1 Support Vector Machine

Suppose there are N data points $\mathbf{x}_1, \dots, \mathbf{x}_N$ and let t_1, \dots, t_N be their labels where $t_k \in \{-1, 1\}$ for all k. We want to find suitable $\phi(\mathbf{x}_k)$, weight \mathbf{w} and bias b that satisfies

$$\mathbf{w}^T \phi(\mathbf{x}_k) + b = \begin{cases} > 0 & \text{if } t_k = 1\\ < 0 & \text{if } t_k = -1 \end{cases}$$
 for all k

This is a linear classifier in feature space. The distance of each data point to this hyper plane is

$$\frac{|\mathbf{w}^T \phi(\mathbf{x}_k) + b|}{\|\mathbf{w}\|}$$

According to *statistical learning theory* (not actually understand), we want to maximize the minimal distance

$$\underset{\mathbf{w},b}{\operatorname{arg\ max}} \left\{ \frac{1}{\|\mathbf{w}\|} \min_{k} |\mathbf{w}^{T} \phi(\mathbf{x}_{k}) + b| \right\}$$

Since $t_k(\mathbf{w}^T\phi(\mathbf{x}_k)+b)>0$ and $t_k\in\{-1,1\}$, the problem is equivalent to

$$\arg\max_{\mathbf{w},b} \left\{ \frac{1}{\|\mathbf{w}\|} \min_{k} t_k(\mathbf{w}^T \phi(\mathbf{x}_k) + b) \right\}$$

Observe that any rescaling of \mathbf{w} and b won't change the ultimate value, hence we can set

$$t_k(\mathbf{w}^T \phi(\mathbf{x}_k) + b) = 1$$

for those \mathbf{x}_k that are closest to the hyper plane. Then other points yield

$$t_k(\mathbf{w}^T\phi(\mathbf{x}_k)+b) > 1$$

Now we simplify the problem into

$$\underset{\mathbf{w},b}{\operatorname{arg max}} \frac{1}{\|\mathbf{w}\|} \quad \text{s.t.} \quad t_k(\mathbf{w}^T \phi(\mathbf{x}_k) + b) \ge 1 \text{ for all } k$$

It's equivalent to

$$\underset{\mathbf{w},b}{\arg\min} \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t.} \quad t_k(\mathbf{w}^T \phi(\mathbf{x}_k) + b) \ge 1 \text{ for all } k$$

And gives the Lagrangian function

$$\mathcal{L}(\mathbf{w}, b, \mathbf{a}) = \frac{1}{2} \|\mathbf{w}\|^2 + \sum_{k=1}^{N} a_k \left[1 - t_k(\mathbf{w}^T \phi(\mathbf{x}_k) + b) \right]$$

where $\mathbf{a} = (a_1, \dots, a_N)^T \geq \mathbf{0}$. For

$$\max_{\mathbf{a}} \min_{\mathbf{w}, b} \mathcal{L}(\mathbf{w}, b, \mathbf{a}) \quad \text{s.t.} \quad \mathbf{a} \ge 0$$

let gradient vanish with respect to \mathbf{w} and b

$$\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}, b, \mathbf{a}) = \mathbf{w} - \sum_{k=1}^{N} a_k t_k \phi(\mathbf{x}_k) = 0$$

$$\nabla_b \mathcal{L}(\mathbf{w}, b, \mathbf{a}) = \sum_{k=1}^N a_k t_k = 0$$

Substitute back then yield the dual form

$$\max_{\mathbf{a}} \sum_{k=1}^{N} a_k - \frac{1}{2} \sum_{k=1}^{N} \sum_{m=1}^{N} a_k a_m t_k t_m \phi(\mathbf{x}_k)^T \phi(\mathbf{x}_m)$$

subject to

$$a_k \ge 0, \quad k = 1, \dots, N$$

$$\sum_{k=1}^{N} a_k t_k = 0.$$

Let $k(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^T \phi(\mathbf{x}')$ stands for the kernel function and let $y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + b$. When \mathbf{w} is the solution, $\mathbf{w} = \sum_k a_k t_k \phi(\mathbf{x}_k)$. Put this into $y(\mathbf{x})$ and have

$$y(\mathbf{x}) = \sum_{k=1}^{N} a_k t_k k(\mathbf{x}_k, \mathbf{x}) + b$$

here we express the classifier in terms of $\{a_k\}$ and the kernel function $k(\mathbf{x}, \mathbf{x}')$.

1.1 Apply KKT Condition

We have a primal problem

$$\underset{\mathbf{w}}{\arg\min} \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t.} \quad t_k y(\mathbf{x}_k) - 1 \ge 0 \text{ for all } k$$

and a dual problem

$$\max_{\mathbf{a}} \sum_{k=1}^{N} a_k - \frac{1}{2} \sum_{k=1}^{N} \sum_{m=1}^{N} a_k a_m t_k t_m k(\mathbf{x}_k, \mathbf{x}_m) \quad \text{s.t.} \quad a_k \ge 0, \ \forall \ k \text{ and } \sum_{k=1}^{N} a_k t_k = 0$$

The KKT condition needs further constraint that

$$a_k\{t_k y(\mathbf{x}_k) - 1\} = 0$$

This implies $a_k = 0$ or $t_k y(\mathbf{x}_k) = 1$. Any data point has $a_k = 0$ will not contribute to the classifier. The rest data points have $t_k y(\mathbf{x}_k) = 1$ are called *support vector*. This tells us that we only need support vectors to predict new point though we need whole data to train. Mathematically, choose one support vector \mathbf{x}' , we can get b by

$$t'y(\mathbf{x}') = t'\left\{\sum_{m} a_m t_m k(\mathbf{x}_m, \mathbf{x}') + b\right\} = 1$$

where m stands for the index of support vector. In practical, multiply each side by one label t_k of one support vector and have

$$b = t_k - \left\{ \sum_m a_m t_m k(\mathbf{x}_m, \mathbf{x}_k) \right\} \text{ for all } k$$

Take the average of all possible b as the final one

$$b = \frac{1}{M} \sum_{k} \left(t_k - \left\{ \sum_{m} a_m t_m k(\mathbf{x}_m, \mathbf{x}_k) \right\} \right)$$

where M is the number of support vectors and k and m are both the index of support vector.

2 Soft Margin Support Vector Machine

The original SVM is

$$\min_{\mathbf{w},b} \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t.} \quad t_k y(\mathbf{x}_k) \ge 1 \text{ for all } k$$

To allow some points can be misclassified, we introduce each point a slack variable ξ_k that is defined by

$$\xi_k = \begin{cases} 0 & \text{if } t_k y(\mathbf{x}_k) \ge 1\\ |t_k - y(\mathbf{x}_k)| & \text{otherwise} \end{cases}$$

Look deeper into this definition. If $0 < t_k y(\mathbf{x}_k) < 1$, we have $0 < y(\mathbf{x}_k) < 1$ or $-1 < y(\mathbf{x}_k) < 0$. Hence $0 < \xi_k = 1 - t_k y(\mathbf{x}_k) < 1$. If $t_k y(\mathbf{x}_k) = 0$, $\xi_k = 1 - t_k y(\mathbf{x}_k) = 1$. If $t_k y(\mathbf{x}_k) < 0$, $\xi_k = 1 - t_k y(\mathbf{x}_k) > 1$. In summary

$$\xi_k \begin{cases} = 0 & \text{if } t_k y(\mathbf{x}_k) \in [1, \infty) \\ = 1 - t_k y(\mathbf{x}_k) & \begin{cases} \in (0, 1) & \text{if } t_k y(\mathbf{x}_k) \in (0, 1) \\ = 1 & \text{if } t_k y(\mathbf{x}_k) = 0 \\ > 1 & \text{if } t_k y(\mathbf{x}_k) \in (-\infty, 0) \end{cases}$$

Replace the constrain with

$$t_k y(\mathbf{x}_k) \ge 1 - \xi_k$$
 for all k

This is so called *soft margin*.

When there exist outliers, they'll have extremely large ξ_k . To avoid this, here comes the soft SVM that also minimize slack variable

$$\min_{\mathbf{w},b,\xi} C \sum_{k=1}^{N} \xi_k + \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t.} \quad t_k y(\mathbf{x}_k) \ge 1 - \xi_k \text{ for all } k$$

where C is some constant. Briefly speaking, slack vairables relax some points' constarint, their $t_k y(\mathbf{x}_k)$ only needs to larger than some value smaller than 1. That's why we call this soft margin.

2.1 Apply KKT Condition

The Lagrangian of soft SVM is

$$\mathcal{L}(\mathbf{w}, b, \xi, \mathbf{a}, \mu) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{k=1}^{N} \xi_k - \sum_{k=1}^{N} a_k \{t_k y(\mathbf{x}_k) - 1 + \xi_k\} - \sum_{k=1}^{N} \mu_k \xi_k$$

where $a_k, \mu_k \geq 0$, $t_k y(\mathbf{x}_k) - 1 + \xi_k \geq 0$ and note that slack variables are non negative $\xi_k \geq 0$. The KKT conditions are

$$\begin{array}{ll} \textbf{Dual Feasibility} & a_k \geq 0, & \mu_k \geq 0 \\ \textbf{Primal Feasibility} & t_k y(\mathbf{x}_k) - 1 + \xi_k \geq 0, & \xi_k \geq 0 \\ \textbf{Complmentary Slackness} & a_k (t_k y(\mathbf{x}_k) - 1 + \xi_k) = 0, & \mu_k \xi_k = 0 \end{array}$$

Use $y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + b$ and compute gradients of \mathcal{L} with respect to \mathbf{w} , b and ξ

$$\nabla_{\mathbf{w}} \mathcal{L} = \mathbf{w} - \sum_{k=1}^{N} a_k t_k \phi(\mathbf{x}_n) = 0$$
$$\nabla_b \mathcal{L} = \sum_{k=1}^{N} a_k t_k = 0$$
$$\nabla_{\xi_k} \mathcal{L} = a_k - C - \mu_k = 0$$

Substitute back and get the dual form

$$\max_{\mathbf{a}} \sum_{k=1}^{N} a_k - \frac{1}{2} \sum_{k=1}^{N} \sum_{m=1}^{N} a_k a_m t_k t_m k(x_k, x_m) \quad \text{s.t.} \quad 0 \le a_k \le C, \ \forall \ k \text{ and } \sum_{k=1}^{N} a_k t_k = 0$$

It's the same as normal SVM, the only difference is the constraint of a_k , which is known as the box constraint.