

# Movement for Gaming

From Chapter 3 “Artificial Intelligence for  
Games”  
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Dijkstra 알고리즘은 O(N^2) longest path 찾기

$G \Rightarrow -G$

예) minimum (path to n1, path to n2 + dist)

path finding  $\Rightarrow$  finding algorithm

Dijkstra's algorithm

A star algorithm \*\*\*

$\Rightarrow$  heuristic algorithm 사용

각 edge에 negative weight (case)가 존재하면  
shortest (minimum case) path 찾기 불가

movement  
path finding

free movement (seek flee wander jump)

steering algorithm

decision making

# Basics

- Characters in games usually move
  - Movement calculation often needs to interact with the "Physics" engine
    - Avoid characters walking through each other or through obstacles

Traditional:

- Characters simply move (often at fixed speed) without regard to how physical objects accelerate or brake

Newer approach:

- Characters accelerate and turn based on physics

# Relationship with Pathfinding

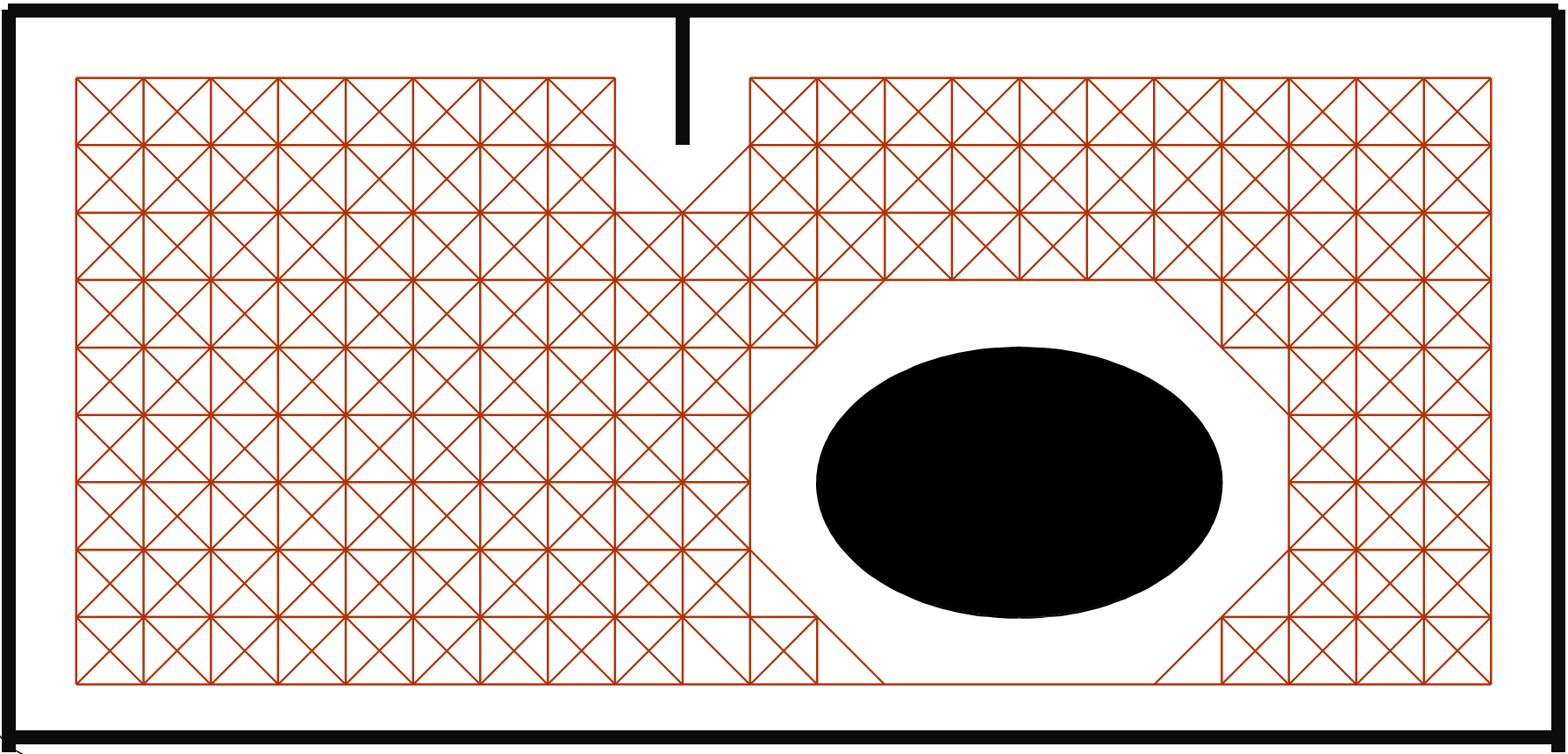
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## 설명 없음

# Relationship with Path Finding

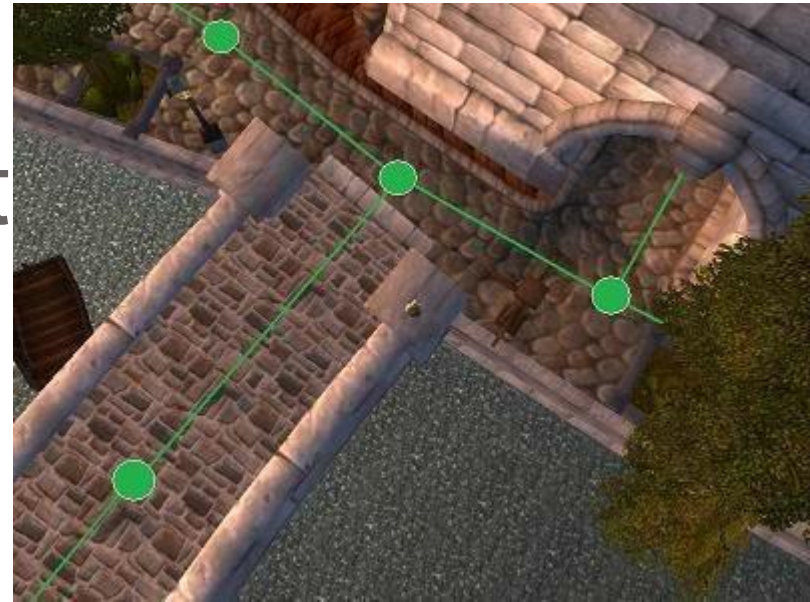
- Classical path finding moves the character along a path in a graph







Stormwind



Stormwind  
Way point graph



Convex polygons

# Way point graph



- Waypoint graphs are relatively easy to implement.
- Waypoint graphs are easy to modify if the changes are known ahead of time. For instance, if a door in the world closes and is locked, it is easy for the developer to mark the edges in the graph that cross the opening of the door and block them when the door is shut.
- Waypoint graphs represent only a small fraction of the points found in a grid. This sparse representation of walkable space is both cheap to store and leads to inexpensive path planning requests.

- Path quality can suffer if there are not enough walkable edges in the graph, but too many walkable edges will impact storage and planning complexity.
- Waypoint graphs may require manual placement of nodes to get good path quality.
- Localization on waypoint graphs requires mapping between game space and the graph. If a character is knocked off of the graph, it may be unclear where the character should actually be within the waypoint graph.
- Because there is no explicit representation of the underlying state space, smoothing off the waypoint graph can result in characters getting stuck on physics or other objects.
- Dynamic changes are difficult when they aren't known ahead of time. If a character can create an unexpected hole in a wall, new connections on the waypoint graph are needed.

# Navigation Mesh

- With the accurate representation of a polygon it is easier to correctly perform smoothing both before and during movement. This accuracy can also be used for tighter animation constraints.
- Path planning on navigation meshes is usually fast, as the representation of the world is fairly coarse. But, this does not impact path quality, as characters are free to walk at any angle.
- Navigation meshes are not as memory-intensive as grids as they can represent large spaces with just a few polygons.



- The time required to implement a navigation mesh is significant, although good open-source implementations are available [Mononen 11].
- Changes to navigation meshes can be difficult or expensive to implement, especially when contrasted with changes to grid worlds.





## Way points

WoW: Halaa



## Halaa (WoW)

Way points



# Halaa

Convex polygons





## Graph Smoothing

Please note that information is available on the graph





free movement

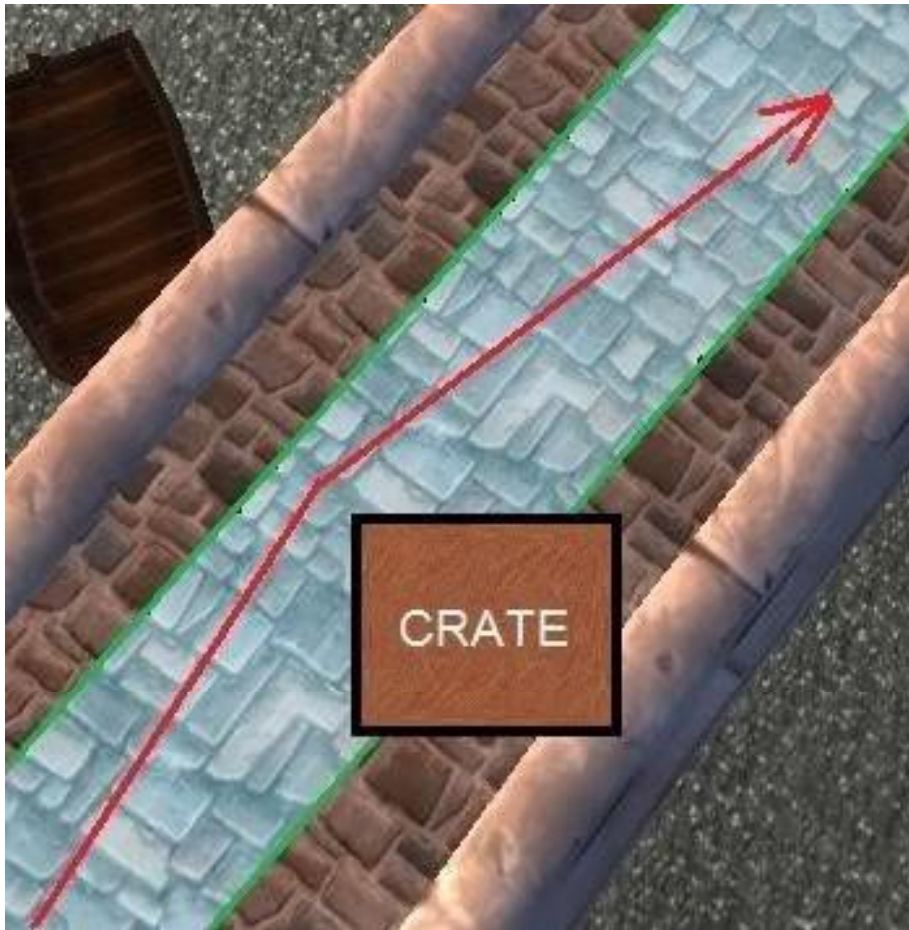
종류 Seek, flee, wander, pursue, jump  
 타겟을 향해  
 1 움직일 때  
 각각을  
 결정함.



Single, crowd movement (flock movement)  
 formation (로봇과 장애물 간에  
 형성 formation) 새끼들 같이 떼로 움직이는 것

Way points, with obstacle



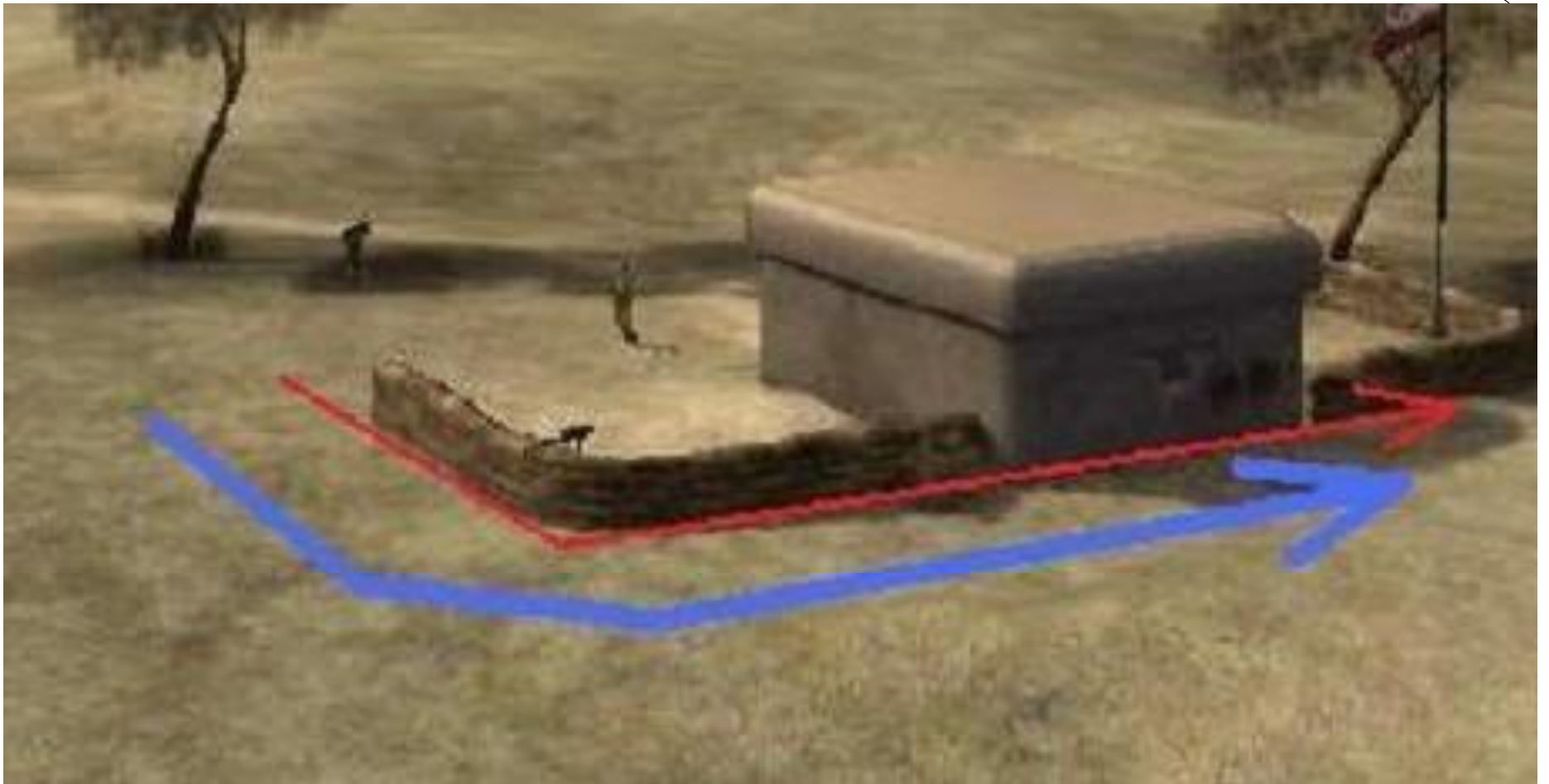


With convex polygons, one can put obstacles



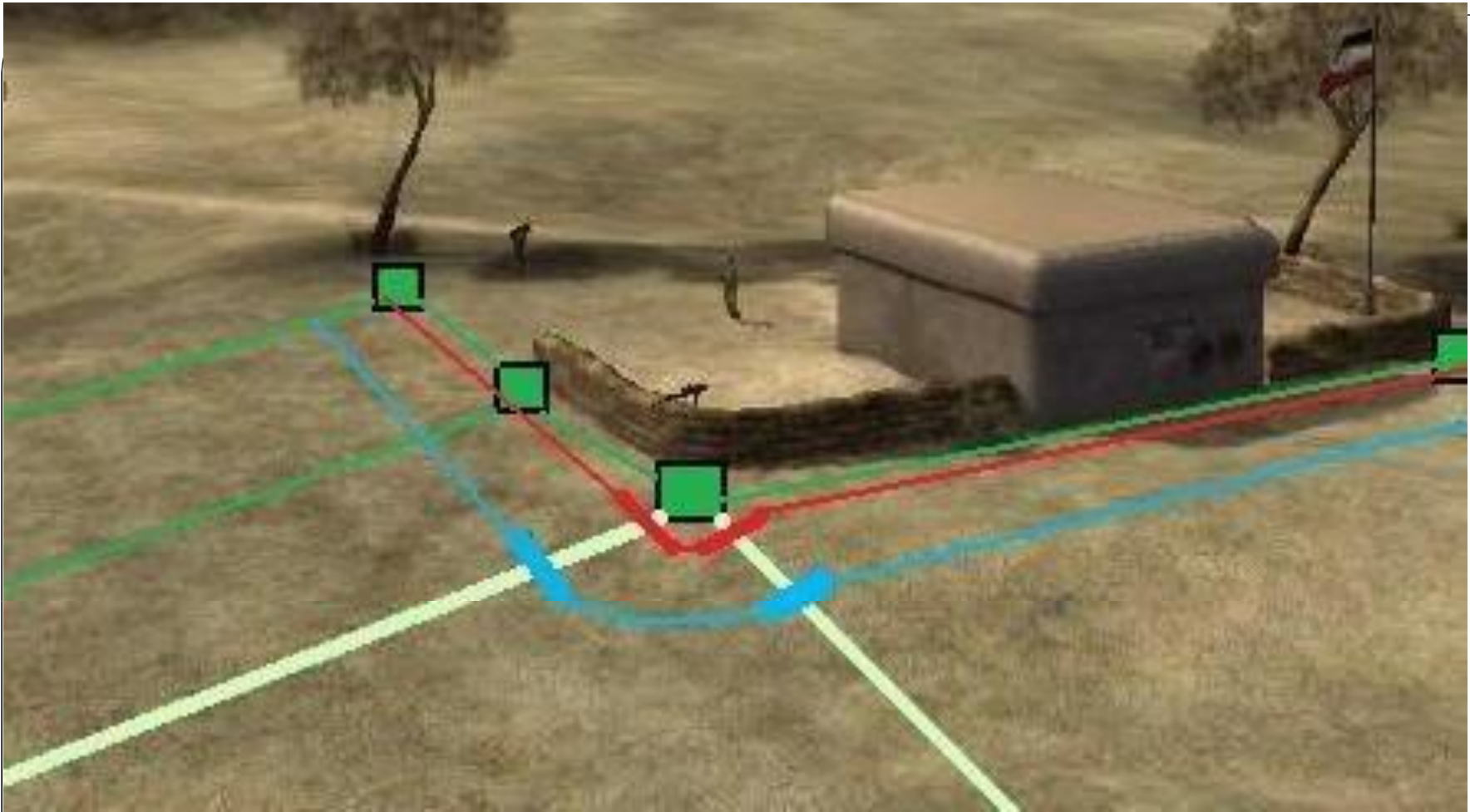
# Desert bunker





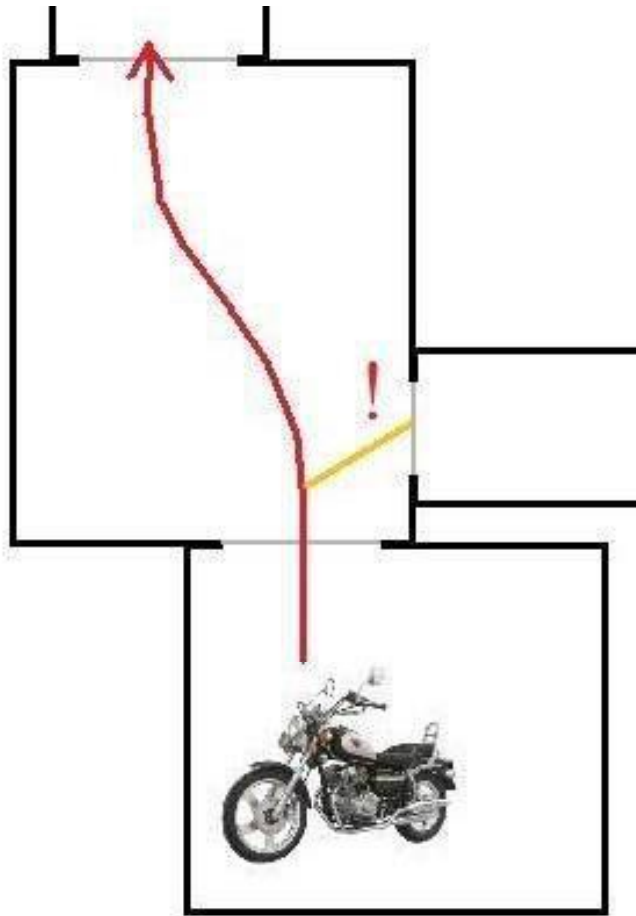
A soldier can move close to the sandbags  
A tank needs to take wider turns





Navigational mesh combined with movement





**Movement radius** is impossible to model  
with waypoint graph



## You can mark places

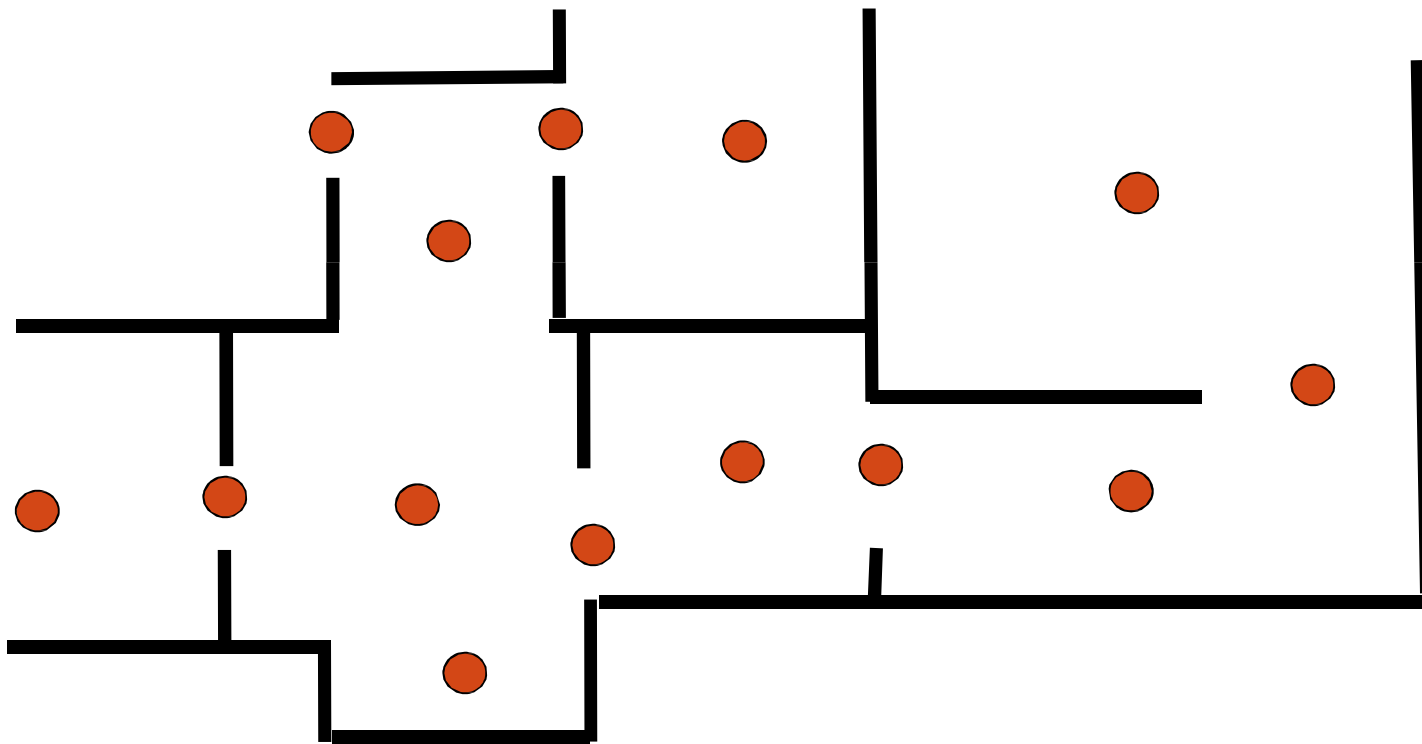
Use the navigational mesh for autonomous movement.

Use the points for scripted behavior



# Waypoint graph generation

- Wide approximation

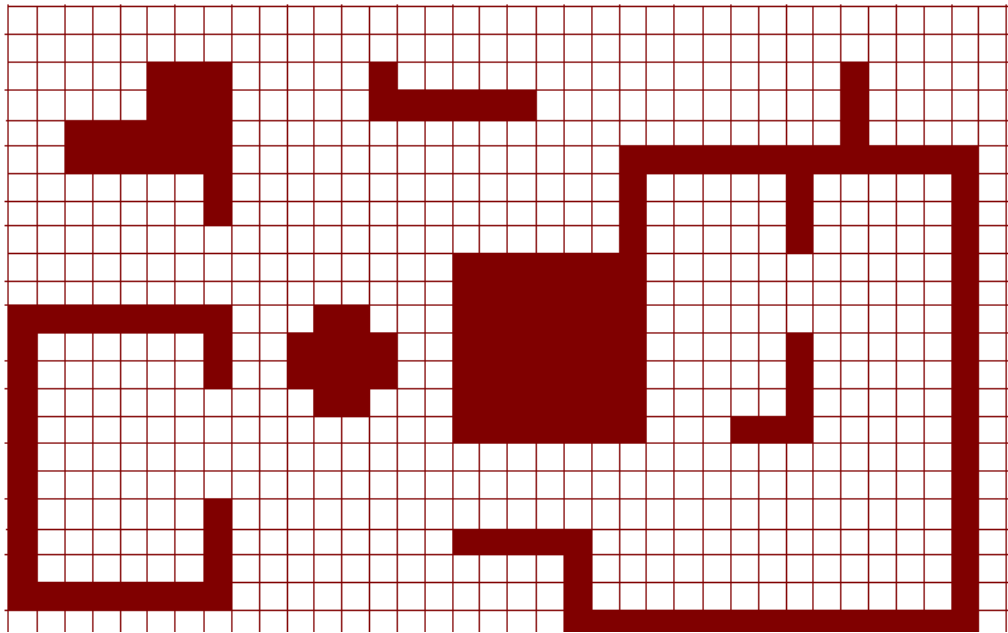






# Waypoint graph generation

- Automatic generation

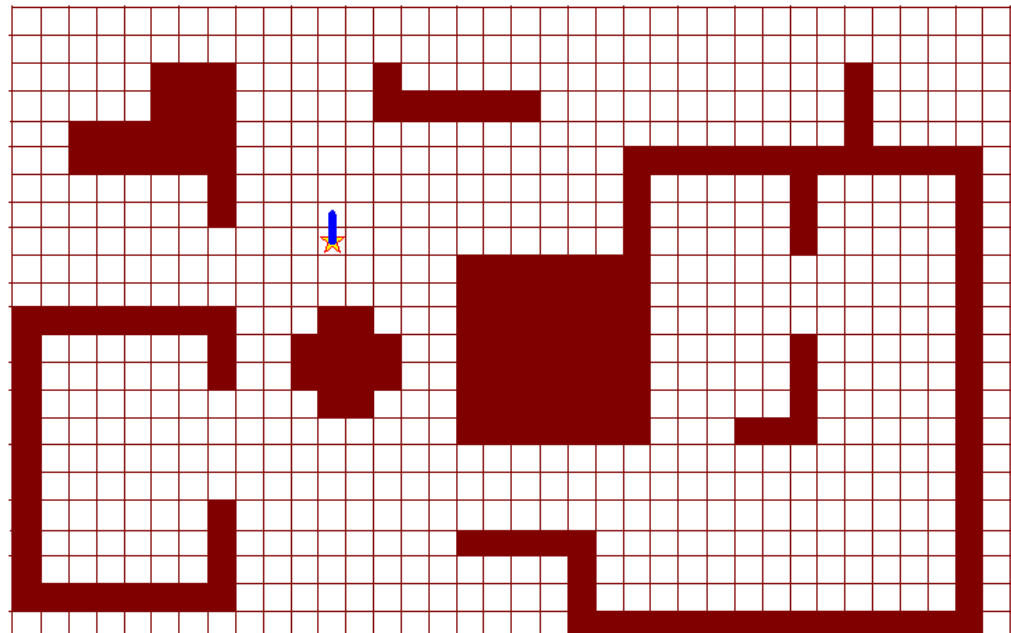


unfilled rectangle(cell)을 way point로 정의.  
인접한 waypoint들 사이를 edge로 연결



# Waypoint graph generation

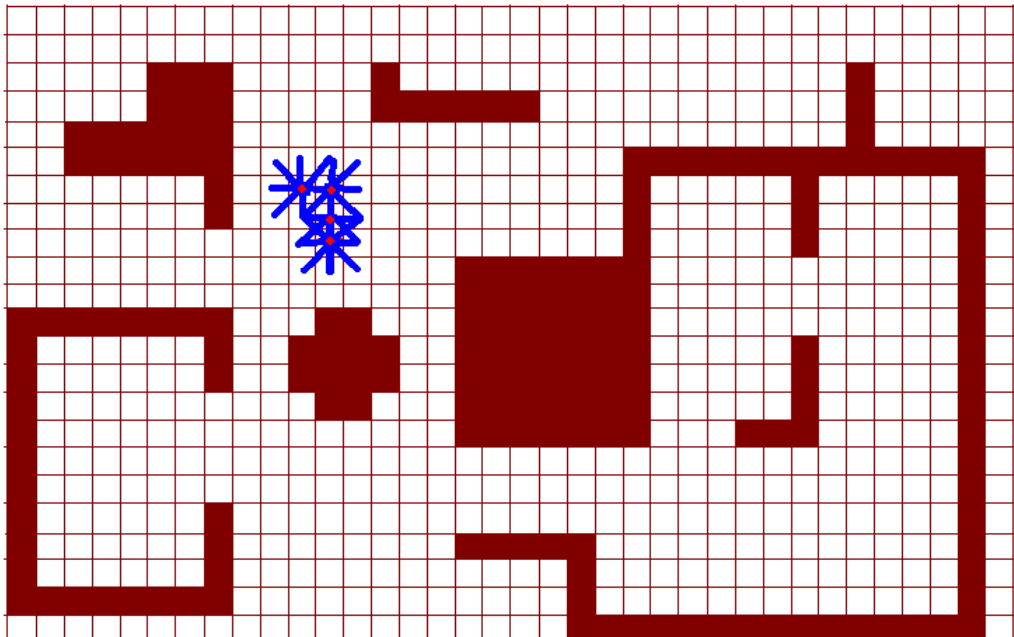
- Dense graph generation
  - Start at a point (unfilled rectangle)
  - Generate points in 4 (or eight directions) at unit distance



# Waypoint graph generation



- Automatic generation





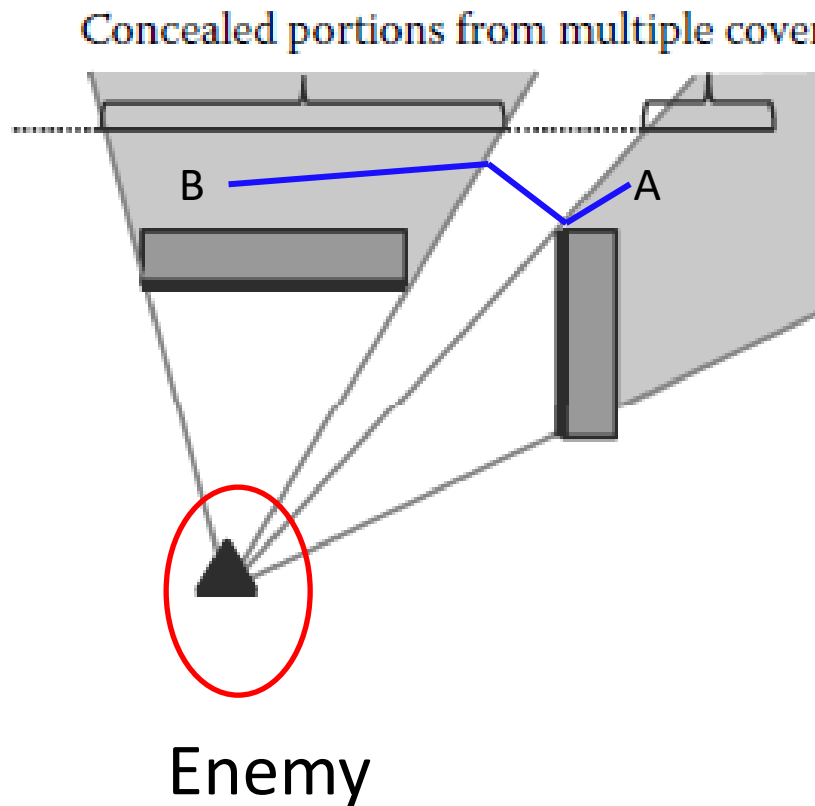
# Challenges

- Obstacles that can be overcome
  - Fords
  - Jumps



- Tactical Pathfinding (ex. safe paths)

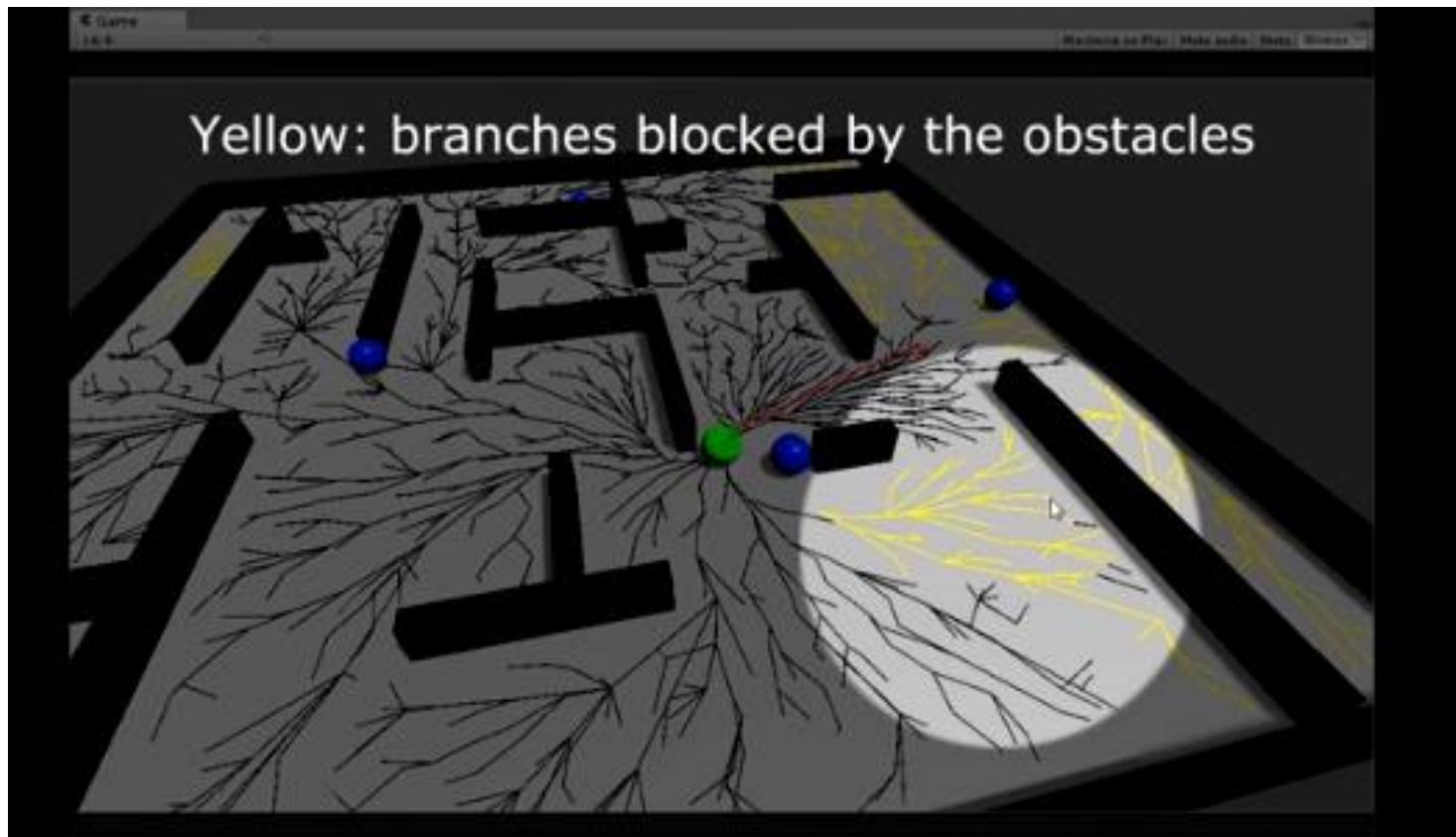
# Tactical Pathfinding for a safe path



총을 쏠 수  
있음

회색 영역은  
Enemy의 총격을  
피할 수 있는  
영역임.

- <https://www.youtube.com/watch?v=QLNSkFnBYuM>  
From a paper titled “ **RT-RRT\*: a real-time path planning algorithm based on RRT\*** ”



# 강의종료

다음 강의 주제는 'Free movement'



# Free movement

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