

# Homework3

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## 5.3

Busy waiting: While a process is in its critical section, any other process that tries to enter its critical section must loop continuously.

Other kind of waiting: a process could block itself, be put in a wait queue and be awakened in the future.

Busy waiting can be avoided, but it requires overhead of putting a process in into a wait queue and waking it up again.

## 5.4

In a single-processor system, a single cpu is shared among many processes. Busy waiting of spinlock wastes CPU cycles that some other process might be able to use productively.

In a multiprocessor system, one thread can “spin” on one processor while another thread performs its CS on another processor.

## 5.10

If a user-level could disable interrupts, it can block all other processes if there is only one processor.

## 5.11

Disabling Interrupts on the processor could not influence processes executed on other processors. So it can not guarantee mutex.

On the other hand, disabling interrupts on every processor can be a difficult task and seriously diminish performance.

## 5.23

```
Int gate = 0; // global shared
```

```
Typedef struct{  
    Int value; //available num  
    Struct process *waiting_queue;  
} semaphore
```

```
Wait(semaphore *s){  
    While(test_and_set(&gate)); //only the first process getting here,  
                                   //or when other process get a semaphore,  
                                   // a process could enter  
  
    If(s->value <= 0){  
        Add this process to s->waiting queue;  
        Block();  
    }else{  
        S->value --;  
        gate = 0; //this process leaves wait, let others getting through the gate  
    }  
}
```

```
Signal(){  
    While(test_and_set(&gate)); // same reason as in wait()  
    If(s->value <= 0 && not_empty(s->waiting_queue)){  
        Wakeup(S->waiting_queue.remove());  
    }  
    Else{  
        s->value ++;  
        gate = 0;  
    }  
}
```

## 5.28

Throughput is increased by allowing multiple reading processes and only one writing process: A process wishing to modify the shared data must request the lock in write mode. Multiple processes are permitted to concurrently acquire a reader-writer lock in read mode, but only one process may acquire the lock for writing, as exclusive access is required for writers.

This approach could cause writer starving.

Solution: 1. Avoid keep letting new readers go into CS: when a new reader comes when several readers are in CS and a writer is waiting, block the new reader until waiting writer finishes.

2.keeping track of the waiting time of every process.

When several readers finish or a writer finish, give access to the process has waited for the longest time.

## 5.29

The signal() operation in monitor resumes exactly one suspended process. If no process is suspended, then the signal() operation has no effect; that is, the state of x is the same as if the operation had never been executed. Contrast this operation with the signal() operation associated with semaphores, which always affects the state of the semaphore(++ operation of the semaphore value).

## 5.32

A file is to be shared among different processes, each of which has a unique number. The file can be accessed simultaneously by several processes, subject to the following constraint: the sum of all unique numbers associated with all the processes currently accessing the file must be less than n. Write a monitor to coordinate access to the file.

```
Monitor fileAllocator{
    Int sum;
    Static int limit;
    Condition x;
    Void accessFile(int process_num){
        While(sum + process_num >= limit)
            x.wait();
        sum += process_num;
    }
    Void release(int process_num){
        Sum -= process_num;
        c.signal();
    }
    Initialization(){
        Sum = 0;
        Limit = n;
    }
}
```

## 5.37

- available\_resources
- available\_resource -= count and available\_resources += count (because -= and += are not atomic op)
- use semaphore with initialized value of MAX\_RESOURCES. All Ops on -= or += are modified to use semaphore.

## 6.2

Under nonpreemptive scheduling, once the CPU has been allocated to a process, the process keeps the CPU until it releases the CPU either by terminating or by switching to the waiting state.

Otherwise, if scheduling also takes place on:

- When a process switches from the running state to the ready state (for example, when an interrupt occurs)
- or
- When a process switches from the waiting state to the ready state (for example, at completion of I/O)

It is preemptive.

## 6.3



$$\text{Average turnaround time} = \frac{(8-0) + (12-0.4) + (13-1.0)}{3} = 10.53$$

B: nonpreemptive SJF

Timeline: 0 | P<sub>1</sub> | 8 | P<sub>3</sub> | 9 | P<sub>2</sub> | 13

$$\frac{(8-0) + (9-1) + (13-0.4)}{3} = 9.53$$

C:

$$\begin{array}{c}
 \begin{array}{ccccccc}
 0 & 1 & 2 & 6 & & & 14 \\
 | & | & | & | & & | & | \\
 P_3 & P_2 & & P_1 & & & 
 \end{array} \\
 \hline
 \frac{(2-1) + (6-2) + (14-6)}{3} = 6.87
 \end{array}$$

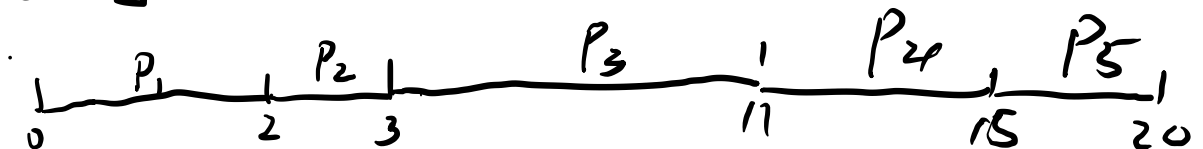
## 6.11

- a. More context switch could decrease response time (like preemptive SJF, RR) but at the same time will require overhead, thus CPU utilization is decreased.
- b. average turnaround could be decreased by using preemptive SJF with the risk of making long burst process waiting forever in a heavily-loaded system.

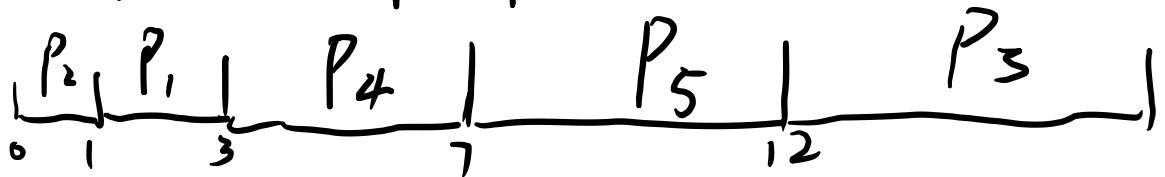
## 6.16

A:

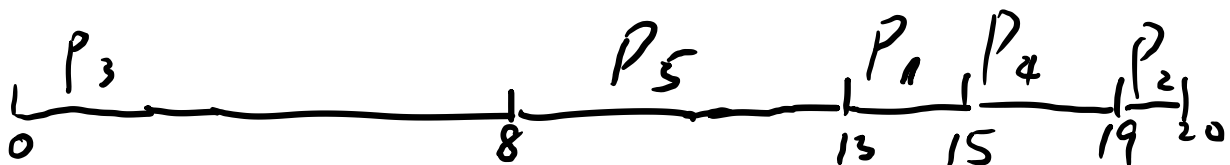
FCFS:



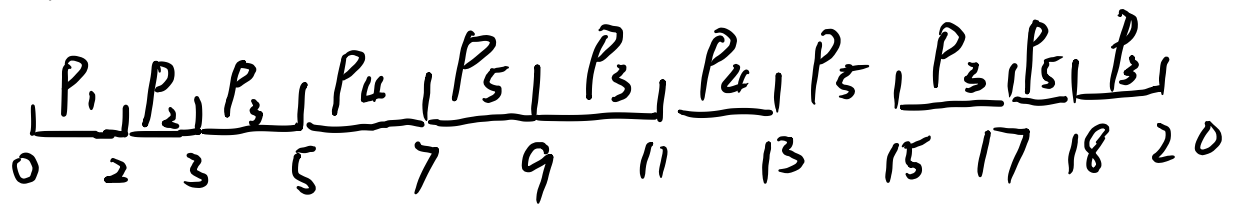
SJF (assume nonpreemptive)



nonpreemptive priority



RR :



B:

	P1	P2	P3	P4	P5
FCFS	2	3	11	15	20
SJF	3	1	20	7	12
NonPrio	15	20	8	19	13
RR	2	3	20	13	18

C:

	P1	P2	P3	P4	P5
FCFS	0	2	3	11	15
SJF	1	0	12	3	7
NonPrio	13	19	0	15	8
RR	0	2	$3+4+4+1 = 12$	$5+4=9$	$7+4+2=13$

D:

SJF has the minimum one.

## 6.24

FCFS:

First come first serve means if short jobs arrive after long jobs, they will have long waiting time.

RR:

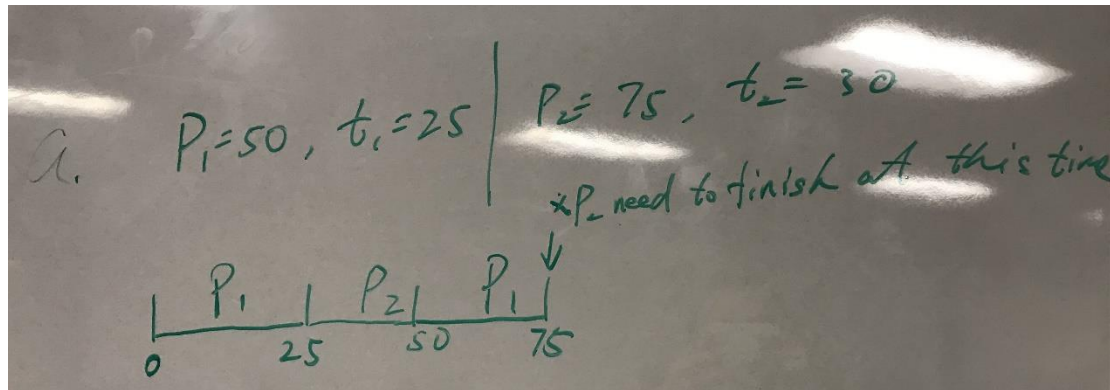
Every job has the same quantum time. So short jobs finish first with the assumption that the quantum is not too large.

Multilevel:

Similar to RR, put different jobs to different queue, but has mechanisms of promoting or degrading jobs

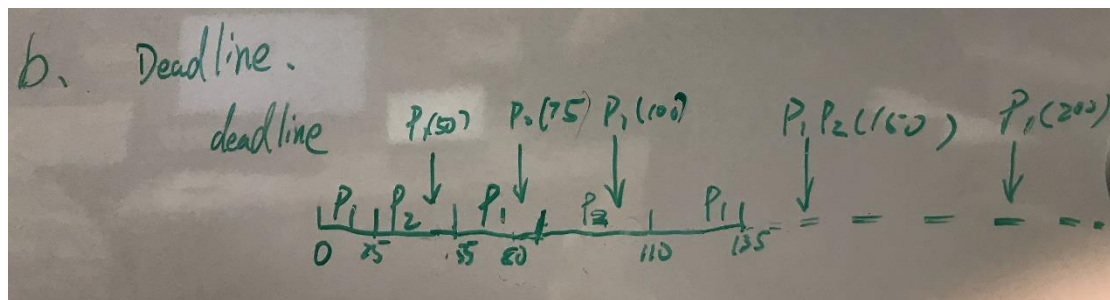
## 6.31

a. These two processes can't be scheduled using rate-monotonic. As it is shown in the graph, when  $p_1$  finishes at 75,  $p_2$  passes its deadline.



b.

As it is shown in the graph, the deadlines are  $p_1(50), p_2(75), p_1(100), p_1 \& p_2(150), p_1(200) \dots$ . This is also the order they are executed.



## Virtual Box Guest Additions

