Goal

Say $X \sim P_{true}$ but P_{true} unknown. Our goal is to generate more X like they are generated from P_{true} .

Maximum Log Likelihood Approach

If P_{true} can be paremetrized by a parameter set θ . We can leverage the maximum likelihood to estimate the θ that yields the "best fit" probability to the given samples.

Suppose we have N real samples $\{x_1, \ldots, x_N\} \sim P_{true}$. Suppose they are i.i.d from different Gaussians

$$f(x_i; \mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}$$

The log likelihood function is

$$L(\lbrace x_i \rbrace; \mu, \sigma) = \ln \prod_{i=1}^{N} f(x_i; \mu, \sigma)$$
$$= \sum_{i=1}^{N} \ln f(x_i; \mu, \sigma)$$

Solve

$$\max_{\mu,\sigma} \sum_{i=1}^{N} \ln f(x_i; \mu, \sigma)$$
$$= \max_{\mu,\sigma} \sum_{i=1}^{N} -\frac{(x_i - \mu)^2}{2\sigma^2} - \ln \sqrt{2\pi\sigma^2}$$

is the classical approach. However, there's no efficient and simple probability model for larger dimensions.

GAN

Min-Max Problem

$$\min_{G} \max_{D} E_{x \sim P_{true}}[\ln D(x)] + E_{z \sim P(z)}[1 - \ln D(G(z))]$$

 $x \sim P_{true}$ and $z \sim P(z)$ implies Monte-Carlo

$$E[\ln D(X)] = \frac{1}{N} \sum_{i=1}^{N} \ln D(x_i)$$

$$E[1 - \ln D(G(Z))] = \frac{1}{N} \sum_{i=1}^{M} \ln D(G(z_i))$$

WGAN

For G fixed, the optimal D is

$$D_G(x) = \frac{P_{true}(x)}{P_{true}(x) + P_G(x)}$$

KL divergence

$$KL(p\|q) = \sum_i p_i \frac{\ln p_i}{q_i} = E_p[\ln \frac{p}{q}]$$

Jensen–Shannon divergence

$$\begin{split} JSD(p,q) &= \frac{1}{2}KL(p\|m) + \frac{1}{2}KL(q\|m), \\ m &= \frac{1}{2}(p+q) \end{split}$$

Let p, q be P_{true}, P_G ,

$$\min_{G} JSD(P_{true}, P_{G})$$

Earth-Mover distance / Wasserstein-1 distance

$$WS(P_{true}, P_G) = \sup_{\|D\|_L \le 1} \{ E_{x \sim P_{true}}[D(x)] - E_{y \sim P_G}[D(y)] \}$$

where D is 1-Lipschitz continuous, i.e.

$$||D(x) - D(y)|| \le ||x - y|| \tag{1}$$