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Progress report week 46

This week we have focused on assignment 3. Everything started good until we couldn't get the robot to find the goal after it found the ball. We had a submachine to another submachine. The problem that occurred was that the robot looped between unwanted submachines. We solved this problem by making the submachine to a submachine for the mainFSM instead. We now have one problem left in assignment three that we cannot fix. We have asked for help and the assistant will look into the problem since it is probably a problem that we cannot fix. The problem is that the robot can't detect a goal, especially the goal type "center". The assistant will look into the problem over the weekend if he finds time for it. For now we will continue with assignment four. This will be in our focus the coming sessions.