

Acceleration in Rotating Frames

From before we had that the velocity of a particle relative to an inertial frame is $\vec{v} = \frac{d\vec{r}}{dt} = \dot{\vec{r}} + \vec{\omega} \times \vec{r}$

Apply this type of expression to acceleration

$$\vec{a} = \frac{d^2\vec{r}}{dt^2} = \dot{\vec{v}} + \vec{\omega} \times \vec{v}$$

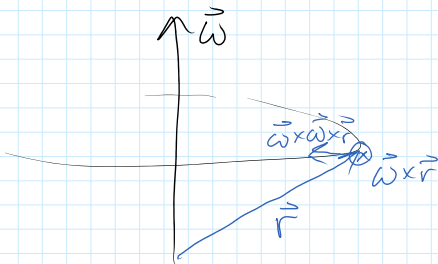
→ dot both sides of the \vec{v} eq'n: assume $\vec{\omega}$ is constant

$$\dot{\vec{v}} = \ddot{\vec{r}} + \dot{\vec{\omega}} \times \vec{r} + \vec{\omega} \times \dot{\vec{r}}$$

→ $\times \vec{\omega}$: $\vec{\omega} \times \vec{v} = \vec{\omega} \times \dot{\vec{r}} + \vec{\omega} \times (\vec{\omega} \times \vec{r})$

$$\therefore \vec{a} = \frac{d^2\vec{r}}{dt^2} = \ddot{\vec{r}} + 2\vec{\omega} \times \dot{\vec{r}} + \vec{\omega} \times (\vec{\omega} \times \vec{r})$$

The $2\vec{\omega} \times \dot{\vec{r}}$ term is the Coriolis acc'n; the $\vec{\omega} \times (\vec{\omega} \times \vec{r})$ term is the centripetal acceleration, directed towards the axis of rotation and is \perp to it. Note the Coriolis acc'n appears only when a particle moves in a rotating coordinate system.



In an inertial frame $\vec{F} = m\vec{a}$ where \vec{F} is the vector sum of all real forces acting on a particle (e.g. gravity)

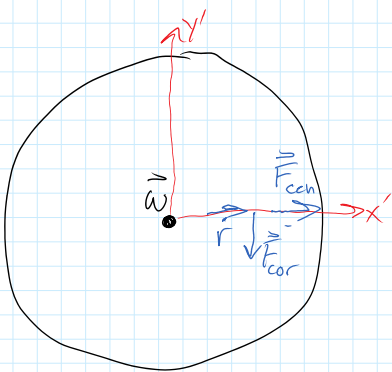
$$\therefore m\ddot{\vec{r}} + 2m\vec{\omega} \times \dot{\vec{r}} + m\vec{\omega} \times (\vec{\omega} \times \vec{r}) = \vec{F}$$

or $m\ddot{\vec{r}} = \vec{F} - 2m\vec{\omega} \times \dot{\vec{r}} - m\vec{\omega} \times (\vec{\omega} \times \vec{r})$

Therefore, an observer in the rotating frame would need to account for 2 apparent (or, fictitious) forces to describe the motion of a particle.

- The centrifugal force $-m\vec{\omega} \times (\vec{\omega} \times \vec{r})$ points away from the axis of rotation. Very familiar (taking a turn in a car)
- The Coriolis force $-2m\vec{\omega} \times \dot{\vec{r}}$. The 'merry-go-round' force. Always \perp to velocity vector in moving coord system. Appears to deflect a particle at right-angles to its direction of motion.
 - important force for computing trajectories in weather systems
 - responsible for circulation of storms, etc.

e.g. A bug crawling outward w/ a constant speed \dot{r} along the spoke of a wheel that is rotating w/ const. vel. $\vec{\omega}$ about a vertical axis. Find all apparent forces acting on the bug.



Consider the $x'y'$ plane on the wheel rotating at ω . Choose the axes so the bug is on the x' axis moving outwards.

$$\begin{aligned}\vec{r} &= x \hat{i}' \\ \dot{\vec{r}} &= \dot{r} \hat{i}' \\ \ddot{\vec{r}} &= 0 \\ \vec{\omega} &= \omega \hat{k}'\end{aligned}$$

So, the Coriolis force is $-2m\vec{\omega} \times \dot{\vec{r}} = -2m\omega \dot{r} (\hat{k}' \times \hat{i}') = -2m\omega \dot{r} \hat{j}'$

$$\begin{aligned}
 \text{The Centrifugal force is } -m\omega \times (\bar{\omega} \times \bar{r}) &= -m\omega^2 [\hat{k}' \times (\hat{k}' \times \hat{i}\hat{x})] \\
 &= -m\omega^2 (\hat{k}' \times (\hat{x}\hat{j}')) \\
 &= m\omega^2 \hat{x}\hat{i}'
 \end{aligned}$$

So, e.o.m. in the rotating frame

$$\vec{F} - 2m\omega \dot{r} \hat{j}' + m\omega^2 x \hat{i}' = 0 \quad \leftarrow \text{why?}$$

Ex: How far can the bug crawl before it starts to slip, given the coefficient of static friction μ_s b/w the bug & the spoke?

The force of friction has a max value $\mu_s mg$.
So slipping will start when $|\vec{F}| = \mu_s mg$

$$\text{or } \sqrt{(2m\omega \dot{r})^2 + (m\omega^2 x)^2} = \mu_s mg$$

solve for x :

$$x = \frac{\sqrt{\mu_s^2 g^2 - 4\omega^2 (\dot{r})^2}}{\omega^2}$$