

MULTIDIMENSIONAL SCALING (MDS)

SETTING: FOR A SET OF N OBJECTS WE HAVE A MEASUREMENT
OF DISSIMILARITIES/DISTANCES BETWEEN EACH PAIR OF OBJECTS

δ_{rs} = DISSIMILARITY OF OBJECTS r AND s

e.g. DISTANCES BETWEEN CITIES, DIFFERENCES IN COLORS FROM
OPINIONS OF A COLLECTION OF RANDOMLY SELECTED
STUDY SUBJECTS, ...

GOAL: FIND A CONFIGURATION OF POINTS IN LOW-DIMENSIONAL
SPACE (USUALLY 1, 2, OR 3), WITH ONE POINT PER SUBJECT
S.T. THE DISTANCE/DISSIMILARITY BETWEEN POINTS/SUBJECTS
MATCHES ORIGINAL DISSIMILARITIES, i.e.

FIND $\vec{x}'_1, \dots, \vec{x}'_N \in \mathbb{R}^k$ S.T.

$$\|\vec{x}'_r - \vec{x}'_s\| \approx \delta_{rs}$$

* GIVE A LOW-DIMENSIONAL VISUAL REPRESENTATION OF DATA TO
HELP VISUALIZE USEFUL INFO. ABOUT RELATIONSHIPS BETWEEN OBJECTS

NOTE: $\vec{x}'_1, \dots, \vec{x}'_N \in \mathbb{R}^k$, $\vec{b} \in \mathbb{R}^k$, $A \in \mathbb{R}^{k \times k}$ ORTHONORMAL

$$\begin{aligned} \|(A\vec{x}'_r + \vec{b}) - (A\vec{x}'_s + \vec{b})\|_2 &= \|A(\vec{x}'_r - \vec{x}'_s)\|_2 \\ &= \sqrt{[A(\vec{x}'_r - \vec{x}'_s)]^T [A(\vec{x}'_r - \vec{x}'_s)]} \\ &= \sqrt{(\vec{x}'_r - \vec{x}'_s)^T \underbrace{A^T A}_{I} (\vec{x}'_r - \vec{x}'_s)} = \|\vec{x}'_r - \vec{x}'_s\|_2 \end{aligned}$$

* LOW DIMENSIONAL REPRESENTATION IS ONLY UNIQUE
UP TO ROTATION/REFLECTION & TRANSLATION
USING EUCLIDEAN DISTANCE

CLASSICAL SCALING (YOUNG, HOUSEHOLDER 1930 TORGERSEN 1952)

DEF. An $N \times N$ MATRIX D IS CALLED A DISTANCE MATRIX IF

1) IT IS SYMMETRIC $D_{rs} = D_{sr}$

2) $D_{rr} = 0$

3) $D_{rs} \geq 0 \quad r \neq s$

FURTHERMORE, D IS CALLED EUCLIDEAN IF THERE EXISTS

A CONFIGURATION OF POINTS IN SOME EUCLIDEAN SPACE,

i.e. $\exists p$ s.t. $\vec{x}_1, \dots, \vec{x}_N \in \mathbb{R}^p$, SUCH THAT

$$\begin{aligned} D_{rs}^2 &= (\vec{x}_r - \vec{x}_s)^T (\vec{x}_r - \vec{x}_s) = \|\vec{x}_r - \vec{x}_s\|^2 \\ &= \vec{x}_r^T \vec{x}_r + \vec{x}_s^T \vec{x}_s - 2 \vec{x}_r^T \vec{x}_s \\ &= \|\vec{x}_r\|^2 + \|\vec{x}_s\|^2 - 2 \vec{x}_r^T \vec{x}_s \end{aligned}$$

RECOVERING COORDINATES

GIVEN A EUCLIDEAN DISTANCE MATRIX $D \in \mathbb{R}^{N \times N}$ CAN WE RECOVER
THE COORDINATES $\vec{x}_1, \dots, \vec{x}_N$? (ASSUME $\sum_{i=1}^N x_{ij} = 0 \quad j=1, \dots, p$)

YES,

1) USE $D \in \mathbb{R}^{N \times N}$ TO FIND $B \in \mathbb{R}^{N \times N}$, $B_{rs} = \vec{x}_r^T \vec{x}_s$

2) USE $B = XX^T$ TO RECOVER $\vec{x}_1, \dots, \vec{x}_N$
↑
INNER PRODUCT MATRIX

$$X = \begin{bmatrix} \vec{x}_1^T \\ \vdots \\ \vec{x}_N^T \end{bmatrix} \in \mathbb{R}^{N \times p}$$

STEP 1: FIND B FROM D

↑
INNER PRODUCT
↑
DISTANCE

$$\begin{aligned} a) \quad \frac{1}{N} \sum_{r=1}^N D_{rs}^2 &= \frac{1}{N} \sum_{r=1}^N (\|\vec{x}_r\|^2 + \|\vec{x}_s\|^2 - 2 \vec{x}_r^T \vec{x}_s) \\ &= \left(\frac{1}{N} \sum_{r=1}^N \|\vec{x}_r\|^2 \right) + \frac{N}{N} \|\vec{x}_s\|^2 - 2 \left(\sum_{r=1}^N \vec{x}_r^T \right) \vec{x}_s \\ &= \frac{1}{N} \sum_{r=1}^N \|\vec{x}_r\|^2 + \|\vec{x}_s\|^2 = \frac{1}{N} \text{tr}(B) + B_{ss} = 0 \end{aligned}$$

$$b) \quad \frac{1}{N} \sum_{s=1}^N d_{rs}^2 = \|\vec{x}_r\|^2 + \frac{1}{N} \sum_{s=1}^N \|\vec{x}_s\|^2 = \frac{1}{N} \text{tr}(B) + \text{tr}(B_{rr})$$

$$c) \quad \frac{1}{N^2} \sum_{r=1}^N \sum_{s=1}^N D_{rs}^2 = \frac{1}{N^2} \left(\sum_{r=1}^N \sum_{s=1}^N \|\vec{x}_r\|^2 + \sum_{r=1}^N \sum_{s=1}^N \|\vec{x}_s\|^2 - 2 \left(\sum_{r=1}^N \vec{x}_r^T \right) \left(\sum_{s=1}^N \vec{x}_s \right) \right)$$

$$= \frac{1}{N^2} \left[2N \sum_{r=1}^N \|\vec{x}_r\|^2 \right] = \frac{2}{N} \text{tr}(B)$$

$$d) \quad B_{rs} = \vec{x}_r^T \vec{x}_s = -\frac{1}{2} \left(D_{rs}^2 - \vec{x}_r^T \vec{x}_r - \vec{x}_s^T \vec{x}_s \right)$$

$$= -\frac{1}{2} \left[D_{rs}^2 - \left(\frac{1}{N} \sum_{s=1}^N D_{rs}^2 - \frac{1}{N} \text{tr}(B) \right) - \left(\frac{1}{N} \sum_{r=1}^N D_{rs}^2 - \frac{1}{N} \text{tr}(B) \right) \right]$$

$$= -\frac{1}{2} \left[D_{rs}^2 - \frac{1}{N} \sum_{s=1}^N D_{rs}^2 - \frac{1}{N} \sum_{r=1}^N D_{rs}^2 + \frac{2}{N} \text{tr}(B) \right]$$

$$= -\frac{1}{2} \begin{bmatrix} \ddots & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \ddots \end{bmatrix} \frac{1}{N^2} \sum_{r,s} D_{rs}^2$$

MATRIX NOTATION

$$\text{LET } \left. \begin{aligned} a_{rs} &= -\frac{1}{2} D_{rs}^2 \\ a_{r.} &= \frac{1}{N} \sum_s a_{rs} = -\frac{1}{2N} \sum_s D_{rs}^2 \\ a_{.s} &= \frac{1}{N} \sum_r a_{rs} = -\frac{1}{2N} \sum_r D_{rs}^2 \\ a_{..} &= \frac{1}{N^2} \sum_{r,s} a_{rs} = \frac{1}{N^2} \sum_{r,s} D_{rs}^2 \end{aligned} \right\} \Rightarrow B_{rs} = a_{rs} - a_{r.} - a_{.s} + a_{..}$$

$$\mathbf{1}_N = (1, 1, 1, \dots, 1)^T \in \mathbb{R}^N$$

$$\text{IF } A \in \mathbb{R}^{N \times N}, \quad A_{rs} = a_{rs} \quad \text{THEN}$$

$$B = HAH \quad H = I_N - \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^T$$

$$= \left(I - \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^T \right) A \left(I - \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^T \right)$$

$$= A - \underbrace{\mathbf{1}_N \left(\frac{1}{N} \mathbf{1}_N^T A \right)}_{\mathbf{1}_N \begin{pmatrix} a_{.1} \\ \vdots \\ a_{.N} \end{pmatrix}^T} - \underbrace{\left(A \frac{1}{N} \mathbf{1}_N \right) \mathbf{1}_N^T}_{\begin{pmatrix} a_{.1} \\ \vdots \\ a_{.N} \end{pmatrix} \mathbf{1}_N^T} + \underbrace{\mathbf{1}_N \left(\frac{1}{N} \mathbf{1}_N^T A \mathbf{1}_N \right) \mathbf{1}_N^T}_{\mathbf{1}_N a_{..} \mathbf{1}_N^T}$$

$$\Rightarrow B_{rs} = A_{rs} - a_{r.} - a_{.s} + a_{..}$$

STEP 2: Find $\vec{x}_1, \dots, \vec{x}_n$ from B

RECALL $B_{rs} = \vec{x}_r^T \vec{x}_s \iff B = XX^T$

- WHAT IS $\text{RANK}(B)$? p
- B IS SYMMETRIC. WHAT IS EIGENDECOMP. OF B ?

$$B = U \Delta U^T, \Delta = \begin{bmatrix} \sigma_1 & & & 0 \\ & \ddots & & \\ & & \sigma_p & \\ 0 & & & 0 \end{bmatrix} \quad \tilde{\Delta} = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_p \end{bmatrix}$$

$$= \tilde{U} \tilde{\Delta} \tilde{U}^T \quad \tilde{U} = [\tilde{u}_1 \dots \tilde{u}_p]$$

- HOW CAN WE FIND X FROM $B = U \Delta U^T$?

$$B = \underbrace{\tilde{U}}_X \underbrace{\tilde{\Delta}^{1/2}}_{X^T} \tilde{U}^T \quad \Delta^{1/2} = \begin{bmatrix} \sigma_1^{1/2} & 0 \\ 0 & \sigma_p^{1/2} \end{bmatrix}$$

$$\Rightarrow X = [\tilde{u}_1 \dots \tilde{u}_p] \begin{bmatrix} \sigma_1^{1/2} & 0 \\ 0 & \sigma_p^{1/2} \end{bmatrix}$$

NOTE: PARITY $\tilde{u}_i \mapsto -\tilde{u}_i$ LEADS TO REFLECTED SOLUTIONS (UNIQUENESS UP TO SIGN)

CLASSICAL SCALING IN PRACTICE

GIVEN A DISTANCE MATRIX D AND WANT TO APPROXIMATELY REPRESEN
IN LOWER DIMENSION.

(NOTE D MAY OR MAY NOT BE EUCLIDEAN)

CLASSICAL SOLUTION TO MDS PROBLEM IN k DIMENSIONS

- FROM D FORM MATRIX A , $A_{rs} = -\frac{1}{2} D_{rs}^2$
- OBTAIN $B = HAH$
- FIND THE k LARGEST EIGENVALUES $\lambda_1, \dots, \lambda_k$ OF B
w/ EIGENVECTORS $\vec{x}_{(1)}, \dots, \vec{x}_{(k)} \in \mathbb{R}^n$

(WE ARE ASSUMING THE FIRST k EIGENVALUES OF B ARE POSITIVE!)

- MDS COORDINATES OF POINTS ARE ROWS OF $\begin{bmatrix} \vec{x}_{(1)} & \dots & \vec{x}_{(k)} \end{bmatrix} \begin{bmatrix} \lambda_1^{1/2} & 0 \\ 0 & \lambda_k^{1/2} \end{bmatrix}$

Thm: LET D BE A DISTANCE MATRIX AND $B = HAH$ w/ $A_{rs} = -\frac{1}{2} D_{rs}^2$

D IS EUCLIDEAN $\Leftrightarrow B$ IS POSITIVE SEMI-DEFINITE

Ex: Suppose $D = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$. IS D EUCLIDEAN, I.E. DOES THERE EXIST $A, p=1,2,\dots$

S.T. THERE ARE POINTS $\vec{x}_1, \dots, \vec{x}_3 \in \mathbb{R}^p$ w/ $\|\vec{x}_i - \vec{x}_j\|_2 = \delta_{ij}$? IF

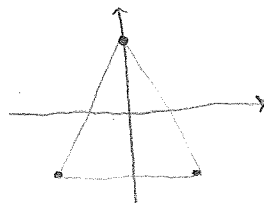
SO FIND THE SMALLEST SUCH p AND DESCRIBE THE SHAPE FORMED BY THE POINTS $\vec{x}_1, \dots, \vec{x}_3$!

$$A = \begin{bmatrix} 0 & -1/2 & -1/2 \\ -1/2 & 0 & -1/2 \\ -1/2 & -1/2 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 1/3 & -1/6 & -1/6 \\ -1/6 & 1/3 & -1/6 \\ -1/6 & -1/6 & 1/3 \end{bmatrix} = HAH$$

$$= \begin{bmatrix} 0 & \sqrt{2}/3 & \sqrt{2}/3 \\ -\sqrt{2}/2 & -\sqrt{1}/6 & -\sqrt{1}/6 \\ \sqrt{2}/2 & -\sqrt{1}/6 & -\sqrt{1}/6 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 0 & -\sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/3 & -\sqrt{1}/6 & \sqrt{1}/6 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & \sqrt{2}/3 \\ -\sqrt{2}/2 & -1/\sqrt{6} \\ \sqrt{2}/2 & -1/\sqrt{6} \end{bmatrix} \begin{bmatrix} \sqrt{2}/2 & 0 \\ 0 & \sqrt{2}/2 \end{bmatrix} = \begin{bmatrix} 0 & 1/\sqrt{3} \\ -1/2 & -1/2\sqrt{3} \\ +1/2 & -1/2\sqrt{3} \end{bmatrix}$$



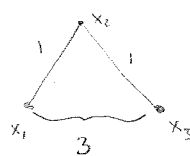
EQUILATERAL TRIANGLE

* CAN ROTATE ABOUT ORIGIN *
AND PRESERVE DISTANCES

Ex: $D = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & 1 \\ 3 & 1 & 0 \end{bmatrix}$

$$A = \begin{bmatrix} 0 & -1/2 & -3/2 \\ -1/2 & 0 & -1/2 \\ -3/2 & -1/2 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 17/3 & 7/6 & -11/6 \\ 7/6 & 7/3 & 7/6 \\ -11/6 & 7/6 & 17/3 \end{bmatrix} = \begin{bmatrix} 12.5 & 0 \\ 0 & -3.5 \end{bmatrix}$$



CANNOT BE CONFIGURED
TO MATCH DISTANCES

CANNOT BE NEGATIVE IF EUCLIDEAN

HANDLING NEGATIVE EIGENVALUES

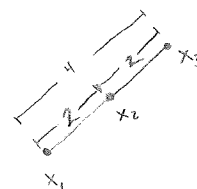
Option 1: ADD A SUITABLE CONSTANT TO DISSIMILARITIES

$$D_{rr} = 0$$

$$D_{rs} \rightarrow D_{rs} + c \rightarrow A \rightarrow B \rightarrow \lambda_1 > \lambda_2 > \dots > \lambda_k > 0$$

In previous example, $D' = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & 1 \\ 3 & 1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

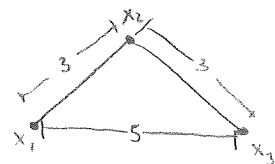
$$= \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 2 \\ 4 & 2 & 0 \end{bmatrix}$$



EXACT
* CAN FIND MDS w/ $k=1$! *

$$D'' = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & 1 \\ 3 & 1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 2 & 2 \\ 2 & 0 & 2 \\ 2 & 2 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 3 & 5 \\ 3 & 0 & 3 \\ 5 & 3 & 0 \end{bmatrix}$$



EXACT
* CAN FIND MDS w/ $k=2$!

Option 2: IGNORE < 0 EIGENVALUES, IF

$$\lambda_1 > \dots > \lambda_{k_0} > 0 > \lambda_{k_0+1} > \dots > \lambda_p$$

THEN TAKE $k \leq k_0$

(SUITABLE WHEN $\lambda_{k_0}, \dots, \lambda_p \approx 0$)

DUALITY OF CLASSICAL SCALING AND PCA USING EUCLIDEAN NORM

SUPPOSE WE ARE GIVEN $\vec{x}_1, \dots, \vec{x}_n \in \mathbb{R}^p$, AND ASKED TO FIND
A CLASSICAL SOLUTION TO MDS PROBLEM

$$\begin{array}{ccccc}
 \vec{x}_1, \dots, \vec{x}_n & \mapsto & D & \mapsto & A \mapsto B \\
 & & \text{OR} & & \updownarrow \\
 X = \begin{bmatrix} \vec{x}_1^T \\ \vdots \\ \vec{x}_n^T \end{bmatrix} & \xrightarrow{\quad\quad\quad} & B = (HX)(HX)^T & & \\
 & & HX = \begin{bmatrix} \vec{x}_1^T - \bar{x}^T \\ \vdots \\ \vec{x}_n^T - \bar{x}^T \end{bmatrix} & &
 \end{array}$$

Now, $\text{RANK}(B) = \text{RANK}(HX) = p$

$\Rightarrow B$ HAS $\underbrace{p \text{ NON-NEGATIVE EIGENVALUES}}_{=0}$

SQUARES OF SINGULAR VALUES
OF HX

p NON-NEGATIVE EIGENVALUES

OF $(X^T H^T H X) = X^T H X = n \sum x \quad (H^2 = H)$

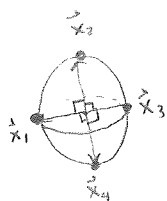
THM: THE MDS COORDINATES OF X IN k DIMENSIONS ARE
GIVEN BY THE FIRST k PRINCIPAL COMPONENT SCORES

* CHOOSING A SUITABLY SMALL CHOICE OF k IN CLASSICAL
MDS IS EQUIVALENT TO CHOOSING A SUITABLY SMALL
 k IN PCA

* CLASSICAL MDS AT DIMENSION k INHERITS ALL OF THE PROPERTIES
OF PCA AT RANK k ; e.g. BEST RANK k APPROX. UNDER FROBENIUS NORM!

Ex: GLOBAL AIRLINE DISTANCES. SEE CANVAS > FILES > NUMERICAL EXAMPLES

Ex: LET \vec{x}_1, \vec{x}_3 BE TWO POINTS ON EQUATOR ON OPPOSITE SIDES OF A SPHERE IN \mathbb{R}^3 w/ RADIUS $\frac{2}{\pi}$. LET \vec{x}_2, \vec{x}_4 BE ON THE NORTH AND SOUTH POLE RESPECTIVELY. LET D_{rs}



BE THE LENGTH OF THE SHORTEST PATH FROM \vec{x}_r TO \vec{x}_s ALONG THE SURFACE OF THE SPHERE (GEODESICS)

$$D = \begin{bmatrix} 0 & 1 & 2 & 1 \\ 1 & 0 & 1 & 2 \\ 2 & 1 & 0 & 1 \\ 1 & 2 & 1 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & -1/2 & -2 & -1/2 \\ -1/2 & 0 & -1/2 & -2 \\ -2 & -1/2 & 0 & -1/2 \\ -1/2 & -2 & -1/2 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 3/4 & 1/4 & -5/4 & 1/4 \\ 1/4 & 3/4 & 1/4 & -5/4 \\ -5/4 & 1/4 & 3/4 & 1/4 \\ 1/4 & -5/4 & 1/4 & 3/4 \end{bmatrix}$$

* IF EUCLIDEAN $\frac{\vec{x}_r^T \vec{x}_s}{\|\vec{x}_r\| \cdot \|\vec{x}_s\|} = \cos(\theta_{rs}) = \frac{B_{rs}}{(\frac{2}{\pi})^2}$

ANGLE BETWEEN \vec{x}_r, \vec{x}_s

$$\frac{B_{12}}{(\frac{2}{\pi})^2} = \frac{\pi^2}{16} \Rightarrow \theta_{12} = \cos^{-1}\left(\frac{\pi^2}{16}\right) \neq \frac{\pi}{2}$$

DISTANCE SCALING

* GIVEN DISSIMILARITIES, δ_{ij} $1 \leq i < j \leq N$, CLASSICAL SCALING SOUGHT A CONFIGURATION $\vec{y}_1, \dots, \vec{y}_N \in \mathbb{R}^t$ ($t=1,2,3$ USUALLY) S.T.

$$\|\vec{y}_i - \vec{y}_j\| = d_{ij} \approx \delta_{ij} \quad (\text{VIEWED DISSIMILARITIES AS DISTANCES})$$

IN DISTANCE SCALING, WE SEEK A CONFIGURATION

$$d_{ij} = f(\delta_{ij})$$

MONOTONIC, INCREASING FUNCTION
"MAPPING DISSIMILARITIES TO DISTANCES"

| METRIC DISTANCE SCALING / METRIC MDS | NON-METRIC DISTANCE SCALING / NON-METRIC MDS |
|--|---|
| <ul style="list-style-type: none"> DISSIMILARITIES ARE QUANTITATIVE e.g. (EUCLIDEAN) DISTANCES BETWEEN POINTS GOAL IS TO PRESERVE "DISTANCES" $f(\delta_{ij}) \approx d_{ij}$ | <ul style="list-style-type: none"> DISSIMILARITIES ARE ORDINAL e.g. RATING SCALES GOAL IS TO PRESERVE RANK ORDER $\delta_{ij} < \delta_{kl} \Rightarrow f(\delta_{ij}) \leq f(\delta_{kl})$ $1 \leq i, j, k, l \leq N$ |

METRIC MDS

• δ_{ij} ARE QUANTITATIVE MEASUREMENTS USING (EUCLIDEAN) DISTANCE METRICS. ALTERNATIVE METRICS INCLUDE MINKOWSKI

$$\delta_{ij} = \left(\sum_k (x_{ik} - x_{jk})^p \right)^{1/p} \quad p \geq 1.$$

• f IS USUALLY TAKEN TO BE A PARAMETRIC, MONOTONE FUNCTION SUCH AS

$$f(\delta_{ij}) = \alpha + \beta \delta_{ij}^p, \quad \alpha, \beta \geq 0 \text{ UNKNOWN}$$

ABSOLUTE MDS ($\alpha=0, \beta=1$)

RATIO MDS ($\alpha=0, \beta>0$)

INTERNAL MDS ($\alpha>0, \beta>0$)

← IZENMAN "NOT VERY USEFUL IN PRACTICE"

IF δ_{ij} ARE EUCLIDEAN THIS IS EQUIVALENT TO CLASSICAL SCALING

METRIC (LEAST-SQUARES) MDS OR KRUSKAL-SHEPARD SCALING

- GIVEN A PARAMETRIC FUNCTION FOR f , AND A CONFIGURATION $\vec{y}_1, \dots, \vec{y}_N \in \mathbb{R}^p$ w/ DISTANCE $d_{ij} = \|\vec{y}_i - \vec{y}_j\|$, THEN $\{d_{ij}\}$ CAN BE FIT TO $\{f(\delta_{ij})\}$ THROUGH LEAST SQUARES BY MINIMIZING

METRIC STRESS FUNCTION $\rightarrow \text{STRESS}(\vec{y}_1, \dots, \vec{y}_N, W) = \sqrt{\sum_{i < j} w_{ij} (d_{ij} - f(\delta_{ij}))^2}$

WHERE $W = (w_{ij}) \succeq 0$ IS A GIVEN MATRIX OF WEIGHTS.

CHOOSING WEIGHTS

- Q: SUPPOSE $w_{ij} \succeq 0$ ARE FIXED AND $f(\delta_{ij}) = \alpha + \beta \delta_{ij}$ w/ $\alpha, \beta \succeq 0$ FREE PARAMETERS. WHAT IS MINIMUM OF $\text{STRESS}(\alpha, \beta, \vec{y}_1, \dots, \vec{y}_N, W)$?

A: SET $\alpha = \beta = 0$, $\vec{y}_1 = \dots = \vec{y}_N = \vec{0}$ SO $d_{ij} = 0 = f(\delta_{ij})$ THEN $\text{STRESS} = 0$, BUT NOT A MEANINGFUL REPRESENTATION

• SAMMONS (NONLINEAR) MAPPING

$$w_{ij} = \delta_{ij}^{-1} \left\{ \sum_{k \neq j} \delta_{kp} \right\}^{-1}, \quad f = \text{IDENTITY}$$

• KRUSKAL'S (STRESS-1) FORMULA

$$w_{ij} = \left\{ \sum_{k \neq j} d_{kp}^2 \right\}^{-1}, \quad \text{COMMONLY USED IN NONMETRIC SCALING}$$

- AND MANY OTHERS (SEE REFERENCE TEXT FOR ADDITIONAL DETAILS)

Ex: SAMMON v CLASSICAL IN GLOBAL CITIES

Ex. SAMMON v CLASSICAL IN MIXTURE OF GAUSSIANS IN \mathbb{R}^2

* SEE CANVAS > FILES > NUMERICAL EXAMPLES > MDS

OBSERVATIONS

- SAMMON MAPPING

$$w_{ij} = \underbrace{\delta_{ij}^{-1}}_{\text{LOCAL NORMALIZATION}} \underbrace{\left\{ \sum_{k \neq j} \delta_{kp} \right\}^{-1}}_{\text{GLOBAL NORMALIZATION}}$$

- IF $\delta_{ij} \ll \delta_{kp} \Rightarrow w_{ij} \gg w_{kp}$

- GIVES GREATER IMPORTANCE TO LESS DISSIMILAR (MORE SIMILAR) PAIRS

- CAN BE USEFUL FOR IDENTIFYING CLUSTERS IN DATA

- $f = \text{IDENTITY} \Rightarrow$ CONFIGURATION $\vec{y}_1, \dots, \vec{y}_n$ FOUND BY GRADIENT DESCENT

METRIC MDS IN PRACTICE

- 1) FIX THE NUMBER OF DIMENSIONS t AND CHOOSE AN INITIAL CONFIGURATION OF POINTS (OFTEN THE CLASSICAL MDS SCALING) AND FUNCTION (PARAMETERS) FOR f
- 2) COMPUTE d_{ij} AND INITIAL STRESS
- 3) CHANGE THE CONFIGURATION $\vec{y}_1, \dots, \vec{y}_n$ THROUGH GRADIENT DESCENT OR PSEUDO-NEWTON ITERATIVE ROOT FINDER (SAMMON MAPPING)
- 4) UPDATE (PARAMETERS) f (OPTIONAL)
- 5) REPEAT 3 : 4 UNTIL CONVERGENCE
- 6) REPEAT (1) - (5) FOR VARIOUS t AND COMPARE STRESS v. t .

NONMETRIC MDS

- SEEKS TO MAINTAIN RANK ORDER OF DISSIMILARITIES
- SEE RELEVANT TEXT FOR DETAILS

Ex: COLOR CIRCLE

* SEE CANVAS > FILES > NUMERICAL EXAMPLES > MDS

PARTING THOUGHTS

- CLASSICAL SCALING APPLIED TO DATA AND EUCLIDEAN DISTANCES. "=" PCA
- (NON) METRIC MDS FOCUSES ON MINIMIZING STRESS
 - STRESS = "DEFORMATION" OF DISTANCE IN LOWER DIMENSIONAL REPRESENTATION
 - MANY DIFFERENT FORMS FOR STRESS WHICH PRIORITIZE DIFFERENT RELATIONSHIPS
 - SENSITIVITY TO CHOICE OF STRESS (MEASURE OF DISTANCE)
 - RELIANCE ON NUMERICAL METHODS FOR MINIMIZATION (CAN BE SLOW WHEN N IS LARGE)
 - HOW DOES ONE CHOOSE A MEANINGFUL MEASURE OF DISSIMILARITY / DISTANCE ?