Training the FNO to Solve the 1D Wave Equation

In this exercise, you will train a model to approximate the solution of the 1D wave equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}, \quad t \in (0,1], \quad x \in [0,1], \quad c = 0.5$$

with boundary conditions

$$u(0,t) = u(1,t) = 0$$

and initial conditions

$$u(x,0) = u_0(x), \quad u_t(x,0) = 0$$

where u_t is the partial derivative with respect to time. Note that the initial conditions are sampled from an unknown distribution. Knowing the exact expression for u_0 is not necessary to complete the tasks below.

You should use a Fourier Neural Operator (FNO) for all the tasks.

Dataset Details

You are provided with the following datasets in this **folder**:

- 1. Training Dataset: train_sol.npy
 - Shape: (128, 5, 64)
 - Description:
 - 128: Number of trajectories.
 - 5: Time snapshots of the solution. For a given trajectory u, the time snapshots are:

u[0]: Initial condition u_0 at t = 0.0,

u[1]: Solution at t = 0.25,

u[2]: Solution at t = 0.50,

u[3]: Solution at t = 0.75,

u[4]: Solution at t = 1.0.

- 64: Spatial resolution of the data.
- Please see Figure 1 for visualization.

2. Testing Datasets:

- test_sol.npy: Similar shape as the training dataset (128, 5, 64). Contains 128 trajectories with all 5 time snapshots.
- test_sol_res_{s}.npy: Testing datasets at varying spatial resolutions $s \in \{32, 64, 96, 128\}$. Shape: (128, 2, s), where:

u[0]: Initial condition u_0 at t=0.0,

u[1]: Solution at t = 1.0.

Note: Intermediate time snapshots are not included.

- test_sol_00D.npy: Out-of-distribution (OOD) testing dataset. Shape: (128, 2, 64), where:
 - u[0]: Initial condition u_0 at t = 0.0,
 - u[1]: Solution at t = 1.0.

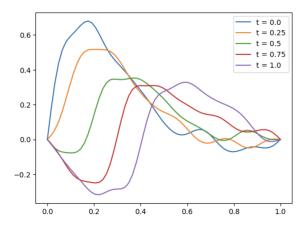


Figure 1: Training Dataset - One trajectory

Tasks

Task 1: One-to-One Training

- 1. Use **64** trajectories from the training dataset.
- 2. Select the first (t = 0.0) and last (t = 1.0) time snapshots for these trajectories.
- 3. Train an FNO model to learn the mapping:

$$G: u_0 \to u(t = 1.0)$$

- 4. Use the remaining trajectories for validation.
- 5. Test the trained model on the test_sol.npy dataset, focusing only on predictions at t = 1.0 (the map $u_0 \to u(t = 1.0)$).
- 6. Report the average relative L2 error:

$$\operatorname{err} = \frac{1}{128} \sum_{n=1}^{128} \frac{\|u_{\text{pred}}^{(n)}(t=1.0) - u_{\text{true}}^{(n)}(t=1.0)\|_{2}}{\|u_{\text{true}}^{(n)}(t=1.0)\|_{2}}$$

Task 2: Testing on Different Resolutions

- 1. Test the trained model from Task 1 on the datasets test_sol_res_{s}.npy for $s \in \{32, 64, 96, 128\}$.
- 2. Compute and report the average relative L2 error for each dataset.
- 3. What do you observe about the model's performance across different resolutions?

Task 3: Testing on Out-of-Distribution (OOD) Dataset

- 1. Test the trained model from Task 1 on the OOD dataset test_sol_OOD.npy.
- 2. Compute and report the average relative L2 error.
- 3. Compare the error to the one obtained in Task 1. What do you observe? Is the error higher or lower?

Task 4: All2All Training

- 1. Use 64 trajectories from the training dataset.
- 2. Use all provided time snapshots (t = 0.0, 0.25, 0.50, 0.75, 1.0) for these trajectories to train a time-dependent FNO model. Note that this is similar to the task that we had in time-dependent CNO tutorial. Hint: Use time-conditional batch normalization and include time as one of the input channels.
- 3. What is the total number of samples used for training in the All2All approach?
- 4. Test the trained model on the test_sol.npy dataset, focusing only on predictions at t = 1.0.
- 5. Report the average relative L2 error.
- 6. Compare the error to the one obtained in Task 1. What do you observe?

Bonus Task

- 1. Use the model from Task 4 to make predictions at multiple time steps: t = 0.25, t = 0.50, t = 0.75, t = 1.0.
- 2. Compute the average relative L2 error for each time step.
- 3. What do you observe about the model's performance over time?
- 4. Use the model from Task 4 to make predictions on the OOD dataset at t = 1.0.
- 5. What do you observe about the model's performance?