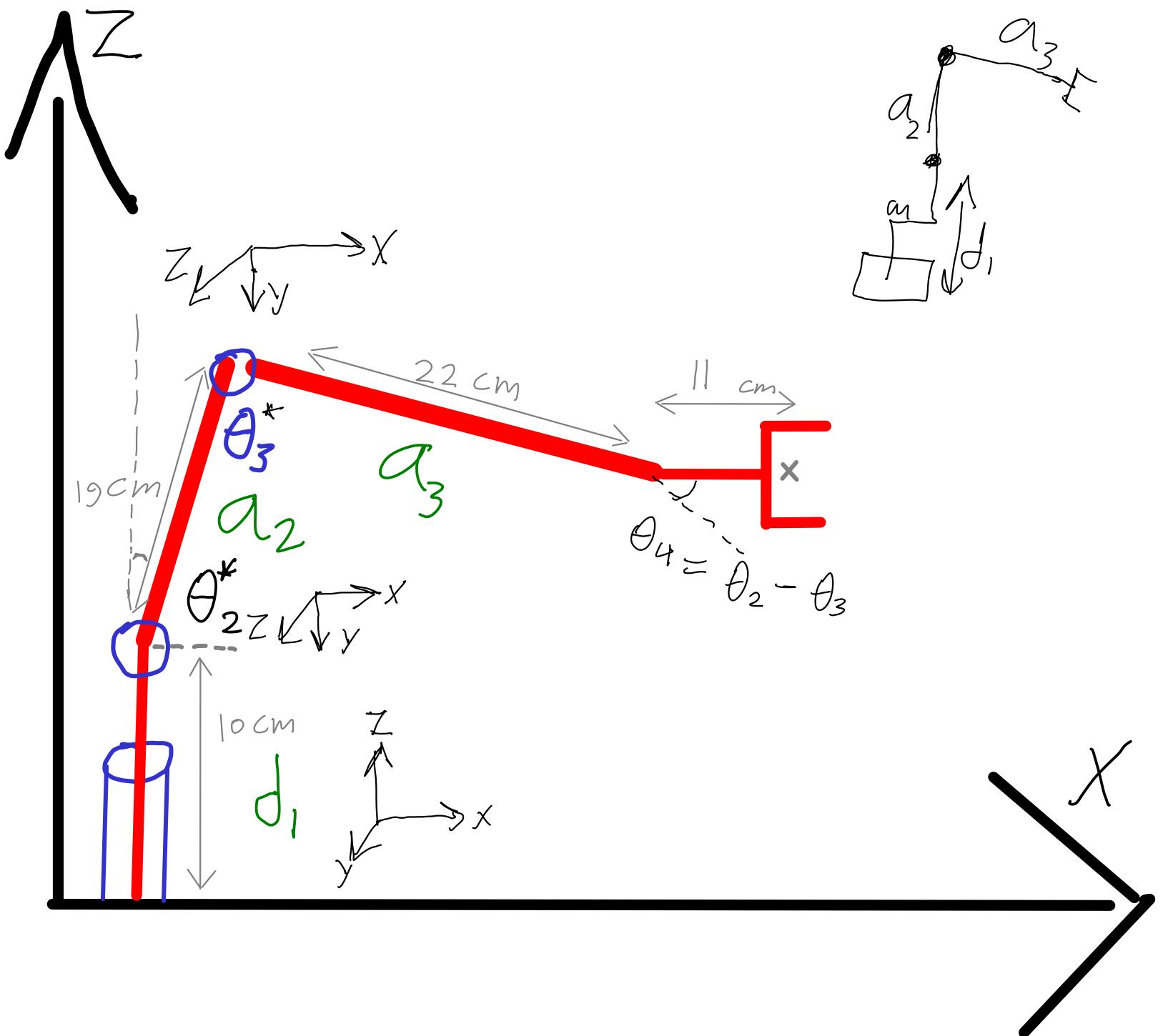


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MK2 Robot Arm Configuration - DH Parameters



Allowed Ranges for x y z according to
the plotted workspace;

$$X: 0 \rightarrow 36 \quad Y: -36 \rightarrow 36 \quad Z: 5 \rightarrow 25$$

DH Parameters:

```
anas@anas-asus-tuf:~$ rosrun mk2_arm mk2_gui.py
DHRobot: MK2 (by E-JUST), 3 joints (RRR), dynamics, standard DH parameters
```

θ_j	d_j	a_j	α_j	q^-	q^+
q_1	10	11	90.0°	-90.0°	90.0°
q_2	0	19	0.0°	40.0°	110.0°
q_3	0	22	0.0°	-90.0°	-30.0°

Calibration for angles.

