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# shared\_ptr class template

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## Introduction

The shared\_ptr class template stores a pointer to a dynamically allocated object, typically with a C++ new-expression. The object pointed to is guaranteed to be deleted when the last shared\_ptr pointing to it is destroyed or reset.

### Example:

```
shared_ptr<X> p1( new X );
shared_ptr<void> p2( new int(5) );
```

shared\_ptr deletes the exact pointer that has been passed at construction time, complete with its original type, regardless of the template parameter. In the second example above, when p2 is destroyed or reset, it will call delete on the original int\* that has been passed to the constructor, even though p2 itself is of type shared\_ptr<void> and stores a pointer of type void\*.

Every shared\_ptr meets the CopyConstructible, MoveConstructible, CopyAssignable and MoveAssignable requirements of the C++ Standard Library, and can be used in standard library containers. Comparison operators are supplied so that shared\_ptr works with the standard library's associative containers.

Because the implementation uses reference counting, cycles of <code>shared\_ptr</code> instances will not be reclaimed. For example, if <code>main()</code> holds a <code>shared\_ptr</code> to A, which directly or indirectly holds a <code>shared\_ptr</code> back to A, A's use count will be 2. Destruction of the original <code>shared\_ptr</code> will leave A dangling with a use count of 1. Use <a href="weak-ptr">weak-ptr</a> to "break cycles."

The class template is parameterized on T, the type of the object pointed to. shared\_ptr and most of its member functions place no requirements on T; it is allowed to be an incomplete type, or void. Member functions that do place additional requirements (constructors, reset) are explicitly documented below.

shared\_ptr<T> can be implicitly converted to shared\_ptr<U> whenever T\* can be implicitly converted to U\*. In particular, shared\_ptr<T> is implicitly convertible to shared\_ptr<T const>, to shared\_ptr<U> where U is an accessible base of T, and to shared\_ptr<void>.

```
shared_ptr is now part of the C++11 Standard, as std::shared_ptr.
```

Starting with Boost release 1.53,  $shared_ptr$  can be used to hold a pointer to a dynamically allocated array. This is accomplished by using an array type (T[] or T[N]) as the template parameter. There is almost no difference between using an unsized array, T[], and a sized array, T[N]; the latter just enables operator[] to perform a range check on the index.

#### Example:

```
shared_ptr<double[1024]> p1( new double[1024] );
shared_ptr<double[]> p2( new double[n] );
```

## **Best Practices**

A simple guideline that nearly eliminates the possibility of memory leaks is: always use a named smart pointer variable to hold the result of new. Every occurrence of the new keyword in the code should have the form:

```
shared_ptr<T> p(new Y);
```

It is, of course, acceptable to use another smart pointer in place of shared\_ptr above; having T and Y be the same type, or passing arguments to Y's constructor is also OK.

If you observe this guideline, it naturally follows that you will have no explicit delete statements; try/catch constructs will be rare.

Avoid using unnamed  ${\tt shared\_ptr}$  temporaries to save typing; to see why this is dangerous, consider this example:

```
void f(shared_ptr<int>, int);
int g();

void ok()
{
    shared_ptr<int> p( new int(2) );
    f( p, g() );
}

void bad()
{
    f( shared_ptr<int>( new int(2) ), g() );
}
```

The function ok follows the guideline to the letter, whereas bad constructs the temporary shared\_ptr in place, admitting the possibility of a memory leak. Since function arguments are evaluated in unspecified order, it is possible for new int(2) to be evaluated first, g() second,

and we may never get to the <code>shared\_ptr</code>constructor if <code>g</code> throws an exception. See <u>Herb Sutter's treatment</u> (also <u>here</u>) of the issue for more information.

The exception safety problem described above may also be eliminated by using the make shared or allocate shared factory functions defined in boost/make\_shared. These factory functions also provide an efficiency benefit by consolidating allocations.

# **Synopsis**

```
namespace boost {
  class bad_weak_ptr: public std::exception;
  template < class T > class weak ptr;
  template<class T> class shared_ptr {
    public:
       typedef see below element type;
       shared ptr(); // never throws
       shared ptr(std::nullptr t); // never throws
       template<class Y> explicit <u>shared ptr(Y * p);</u>
       template \langle class Y, class D \rangle \frac{shared ptr}{} (Y * p, D d);
       template \langle class \ Y, \ class \ D, \ class \ A \rangle  shared ptr (Y * p, \ D \ d, \ A \ a);
       template<class D> shared ptr(std::nullptr_t p, D d);
template<class D, class A> shared ptr(std::nullptr_t p, D d, A a);
       <u>shared ptr</u>(); // never throws
       shared_ptr (shared_ptr const & r); // never throws
       template < class Y > shared ptr (shared ptr < Y > const & r); // never throws
       shared_ptr (shared_ptr && r); // never throws
       template < class Y > shared ptr (shared_ptr < Y > && r); // never throws
       template < class Y > shared ptr (shared ptr < Y > const & r, element type * p); // never throws
       template < class Y > explicit shared ptr (weak ptr < Y > const & r);
       template < class Y > explicit shared ptr(std::auto_ptr < Y > & r);
       template<class Y> shared ptr(std::auto_ptr<Y> && r);
       template < class Y, class D> <a href="mailto:shared_ptr">shared_ptr</a> (std::unique_ptr<Y, D> && r);
       shared_ptr & operator=(shared_ptr const & r); // never throws
       template\langle class \ Y \rangle shared_ptr & operator=(shared_ptr\langle Y \rangle const & r); // never throws
       shared\_ptr \ \& \ \underline{operator=}(shared\_ptr \ const \ \&\& \ r); \ // \ never \ throws
       template < class Y > shared ptr & operator = (shared ptr < Y > const && r); // never throws
       template < class Y > shared_ptr & operator = (std::auto_ptr < Y > & r);
       template < class Y > shared_ptr & operator = (std::auto_ptr < Y > && r);
       template<class Y, class D> shared_ptr & operator=(std::unique_ptr<Y, D> && r);
       shared_ptr & operator=(std::nullptr_t); // never throws
       void <u>reset(); // never throws</u>
       template < class Y > void <u>reset</u> (Y * p);
       template <class Y, class D> void reset(Y * p, D d);
       template \langle class Y, class D, class A \rangle void \underline{reset}(Y * p, D d, A a);
```

```
template < class Y > void reset (shared ptr < Y > const & r, element type * p); // never throws
    T & operator*() const; // never throws; only valid when T is not an array type
    T * operator \rightarrow () const; // never throws; only valid when T is not an array type
    element_type & operator[](std::ptrdiff_t i) const; // never throws; only valid when T is an ar
    element_type * get() const; // never throws
    bool <u>unique</u>() const; // never throws
    long <u>use count</u>() const; // never throws
    explicit operator bool() const; // never throws
    void <u>swap</u>(shared_ptr & b); // never throws
    template<class Y> bool owner before (shared_ptr<Y> const & rhs) const; // never throws
    template<class Y> bool owner before (weak_ptr<Y> const & rhs) const; // never throws
};
template <class T, class U>
  bool operator== (shared_ptrT const & a, shared_ptrU const & b); // never throws
template < class T, class U>
  bool operator!=(shared ptr<T> const & a, shared ptr<U> const & b); // never throws
template < class T, class U>
  bool operator (shared_ptr T const & a, shared_ptr U const & b); // never throws
template < class T>
  bool operator == (shared_ptr <T > const & p, std::nullptr_t); // never throws
template < class T>
  bool operator == (std::nullptr_t, shared_ptr <T> const & p); // never throws
template < class T>
  bool operator!=(shared_ptr<T> const & p, std::nullptr_t); // never throws
template < class T>
  bool operator!=(std::nullptr_t, shared_ptr<T> const & p); // never throws
template < class T > void swap(shared_ptr<T > & a, shared_ptr<T > & b); // never throws
template \langle \text{class T} \rangle typename shared ptr\langle \text{T} \rangle::element type * get pointer (shared ptr\langle \text{T} \rangle const & p); // 1
template < class T, class U>
  shared ptr<T> static pointer cast (shared ptr<U> const & r); // never throws
template < class T, class U>
  shared\_ptr\langle T \rangle \xrightarrow{const} \xrightarrow{pointer} \xrightarrow{cast} (shared\_ptr\langle U \rangle \ const \ \& \ r) \ ; \ // \ never \ throws
template < class T, class U>
  shared ptr<T> dynamic pointer cast(shared ptr<U> const & r); // never throws
template < class T, class U>
  shared ptr<T> reinterpet pointer cast (shared ptr<U> const & r); // never throws
template < class E, class T, class Y>
  std::basic_ostream<E, T> & operator<< (std::basic_ostream<E, T> & os, shared_ptr<Y> const & p);
template <class D, class T>
  D * get deleter (shared ptr<T> const & p);
```

## **Members**

## element type

```
typedef ... element_type;
element type is T when T is not an array type, and U when T is U[] or U[N].
```

#### default constructor

```
shared_ptr(); // never throws
shared_ptr(std::nullptr_t); // never throws
```

**Effects:** Constructs an *empty* shared\_ptr.

Postconditions: use\_count() == 0 && get() == 0.

Throws: nothing.

[The nothrow guarantee is important, since reset() is specified in terms of the default constructor; this implies that the constructor must not allocate memory.]

## pointer constructor

```
template<class Y> explicit shared_ptr(Y * p);
```

**Requirements:** Y must be a complete type. The expression delete[] p, when T is an array type, or delete[] p, when T is not an array type, must be well-formed, must not invoke undefined behavior, and must not throw exceptions. When T is U[N], Y (\*) [N] must be convertible to T\*; when T is U[], Y (\*) [] must be convertible to T\*; otherwise, Y\* must be convertible to T\*.

**Effects:** When T is not an array type, constructs a  $shared_ptr$  that *owns* the pointer p. Otherwise, constructs a  $shared_ptr$  that *owns* p and a deleter of an unspecified type that calls delete[] p.

**Postconditions:**  $use\_count() == 1 \&\& get() == p$ . If T is not an array type and p is unambiguously convertible to  $\underline{enable \ shared \ from \ this} < V > * for some V, p - > shared\_from\_this() returns a copy of *this.$ 

**Throws:** std::bad\_alloc, or an implementation-defined exception when a resource other than memory could not be obtained.

**Exception safety:** If an exception is thrown, the constructor calls delete[] p, when T is an array type, or delete[] p, when T is not an array type.

**Notes:** p must be a pointer to an object that was allocated via a C++ new expression or be 0. The postcondition that <u>use count</u> is 1 holds even if p is 0; invoking delete on a pointer that has a value of 0 is harmless.

[This constructor is a template in order to remember the actual pointer type passed. The destructor will call delete with the same pointer, complete with its original type, even when T does not have a virtual destructor, or is void.]

## constructors taking a deleter

```
template<class Y, class D> shared_ptr(Y * p, D d);
template<class Y, class D, class A> shared_ptr(Y * p, D d, A a);
template<class D> shared_ptr(std::nullptr_t p, D d);
template<class D, class A> shared_ptr(std::nullptr_t p, D d, A a);
```

**Requirements:** D must be CopyConstructible. The copy constructor and destructor of D must not throw. The expression d(p) must be well-formed, must not invoke undefined behavior, and must not throw exceptions. A must be an *Allocator*, as described in section 20.1.5 (Allocator requirements) of the C++ Standard. When T is U[N], Y (\*) [N] must be convertible to T\*; when T is U[T], Y (\*) [I] must be convertible to T\*; otherwise, Y\* must be convertible to T\*.

**Effects:** Constructs a shared\_ptr that *owns* the pointer p and the deleter d. The constructors taking an allocator a allocate memory using a copy of a.

```
Postconditions: use_count() == 1 && get() == p. If T is not an array type and p is unambiguously convertible to enable shared from thisconvertible to enable shared from thiscopy of *this.
```

**Throws:** std::bad\_alloc, or an implementation-defined exception when a resource other than memory could not be obtained.

**Exception safety:** If an exception is thrown, d(p) is called.

**Notes:** When the time comes to delete the object pointed to by p, the stored copy of d is invoked with the stored copy of d as an argument.

[Custom deallocators allow a factory function returning a shared\_ptr to insulate the user from its memory allocation strategy. Since the deallocator is not part of the type, changing the allocation strategy does not break source or binary compatibility, and does not require a client recompilation. For example, a "no-op" deallocator is useful when returning a shared\_ptr to a statically allocated object, and other variations allow a shared\_ptr to be used as a wrapper for another smart pointer, easing interoperability.

The support for custom deallocators does not impose significant overhead. Other shared\_ptr features still require a deallocator to be kept.

The requirement that the copy constructor of D does not throw comes from the pass by value. If the copy constructor throws, the pointer would leak.]

## copy and converting constructors

```
shared_ptr(shared_ptr const & r); // never throws
template<class Y> shared_ptr(shared_ptr<Y> const & r); // never throws
```

**Requires:** Y\* should be convertible to T\*.

**Effects:** If r is *empty*, constructs an *empty* shared\_ptr; otherwise, constructs a shared\_ptr that *shares ownership* with r.

```
Postconditions: get() == r.get() && use_count() == r.use_count().
```

#### move constructors

```
shared_ptr(shared_ptr && r); // never throws
template<class Y> shared ptr(shared ptr<Y> && r); // never throws
```

**Requires:** Y\* should be convertible to T\*.

**Effects:** Move-constructs a shared ptr from r.

**Postconditions:** \*this contains the old value of r. r is *empty* and r. get () == 0.

Throws: nothing.

## aliasing constructor

```
template < class \ Y > \ shared\_ptr(shared\_ptr < Y > \ const \ \& \ r, \ element\_type \ * \ p); \ // \ never \ throws
```

**Effects:** constructs a shared\_ptr that *shares ownership* with r and stores p.

Postconditions: get() == p && use\_count() == r.use\_count().

Throws: nothing.

# weak\_ptr constructor

```
template<class Y> explicit shared ptr(weak ptr<Y> const & r);
```

**Requires:** Y\* should be convertible to T\*.

**Effects:** Constructs a  $shared_ptr$  that *shares ownership* with r and stores a copy of the pointer stored in r.

**Postconditions:** use count() == r. use count().

Throws: bad weak ptr when r. use count () == 0.

**Exception safety:** If an exception is thrown, the constructor has no effect.

## auto\_ptr constructors

```
template<class Y> shared_ptr(std::auto_ptr<Y> & r);
template<class Y> shared_ptr(std::auto_ptr<Y> && r);
```

**Requires:** Y\* should be convertible to T\*.

**Effects:** Constructs a shared\_ptr, as if by storing a copy of r. release().

**Postconditions:** use count() == 1.

**Throws:** std::bad\_alloc, or an implementation-defined exception when a resource other than memory could not be obtained.

**Exception safety:** If an exception is thrown, the constructor has no effect.

# unique\_ptr constructor

```
template < class Y, class D> shared_ptr(std::unique_ptr < Y, D> && r);
```

**Requires:** Y\* should be convertible to T\*.

**Effects:** Equivalent to  $shared_ptr(r.release(), r.get_deleter())$  when D is not a reference type. Otherwise, equivalent to  $shared_ptr(r.release(), del)$ , where *del* is a deleter that stores the reference rd returned from r.get\_deleter() and del(p) calls rd(p).

```
Postconditions: use count() == 1.
```

**Throws:** std::bad\_alloc, or an implementation-defined exception when a resource other than memory could not be obtained.

**Exception safety:** If an exception is thrown, the constructor has no effect.

#### destructor

```
~shared_ptr(); // never throws
```

#### **Effects:**

- If \*this is *empty*, or *shares ownership* with another shared\_ptr instance (use count() > 1), there are no side effects.
- Otherwise, if \*this owns a pointer p and a deleter d, d(p) is called.
- Otherwise, \*this owns a pointer p, and delete p is called.

**Throws:** nothing.

## assignment

```
shared_ptr & operator=(shared_ptr const & r); // never throws
template<class Y> shared_ptr & operator=(shared_ptr<Y> const & r); // never throws
template<class Y> shared_ptr & operator=(std::auto_ptr<Y> & r);
```

**Effects:** Equivalent to shared\_ptr(r). swap(\*this).

**Returns:** \*this.

**Notes:** The use count updates caused by the temporary object construction and destruction are not considered observable side effects, and the implementation is free to meet the effects (and the implied guarantees) via different means, without creating a temporary. In particular, in the example:

```
shared_ptr<int> p(new int);
shared_ptr<void> q(p);
p = p;
q = p;
```

both assignments may be no-ops.

```
shared\_ptr \& operator=(shared\_ptr \&\& r); // never throws \\ template < class Y> shared\_ptr \& operator=(shared\_ptr < Y> \&\& r); // never throws \\ template < class Y> shared\_ptr & operator=(std::auto\_ptr < Y> &\& r); \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ \\ template < class Y, class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ template < class Y, class D> shared\_ptr & operator=(std::unique\_ptr < Y, D> && r); \\ template < class Y, class Y,
```

**Effects:** Equivalent to  $shared_ptr(std::move(r)).swap(*this)$ .

```
Returns: *this.
shared ptr & operator=(std::nullptr t); // never throws
     Effects: Equivalent to shared_ptr().swap(*this).
     Returns: *this.
reset
void reset(); // never throws
     Effects: Equivalent to shared_ptr(). swap(*this).
template<class Y> void reset(Y * p);
     Effects: Equivalent to shared_ptr(p). swap(*this).
template<class Y, class D> void reset(Y * p, D d);
     Effects: Equivalent to shared_ptr(p, d). swap(*this).
template < class Y, class D, class A> void reset(Y * p, D d, A a);
     Effects: Equivalent to shared_ptr(p, d, a). swap(*this).
template<class Y> void reset(shared_ptr<Y> const & r, element_type * p); // never throws
     Effects: Equivalent to shared_ptr(r, p).swap(*this).
indirection
T & operator*() const; // never throws
     Requirements: T should not be an array type. The stored pointer must not be 0.
     Returns: a reference to the object pointed to by the stored pointer.
     Throws: nothing.
T * operator->() const; // never throws
     Requirements: T should not be an array type. The stored pointer must not be 0.
     Returns: the stored pointer.
     Throws: nothing.
element_type & operator[](std::ptrdiff_t i) const; // never throws
     Requirements: T should be an array type. The stored pointer must not be 0. i \ge 0
     0. If T is U[N], i < N.
     Returns: get()[i].
```

### get

```
element_type * get() const; // never throws
```

**Returns:** the stored pointer.

**Throws:** nothing.

## unique

```
bool unique() const; // never throws
```

Returns: use count() == 1.

Throws: nothing.

**Notes:** unique() may be faster than use\_count(). If you are using unique() to implement copy on write, do not rely on a specific value when the stored pointer is zero.

### use count

```
long use_count() const; // never throws
```

**Returns:** the number of shared\_ptr objects, \*this included, that *share ownership* with \*this, or 0 when \*this is *empty*.

Throws: nothing.

**Notes:** use\_count() is not necessarily efficient. Use only for debugging and testing purposes, not for production code.

#### conversions

```
explicit operator bool() const; // never throws
```

**Returns:** get() != 0.

**Throws:** nothing.

**Notes:** This conversion operator allows shared\_ptr objects to be used in boolean contexts, like if (p && p->valid()) {}.

[The conversion to bool is not merely syntactic sugar. It allows shared\_ptrs to be declared in conditions when using <u>dynamic\_pointer\_cast</u> or <u>weak\_ptr::lock.</u>]

### swap

```
void swap(shared_ptr & b); // never throws
```

**Effects:** Exchanges the contents of the two smart pointers.

#### swap

```
template<class Y> bool owner_before(shared_ptr<Y> const & rhs) const; // never throws template<class Y> bool owner_before(weak_ptr<Y> const & rhs) const; // never throws
```

**Effects:** See the description of operator.

Throws: nothing.

# **Free Functions**

## comparison

```
template < class T, class U>
 bool operator == (shared_ptr <T > const & a, shared_ptr <U > const & b); // never throws
     Returns: a. get() == b. get().
     Throws: nothing.
template <class T, class U>
 bool operator!=(shared_ptrT const & a, shared_ptrU const & b); // never throws
     Returns: a. get() != b. get().
     Throws: nothing.
template < class T>
 bool\ operator == (shared\_ptr < T > const \& p, std::nullptr\_t); // \ never \ throws
template < class T>
 bool operator==(std::nullptr_t, shared_ptr<T> const & p); // never throws
     Returns: p. get() == 0.
     Throws: nothing.
template < class T>
 bool operator!=(shared ptr<T> const & p, std::nullptr t); // never throws
template < class T>
 bool operator!=(std::nullptr t, shared ptr<T> const & p); // never throws
     Returns: p. get() != 0.
     Throws: nothing.
template < class T, class U>
 bool operator (shared ptr <T > const & a, shared ptr <U > const & b); // never throws
```

### Returns: an unspecified value such that

- operator< is a strict weak ordering as described in section 25.3</li>
   [lib. alg. sorting] of the C++ standard;
- under the equivalence relation defined by <code>operator<</code>, <code>!(a < b) && !(b < a)</code>, two <code>shared\_ptr</code> instances are equivalent if and only if they share ownership or are both empty.

**Notes:** Allows shared\_ptr objects to be used as keys in associative containers.

[Operator< has been preferred over a std::less specialization for consistency and legality reasons, as std::less is required to return the results of operator<, and many standard algorithms use operator< instead of std::less for comparisons when a predicate is not supplied. Composite objects, like std::pair, also implement their operator< in terms of their contained subobjects' operator<.

The rest of the comparison operators are omitted by design.]

### swap

```
template<class T>
  void swap(shared_ptr<T> & a, shared_ptr<T> & b); // never throws

Effects: Equivalent to a. swap(b).
```

Throws: nothing.

**Notes:** Matches the interface of std::swap. Provided as an aid to generic programming.

[swap is defined in the same namespace as shared\_ptr as this is currently the only legal way to supply a swap function that has a chance to be used by the standard library.]

## get\_pointer

```
template<class T>
    typename shared_ptr<T>::element_type * get_pointer(shared_ptr<T> const & p); // never throws

Returns: p. get().

Throws: nothing.
```

**Notes:** Provided as an aid to generic programming. Used by <u>mem\_fn</u>.

## static\_pointer\_cast

```
template<class T, class U>
    shared_ptr<T> static_pointer_cast(shared_ptr<U> const & r); // never throws

Requires: The expression static_cast<T*>( (U*)0 ) must be well-formed.

Returns: shared_ptr<T>( r, static_cast<typename shared_ptr<T>::element_type*>(r.get())
).

Throws: nothing.
```

**Notes:** the seemingly equivalent expression <code>shared\_ptr<T>(static\_cast<T\*>(r.get()))</code> will eventually result in undefined behavior, attempting to delete the same object twice.

## const\_pointer\_cast

```
template < class T, class U>
    shared_ptr<T> const_pointer_cast(shared_ptr<U> const & r); // never throws

Requires: The expression const_cast<T*>( (U*)0 ) must be well-formed.

Returns: shared_ptr<T>( r, const_cast<typename shared_ptr<T>::element_type*>(r.get())
).

Throws: nothing.
```

## dynamic\_pointer\_cast

```
template < class T, class U>
    shared_ptr < T> dynamic_pointer_cast (shared_ptr < U> const & r);
```

**Requires:** The expression dynamic\_cast<T\*>( (U\*)0 ) must be well-formed.

#### **Returns:**

- When dynamic\_cast<typename shared\_ptr<T>::element\_type\*>(r.get()) returns a nonzero value p, shared\_ptr<T>(r, p);
- Otherwise, shared ptr<T>().

Throws: nothing.

## reinterpret pointer cast

```
\label{template} $$ \ensuremath{\mathsf{template}}$ \ensuremath{\mathsf{class}}$ $\mathsf{U}$ shared_ptr<T> reinterpret_pointer_cast(shared_ptr<U> const & r); // never throws $$ \ensuremath{\mathsf{emplate}}$ $$ $\mathsf{U}$ $\mathsf{U}$ $$ $\mathsf{U}$ $\mathsf{U}$ $$ $\mathsf{U}$ $\mathsf{U}$ $$ $\mathsf{U}$ $\mathsf{U}
```

**Requires:** The expression reinterpret\_cast<T\*>( (U\*)0 ) must be well-formed.

```
Returns: shared_ptr<T>( r, reinterpret_cast<typename shared_ptr<T>::element_type*> (r.get()) ).
```

Throws: nothing.

## operator<<

```
template < class E, class T, class Y>
    std::basic_ostream < E, T > & operator << (std::basic_ostream < E, T > & os, shared_ptr < Y > const & p);

Effects: os << p.get();.

Returns: os.</pre>
```

## get\_deleter

```
template<class D, class T>
    D * get_deleter(shared_ptr<T> const & p);
```

**Returns:** If \*this *owns* a deleter d of type (cv-unqualified) D, returns &d; otherwise returns 0.

# **Example**

See <u>shared\_ptr\_example.cpp</u> for a complete example program. The program builds a std::vector and std::set of shared\_ptr objects.

Note that after the containers have been populated, some of the <code>shared\_ptr</code> objects will have a use count of 1 rather than a use count of 2, since the set is a <code>std::set</code> rather than a <code>std::multiset</code>, and thus does not contain duplicate entries. Furthermore, the use count may be even higher at various times while <code>push\_back</code> and <code>insert</code> container operations are performed. More complicated yet, the container operations may throw exceptions under a variety of circumstances. Getting the memory management and exception handling in this example right without a smart pointer would be a nightmare.

# **Handle/Body Idiom**

One common usage of shared\_ptr is to implement a handle/body (also called pimpl) idiom which avoids exposing the body (implementation) in the header file.

The <u>shared\_ptr\_example2\_test.cpp</u> sample program includes a header file, <u>shared\_ptr\_example2.hpp</u>, which uses a <u>shared\_ptr</u> to an incomplete type to hide the implementation. The instantiation of member functions which require a complete type occurs in the <u>shared\_ptr\_example2.cpp</u> implementation file. Note that there is no need for an explicit destructor. Unlike <u>scoped\_ptr</u>, <u>shared\_ptr\_does not require that T be a complete type</u>.

# **Thread Safety**

shared\_ptr objects offer the same level of thread safety as built-in types. A shared\_ptr instance can be "read" (accessed using only const operations) simultaneously by multiple threads. Different shared\_ptr instances can be "written to" (accessed using mutable operations such as operator= or reset) simultaneously by multiple threads (even when these instances are copies, and share the same reference count underneath.)

Any other simultaneous accesses result in undefined behavior.

#### Examples:

```
shared_ptr<int> p(new int(42));
//--- Example 1 ---

// thread A
shared_ptr<int> p2(p); // reads p

// thread B
shared_ptr<int> p3(p); // OK, multiple reads are safe

//--- Example 2 ---

// thread A
p. reset(new int(1912)); // writes p

// thread B
p2.reset(); // OK, writes p2
```

```
//--- Example 3 ---
// thread A
p = p3; // reads p3, writes p

// thread B
p3.reset(); // writes p3; undefined, simultaneous read/write

//--- Example 4 ---

// thread A
p3 = p2; // reads p2, writes p3

// thread B
// p2 goes out of scope: undefined, the destructor is considered a "write access"

//--- Example 5 ---

// thread A
p3.reset(new int(1));

// thread B
p3.reset(new int(2)); // undefined, multiple writes
```

Starting with Boost release 1.33.0, shared\_ptr uses a lock-free implementation on most common platforms.

If your program is single-threaded and does not link to any libraries that might have used shared\_ptr in its default configuration, you can #define the macro BOOST\_SP\_DISABLE\_THREADS on a project-wide basis to switch to ordinary non-atomic reference count updates.

(Defining BOOST\_SP\_DISABLE\_THREADS in some, but not all, translation units is technically a violation of the One Definition Rule and undefined behavior. Nevertheless, the implementation attempts to do its best to accommodate the request to use non-atomic updates in those translation units. No guarantees, though.)

You can define the macro BOOST\_SP\_USE\_PTHREADS to turn off the lock-free platform-specific implementation and fall back to the generic pthread\_mutex\_t-based code.

# **Frequently Asked Questions**

- **Q.** There are several variations of shared pointers, with different tradeoffs; why does the smart pointer library supply only a single implementation? It would be useful to be able to experiment with each type so as to find the most suitable for the job at hand?
- **A.** An important goal of <code>shared\_ptr</code> is to provide a standard shared-ownership pointer. Having a single pointer type is important for stable library interfaces, since different shared pointers typically cannot interoperate, i.e. a reference counted pointer (used by library A) cannot share ownership with a linked pointer (used by library B.)
- **Q.** Why doesn't shared\_ptr have template parameters supplying traits or policies to allow extensive user customization?
- **A.** Parameterization discourages users. The shared\_ptr template is carefully crafted to meet common needs without extensive parameterization. Some day a highly configurable smart

pointer may be invented that is also very easy to use and very hard to misuse. Until then, shared\_ptr is the smart pointer of choice for a wide range of applications. (Those interested in policy based smart pointers should read Modern C++ Design by Andrei Alexandrescu.)

- **Q.** I am not convinced. Default parameters can be used where appropriate to hide the complexity. Again, why not policies?
- **A.** Template parameters affect the type. See the answer to the first question above.
- **Q.** Why doesn't shared\_ptr use a linked list implementation?
- **A.** A linked list implementation does not offer enough advantages to offset the added cost of an extra pointer. See <u>timings</u> page. In addition, it is expensive to make a linked list implementation thread safe.
- **Q.** Why doesn't shared\_ptr (or any of the other Boost smart pointers) supply an automatic conversion to T\*?
- **A.** Automatic conversion is believed to be too error prone.
- **Q.** Why does shared\_ptr supply use\_count()?
- **A.** As an aid to writing test cases and debugging displays. One of the progenitors had use\_count(), and it was useful in tracking down bugs in a complex project that turned out to have cyclic-dependencies.
- **Q.** Why doesn't shared\_ptr specify complexity requirements?
- **A.** Because complexity requirements limit implementors and complicate the specification without apparent benefit to shared\_ptr users. For example, error-checking implementations might become non-conforming if they had to meet stringent complexity requirements.
- **Q.** Why doesn't shared\_ptr provide a release() function?
- **A.** shared\_ptr cannot give away ownership unless it's unique() because the other copy will still destroy the object.

#### Consider:

```
shared_ptr<int> a(new int);
shared_ptr<int> b(a); // a.use_count() == b.use_count() == 2
int * p = a.release();
// Who owns p now? b will still call delete on it in its destructor.
```

Furthermore, the pointer returned by release() would be difficult to deallocate reliably, as the source shared\_ptr could have been created with a custom deleter.

- **Q.** Why is operator->() const, but its return value is a non-const pointer to the element type?
- **A.** Shallow copy pointers, including raw pointers, typically don't propagate constness. It makes little sense for them to do so, as you can always obtain a non-const pointer from a const one and then proceed to modify the object through it. shared\_ptr is "as close to raw pointers as possible but no closer".

## \$Date\$

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