

暨大資工系 線性代數 期末考 111.6.1

Theorem 1 If S is an orthonormal basis for an n -dimensional inner product space, and if $(u)_S = (u_1, u_2, \dots, u_n)$ & $(v)_S = (v_1, v_2, \dots, v_n)$ then:

$$(a) \|u\| = \sqrt{u_1^2 + u_2^2 + \dots + u_n^2}$$

$$(b) d(u, v) = \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2 + \dots + (u_n - v_n)^2}$$

$$(c) \langle u, v \rangle = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

Theorem 2 If $S = \{v_1, v_2, \dots, v_n\}$ is an orthonormal basis for an inner product space V , and u is any vector in V , then $u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + \dots + \langle u, v_n \rangle v_n$

Theorem 3. Let \mathcal{W} be a finite-dimensional subspace of an inner product space V .

(a) If $\{v_1, v_2, \dots, v_r\}$ is an orthonormal basis for \mathcal{W} , and u is any vector in V ,

$$\text{then } \text{proj}_{\mathcal{W}} u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + \dots + \langle u, v_r \rangle v_r$$

(b) If $\{v_1, v_2, \dots, v_n\}$ is an orthogonal basis for \mathcal{W} , and u is any vector in V ,

$$\text{then } \text{proj}_{\mathcal{W}} u = \frac{\langle u, v_1 \rangle}{\|v_1\|^2} v_1 + \frac{\langle u, v_2 \rangle}{\|v_2\|^2} v_2 + \dots + \frac{\langle u, v_n \rangle}{\|v_n\|^2} v_n$$

Theorem 4: A least squares solution of $Ax=b$ must satisfy the equality $A^T Ax=A^T b$ (i.e. $x=(A^T A)^{-1} A^T b$) [it is called the *normal system* associated with $Ax=b$].

If A is an $m \times n$ matrix with linearly independent column vectors, then for every $n \times 1$ matrix b , the linear system $Ax=b$ has a unique least squares solution. This solution is given by $x=(A^T A)^{-1} A^T b$. Moreover, if \mathcal{W} is the column space of A , then the orthogonal projection of b on \mathcal{W} is $\text{proj}_{\mathcal{W}} b = Ax = A(A^T A)^{-1} A^T b$

Theorem 5.

If $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a linear transformation, and e_1, e_2, \dots, e_n are the standard basic vectors for \mathbb{R}^n , then the standard matrix for T is $[T] = [T(e_1) | T(e_2) | \dots | T(e_n)]$

1. (15%) Let A be a 2×2 matrix, and call a line through the origin of \mathbb{R}^2 invariant under A if Ax lies on the line when x does.

(a) (10%) Find equations for all lines in \mathbb{R}^2 , if any, that are invariant

$$\text{under the matrix } A = \begin{bmatrix} 4 & -1 \\ 2 & 1 \end{bmatrix}.$$

$$Ax = \lambda x$$

(b) (5%) Find A^{1000} .

$$[T]_B = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

2. (15%) Let $T: M_{22} \rightarrow M_{22}$ be defined by

$$T \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 2c & a+c \\ b-2c & d \end{bmatrix}$$

(a) (5%) Find the representative matrix $[T]_B$ of the linear operator

relative to the standard basis $B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$.

(b) (10%) Find those three bases respectively for the eigenspaces of T .

3. (35%) Let W be the plane in R^3 with equation $x + z = 0$.

(a) (10%) Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \\ -1 & 0 \end{bmatrix}$, $b = \begin{bmatrix} 1 \\ -2 \\ 4 \end{bmatrix}$. Find the least squares solution of the

linear system $Ax = b$.

(b) (5%) Find an orthonormal basis for W .

(c) (5%) Utilize the above Theorem 4, to find the standard matrix for the orthogonal projection onto W .

(d) (5%) Use the matrix obtained in (c) to find the orthogonal projection of a point $b(1, -2, 4)$ onto W .

(e) (5%) Could you solve the problem (d) directly through the inner product method by using Theorem 3?

(f) (5%) Find all of the points in R^3 , such that all of them are orthogonally projected to the vector $(1, 1, -1)$ through the linear transformation T (orthogonal projection).

4. (7%) Prove that if S is an orthonormal basis for an n -dimensional inner product space, and if $(u)_S = (u_1, u_2, \dots, u_n)$ & $(v)_S = (v_1, v_2, \dots, v_n)$ then $\langle u, v \rangle = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$.

5. (8%) Let $A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ be an orthogonal matrix. Suppose

$\begin{bmatrix} y_0 \\ y_1 \end{bmatrix} = A \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$, where $\begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$ and $\begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$ are the coordinate vectors relative to

the old orthonormal basis $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ and a new basis, respectively.

(a) (4%) Find the new basis.

(b) (4%) For the vector $(1,1)$, find the coordinate vector corresponding to the new basis.

6. (10%) Let $F(-\infty, \infty)$ be the vector space of real-valued functions.

Suppose that W is a subspace of $F(-\infty, \infty)$ and W is spanned by

$\varphi_1(t)$ and $\varphi_2(t)$, where

$\varphi_1(t) = \sqrt{2} \cos(2\pi t)$ and $\varphi_2(t) = \sqrt{2} \sin(2\pi t)$, $0 \leq t \leq 1$. Let W have

the inner product $\langle p(t), q(t) \rangle \triangleq \int_0^1 p(t)q(t)dt$, where $p(t), q(t) \in W$; and

the norm (or length) of $p(t)$ is defined by $\|p(t)\| = \sqrt{\langle p(t), p(t) \rangle}$.

Suppose

$$s_1(t) = \frac{-\sqrt{2}}{2} \varphi_1(t) + \frac{\sqrt{2}}{2} \varphi_2(t) \text{ and } s_2(t) = \frac{\sqrt{2}}{2} \varphi_1(t) - \frac{\sqrt{2}}{2} \varphi_2(t).$$

(a) (4%) Find the coordinate vectors of $s_1(t)$ and $s_2(t)$ respectively with respect to the basis S .

(b) (6%) Find the distance between $s_1(t)$ and $s_2(t)$ (write down two methods)

7. (10%) Given the matrix

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

and let the column matrix $X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$.

Find all possible vectors \mathbf{b} , such that $AX = \mathbf{b}$ is consistent.

Handwritten work for problem 7:

Column space

$$[c_1 \ c_2 \ c_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 & 0 & 0 \\ +x(2 \ 2 \ 1) \end{bmatrix} \in \mathbb{R}^3$$

$$\sum_{i=1}^3 c_i x_i$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 2 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & \frac{1}{2} \end{bmatrix}$$

$\hat{x} = 2k + l$
 $\hat{y} = 2k + l$
 $\hat{z} = k$

$k(1 \ 0 \ 0) + l(0 \ 1 \ \frac{1}{2})$

1/ (a)

$$\lambda=2 \begin{bmatrix} -2 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$-2x + y = 0$$

$$y = 2x$$

$$(4-\lambda)(1-\lambda)+2=0$$

$$4-5\lambda+\lambda^2+2=0$$

$$\lambda^2-5\lambda+6=0$$

$$\lambda=3, 2$$

$$AX = \lambda X$$

$$(\lambda I - A)X = 0$$

$$\lambda=3 \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$y = x$$

Note: 需要求出特征方程式

$$(b) \begin{bmatrix} \lambda-4 & 1 \\ -2 & \lambda-1 \end{bmatrix}$$

$$(\lambda-4)(\lambda-1)+2=0, \lambda^2-5\lambda+6=0$$

$$\lambda=3, 2$$

$$\lambda=3 \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \quad -x_1 + x_2 = 0$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

basis

$$\lambda=2 \begin{bmatrix} -2 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \quad -2x_1 + x_2 = 0$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} t \\ 2t \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$$P^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

$$D = P^{-1}AP = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 4 & -1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 6 & -3 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$

$$A^{1000} = P D^{1000} P^{-1} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 3^{1000} & 0 \\ 0 & 2^{1000} \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3^{1000} & 2^{1000} \\ 3^{1000} & 2^{1000} \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 2 \times 3^{1000} - 2^{1000} & -3^{1000} + 2^{1000} \\ 2 \times 3^{1000} - 2^{1000} & -3^{1000} + 2^{1000} \end{bmatrix}$$

$$A = PDP^{-1}$$

$$B = \left\{ \underset{B_1}{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}, \underset{B_2}{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}, \underset{B_3}{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}, \underset{B_4}{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}} \right\} \text{ basis for } M_{2,2}$$

$$(a) [T(B_1)]_B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad [T(B_2)]_B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \quad [T(B_3)]_B = \begin{bmatrix} 2 & 1 \\ -2 & 0 \end{bmatrix} \quad [T(B_4)]_B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$[T]_B = \begin{bmatrix} 0 & 0 & 2 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \checkmark$$

$$[T(B_4)]_B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{最簡單} \quad \text{向} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$(b) \begin{vmatrix} \lambda & 0 & -2 & 0 \\ 1 & \lambda & -1 & 0 \\ 0 & -1 & \lambda & 2 \\ 0 & 0 & 0 & \lambda-1 \end{vmatrix} = 0$$

$$(\lambda-1)^2(\lambda+1)(\lambda+2) = 0$$

$$\lambda = 1, 1, -1, -2$$

$$(\lambda-1)(\lambda+2)(\lambda-1) = 2$$

$$\lambda = 1: \begin{bmatrix} 1 & 0 & -2 & 0 \\ 1 & 1 & -1 & 0 \\ 0 & -1 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\begin{aligned} x_1 - 2x_3 &= 0 \\ x_1 + x_2 - x_3 &= 0 \\ x_2 + 3x_3 &= 0 \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2t \\ 3t \\ t \\ 5 \end{bmatrix} = t \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

the basis for

$$\text{basis} \left\{ \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

It's the eigenspace of $[T]_B$

$$\lambda = -2: \begin{bmatrix} -2 & 0 & -2 & 0 \\ -1 & -2 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\begin{aligned} -2x_1 - 2x_3 &= 0 \\ -x_1 - 2x_2 - x_3 &= 0 \\ -x_2 &= 0 \\ -3x_4 &= 0 \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -t \\ 0 \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

真正答案應該

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

$$\text{basis} \left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$$\left\{ \begin{bmatrix} 2 & 3 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

is the basis

$$\lambda = -1: \begin{bmatrix} -1 & 0 & -2 & 0 \\ -1 & -1 & -1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\begin{aligned} -x_1 - 2x_3 &= 0 \\ -x_1 - x_2 - x_3 &= 0 \\ -x_2 + x_3 &= 0 \\ -2x_4 &= 0 \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = t \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{basis} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

for the eigenspace of

T

Corresponding

check:

$$\lambda = 1 \quad T\left(k_1 \begin{bmatrix} 2 & 3 \\ 1 & 0 \end{bmatrix} + k_2 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\right) = k_1 \begin{bmatrix} 2 & 3 \\ 1 & 0 \end{bmatrix} + k_2 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = X$$

$$\lambda = -2 \quad T\left(k_1 \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix}\right) = k_1 \begin{bmatrix} 2 & 0 \\ -2 & 0 \end{bmatrix} = -2X$$

$$\lambda = -1 \quad T\left(k_1 \begin{bmatrix} -2 & 1 \\ 1 & 0 \end{bmatrix}\right) = k_1 \begin{bmatrix} 2 & -1 \\ -1 & 0 \end{bmatrix} = -X$$

3. $w: x+0y+z=0$

(a) $A^T A x = A^T b$

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 4 \\ 0 & 0 \end{bmatrix} (A^T A)$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ -2 \\ 4 \end{bmatrix} = \begin{bmatrix} -5 \\ -4 \\ 0 \end{bmatrix}$$

$$2x_1 = -5 \\ 4x_2 = -4$$

$$x_1 = -\frac{5}{2} \quad x_2 = -1 \quad \#$$

$AX \neq b$
but $A^T A x = A^T b$
有解



$$x = (A^T A)^{-1} A^T b$$

$$AX = A(A^T A)^{-1} A^T b$$

(b) $x = -3 \quad y = t \quad z = 3$

$$\begin{bmatrix} -3 \\ t \\ 3 \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \quad \checkmark$$

orthonormal basis $(0, 1, 0), (\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$

(c) $A(A^T A)^{-1} A^T$

$$A^T A = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix} \quad (A^T A)^{-1} = \frac{1}{8} \begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\frac{1}{8} \begin{bmatrix} 1 & 0 \\ 0 & 2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 4 & 0 \\ 0 & 4 \\ -4 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \end{bmatrix} = \begin{bmatrix} 4 & 0 & -4 \\ 0 & 8 & 0 \\ -4 & 0 & 4 \end{bmatrix} \frac{1}{8}$$

$$\Rightarrow \begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & 1 & 0 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix} \quad \checkmark$$

(d) $\begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & 1 & 0 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 4 \end{bmatrix} = \begin{bmatrix} -\frac{3}{2} \\ -2 \\ \frac{3}{2} \end{bmatrix} \quad \checkmark \quad \#$

(e)

$$(1, -2, 4) \cdot (0, 1, 0) \times (0, 1, 0) = (0, -2, 0)$$

$$(1, -2, 4) \cdot \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right) \times \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right) = \frac{3}{\sqrt{2}} \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right) \\ = \left(-\frac{3}{2}, 0, \frac{3}{2}\right)$$

$$(0, -2, 0) + \left(-\frac{3}{2}, 0, \frac{3}{2}\right) = \left(-\frac{3}{2}, -2, \frac{3}{2}\right) \neq \checkmark$$

$$(f) \begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & 1 & 0 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

$$\frac{1}{2}x_1 - \frac{1}{2}x_3 = 1 \quad x_2 = 1$$

$$x_2 = 1$$

$$\Rightarrow x_1 = t$$

$$\Rightarrow x_1 = t, x_2 = 1, x_3 = t - 2$$

$$-\frac{1}{2}x_1 + \frac{1}{2}x_3 = -1$$

$$x_3 = t - 2$$

$$(t, 1, t-2) \quad t \in \mathbb{R} \neq$$

$$(0, 1, 0) + t(1, 0, -2)$$

4.

$$S = \{e_1, e_2, \dots, e_n\}$$

$$u = u_1 e_1 + u_2 e_2 + \dots + u_n e_n$$

$$v = v_1 e_1 + v_2 e_2 + \dots + v_n e_n$$

$$\langle u, v \rangle = \langle (u_1 e_1 + u_2 e_2 + \dots + u_n e_n), (v_1 e_1 + v_2 e_2 + \dots + v_n e_n) \rangle$$

$$= \langle u_1 e_1, v_1 e_1 \rangle + \dots + \langle u_n e_n, v_n e_n \rangle$$

$$+ \langle u_2 e_2, v_2 e_2 \rangle + \dots + \langle u_n e_n, v_n e_n \rangle$$

$$= u_1 v_1 \langle e_1, e_1 \rangle + \dots + u_n v_n \langle e_n, e_n \rangle$$

$$\because \text{orthonormal basis } |e_n| = 1 = \langle e_n, e_n \rangle$$

$$= u_1 v_1 + u_2 v_2 + \dots + u_n v_n \neq$$

5.

(a)

$$T\left[\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right] = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$T\left[\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right] = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$[T]_{B'} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\text{basis} = \left\{ \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} \right\}$$

$$(b) \quad 1 = a \frac{1}{\sqrt{2}} + b \frac{1}{\sqrt{2}}$$

$$\frac{2a}{\sqrt{2}} = 2$$

$$a = \sqrt{2}$$

$$1 = a \frac{1}{\sqrt{2}} - b \frac{1}{\sqrt{2}}$$

$$b = 0$$

$$\langle (1, 1) \rangle_{B'} = (\sqrt{2}, 0) \neq$$

6

$$(a) \langle z_1(t) \rangle_5 = \left(\frac{-\sqrt{2}}{2}, \frac{\sqrt{2}}{2} \right), \quad \langle z_2(t) \rangle_5 = \left(\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2} \right)$$

$$(b) \quad \textcircled{1} \quad f = z_1 - z_2 = -\sqrt{2} \varphi_1(t) + \sqrt{2} \varphi(t) \\ = 2 \sin(2\pi t) - 2 \cos(2\pi t) \\ = 2(\sin(2\pi t) - \cos(2\pi t))$$

$$|f| = \sqrt{\langle f, f \rangle} \quad \theta = 2\pi t$$

$$(2\sin\theta - 2\cos\theta)^2 = 4\sin^2\theta - 8\sin\theta\cos\theta + 4\cos^2\theta \\ = 4 - 8\sin\theta\cos\theta \\ = 4 - 4\sin 2\theta = 4 - 4\sin(4\pi t)$$

$$\int_0^1 4 - 4\sin(4\pi t) dt = 4 - 4 \int_0^1 \sin(4\pi t) dt \\ = 4 - 4 \left(-\frac{1}{4\pi} \cos(4\pi t) \right) \Big|_0^1 \\ = 4$$

$$|f| = \sqrt{4} = 2 \#$$

$$\textcircled{2} \quad [f]_5 = (-\sqrt{2}, \sqrt{2})$$

$$|f| = \sqrt{(-\sqrt{2})^2 + (\sqrt{2})^2} = 2 \#$$

$$7. \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 2 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & b_1 \\ 0 & 2 & 2 & b_2 \\ 0 & 1 & 1 & b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 1 & b_1 \\ 0 & 0 & 0 & b_2 - 2b_3 \\ 0 & 1 & 1 & b_3 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 0 & b_1 - b_3 \\ 0 & 1 & 1 & b_3 \\ 0 & 0 & 0 & b_2 - 2b_3 \end{bmatrix}$$

$$b_2 - 2b_3 = 0$$

$$b_2 = 2t \quad b_3 = t \quad b_1 = s$$

$$b = \begin{bmatrix} s \\ 2t \\ t \end{bmatrix} \quad s, t \in \mathbb{R} \quad \#$$

$$b = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$$

$$s, t \in \mathbb{R}$$