

Sample Midterm 1B, Math 1554

PLEASE PRINT YOUR NAME CLEARLY IN ALL CAPITAL LETTERS

First Name _____ Last Name _____

GTID Number: _____

Student GT Email Address: _____@gatech.edu

Section Number (e.g. A4, QH3, etc.) _____ TA Name _____

Student Instructions

- **Show your work** and justify your answers for all questions unless stated otherwise.
- **Organize your work** in a reasonably neat and coherent way.
- Calculators, notes, cell phones, books are not allowed.
- Use dark and clear writing: your exam will be scanned into a digital system.
- Exam pages are double sided. Be sure to complete both sides.
- Leave a 1 inch border around the edges of exams.
- Any work done on scratch paper will not be collected and will not be graded.

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You do not need to justify your reasoning for questions on this page.

1. (a) (5 points) Suppose A is an $m \times n$ matrix, $\vec{b} \in \mathbb{R}^m$. Select **true** if the statement is true for all choices of A and \vec{b} . Otherwise, select **false**.

true false

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- ☐ ☐ If $A\vec{x} = \vec{0}$ and A has reduced echelon form E , then $E\vec{x} = \vec{0}$.
☐ ☐ If every column of A is pivotal, then $A\vec{x} = \vec{b}$ is consistent for any \vec{b} .
☐ ☐ The echelon form of A is unique.
☐ ☐ If A is 5×7 and has two pivot columns, then $A\vec{x} = \vec{b}$ has 3 free variables.
☐ ☐ If A has linearly dependent columns, then the columns of A cannot span \mathbb{R}^m .
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- (b) (3 points) Fill in the entries of the matrices below so that they are standard matrices for a one-to-one linear transformation. If it is not possible, write “NP” below the matrix.

$$\begin{pmatrix} 1 & 1 \\ 0 & \\ 0 & \end{pmatrix}, \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \end{pmatrix}, \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \\ 1 & 0 & 0 \end{pmatrix}$$

- (c) (2 points) Suppose T_A maps \mathbb{R}^4 to \mathbb{R}^2 has standard matrix

$$A = \begin{pmatrix} 5 & -3 & 2 & -3 \\ 1 & 0 & -2 & 1 \end{pmatrix}$$

Fill in the blanks below:

$$T_A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} \boxed{}x_1 + \boxed{}x_2 + \boxed{}x_3 + \boxed{}x_4 \\ \boxed{}x_1 + \boxed{}x_2 + \boxed{}x_3 + \boxed{}x_4 \end{pmatrix}$$

- (d) (4 points) Let $A \in \mathbb{R}^{3 \times 4}$, $B \in \mathbb{R}^{4 \times 3}$ and $\vec{x} \in \mathbb{R}^4$. Circle the operations below that are defined.

$$B^T B \quad A^T B \quad \vec{x}^T A \vec{x} \quad \vec{x}^T B A$$

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2. (10 points) If possible, write down an example of a matrix with the following properties. If it is not possible to do so, write *not possible*. You do not need to justify your reasoning.

(a) A 3×3 matrix A , in echelon form, with just the first and third columns pivotal.

(b) A 3×2 non-zero matrix A , that is in row reduced echelon form, and $A\vec{x} = \vec{0}$ has a non-trivial solution.

(c) A 2×3 non-zero matrix in echelon form that is the standard matrix for linear transform T . T is not one-to-one, and T is not onto.

(d) A matrix $A \in \mathbb{R}^{2 \times 2}$ such that $T(\vec{x}) = A\vec{x}$, where T is a linear transformation that reflects vectors in \mathbb{R}^2 about the line $x_1 = x_2$ and then projects them onto the x_2 axis.

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3. (3 points) Suppose $T_A : \mathbb{R}^4 \mapsto \mathbb{R}^3$ is a onto linear transformation. Circle the matrices, if any, that A could be equal to. You do not need to justify your reasoning for this question.

$$\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & 3 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & -2 & 2 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 2 & -2 \end{pmatrix}$$

4. (7 points) For what values of $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ is the system below consistent? Express your answer using parametric vector form.

$$\begin{pmatrix} 0 & 5 \\ 1 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

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5. (6 points) For what values of t , if any, are the three vectors below linearly independent?

$$\begin{pmatrix} 1 \\ 0 \\ t \end{pmatrix}, \quad \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \quad \begin{pmatrix} t \\ 8 \\ 2t \end{pmatrix}$$

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6. (10 points) Consider the linear system $A\vec{x} = \vec{b}$, where

$$A = \begin{pmatrix} 1 & -3 & 7 & -5 \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 1 & 0 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} 10 \\ 0 \\ 2 \end{pmatrix}$$

- (a) Express the augmented matrix $[A \mid \vec{b}]$ in row reduced echelon form.

- (b) Write the set of solutions to $A\vec{x} = \vec{b}$ in parametric vector form.

Solutions

1. (a)
 - true
 - false
 - false
 - false
 - false

- (b) First matrix: Fill in with 1 in the second row, 0 in the third row
 Second matrix: not possible
 Third matrix: not possible

(c)

$$T_A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} \boxed{5} x_1 + \boxed{-3} x_2 + \boxed{2} x_3 + \boxed{-3} x_4 \\ \boxed{1} x_1 + \boxed{0} x_2 + \boxed{-2} x_3 + \boxed{1} x_4 \end{pmatrix}$$

(d) $B^T B$ $\vec{x}^T B A$

2. (a) $\begin{pmatrix} \bullet & * & * \\ 0 & 0 & \bullet \\ 0 & 0 & 0 \end{pmatrix}$, where $*$ denotes anything, and \bullet denotes anything non-zero

(b) $\begin{pmatrix} 1 & * \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$ or $\begin{pmatrix} 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$

(c) $\begin{pmatrix} * & * & * \\ 0 & 0 & 0 \end{pmatrix}$ or $\begin{pmatrix} 0 & * & * \\ 0 & 0 & 0 \end{pmatrix}$ or $\begin{pmatrix} 0 & 0 & * \\ 0 & 0 & 0 \end{pmatrix}$

(d) $T = A\vec{x} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \vec{x} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \vec{x}$
 $\implies A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$

3. $\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 1 & 2 & -2 & 2 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 2 & -2 \end{pmatrix}$

4.

$$\begin{pmatrix} 0 & 5 & | & b_1 \\ 1 & 3 & | & b_2 \\ 2 & 1 & | & b_3 \end{pmatrix} \sim \begin{pmatrix} 1 & 3 & | & b_2 \\ 0 & 1 & | & b_1/5 \\ 0 & -5 & | & b_3 - 2b_2 \end{pmatrix} \\ \sim \begin{pmatrix} 1 & 3 & | & b_2 \\ 0 & 1 & | & b_1/5 \\ 0 & 0 & | & b_3 - 2b_2 + b_1 \end{pmatrix}$$

$$\implies \text{need } b_3 - 2b_2 + b_1 = 0$$

$$\implies b_1 = 2b_2 - b_3$$

$$\implies \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} 2b_2 - b_3 \\ b_2 \\ b_3 \end{pmatrix} = b_2 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + b_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

5.

$$\begin{pmatrix} 1 & 0 & t & | & 0 \\ 0 & 1 & 8 & | & 0 \\ t & -1 & 2t & | & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & t & | & 0 \\ 0 & 1 & 8 & | & 0 \\ 0 & -1 & 2t - t^2 & | & 0 \end{pmatrix} \\ \sim \begin{pmatrix} 1 & 0 & t & | & 0 \\ 0 & 1 & 8 & | & 0 \\ 0 & 0 & 2t - t^2 + 8 & | & 0 \end{pmatrix}$$

$$\implies \text{for L.I., we need } -t^2 + 2t + 8 \neq 0, \text{ or } -(t+2)(t-4) \neq 0$$

$$\implies t \neq -2, 4$$

$$6. \quad (a) \quad \begin{pmatrix} 1 & -3 & 7 & -5 & | & 10 \\ 0 & 1 & -2 & 3 & | & 0 \\ 0 & 0 & 1 & 0 & | & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & -3 & 0 & -5 & | & -4 \\ 0 & 1 & 0 & 3 & | & 4 \\ 0 & 0 & 1 & 0 & | & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & 4 & | & 8 \\ 0 & 1 & 0 & 3 & | & 4 \\ 0 & 0 & 1 & 0 & | & 2 \end{pmatrix}$$

$$(b) \quad \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 8 - 4x_4 \\ 4 - 3x_4 \\ 2 \\ 0 + x_4 \end{pmatrix} = \begin{pmatrix} 8 \\ 4 \\ 2 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -4 \\ -3 \\ 0 \\ 1 \end{pmatrix}$$