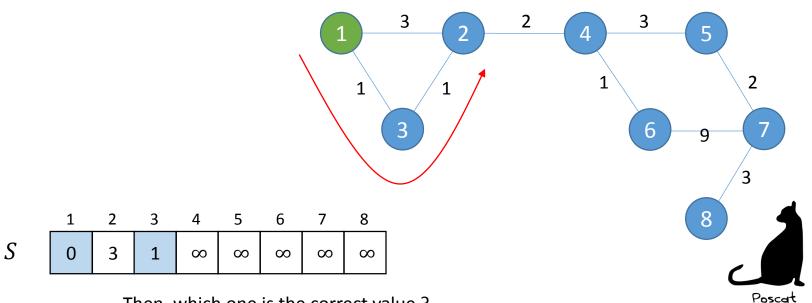
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Approach

Also, we can fill another cell of S by using this information!

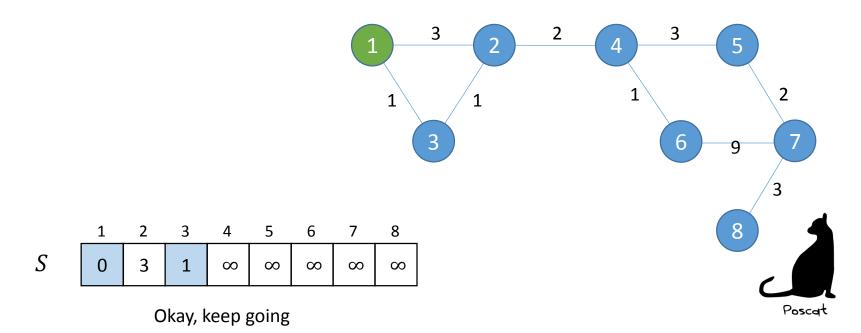
We can move from 1 to 2 and 3



Then, which one is the correct value?

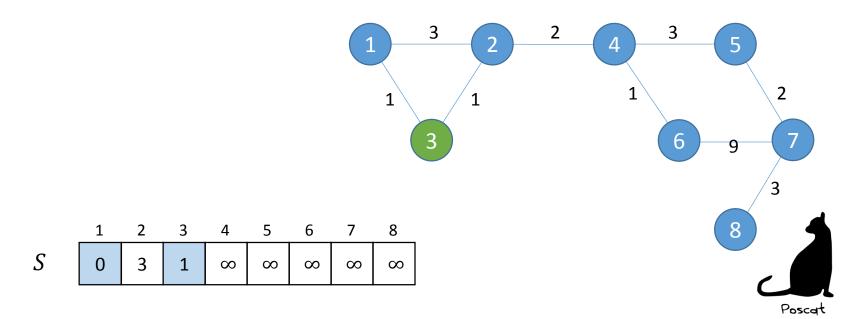
Approach

Also, we can fill another cell of S by using this information!



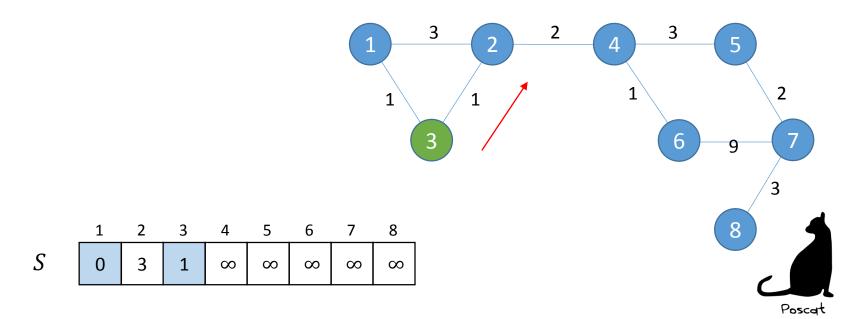
Approach

Because S(3) is the correct value, also we can fill another cell



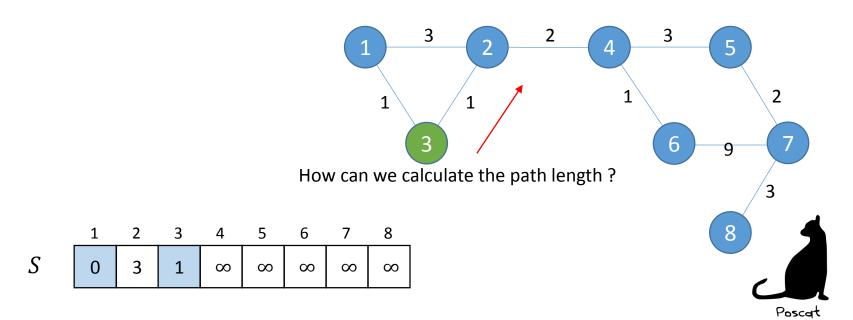
Approach

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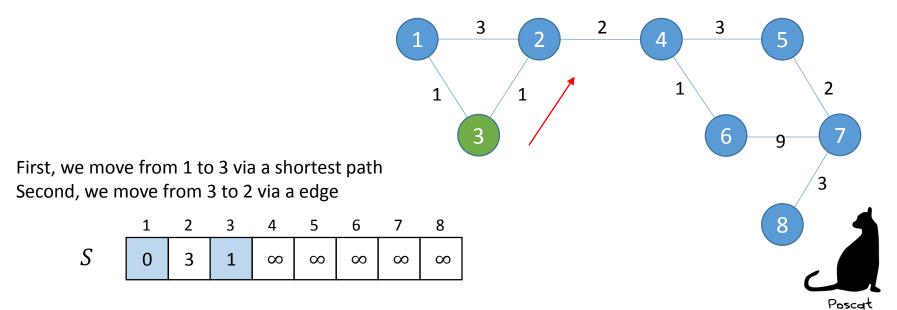
Approach

Because S(3) is the correct value, also we can fill another cell



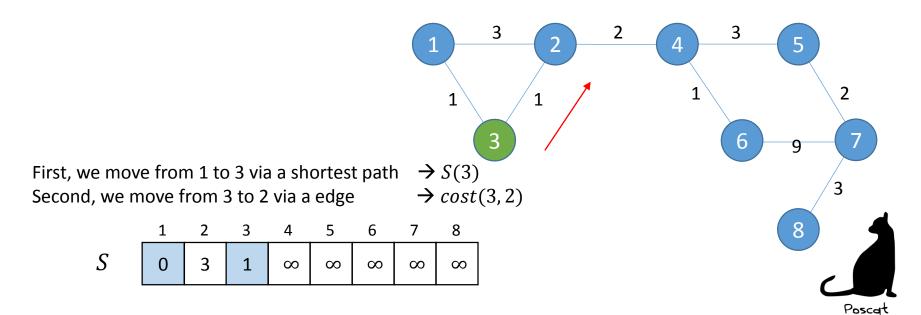
Approach

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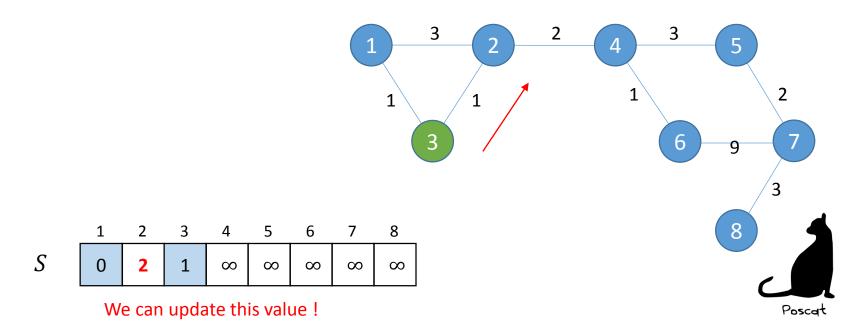
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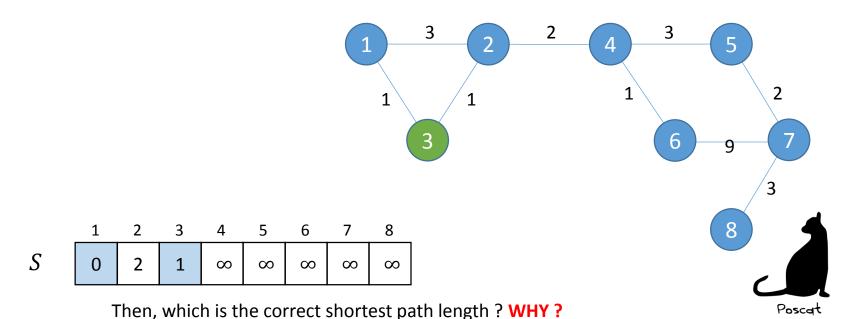
Approach

Because S(3) is the correct value, also we can fill another cell



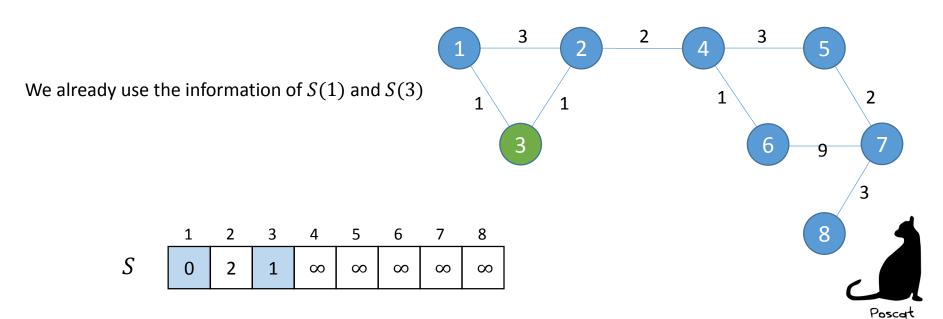
Approach

Because S(3) is the correct value, also we can fill another cell



Approach

Because S(3) is the correct value, also we can fill another cell



Approach

S

Because S(3) is the correct value, also we can fill another cell

We can move from 1 to 2 and 3

We already use the information of S(1) and S(3) It means that we already consider paths which contains the vertex 1 or 3

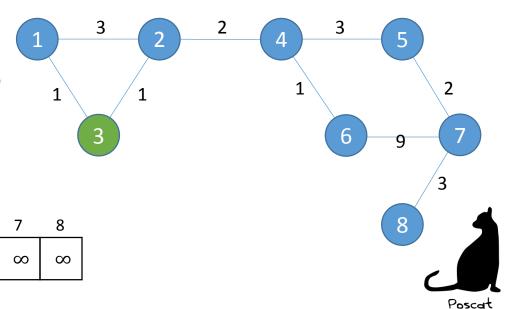
1

 ∞

5

 ∞

 ∞



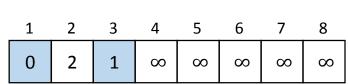
Approach

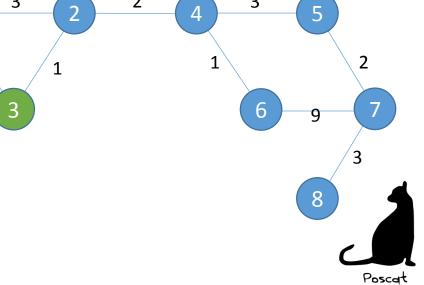
S

Because S(3) is the correct value, also we can fill another cell

We can move from 1 to 2 and 3

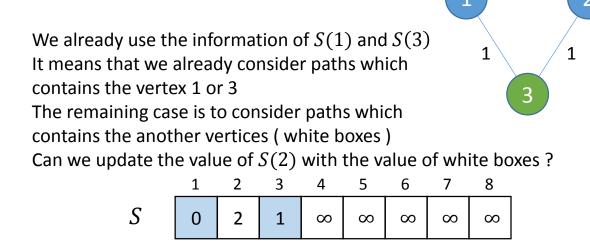
We already use the information of S(1) and S(3) It means that we already consider paths which contains the vertex 1 or 3 The remaining case is to consider paths which contains the another vertices (white boxes)

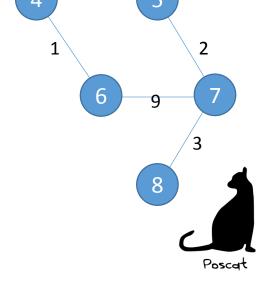




Approach

Because S(3) is the correct value, also we can fill another cell





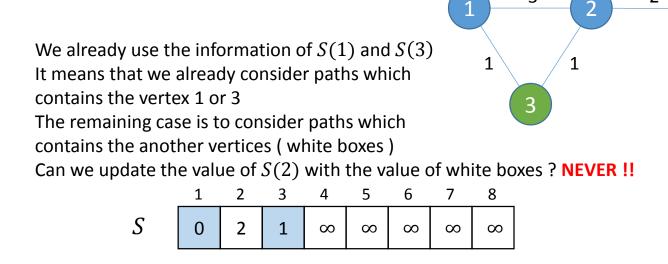
9

8

Dijkstra Algorithm

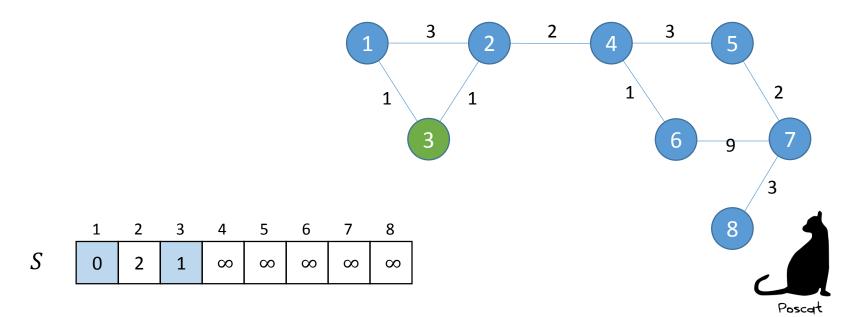
Approach

Because S(3) is the correct value, also we can fill another cell



Approach

Blue boxes contain the correct value of shortest path length We NEVER update the minimum value of white boxes!

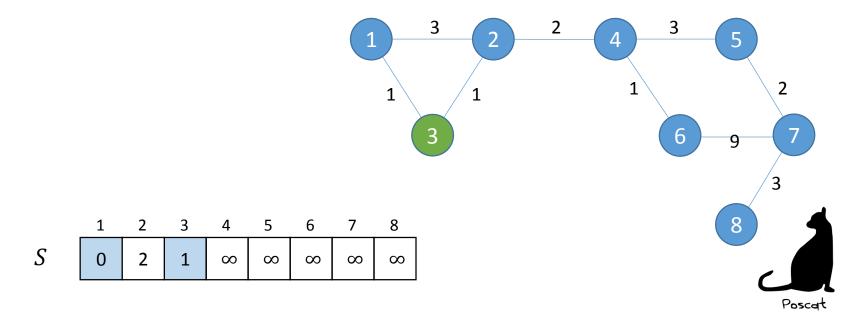


Approach

Blue boxes contain the correct value of shortest path length
We NEVER update the minimum value of white boxes!

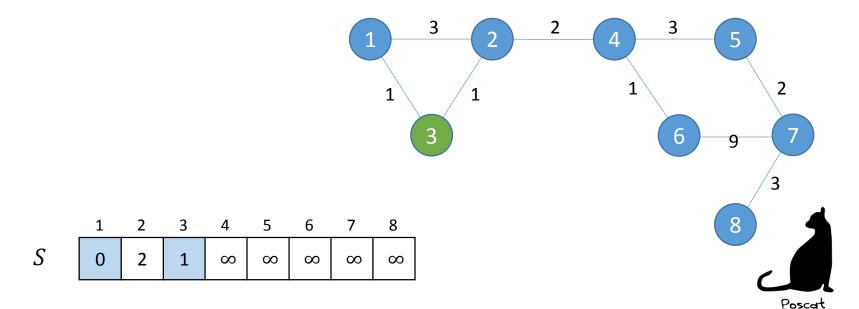
Therefore, the minimum value of white boxes is the correct value

We can move from 1 to 2 and 3

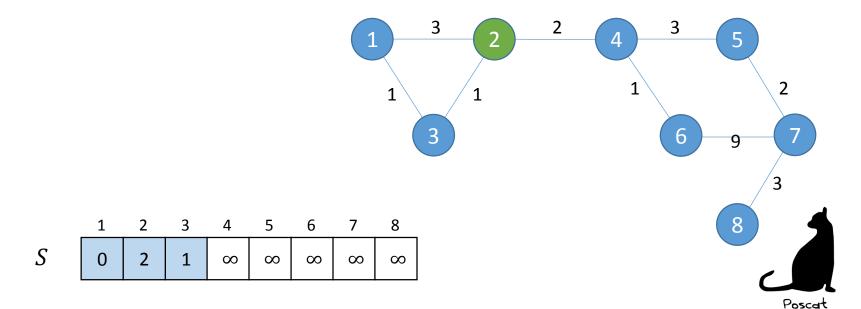


Overall algorithm

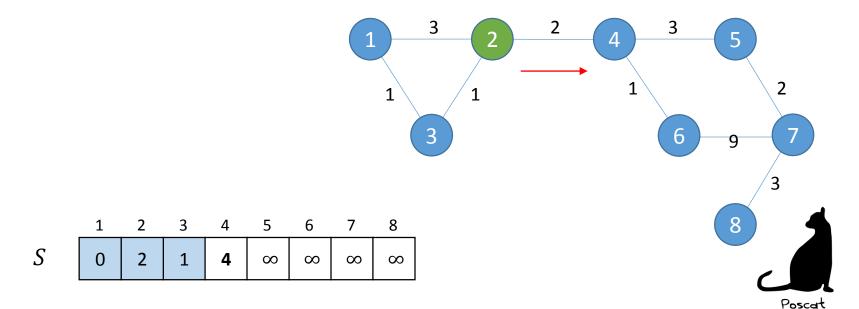
- Choose the white box which contains minimum value
- 2. Update another cell
- 3. Repeat!



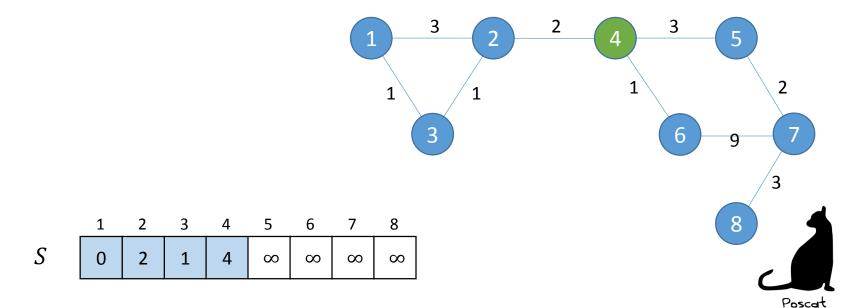
- Overall algorithm
 - 1. Choose the white box which contains minimum value
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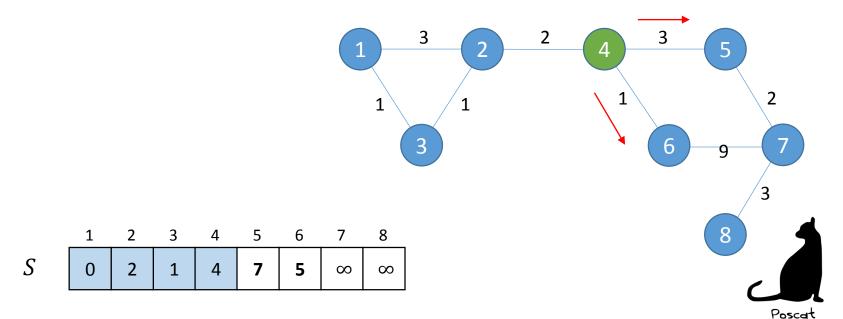
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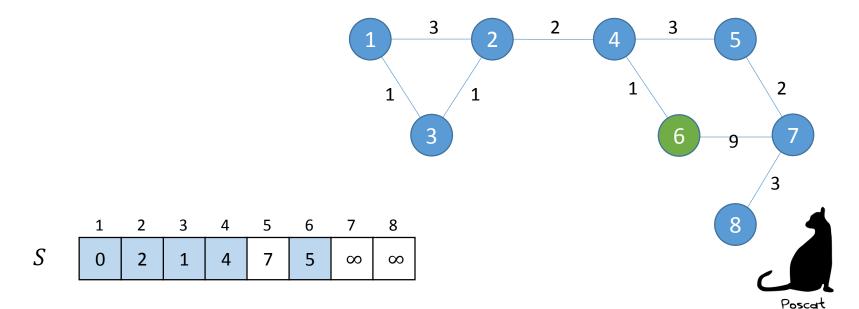
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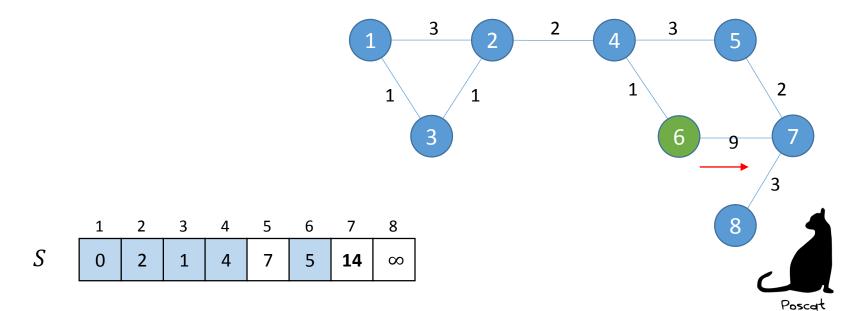
- Overall algorithm
 - 1. Choose the white box which contains minimum value
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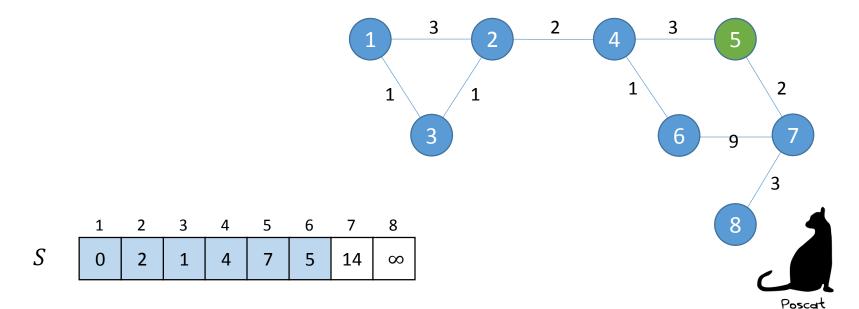
- Overall algorithm
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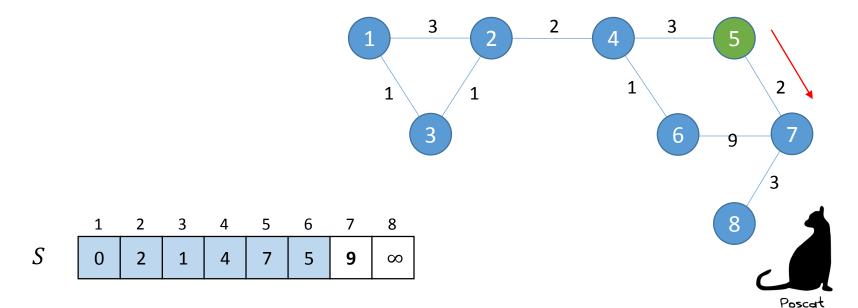
- Overall algorithm
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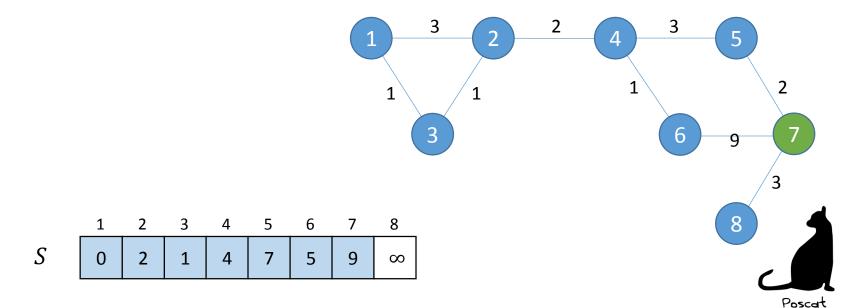
- Overall algorithm
 - 1. Choose the white box which contains minimum value
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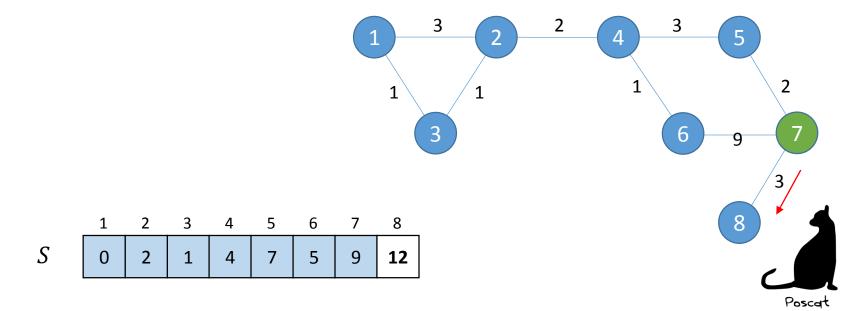
- Overall algorithm
 - Choose the white box which contains minimum value
 - 2. Update another cell
 - 3. Repeat!



- Overall algorithm
 - 1. Choose the white box which contains minimum value
 - 2. Update another cell
 - 3. Repeat!

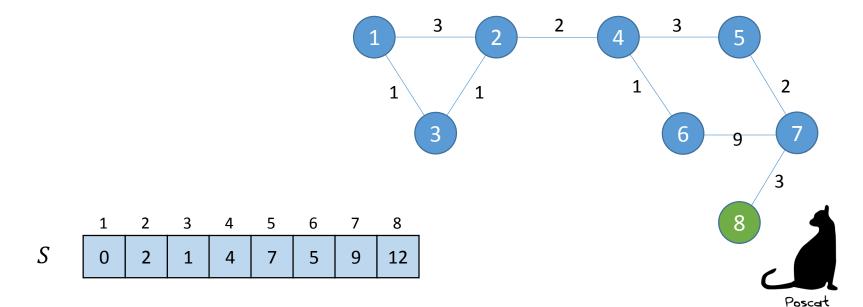


- Overall algorithm
 - 1. Choose the white box which contains minimum value
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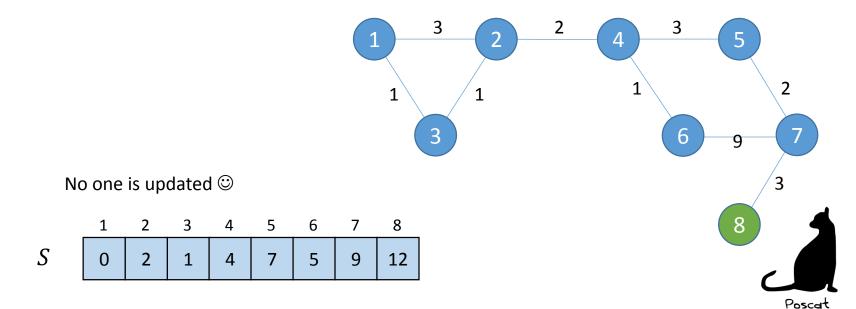
Overall algorithm

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- 3. Repeat!



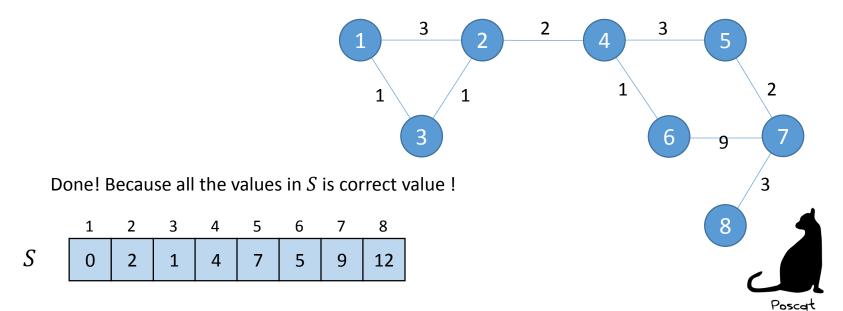
Overall algorithm

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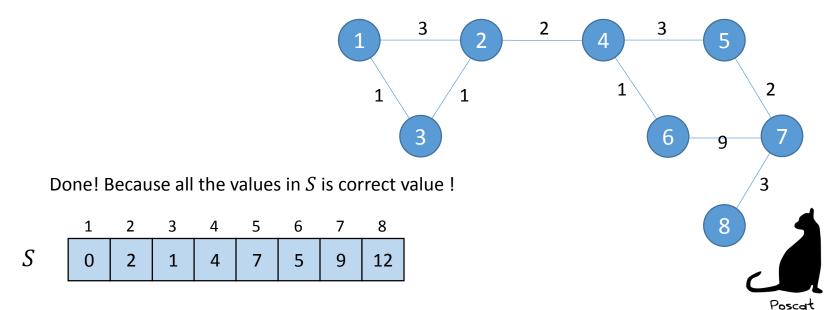
Overall algorithm

- 1. Choose the white box which contains minimum value
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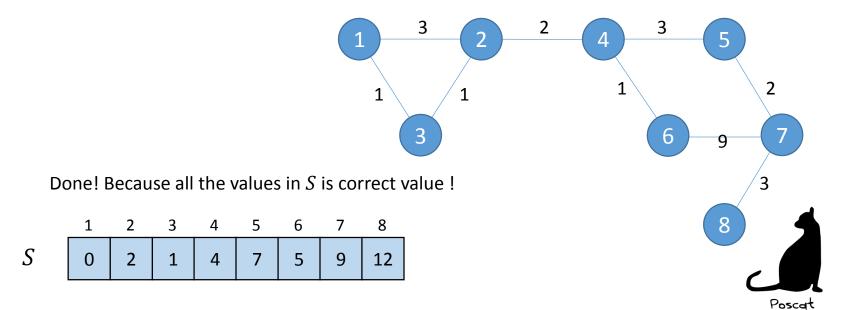
Analysis

- 1. Choose the white box which contains minimum value
- 2. Update another cell
- 3. Repeat!



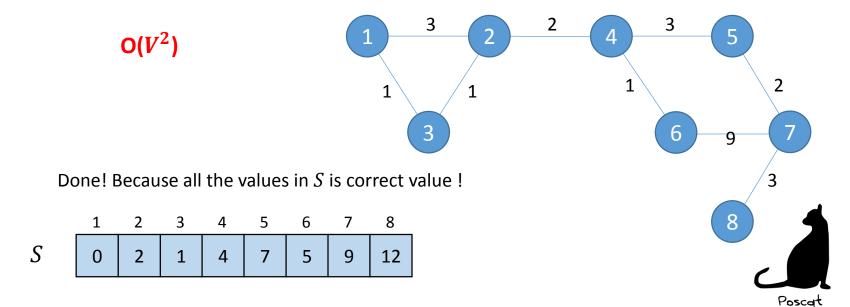
Analysis

- 1. Choose the white box which contains minimum value \rightarrow O(V)
- 2. Update another cell \rightarrow O(V)
- 3. Repeat!



Analysis

- 1. Choose the white box which contains minimum value \rightarrow O(V)
- 2. Update another cell \rightarrow O(V)
- 3. Repeat!



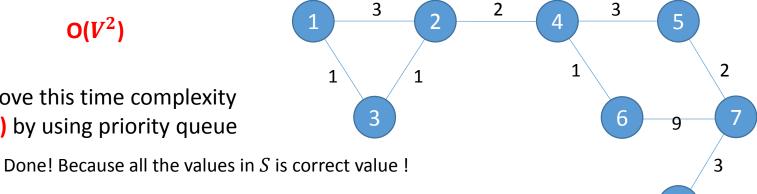
Analysis

- Choose the white box which contains minimum value \rightarrow O(V)
- Update another cell \rightarrow O(V)
- Repeat! 3.

We can move from 1 to 2 and 3

 $O(V^2)$

We can improve this time complexity as $O(E \log V)$ by using priority queue



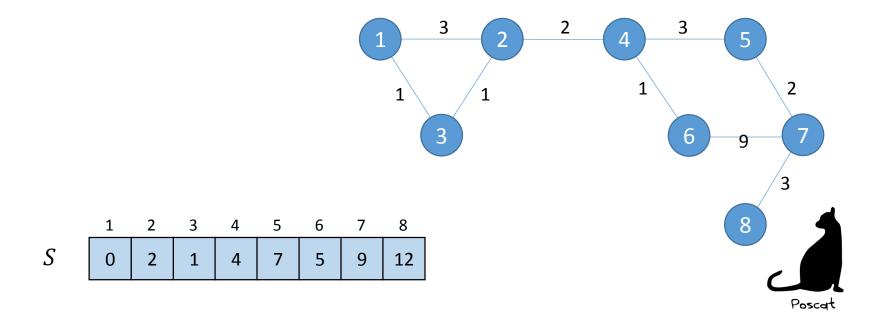
1 3 8 S 1 5 9 12



Pitfall

However, does our logic clear?

In other words, is it really true that white cell with minimum value never be updated?

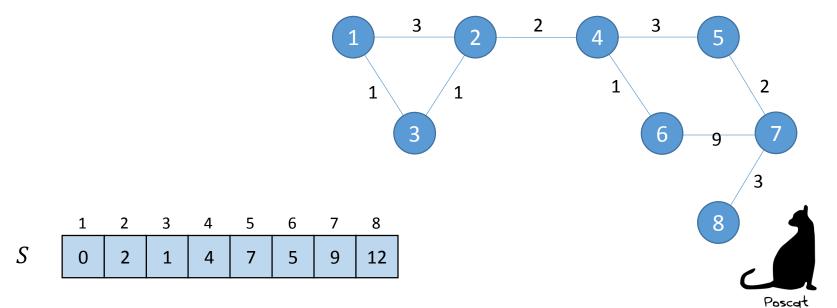


Pitfall

However, does our logic clear ?

In other words, is it really true that white cell with minimum value never be updated?

What if we have **negative cost**?

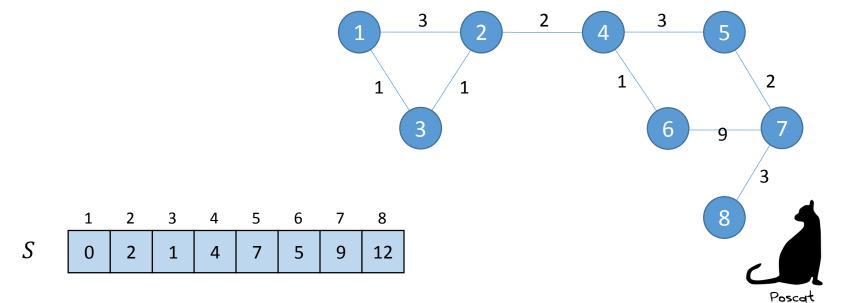


Pitfall

However, does our logic clear?

In other words, is it really true that white cell with minimum value never be updated?

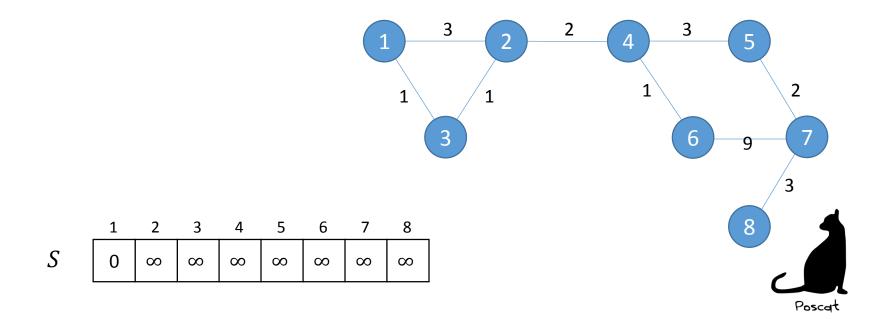
What if we have **negative cost**? \rightarrow **Fail**!



Approach

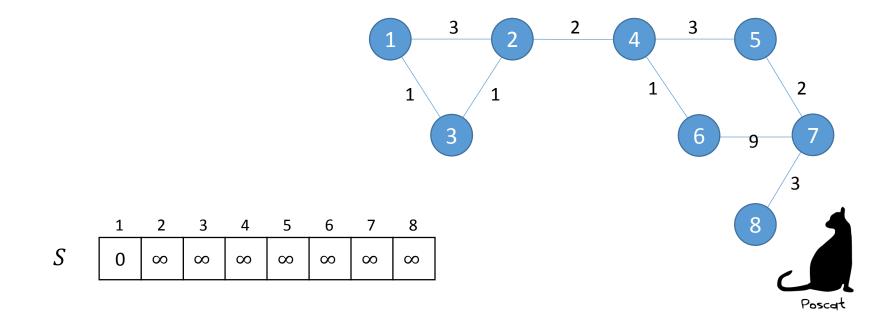
Iterative Approach

Let me use S(i) one more time



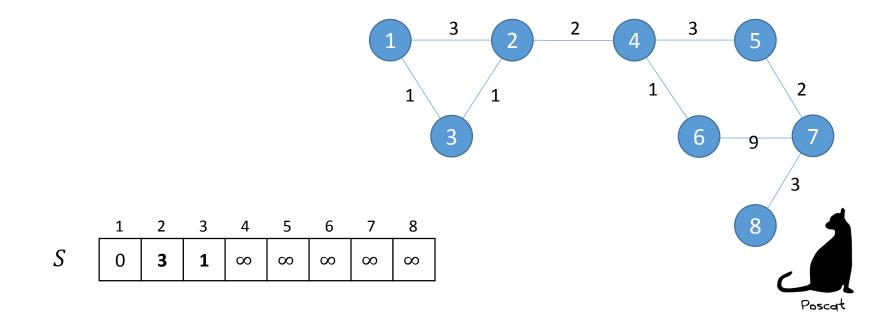
Approach

Just update one time by using S



Approach

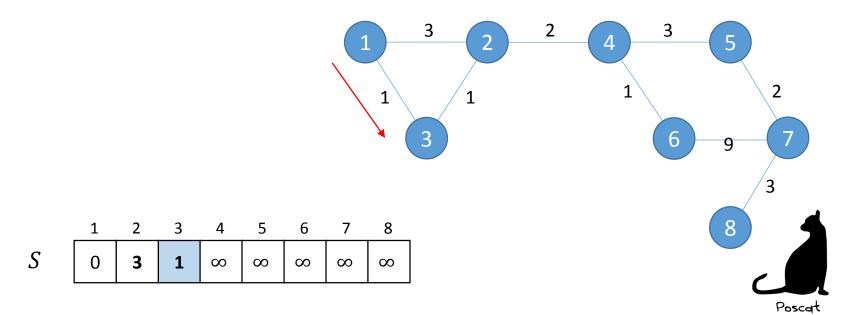
Just update one time by using S



Approach

Just update one time by using S

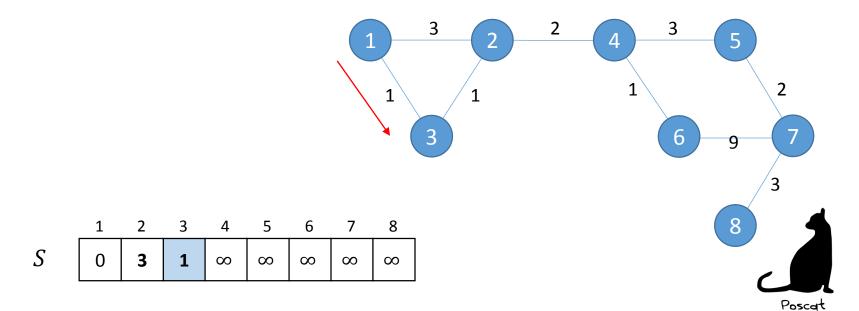
We can guarantee that we successfully calculate the **length** of shortest path **which consists of 1 edge**. The shortest path consists of 1 edge for vertex 3. Therefore, we calculate the shortest path length of vertex 3!



Approach

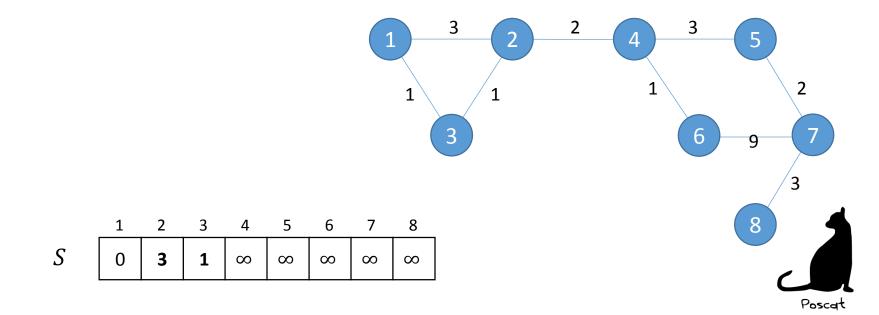
Just update one time by using S

However, we don't know which one is the shortest path. In other words, we don't know whether the value of S(3) is correct or not



Approach

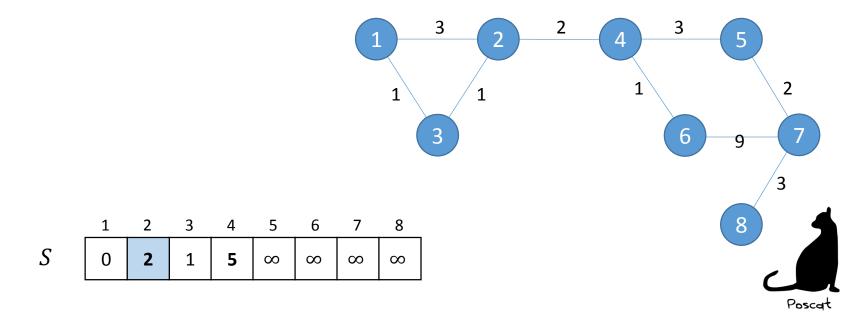
Update one more time!



Approach

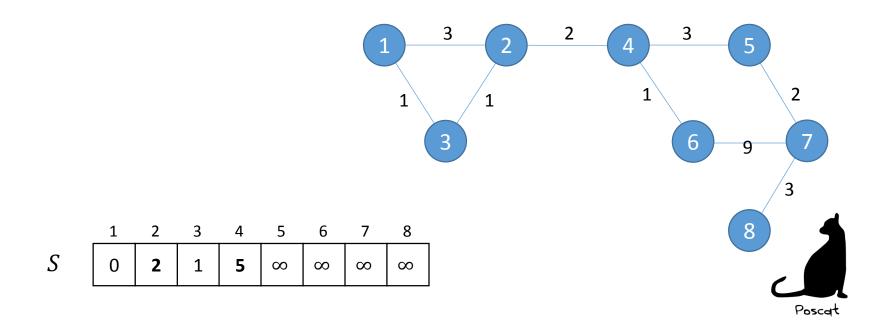
Update one more time!

We can calculate the length of shortest path with 2 edges correctly ! Also, we don't know whether S(2) is correct value or not



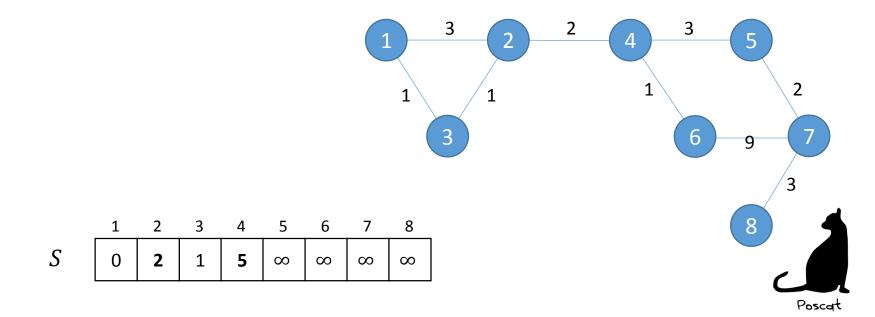
Approach

If we update n times, then we can guarantee that We successfully calculate the length of shortest path with n edges!



Approach

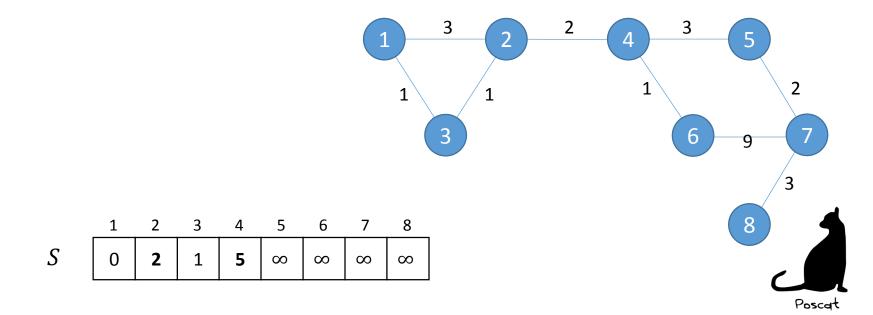
However, shortest path have to consist of at most (V-1) edges Therefore, (V-1) iteration is enough to get the correct value



Analysis

Each iteration needs O(E)

We need O(V) iterations

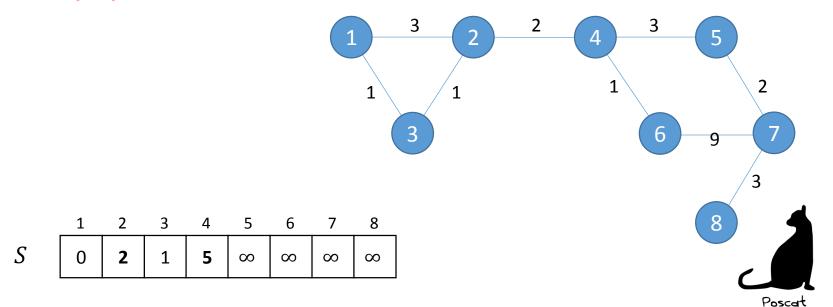


Analysis

Each iteration needs O(E)

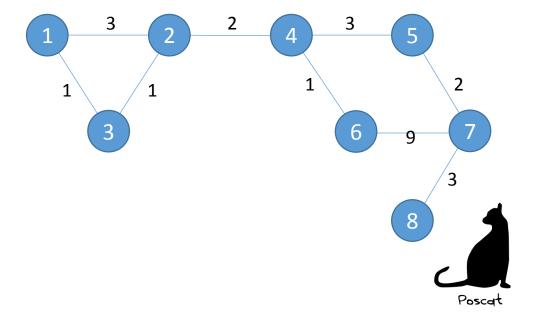
We need O(V) iterations

O(VE)



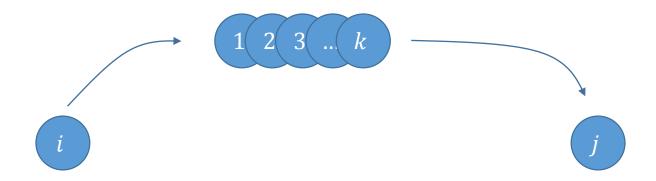
Approach

Dynamic Programming Approach Remember 3 steps



Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

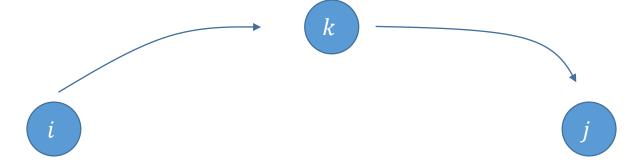




Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

Case 1. we use Vertex k

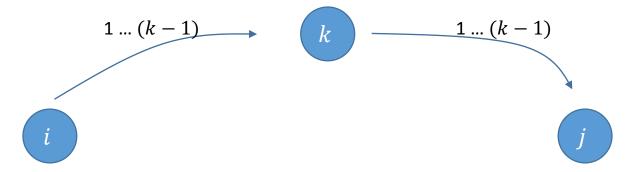




Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

Case 1. we use Vertex k



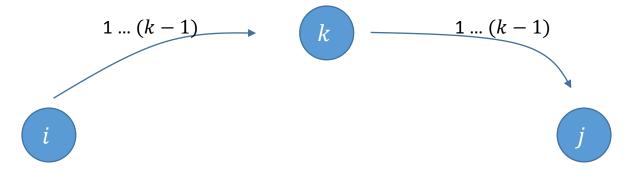
Then we can use vertex 1 \sim (k-1) to move from i to k Also, we can use same vertices to move from k to j



Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

Case 1. we use Vertex k





Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

Case 2. we don't use vertex k



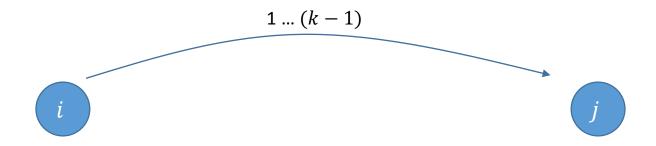




Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

Case 2. we don't use vertex k



$$T(k,i,j) = T(k-1,i,j)$$



Approach

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

```
\therefore T(k,i,j) = \min (T(k-1,i,j), T(k-1,i,k) + T(k-1,k,j))
```



Analysis

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

$$\therefore T(k, i, j) = \min (T(k - 1, i, j), T(k - 1, i, k) + T(k - 1, k, j))$$



Analysis

Let T(k, i, j) = the shortest path length from i to j when we use vertices from 1 to k only

$$\therefore T(k, i, j) = \min (T(k - 1, i, j), T(k - 1, i, k) + T(k - 1, k, j))$$

 $O(n^3)$



Disjoint Set

Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not





Disjoint Set

Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not















Merge!



Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not













Merge! Merge!



Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not











Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not









Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not







Determine whether vertex 1 and 3 is in the same group



Problem

Initially, there are n groups. You can merge two group into one. Determine whether two elements is in the same group or not







Determine whether vertex 1 and 3 is in the same group **NO**



Approach

How can we represent a group?







Approach

How can we represent a group? Using array is bad







Approach

How can we represent a group? Using array is bad We use tree structure!







Approach

How can we represent a group? Using array is bad We use tree structure!





Approach

How can we determine that two vertices are in the same group?



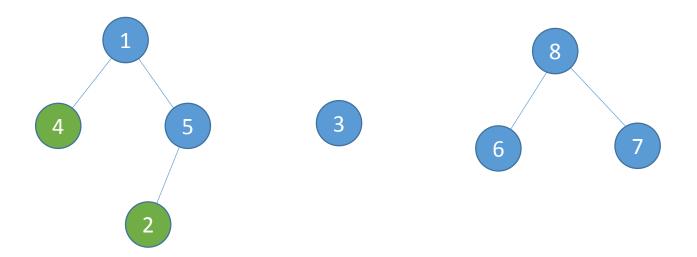


Approach





Approach





Approach





Approach





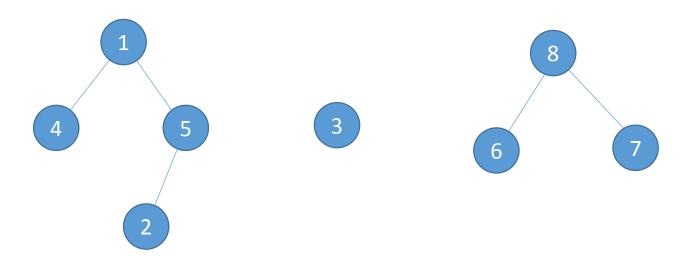
Approach





Approach

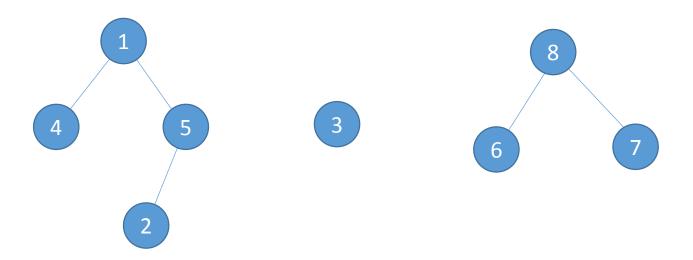
Finding their root is quite simple. Just follow their parent node.





Approach

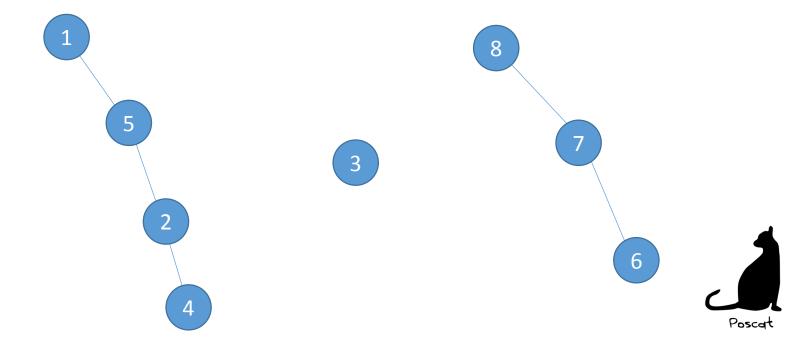
Finding their root is quite simple. Just follow their parent node. Is it efficient?





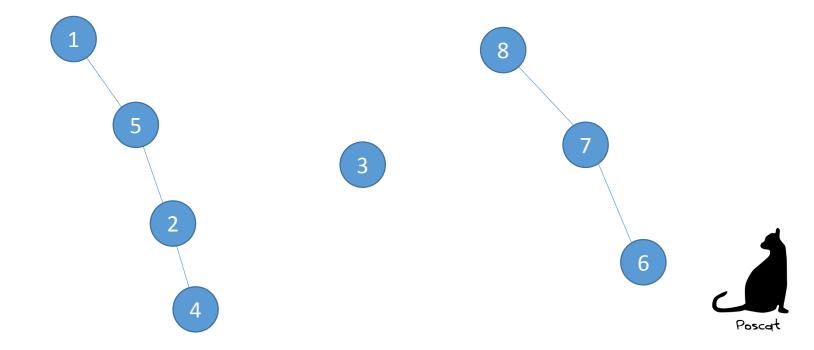
Approach

Finding their root is quite simple. Just follow their parent node. Is it efficient?

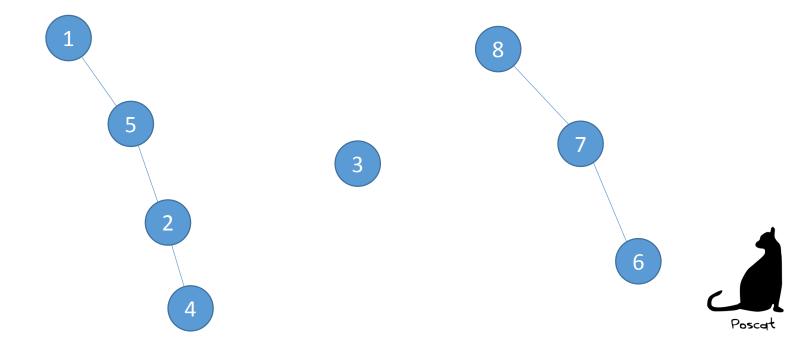


Approach

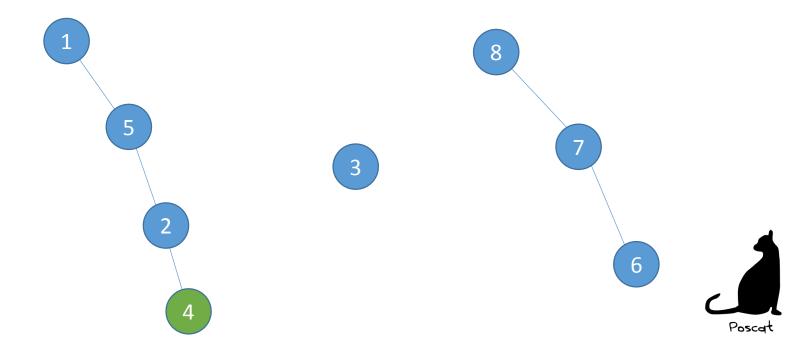
Finding their root is quite simple. Just follow their parent node. Is it efficient? If the shape of tree is bad, it takes O(n)



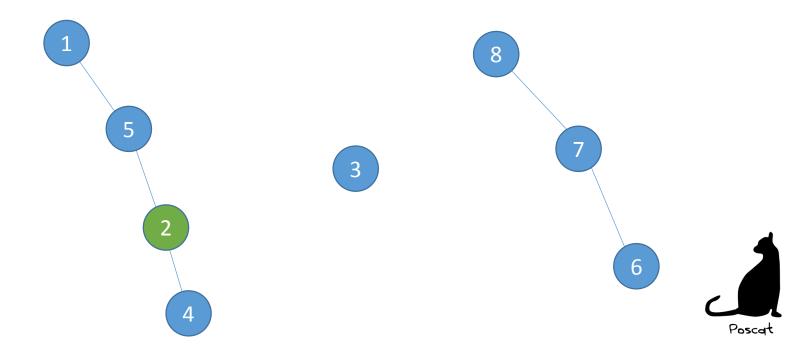
Approach



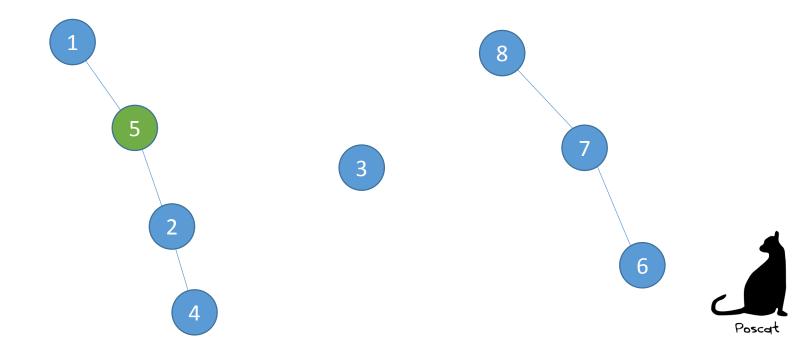
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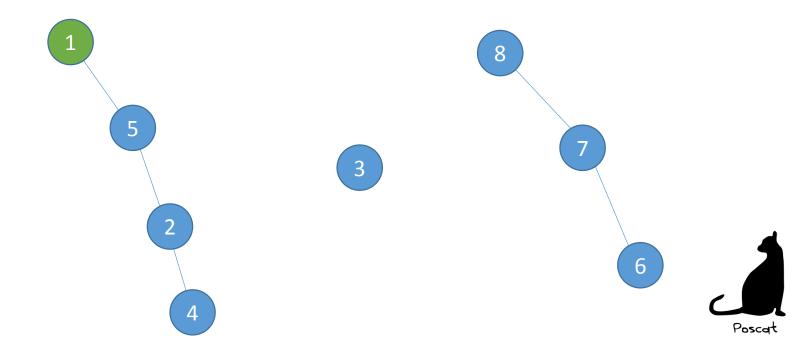
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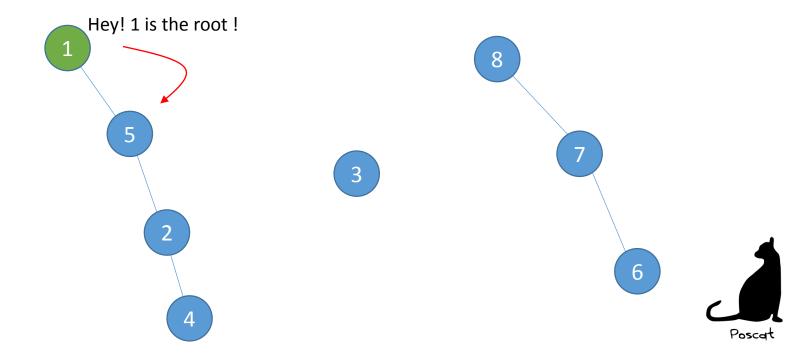
Approach



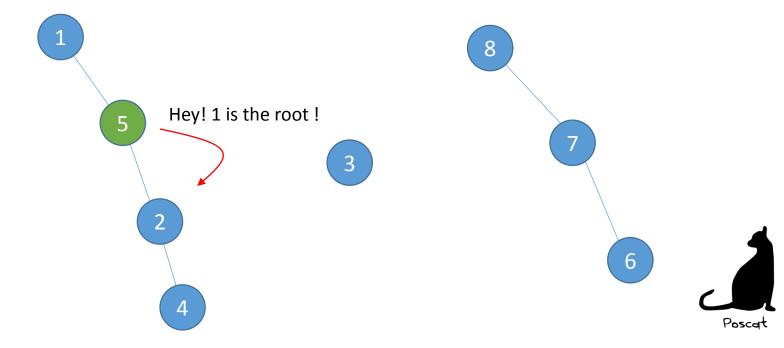
Approach



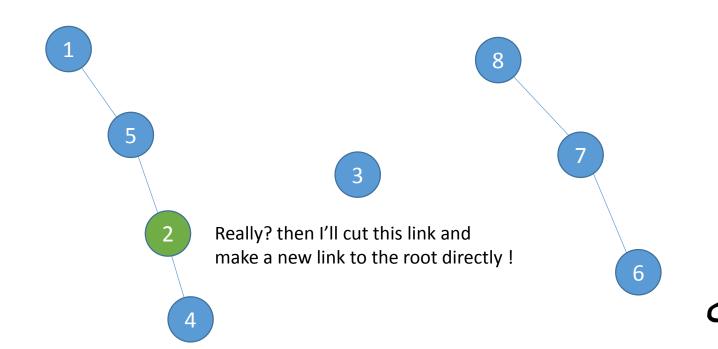
Approach



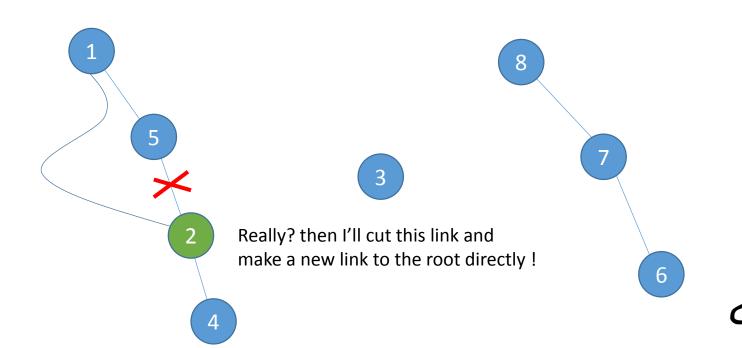
Approach



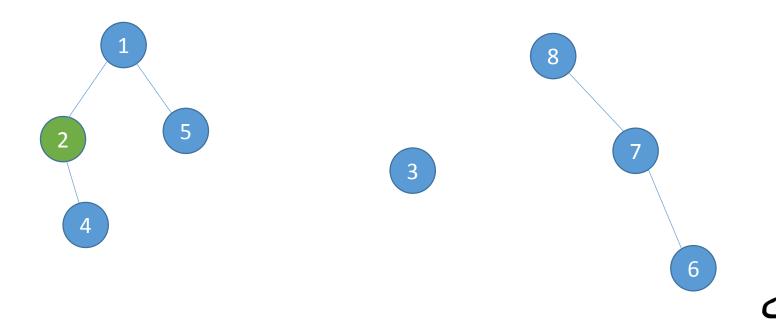
Approach



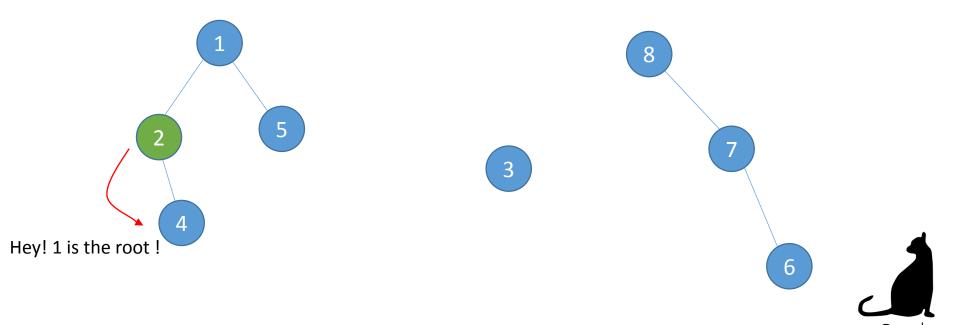
Approach



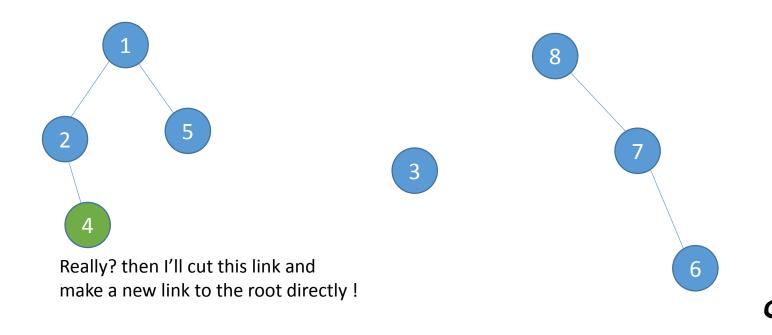
Approach



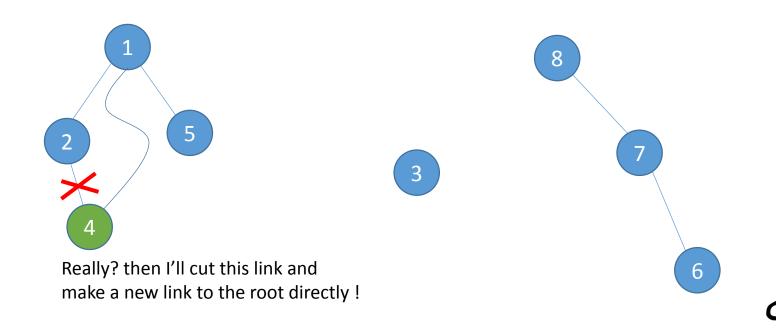
Approach



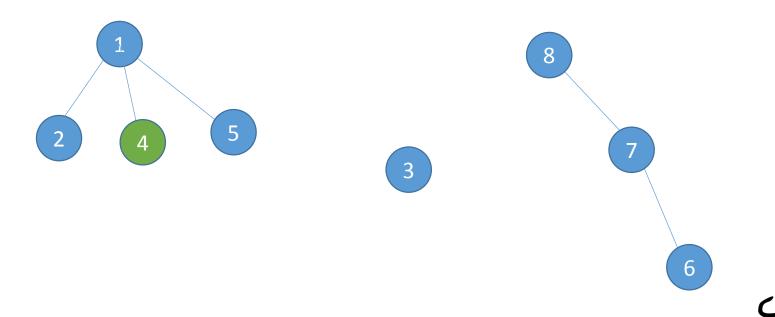
Approach



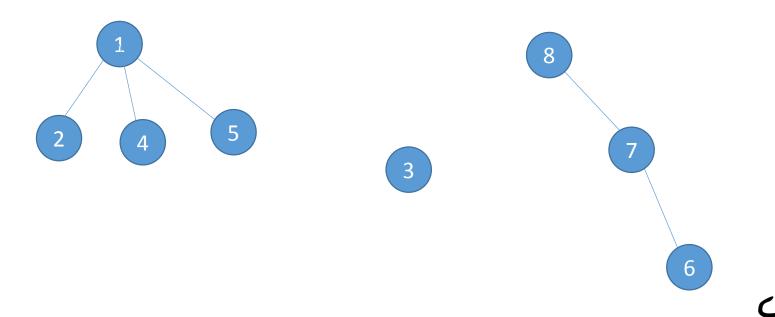
Approach



Approach



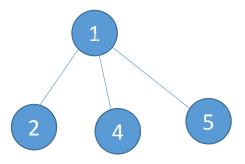
Approach

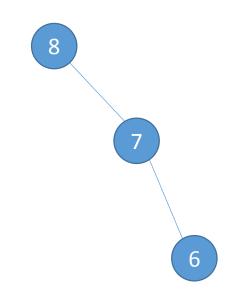


Approach

We perform two things simultaneously

- 1. Find a root
- 2. Compress the tree!

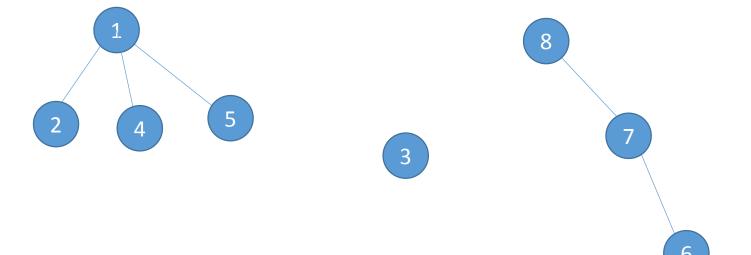






Approach

Then, How long does it take?



Approach

Then, How long does it take?

Amazingly, it takes just constant time. i.e. O(1)

Analysis is very complex. We don't discuss it.

