

## Maths

This is  $x^2 = \frac{1}{4}$  in inline mode. Here it is in display mode:

$$x^2 = \frac{1}{4}$$

## More maths

Fraction:  $\frac{dy}{dx} = \frac{dy}{dx}$

Sum:  $\sum_{n=1}^{\infty} = \sum_{n=1}^{\infty}$

Limit:  $\lim_{n \rightarrow \infty} = \lim_{n \rightarrow \infty}$

Integral:  $\int_a^b = \int_a^b$

## Matrices

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \quad B = \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix}, \quad |A| = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$$

## More frightening equations

$$\begin{aligned} f(x) &= e^{x-1} \\ \int_1^2 f(x) \, dx &= e^{x-1} \Big|_1^2 \\ &= e - 1 \end{aligned}$$

$$2x - 4y - 7z + 8w = \pi \tag{1}$$

$$3x + 5y + 9z = 213 \tag{2}$$

## Math symbols

A projection defines a function ( $f$ ) that transforms data in  $\mathbb{R}^\eta$  to  $\mathbb{R}^\kappa$  (where  $\eta \geq \kappa$ ). $\dots$   $f$  transforms the point set  $\mathcal{V}$  to another set  $\mathcal{P}$  can be denoted as a

mapping of a data point  $(\chi)$  in  $\mathbb{R}^n$  to another point  $(\rho)$  in  $\mathbb{R}^k$  that is subject to:

$$f_{\chi} = \rho \begin{cases} \mathcal{V} = (\chi_0, \chi_1, \dots, \chi_i) & \forall \chi_i \in \mathbb{R}^n & 0 \leq i < N \\ \mathcal{P} = (\rho_0, \rho_1, \dots, \rho_j) & \forall \rho_j \in \mathbb{R}^k & 0 \leq j < n \\ \eta \geq \kappa \\ N \geq n \end{cases} \quad (3)$$