

A hyperparameter selection for image classification performance

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Abstract

This report provides experiments and discussions on four different machine learning models (KNN, SVM, Decision Tree, Random Forest) in image classification tasks on CIFAR-10 dataset.

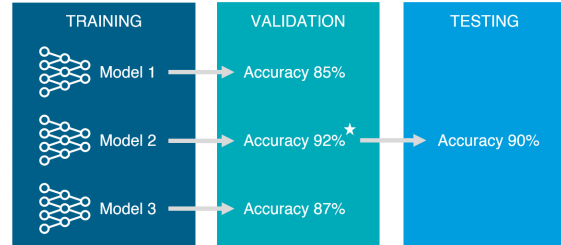


Figure 1. Validation on a separate validation dataset

1. Introduction

1.1. Image Classification

Image classification is a supervised learning problem. In this problem, datasets contain images and labels that are objects to identify in images. Machine learning models are trained to learn features of such images and after training, models can distinguish different image labels by predicting most probable labels from the test datasets.

It is well known that deep learning models such as convolutional neural networks can extract features from images well, but machine learning models still can learn features to predict image labels. Therefore, in this report, image classification tasks will be conducted with four different machine learning algorithms.

1.2. Hyperparameter Selection in Machine Learning Performance

Hyperparameters are parameters that users define to give machine learning models diverse variations. Hyperparameter optimization is one of main challenges in the field of machine learning. This is because it affects performance greatly.

One of the most common method of finding the best set of hyperparameters is to search for every possible combinations of hyperparameters by specifying certain ranges. Also, cross-validation makes hyperparameter search more reliable when training data is not sufficient. Therefore, in this paper, the best set of hyperparameters will be compared with cross-validation and validation on a separate validation set.

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1.3. Problem Definition

In this report, experiments aim to find the best model and optimal set of hyperparameters that gives the best performance. Hyperparameters are examined by searching all possible combinations within the ranges for each parameter. Performances are measured by accuracy, which tells the percentage of all samples predicted correctly.

2. Experiments

All submissions must follow the specified format.

2.1. Data Description

CIFAR-10 dataset consists of 60000 32x32 color images in 10 classes. There are 50000 training images and 10000 test images. Examples of classes include whale, bed, chair, bee, bus, tank, etc.

2.2. Hyperparameter Selection Strategies

In this paper, two strategies are used to find the optimal set of hyperparameters.

First strategy is to use a separate validation dataset to validate trained model. In this case, models are trained with training dataset with a set of hyperparameters. Then, trained models are evaluated by validation dataset. Optimal hyperparameters are determined to be the ones that have the highest accuracies when testing by validation data. Figure [1]

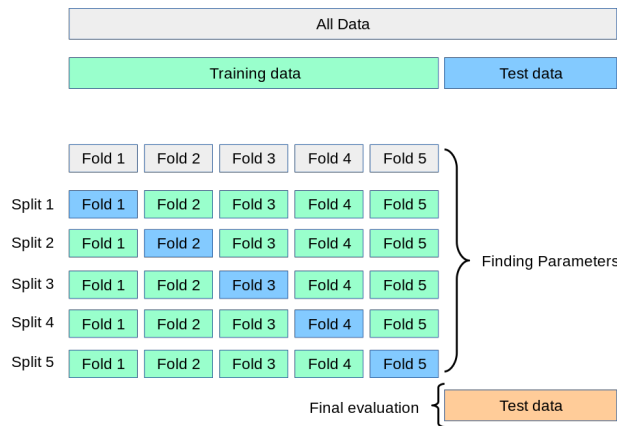


Figure 2. 5-fold Cross-validation

Second strategy is to perform k-fold cross validation. In this case, training dataset is divided into k-folds and the models are trained k times. At each iteration of k times, models are trained with training data without one fold out of k-folds that is selected to be validation set. After k iterations, the model's validation performances are averaged to get the final validation performance. Optimal hyperparameters are determined to be the ones that have the highest average accuracy. Figure [2]

In both of two cases, the optimal hyperparameters are finally used for a final test with a test dataset to get an actual performance.

2.3. Machine Learning Models

2.3.1. RUNTIME AND ACCURACY

To see how runtime and accuracy change according to the number of training dataset, models are trained with different number of data. In this experiment, wandb.ai is used for tracking runtime and accuracy. In Figure [3], the range of train dataset and hyperparameters used are specified for each models.

It is expected that accuracies go up as the number of train data grows. However, in results in [Figure 4-6], the unlikely cases happened at some models where the accuracies go down at larger number of train data. This is because the range of the number of train data was too small due to the resource and time limit. It seems that if the range was wider with larger numbers of train data, accuracies would be going up as the number of train data grows.

2.3.2. HYPERPARAMETER SELECTION

To find the best set of hyperparameters, different kinds of hyperparameters are searched for each models. Parameters used and their ranges are specified in Figure [7]. In the

figure, numbers of data for training, validation, testing are shown as well.

Optimal sets of hyperparameters found are listed with their test set accuracies are listed in Figure [8]. Methods in the figure indicates (1) Default: No hyperparameter searching was conducted (2) Validation: Hyperparameters are determined by validation on a separate validation set (3) Cross-validation: Hyperparameters are determined by cross-validation.

It was expected that hyperparameter sets found from cross-validation would have the highest test accuracies. However, in my results, hyperparameters did not change from default because not much of parameters were searched due to resource and time limit. For example, KNN and SVM models had to be trained with only 1000 train set and tree-based models had to be trained with only 500 train data.

Tree-based models have particularly low accuracies, which may have been caused by a small number of features used. In other words, when greedy searching to find the best feature and the best split thresholds in tree algorithms, only 10 features were searched to produce results in time.

If the experiments were conducted with sufficient amount of training dataset and sufficient range of hyperparameters to be searched, results would have been more reliable. For example, hyperparameters may have been very different from default parameters and hyperparameters selected from cross-validation would have had a lot higher accuracies because it brings a robust performance.

The visualization of hyperparameter combinations in [Figure 9-17, Appendix] shows some hyperparameters are better than the others. For example, KNN models worked better with L1 distance metric than the others. But the effect of varying the number of neighbors was negligible.

Non-linear SVM model shows that the key determinant of model performance is the value of gamma, where smaller values brought better accuracies.

Decision Tree shows a clear finding that minimum number of samples to split should be smaller. However, when using a large number of data and this parameter is too small, tree models can be overfitted. Therefore, a sufficient amount of train dataset and cross-validation could have found the optimal number for this parameter - small enough, but not too small to overfit.

3. Conclusion

In this report, four different machine learning models (KNN, SVM, Decision Tree, Random Forest) are conducted to perform image classification tasks. To find the best model, a range of hyperparameters are tested by greedy search. The

| Model | Train set range | Test set | Hyperparameters | Value |
|----------------|--------------------------|----------|--------------------------------|-------------|
| KNN | [1000, 2000, 3000, 4000] | 100 | N_neighbors Distance | 3 L1 |
| Linear SVM | [1000, 2000, 3000, 4000] | 100 | C | 1 |
| Non-linear SVM | [1000, 2000, 3000, 4000] | 100 | C Gamma | 1 0.2857 |
| Decision Tree | [1000, 1500, 2000] | 100 | Min_samples_split Max_depth | 100 3 |
| Random Forest | [500, 600, 700] | 50 | Min_samples_split Max_depth | 10 3 |

Figure 3. Train dataset range

results show that SVM model worked best with parameters $C=1$ for linear SVM model, and $C=30$ and $\text{Gamma}=0.0001$ for nonlinear SVM model.

However, the experiments were not fair for tree-based models because the number of train dataset was smaller than the other models due to the resource and time limit. Also, for all of algorithms, it would have been better if the search range was wider and a sufficient amount of data was used to train.

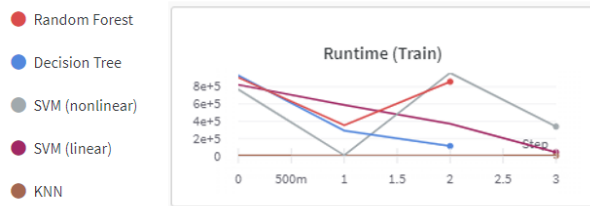


Figure 4. Runtime (train)

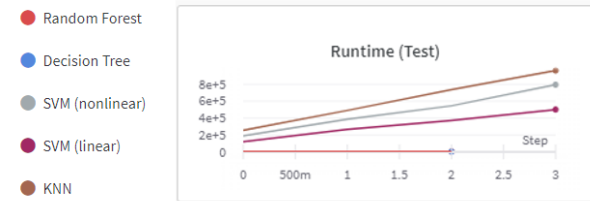


Figure 5. Runtime (test)

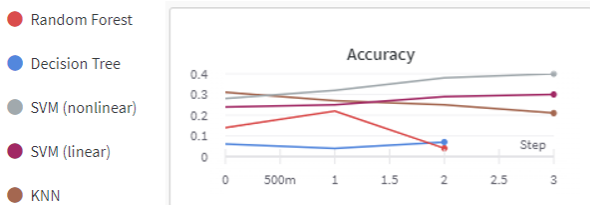


Figure 6. Accuracy

| Model | Hyperparameter | Range | Train set | Valid set | Test set |
|----------------|-------------------|-----------------------|-----------|-----------|----------|
| KNN | N_neighbors | [3, 5, 7] | 1000 | 100 | 100 |
| | Distance | [L1, L2, minkowski] | | | |
| Linear SVM | C | [10, 30, 100] | 1000 | 100 | 100 |
| Non-linear SVM | C | [10, 30, 100] | 1000 | 100 | 100 |
| | Gamma | [0.01, 0.001, 0.0001] | | | |
| Decision Tree | Min_samples_split | [100, 150] | 500 | 50 | 50 |
| | Max_depth | [2, 3] | | | |
| Random Forest | Min_samples_split | [100, 150] | 500 | 50 | 50 |
| | Max_depth | [2,3] | | | |

Figure 7. Hyperparameter search ranges

| Model | Method | N_neighbors | Distance | Test Acc |
|-------|------------------|-------------|----------|-------------|
| KNN | Default | 3 | L1 | 0.31 |
| | Validation | 3 | L1 | 0.16 |
| | Cross-validation | 3 | L1 | 0.16 |

| Model | Method | C | Test Acc |
|------------|------------------|---|-------------|
| Linear SVM | Default | 1 | 0.24 |
| | Validation | 1 | 0.33 |
| | Cross-validation | 1 | 0.33 |

| Model | Method | C | Gamma | Test Acc |
|----------------|------------------|-----|--------|-------------|
| Non-linear SVM | Default | 1 | 0.2857 | 0.28 |
| | Validation | 100 | 0.0001 | 0.31 |
| | Cross-validation | 30 | 0.0001 | 0.33 |

| Model | Method | Min_samples_split | Max_depth | Test Acc |
|---------------|------------------|-------------------|-----------|-------------|
| Decision Tree | Default | 100 | 3 | 0.06 |
| | Validation | 100 | 3 | 0.16 |
| | Cross-validation | 100 | 2 | 0.08 |

| Model | Method | Min_samples_split | Max_depth | Test Acc |
|---------------|------------------|-------------------|-----------|-------------|
| Random Forest | Default | 100 | 2 | 0.02 |
| | Validation | 100 | 2 | 0.08 |
| | Cross-validation | 100 | 2 | 0.12 |

Figure 8. Optimal hyperparameters

3. Appendix

Visualization of different hyperparameter sets and corresponding accuracies are shown in [Figure 9-18]

4. References

<https://www.cs.toronto.edu/~kriz/cifar.html>

Claesen, M., De Moor, B. (2015). Hyperparameter search in machine learning. arXiv preprint arXiv:1502.02127.

<https://developers.google.com/machine-learning/practica/image-classification?hl=ko>

https://www.tensorflow.org/datasets/catalog/fashion_mnist

<https://paperswithcode.com/dataset/caltech-256>

https://scikit-learn.org/stable/modules/cross_validation.html

<https://modern-manual.tistory.com/19>

Maximum Accuracy: 0.2000
Optimum n_neighbors: 3.000000
Optimum distance: 1.000000

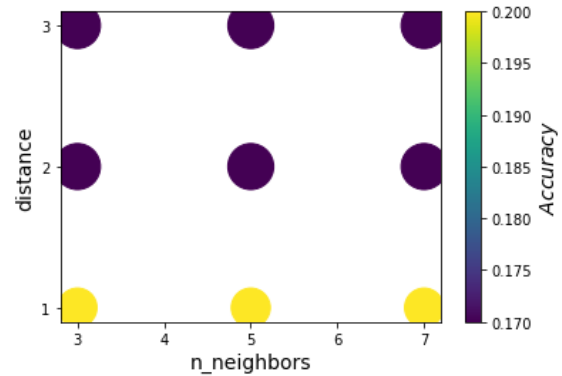


Figure 9. KNN with validation

Maximum Accuracy: 0.1920
Optimum n_neighbors: 3.000000
Optimum distance: 1.000000

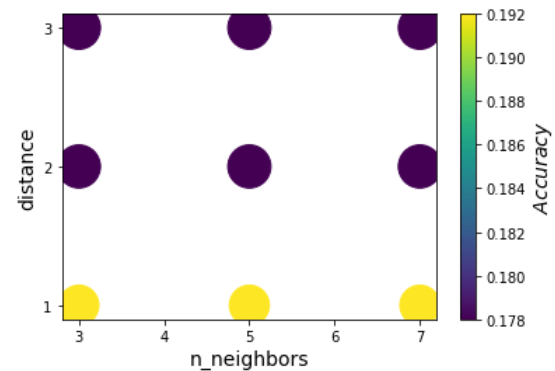


Figure 10. KNN with cross-validation

Maximum Accuracy: 0.2500
Optimum C: 1.000000
Optimum kernel: 1.000000

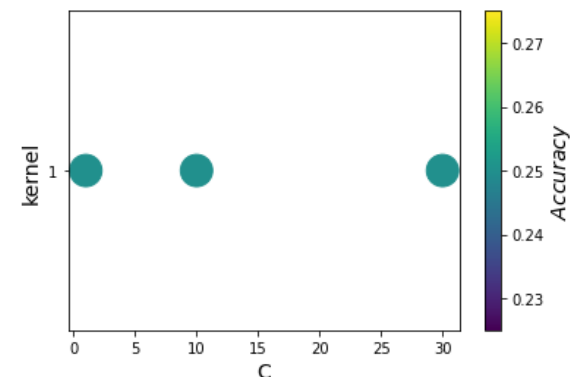


Figure 11. linear SVM with validation

Maximum Accuracy: 0.2360
 Optimum C: 1.000000
 Optimum kernel: 1.000000

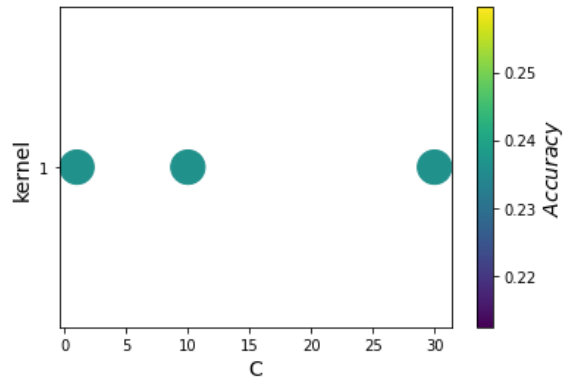


Figure 12. linear SVM with cross-validation

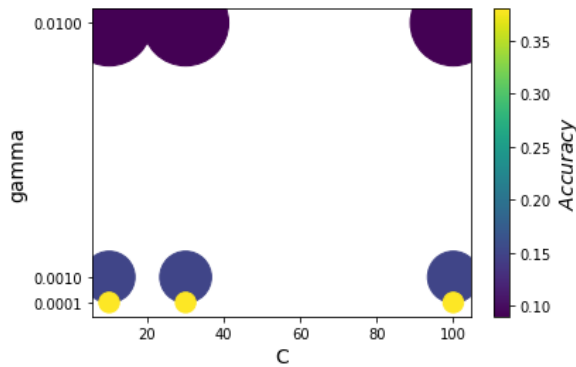


Figure 13. nonlinear SVM with validation

Maximum Accuracy: 0.2530
 Optimum C: 30.000000
 Optimum gamma: 0.000100

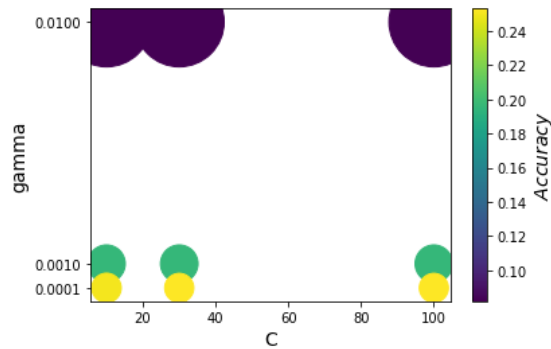


Figure 14. nonlinear SVM with cross-validation

Maximum Accuracy: 0.2000
 Optimum min_samples_split: 100.000000
 Optimum max_depth: 3.000000
 C:\Users\YOUNGBIN\AppData\Local\Temp\ipykernel_29620
 size_list=30/(size_list)**2

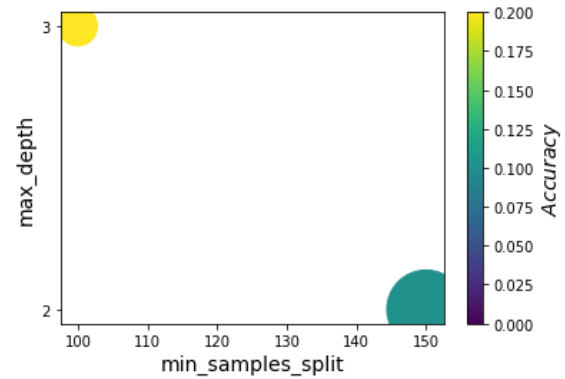


Figure 15. Decision Tree with validation

Maximum Accuracy: 0.1280
 Optimum min_samples_split: 100.000000
 Optimum max_depth: 2.000000

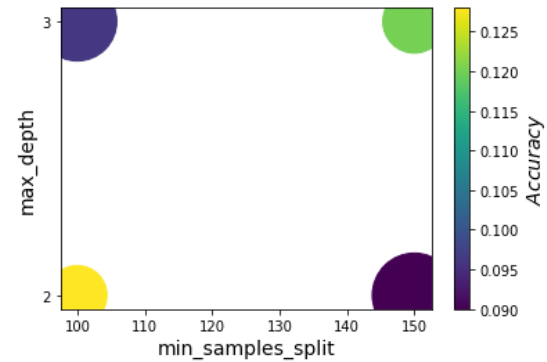


Figure 16. Decision Tree with cross-validation

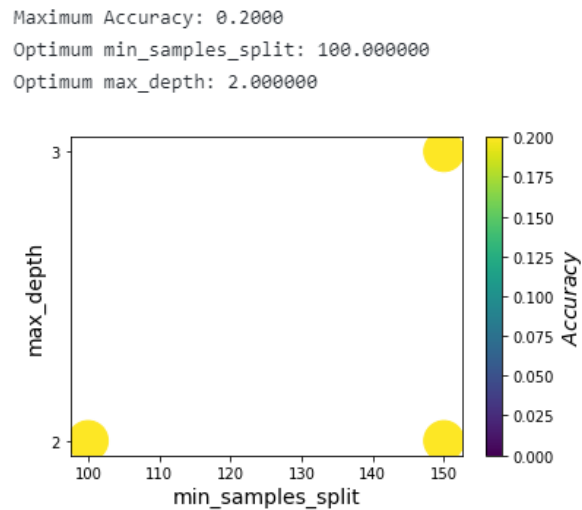


Figure 17. Random Forest with validation

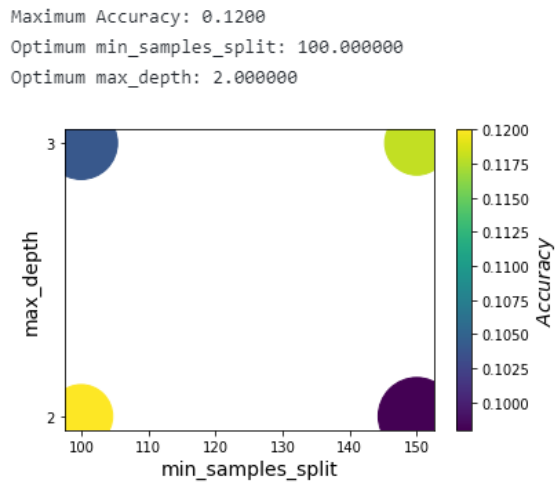


Figure 18. Random Forest with cross-validation