

## *Answers*

### Sample Midterm 2B, Math 1554

**PLEASE PRINT YOUR NAME CLEARLY IN ALL CAPITAL LETTERS**

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#### **Student Instructions**

- **Show your work** and justify your answers for all questions unless stated otherwise.
- **Organize your work** in a reasonably neat and coherent way.
- Calculators, notes, cell phones, books are not allowed.
- Use dark and clear writing: your exam will be scanned into a digital system.
- Exam pages are double sided. Be sure to complete both sides.
- Leave a 1 inch border around the edges of exams.
- Any work done on scratch paper will not be collected and will not be graded.

Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

You do not need to justify your reasoning for questions on this page.

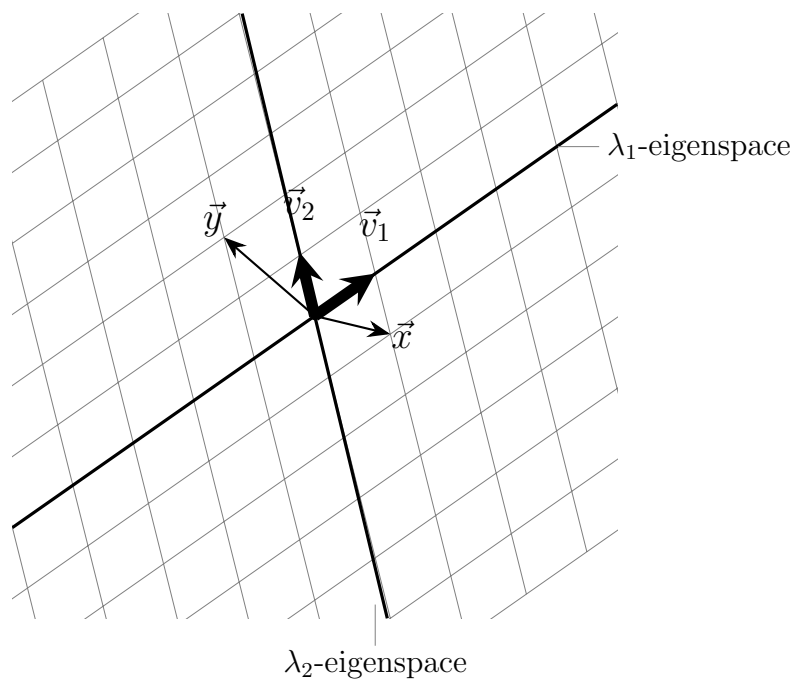
1. (10 points) Indicate **true** if the statement is true, otherwise, indicate **false**.

	true	false
a) If $A\vec{x} = \vec{b}$ has exactly one solution for every $\vec{b}$ , $A$ must be singular.	<input type="radio"/>	<input type="radio"/>
b) If $\vec{x}, \vec{y} \in \mathbb{R}^3$ are linearly independent, then $\{\vec{x}, \vec{y}, \vec{x} + \vec{y}\}$ is a basis for $\mathbb{R}^3$ .	<input type="radio"/>	<input type="radio"/>
c) The set of solutions to $A\vec{x} = \vec{b}$ , for any $\vec{b} \in \mathbb{R}^n$ , is a subspace.	<input type="radio"/>	<input type="radio"/>
d) If $A, B \in \mathbb{R}^{n \times n}$ and $AB = I$ , then $BA = I$ .	<input type="radio"/>	<input type="radio"/>
e) Any matrix that is similar to the identity matrix must be equal to the identity matrix.	<input type="radio"/>	<input type="radio"/>
f) If $A, B \in \mathbb{R}^{m \times n}$ have the same null space, then they have the same RREF.	<input type="radio"/>	<input type="radio"/>
g) If $A$ is $n \times n$ , and there exists a $\vec{b} \in \mathbb{R}^n$ such that $A\vec{x} = \vec{b}$ is inconsistent, then $\det(A) = 0$ .	<input type="radio"/>	<input type="radio"/>
h) If $A$ has an $LU$ factorization, then $A$ is invertible.	<input type="radio"/>	<input type="radio"/>
i) If $A \in \mathbb{R}^{n \times n}$ has eigenvector $\vec{x}$ then $2\vec{x}$ is also an eigenvector of $A$ .	<input type="radio"/>	<input type="radio"/>
j) Swapping the rows of $A$ does not change the value of $\det(A)$ .	<input type="radio"/>	<input type="radio"/>

Answers:

- a) false
- b) false
- c) false
- d) true
- e) true
- f) true
- g) true
- h) false
- i) true
- j) false

2. (2 points) A  $2 \times 2$  matrix  $A$  has eigenvalues  $\lambda_1 = 1$  and  $\lambda_2 = 2$ , with eigenvectors and eigenspaces indicated in the picture. Draw  $A\vec{x}$  and  $A\vec{y}$ .



Answer:

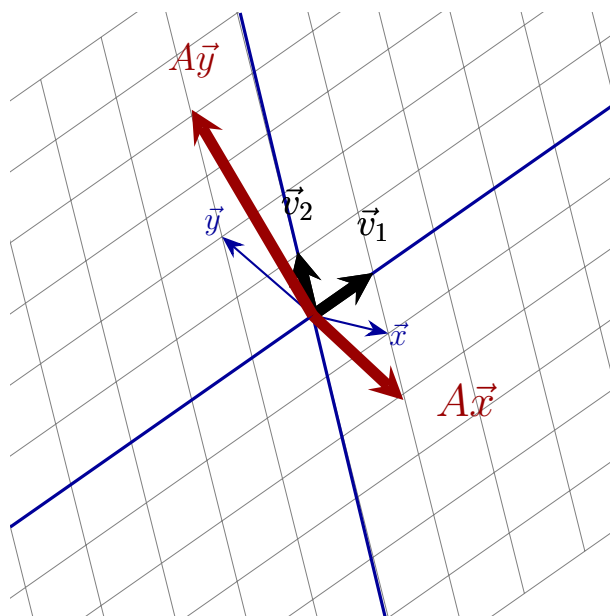
We can see from the graph that

$$\vec{x} = \vec{v}_1 - \vec{v}_2, \quad \vec{y} = 2\vec{v}_2 - \vec{v}_1$$

Using  $A\vec{v}_1 = \vec{v}_1$  and  $A\vec{v}_2 = 2\vec{v}_2$ ,

$$A\vec{x} = A(\vec{v}_1 - \vec{v}_2) = A\vec{v}_1 - A\vec{v}_2 = \vec{v}_1 - 2\vec{v}_2$$

$$A\vec{y} = A(2\vec{v}_2 - \vec{v}_1) = 2A\vec{v}_2 - A\vec{v}_1 = 4\vec{v}_2 - \vec{v}_1$$



Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

You do not need to justify your reasoning for questions on this page.

3. (2 points) Fill in the missing entries of the  $3 \times 3$  matrix  $A$  with **non-zero** numbers so that  $A$  has null space spanned by  $\vec{v}$ .

$$\vec{v} = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, \quad A = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & - & - \end{pmatrix}$$

An acceptable answer is:

$$\begin{pmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & 1 & -1 \end{pmatrix}$$

Or, more generally:

$$\begin{pmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & k & -k \end{pmatrix}, \quad k \in \mathbb{R}$$

4. (6 points) If possible, write down an example of a matrix with the following properties. If it is not possible to do so, write *not possible*. You do not need to justify your reasoning.

- (a) A  $4 \times 3$  matrix  $A$  with  $\text{rank}(A) = 3$  and  $\text{rank}(A^T) = 4$ .

Answer: not possible (because  $A^T$  is  $3 \times 4$ , its rank is at most 3).

- (b) A  $2 \times 3$  matrix in RREF whose null space is spanned by  $\begin{pmatrix} 2 \\ -4 \\ 1 \end{pmatrix}$ .

Answer:  $\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 4 \end{pmatrix}$ . This is the unique answer.

- (c) A  $3 \times 3$  matrix in echelon form,  $A$ , such that  $\text{Col}(A)$  is spanned by the vectors  $\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$ .

Answer:  $\begin{pmatrix} 2 & 1 & * \\ 0 & 2 & * \\ 0 & 0 & 0 \end{pmatrix}$ , where  $*$  can be anything.

- (d) A  $4 \times 4$  stochastic matrix,  $P$ , such that the Markov Chain  $x_{k+1} = Px_k$  for  $k = 0, 1, 2, \dots$ , does not have a unique steady-state.

Answer:  $P = I_4$ , the  $4 \times 4$  identity matrix.

5. (1 point) Suppose  $\vec{v}_1, \vec{v}_2$  are eigenvectors of an  $3 \times 3$  matrix  $A$  that correspond to eigenvalues  $\lambda_1$  and  $\lambda_2$ .

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 8 \\ 0 \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} 5 \\ 0 \\ 2 \end{pmatrix}, \quad \lambda_1 = 1, \quad \lambda_2 = \frac{1}{10}$$

Vector  $\vec{p}$  is such that  $\vec{p} = \vec{v}_1 - 13\vec{v}_2$ . What does  $A^k\vec{p}$  tend to as  $k \rightarrow \infty$ ?

Answer: by inspection,  $A^k p \rightarrow v_1$ . To see this, note that  $Av_1 = v_1$  and  $Av_2 = \frac{1}{10}v_2$ .

$$\begin{aligned}Ap &= A(v_1 - 13v_2) = Av_1 - 13Av_2 = v_1 - \frac{13}{10}v_2 \\A^2p &= A^2(v_1 - 13v_2) = A^2v_1 - 13A^2v_2 = v_1 - \frac{13}{10^2}v_2 \\A^3p &= A^3(v_1 - 13v_2) = A^3v_1 - 13A^3v_2 = v_1 - \frac{13}{10^3}v_2 \\A^kp &= A^k(v_1 - 13v_2) = A^kv_1 - 13A^kv_2 = v_1 - \frac{13}{10^k}v_2\end{aligned}$$

The second term goes to zero as  $k \rightarrow \infty$ . If you would like to see another example like this, check out Example 5 from Section 5.2 of our textbook. Or solve Problem #25, or #27 from that section.

Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

You do not need to justify your reasoning for questions on this page.

6. (3 points) If the determinant  $\left| \begin{pmatrix} a & b \\ 1 & 0 \end{pmatrix} \right| = 3$ , compute the value of  $\left| \begin{pmatrix} -1 & 0 & 0 \\ 2a & 2b & 0 \\ 0 & 0 & 5 \end{pmatrix} \right|$ .

Answer:  $\begin{vmatrix} -1 & 0 & 0 \\ 2a & 2b & 0 \\ 0 & 0 & 5 \end{vmatrix} = 5 \begin{vmatrix} -1 & 0 \\ 2a & 2b \end{vmatrix} = -5 \begin{vmatrix} 2a & 2b \\ -1 & 0 \end{vmatrix} = 10 \begin{vmatrix} a & b \\ 1 & 0 \end{vmatrix} = 30$

7.  $A$  is the  $3 \times 6$  matrix  $A = \begin{bmatrix} 1 & 6 & -4 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 2 & -6 \\ 0 & 0 & 0 & 0 & 1 & 6 \end{bmatrix}$

- (a) (1 point) The rank of  $A$  is \_\_\_\_\_.  
 (b) (1 point) The dimension of  $\text{Null}(A)$  is \_\_\_\_\_.  
 (c) (2 points) Write down a basis for  $\text{Col}(A)$ .  
 (d) (3 points) Construct a basis for  $\text{Null}(A)$ .

Answer:

(a) 3

(b) 3

(c)  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$

(d)  $\sim \begin{pmatrix} 1 & 6 & -4 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 0 & -18 \\ 0 & 0 & 0 & 0 & 1 & 6 \end{pmatrix}$

$$\Rightarrow \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} -6x_2 + 4x_3 + x_6 \\ x_2 \\ x_3 \\ 18x_6 \\ -6x_6 \\ x_6 \end{pmatrix} = x_2 \begin{pmatrix} -6 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 4 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_6 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 18 \\ -6 \\ 1 \end{pmatrix}$$

$$\Rightarrow \text{basis is the set } \left\{ \begin{pmatrix} -6 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 4 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 18 \\ -6 \\ 1 \end{pmatrix} \right\}$$

Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

8. (4 points)  $S$  is the parallelogram determined by  $\vec{v}_1 = \begin{pmatrix} 4 \\ -2 \end{pmatrix}$ , and  $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . If  $A = \begin{pmatrix} 2 & 3 \\ 2 & 2 \end{pmatrix}$ , what is the area of the image of  $S$  under the map  $\vec{x} \mapsto A\vec{x}$ ?

Answer:

$$\text{area} = \left| \begin{vmatrix} 4 & 0 \\ -2 & 1 \end{vmatrix} \cdot \begin{vmatrix} 2 & 3 \\ 2 & 2 \end{vmatrix} \right| = |4 \cdot (-2)| = 8$$

9. (4 points) If possible, compute the  $LU$  factorization of  $A = \begin{pmatrix} 5 & 4 \\ 10 & 6 \\ 0 & 2 \\ -5 & 1 \end{pmatrix}$

Answer:

$$\begin{pmatrix} 5 & 4 \\ 10 & 6 \\ 0 & 2 \\ -5 & 1 \end{pmatrix} \sim \begin{pmatrix} 5 & 4 \\ 0 & -2 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} = U$$
$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ -1 & \frac{-5}{2} & 0 & 1 \end{pmatrix}$$

Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

10. (4 points) List all possible values of  $k$ , if any, so that  $A$  has a real eigenvalue with geometric multiplicity 2. Show your work.

$$A = \begin{pmatrix} 3 & 2 & 0 \\ 2 & 3 & 0 \\ 0 & 0 & k \end{pmatrix}$$

Answer:

$$0 = \det(A - \lambda I) \tag{1}$$

$$= (k - \lambda) ((3 - \lambda)(3 - \lambda) - 4) \tag{2}$$

$$= (k - \lambda)(\lambda^2 - 6\lambda + 5) \tag{3}$$

$$= (k - \lambda)(\lambda - 1)(\lambda - 5) \tag{4}$$

$$\implies k = 1 \text{ or } 5$$

11. (4 points) Construct a basis for the subspace

$$H = \{\vec{x} \in \mathbb{R}^3 : 5x_1 + 4x_2 - 7x_3 = 0\}.$$

Answer:

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{-4}{5}x_2 + \frac{7}{5}x_3 \\ x_2 \\ x_3 \end{pmatrix} = x_2 \begin{pmatrix} -4/5 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 7/5 \\ 0 \\ 1 \end{pmatrix} \implies \text{basis is } \left\{ \begin{pmatrix} -4/5 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 7/5 \\ 0 \\ 1 \end{pmatrix} \right\}$$



Math 1554, Sample Midterm 2B. Your initials: \_\_\_\_\_

12. (5 points)  $A$  has only two distinct eigenvalues, 0 and 1.  $A = \begin{pmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & -1 & 2 \end{pmatrix}$ .

(a) Construct the eigenbasis for eigenvalue  $\lambda = 0$ .

(b) Construct the eigenbasis for eigenvalue  $\lambda = 1$ .

Answer:

$$\begin{aligned} \text{a) } A &= \begin{pmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 0 & -1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \implies \vec{v}_1 = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} \\ &\implies \text{basis is } \{\vec{v}_1\} \end{aligned}$$

$$\begin{aligned} \text{b) } A - I &= \begin{pmatrix} -1 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & -1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ &\implies \vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \\ &\implies \text{eigenbasis is } \{\vec{v}_1, \vec{v}_2\} \end{aligned}$$