YOUNGIAE MIN

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https://youngjae-min.github.io

INTERESTS Perception, inference, learning, and control for safe and robust autonomous systems

EDUCATION Massachusetts Institute of Technology

Cambridge, MA

Master Student in Dept. of Aeronautics and Astronautics

From Sep. 2021

Korea Advanced Institute of Science and Technology

Daejeon, Korea

B.S. in Electrical Engineering and Mathematical Sciences (double major) Mar. 2014 - Feb. 2020* GPA: 4.1/4.3 (*summa cum laude*)

*Paused two years for military service

RESEARCH EXPERIENCE

Perception, Inference, Planning | PI: Prof. Han-Lim Choi

Feb. 2019 - Aug. 2021

Laboratory for Information and Control Systems, Dept. of Aerospace Eng., KAIST

- Proposed real-time capable 3-D dynamic occupancy mapping algorithm from LiDAR data [C1]
- Proposed path planning algorithm of mobile sensor networks with stochastic motion model under GPS-denied environments through combined Bayesian filters (PF and EKF) [C2]
- Proposed online learning of partially observable dynamical systems by applying variational inference methods on Gaussian process models [J1]
- Proposed non-myopic path planning algorithm of mobile sensors for multi-target tracking tasks by adopting distributive optimization algorithm, ADMM [J2]

Provable Neural Network Classifier | PI: Prof. Hye Won Chung

Mar. 2018 - Jan. 2019

Inference and Information for Data Science Lab, Sch. of Electrical Eng., KAIST

• Designed neural networks that provably classify any dataset following separable distribution with small margin [C3]

Vital Sign Monitoring | PI: Prof. Fadel Adib

June 2018 - Sep. 2018

Signal Kinetics Group, Media Lab, MIT

• Built real-time blood flow measurement system from scratch using mmWave radar technology

Indoor Localization | PI: Prof. Sung-Ju Lee

June 2017 - Feb. 2018

Networking & Mobile Systems Lab, Sch. of Computing, KAIST

o Estimated indoor person location through channel information from commodity Wi-Fi devices

PUBLICATIONS Conference Proceedings

1. Y. Min, D. Kim, H. Choi

"Kernel-Based 3-D Dynamic Occupancy Mapping with Particle Tracking" *IEEE International Conference on Robotics and Automation* (ICRA), Xi'an, China, June 2021

2. **Y. Min**, S. Park, H. Choi [arXiv: 1909.11046]

"Informative Planning of Mobile Sensor Networks in GPS-Denied Environments" *AIAA SciTech: Guidance, Navigation, and Control* (GN&C), Orlando, USA, Jan. 2020

3. **Y. Min** and H. W. Chung [arXiv: 1904.09109]

"Shallow Neural Network can Perfectly Classify an Object following Separable Probability Distribution," *IEEE International Symposium on Information Theory* (ISIT), Paris, France, July 2019

- 4. S. Kim, **Y. Min**, Y. H. Kim
 - "Measurements of sliding friction forces under ultrasonic oscillations: out-of-plane oscillations" IEEE International Ultrasonics Symposium (IUS), Chicago, USA, Sep. 2014
- G. Yun, K. Kim, Y. Roh, Y. Min, J. Lee, Y. H. Kim "Comparison of slowness curves of Lamb wave with elastic moduli and crystal structure in silicon wafers," IEEE International Ultrasonics Symposium (IUS), Prague, Czech Republic, July 2013

Journal Articles

- 1. S. Park, Y. Park, Y. Min, H. Choi [arXiv: 1903.08643] "Online Gaussian Process State-Space Model: Learning and Planning for Partially Observable Dynamical Systems," submitted to International Journal of Control, Automation and Systems
- 2. S. Park*, Y. Min*, J. Ha, D. Cho, H. Choi (*equally contributed) [arXiv: 1807.11068] "A Distributed ADMM Approach to Non-Myopic Path Planning for Multi-Target Tracking" IEEE Access, vol. 7, no. 1, pp. 163589-163603, Nov. 2019
- 3. **Y. Min**, G. Yun, K. Kim, Y. Roh, Y. H. Kim "Comparison of slowness profiles of Lamb wave with elastic moduli and crystal structure in single crystalline silicon wafers" Journal of the Korean Society for Nondestructive Testing, vol. 36, no. 1, pp. 1-8, Feb. 2016

2020 Global Lead	ership Award, <i>KAIST</i>		2020
KAIST Presidentia	al Fellowship, <i>KAIST</i>		2014 - 2020
Dean's List, Colleg	ge of Engineering, KAIST	g, KAIST Fall'14, Spring'15, Spring'17, Spring'19	
GE Foundation Scholar-Leaders Program, Fulbright / GE Foundation Undergraduate Student Scholarship, Korea Foundation for Advanced Studies		2015 - 2019	
		2015 - 2019	
Army Commendation Medal, United States Department of the Army 2017			
	•	KAIST	Spring'15, Spring'17 Aug. 2014 - July 2015
KAIST EE Newsletter, Reporter, KAIST		Mar. 2017 - Dec. 2017	
ROK Army & U.S. Army, IT Specialist (Sergeant, KATUSA), Cp. Carroll		July 2015 - Apr. 2017	
The Real LUNATI	C, B-Boy, <i>KAIST</i>		Mar. 2014 - July 2015
Programming	•		59/170)
	KAIST Presidentia Dean's List, Colleg GE Foundation So Undergraduate St Army Commenda PH141 General Ph KAIST Global Inst KAIST EE Newsler ROK Army & U.S. The Real LUNATIO	Undergraduate Student Scholarship, <i>Korea Foundation for Ad</i> Army Commendation Medal, <i>United States Department of the</i> PH141 General Physics I, Tutor, <i>KAIST</i> KAIST Global Institute for Talented Education, Online Tutor, <i>E</i> KAIST EE Newsletter, Reporter, <i>KAIST</i> ROK Army & U.S. Army, IT Specialist (Sergeant, KATUSA), <i>Cp.</i> The Real LUNATIC, B-Boy, <i>KAIST</i> Programming C/C++, Python, MATLAB, ROS, CUDA, Ten	KAIST Presidential Fellowship, <i>KAIST</i> Dean's List, <i>College of Engineering, KAIST</i> GE Foundation Scholar-Leaders Program, <i>Fulbright / GE Foundation</i> Undergraduate Student Scholarship, <i>Korea Foundation for Advanced Studies</i> Army Commendation Medal, <i>United States Department of the Army</i> PH141 General Physics I, Tutor, <i>KAIST</i> KAIST Global Institute for Talented Education, Online Tutor, <i>KAIST</i> KAIST EE Newsletter, Reporter, <i>KAIST</i> ROK Army & U.S. Army, IT Specialist (Sergeant, KATUSA), <i>Cp. Carroll</i> The Real LUNATIC, B-Boy, <i>KAIST</i> Programming C/C++, Python, MATLAB, ROS, CUDA, TensorFlow