

STAT 185 - Problem Set #6

November 19, 2019

Instructions

This assignment covers nonlinear manifold learning (ISOMAP and LLE) and the Johnson-Lindenstrauss Lemma through a mixture of theory and coding. You will need the file *pset6.Rdata* available on Canvas. The commands for loading the data assume this file, *pset6.Rmd*, and the Rdata file are in the same folder.

You can use the command `out<-embed(data, "Isomap", ndim = d, knn = k, get_geod = TRUE)` to compute the d dimensional representation of a data matrix *data* using the ISOMAP algorithm with k -nearest neighbors. The d -dimensional representation of the data is stored in `out@data@data` and the estimated geodesic distances are stored in `out@other.data$geod`.

You can use the command `out<-embed(data, "LLE", ndim = d, knn = k)` to compute the d dimensional representation of a data matrix *data* using the LLE algorithm with k -nearest neighbors. The d -dimensional representation of the data is stored in `out@data@data`.

You can add the option `.mute = c("message", "output")` to each call of *embed* to suppress the messages.

Complete the following questions and submit your solutions as a *pdf* via Canvas by 11:59 PM on Tuesday November 19th.

Problems

1. The variable *faces* contains 33 images (112×92 pixels) of a person taken at different angles. The data were obtained (and modified slightly) from the [github repository](#) maintained by Yuan Yao. Three images are shown below.



- a. Compute a one-dimensional representation of the faces using ISOMAP with $k = 3$ nearest neighbors. Plot the first 32 images (ordered from the lowest 1-dimensional coordinate to the largest 1-dimensional coordinate) in an 8×4 grid. What feature of the images is the ISOMAP embedding capturing?
 - b. Repeat part a, using LLE.
 - c. The original ordering of the images (1 = face-forward, 33 = profile) is stored in the variable *faces.order*. Compare the ordering given by ISOMAP and LLE with the true ordering of the images.
2. The variable *digits* contains 28×28 pixel images (saved as 784-dimensional vectors) in the array *digits\$pixels* and their associated labels *digits\$labels*.
 - a. Extract the first 1000-ones from the handwritten digits and the first 1000-sevens from the *digits* data and combine into a single data matrix. Generate a two-dimensional representation of the data saved in this new data matrix using ISOMAP with $k = 10, 50, 100, 500$ nearest neighbors. Show the two-dimensional configurations with the points corresponding to ones colored in blue

and the points corresponding to sevens colored in red. Which choice of k nearest neighbors shows the best separation between the ones and sevens?

- b. Repeat part a using LLE.
 - c. Repeat parts a and b using the first 1000-fours and 1000-nines. How does the performance compare to the results for a/b.
 - d. Discuss the different performance for the choice of algorithm and number of nearest neighbors. In particular, discuss the different performance between the 1/7 and 4/9 studies.
3. Extract the first 1000-twos from the *digits* images.
 - a. Generate a two-dimensional representation of the subset of twos using ISOMAP. Discuss your choice of k -nearest neighbors. Plot the two-dimensional configuration.
 - b. Show the images of the four handwritten twos from the most extremal points (left-most, rightmost, upmost, downmost) of the two-dimensional embedding. Do the horizontal and vertical axes appear to have any association with features of the twos?
 4. The swiss roll can be generated by mapping the rectangle

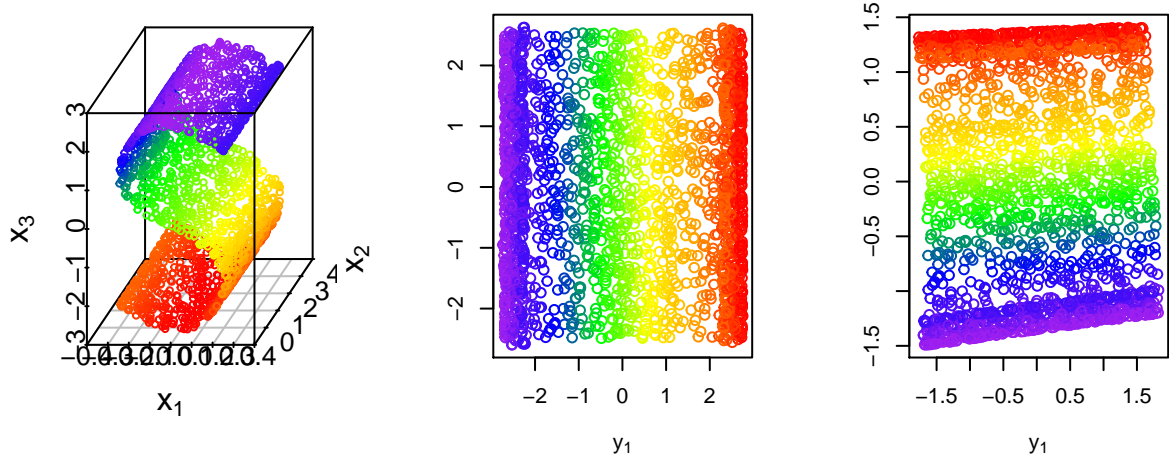
$$\left[\frac{3\pi}{2}, \frac{9\pi}{2} \right] \times [0, 15] \subset \mathbb{R}^2$$

to \mathbb{R}^3 through the map

$$\psi : \mathbb{R}^2 \mapsto \mathbb{R}^3, \quad \psi((s, t)) = (s \cos(s), s \sin(s), t)^T$$

The points $\vec{x}_1 = (0, -3\pi/2, 0)$ and $\vec{x}_2 = (8\pi, 0, 15)$ are points on the swiss roll.

- a. Estimate the geodesic distance from \vec{x}_1 to \vec{x}_2 . Explain your work.
 - b. (BONUS) Compute the geodesic distance between these points analytically.
5. In this problem, we will investigate the effect of noise on the performance of ISOMAP and LLE. The variable *S\$points* contains 2000 samples from a S-shaped sheet in \mathbb{R}^3 . To assist with plotting, associated colors for each point are stored in the variable *S\$colors*. For reference, the manifold is shown below with two-dimensional ISOMAP and LLE representations obtained using $k = 50$ nearest neighbors.



- a. Add independent $N(0, 1)$ noise to each entry of *S\$points*. Generate a two-dimensional representation of the data using ISOMAP with $k = 5$ nearest neighbors. Repeat with $N(0, 1/4)$ and $N(0, 1/10)$ noise.
- b. Repeat part a using LLE.
- c. Repeat parts a and b with $k = 50$ nearest neighbors.

- d. Discuss the performance of each algorithm for $k = 5, 50$ nearest neighbors and each value of the noise.
6. In this problem, we are going to compare some of the features of the Johnson-Lindenstrauss Theorem (after some probability).
- a. Consider a matrix $U \in \mathbb{R}^{54,613 \times 54,613}$ with independent $N(0, 1)$ entries. Find $E[UU^T]$.
- b. Let U be as in part a. Find an upper bound on

$$P(\|U\|_F \geq a)$$

where $\|U\|_F = \sqrt{\sum_{jk} U_{jk}^2}$ is the Frobenius norm.

- c. The variable `sun$X` contains 180 observations of random vectors in \mathbb{R}^{54613} . Each vector corresponds to the expression level of 54,613 genes in one of 180 cells (157 Glioma, 23 nontumor) in the experiments from [Sun et al 2006](#). These data were obtained from the github repository [datamicroarray](#). Suppose we map the gene expression vectors to k dimensional space using the first k columns of U , i.e.

$$f : \mathbb{R}^{54613} \mapsto \mathbb{R}^k, \quad f(\vec{x}) = U_k^T \vec{x}, \quad U_k = [\vec{u}_1, \dots, \vec{u}_k] \in \mathbb{R}^{54613 \times k}.$$

Here U is as in part a. Compare all of the pairwise Euclidean distances in the original data with the pairwise Euclidean distances after applying the random map for $k = 50, 100, 500, 1000$. Note, memory restrictions will likely prevent you from generating $U \in \mathbb{R}^{54613 \times 54613}$ but you should be able to generate U_{1000} then use its first 50, 100, 500 columns for U_{50} , U_{100} , and U_{500} respectively.

- i. Plot the original distances on the horizontal axis and the k -dimensional distances on the y axis.
- ii. For each k , generate histograms of the relative error between $\|\vec{x}_i - \vec{x}_j\|$ and $\|U_k^T \vec{x}_i - U_k^T \vec{x}_j\|/\sqrt{k}$ for $1 \leq i < j \leq 180$.
- d. From Johnson-Lindenstrauss, how large must k be so that the relative error between $\|\vec{x}_i - \vec{x}_j\|$ and $\|U_k^T \vec{x}_i - U_k^T \vec{x}_j\|/\sqrt{k}$ is no more than 20% for all $1 \leq i < j \leq 180$ with probability at least 99%?