Libuv usages & internals

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Libuv basics

- Blocking VS non-blocking
- Synchronous VS asynchronous
- BIO, NIO and AIO
- Event & callback
- · epoll

Libuv basics

- What is libuv?
 <u>multi-platform</u> <u>event-driven</u> <u>asynchronous I/O library</u>
- Multi-platform
 Unix(Linux/BSDs/AIX/Solaris) and Windows
- **Event-driven**register callback for each event, callback will be called after event happens
- Asynchronous I/O library others include libevent and libev

Libuv basics

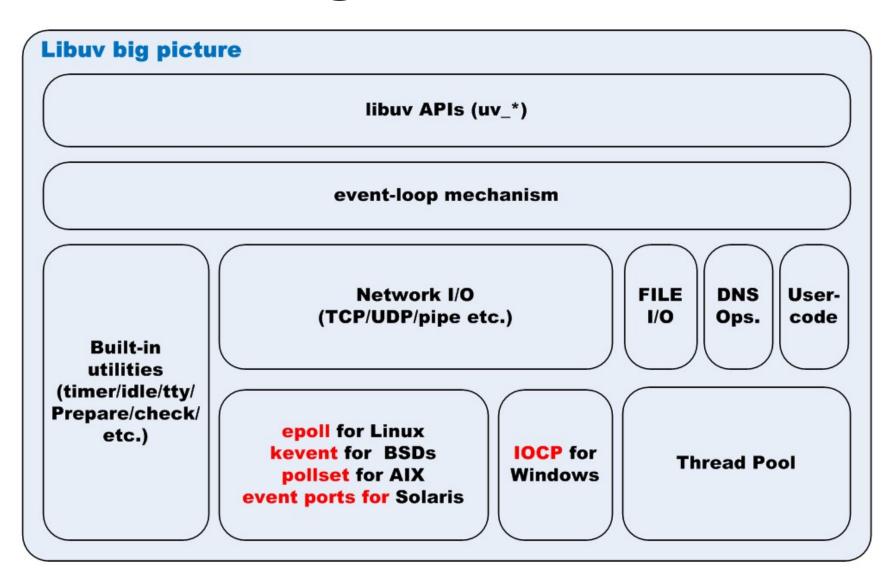
Handle

long-lived objects capable of performing operations while active (get its callback called), such as TCP/UDP, tty and timers

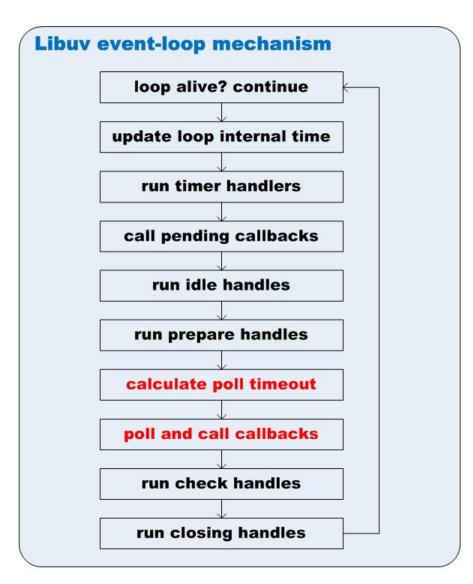
Request

short-lived objects, performed over handles (write/connect) or standalone (getaddrinfo)

Libuv design overview



Libuv design overview



Download source code

\$ git clone https://github.com/libuv/libuv; cd libuv

Automation or benchmark test

```
$ ./gyp_uv.py -f ninja
$ ninja -C out/Debug
$ cd out/Debug
$ ./run-tests
$ ./run-benchmarks
```

Install headers and shared library

```
$ ./autogen.sh
$ ./configure
$ make
$ sudo make install
$ sudo ldconfig
```

Simple API test

```
$ gcc version.c -luv
$ ./a.out
$ 1.8.1-dev
```

```
#include <stdio.h>
#include <uv.h>

int main()
{
    printf("%s\n", uv_version_string());
    return 0;
}
```

A simple example – uvcat

```
int main(int argc, char **argv) {
    uv fs_open(uv_default_loop(), &open_req, argv[1], 0_RDONLY, 0, on_open);
    uv run(uv default loop(), UV RUN_DEFAULT);
    uv fs req cleanup(&open req);
    uv fs req cleanup(&read req);
    uv_fs_req_cleanup(&write_req);
    return 0;
void on open(uv fs t *req) {
   // The request passed to the callback is the same as the one the call setup
   // function was passed.
   assert(req == &open req);
   if (req->result >= 0) {
       iov = uv buf init(buffer, sizeof(buffer));
       uv_fs_read(uv_default_loop(), &read_req, req->result,
                   &iov, 1, -1, on read);
    else {
        fprintf(stderr, "error opening file: %s\n", uv strerror((int)req->result));
```

A simple example – uvcat (cont.)

```
void on read(uv fs t *req) {
    if (req->result < 0) {
        fprintf(stderr, "Read error: %s\n", uv strerror(req->result));
    else if (req->result == 0) {
        uv_fs_t close_req;
        // synchronous
        uv_fs_close(uv_default_loop(), &close_req, open_req.result, NULL);
    else if (req->result > 0) {
        iov.len = req->result;
       uv fs write(uv default loop(), &write req, 1, &iov, 1, -1, on write);
}
void on_write(uv_fs_t *req) {
    if (req->result < 0) {
        fprintf(stderr, "Write error: %s\n", uv_strerror((int)req->result));
    else {
        uv fs read(uv default loop(), &read req, open req.result, &iov, 1, -1, on read);
    }
```

Normal BIO

VS

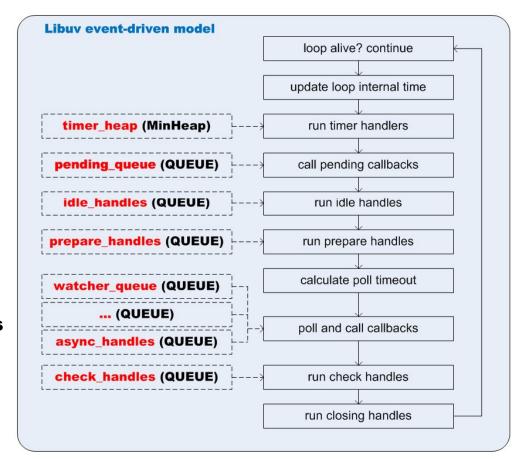
libuv AIO

```
// BIO mode
void main()
{
    fd = open(path, ...);
    while (read(fd, ...) != 0) {
        write(STDOUT_FILENO, ...);
    }
    close(fd);
}
```

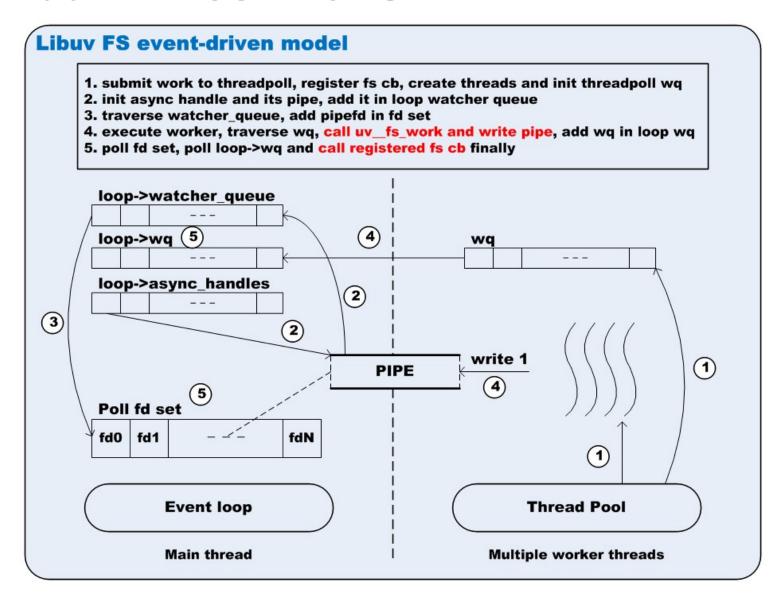
```
// libuv AIO mode
void main()
    fd = uv_fs_open(&open_req, path, ..., open_cb);
    uv run(...);
void open_cb(uv_fs_t *req) {
    uv fs read(req->result, ..., read cb);
}
void read cb(uv fs t *req) {
    if (req->result > 0) {
        uv fs write(STDOUT FILENO, ..., write cb);
    } else if (req->result == 0) {
        uv fs close(open req.result, NULL);
void write_cb(uv_fs_t *req) {
    uv fs read(open req.result, ..., read cb);
}
```

- How cross-platform?
- For compilation, use cross-platform GYP build tool
- For asynchronous I/Os, use Unix libev and Windows IOCP
 - Epoll for Linux (uv io poll -> epoll wait sycall)
 - Kqueue for Mac OS X and other BSDs (uv__io_poll -> kevent)
 - Pollset for IBM-AIX (uv io poll -> pollset poll)
 - Event ports for Sun-Solaris (uv__io_poll -> port_getn)
 - IOCP for Windows (uv io poll -> GetQueueCompletionStatus)
- For threadpoll, use high-level abstracted APIs + MT libraries
 - Pthread for POSIX Unix (uv_thread_create -> pthread_create)
 - Built-in MT APIs for Windows (uv_thread_create ->_beginthreadex)

- Event-driven model
- Components:
 - Registered callbacks
 - Event queues
 - Poll mechanism
- Steps
- 1. registered callback
- 2. add to queue when event happens
- 3. poll queues in loop
- 4. call registered callbacks



- FS event-driven model
- Components
 - Blocking FS Operations: worker threads in threadpoll
 - Event loop: main thread
 - Inner-Thread Communication: pipe-based async handle



- FS event-driven model (cont.)
- Steps and source code trace
- 1. submit work to threadpoll, register fs cb, create threads and init threadpoll wq

```
uv fs XXX(CB) -> POST -> uv work submit(uv fs work, uv fs done)
```

2. init async handle and its pipe, add it in loop watcher queue

```
uv_loop_init -> uv_async_init -> uv_async_start
```

3. traverse watcher_queue, add pipefd in fd

```
setuv run -> uv io poll -> uv epoll ctl
```

4. execute worker, traverse wq, call uv_fs_work, write pipe, add wq in loop wq

```
worker -> uv fs work -> uv async send
```

5. poll fd set, call registered fs cb finally

```
Uv__io_poll -> uv__async_io -> uv__async_event -> uv__work_done -> uv__fs_done -> fs cb
```

Questions

- epoll is NIO or AIO ?
- What is the relationship between <u>epoll</u> and <u>libuv</u>?
- What is the difference between <u>libev</u> and <u>libuv</u>?

References

Libuv source code

https://github.com/libuv/libuv

uvbook (intro ebook, examples and ex-examples)

http://nikhilm.github.io/uvbook/An%20Introduction%20to%20libuv.pdf
https://github.com/nikhilm/uvbook
https://github.com/thlorenz/libuv-dox/

Libuv official API documentation

http://docs.libuv.org/en/v1.x/

Thank you!