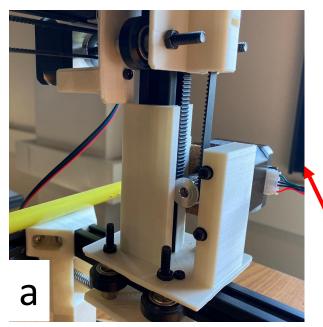
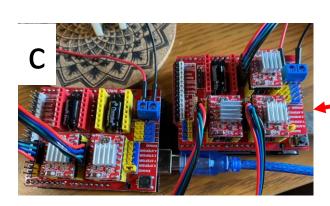
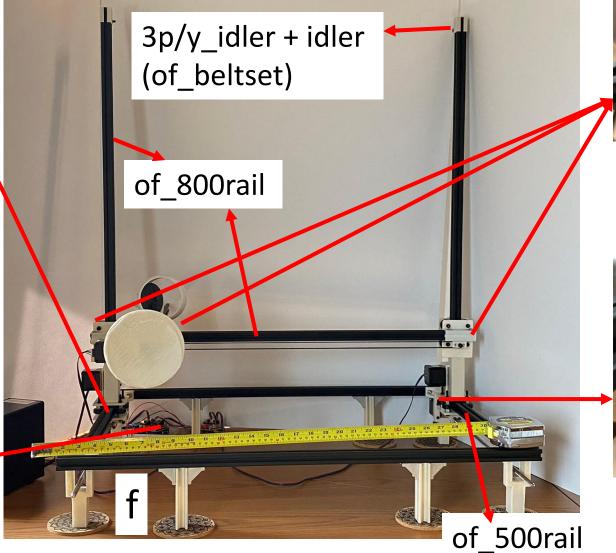
# ETHD components







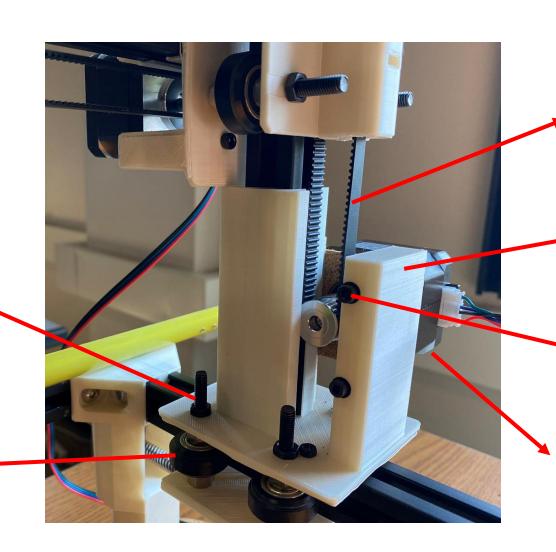




### a: y axis carrier

M5 screws (should be at least 40mm)

of\_wheelgroup (four wheels)



of\_beltset

3p/y\_fix\_gantry (may need to mirror when printing

M3 screws

of\_motor + of\_heatsink

## a: z axis (below y axis container to move it)

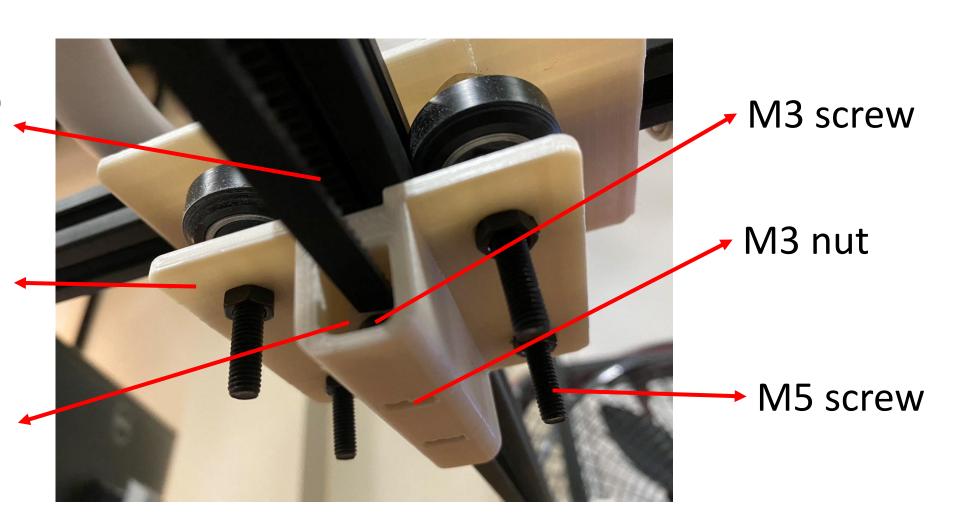
3p/nutmount\_gantry of leadscrew500 M3 screws

## b: y axis

of\_wheelgroup (four wheels)

3p/y\_belt\_gan try

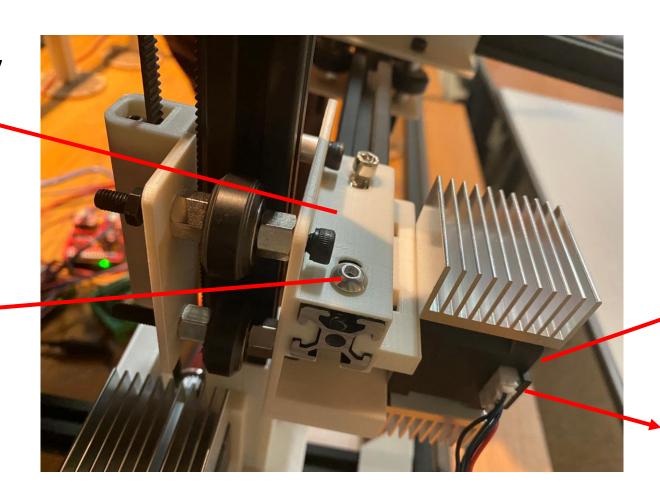
3p/tensioner\_block



#### b: x axis carrier

3p/x\_motor\_gantry

T-slot nuts + M5 screws (of\_connect erset)



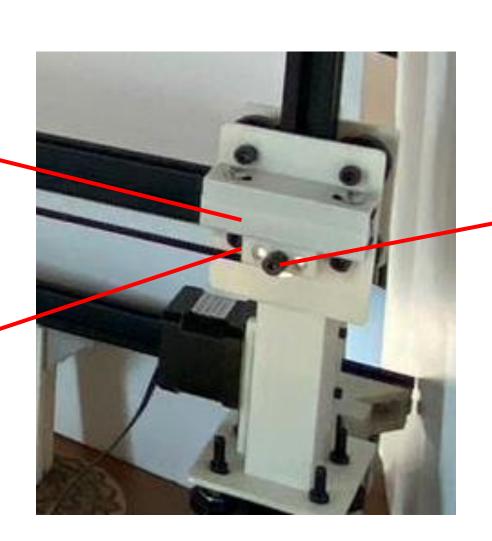
M3 screws

of\_motor + of\_heatsink

#### b: x axis idler

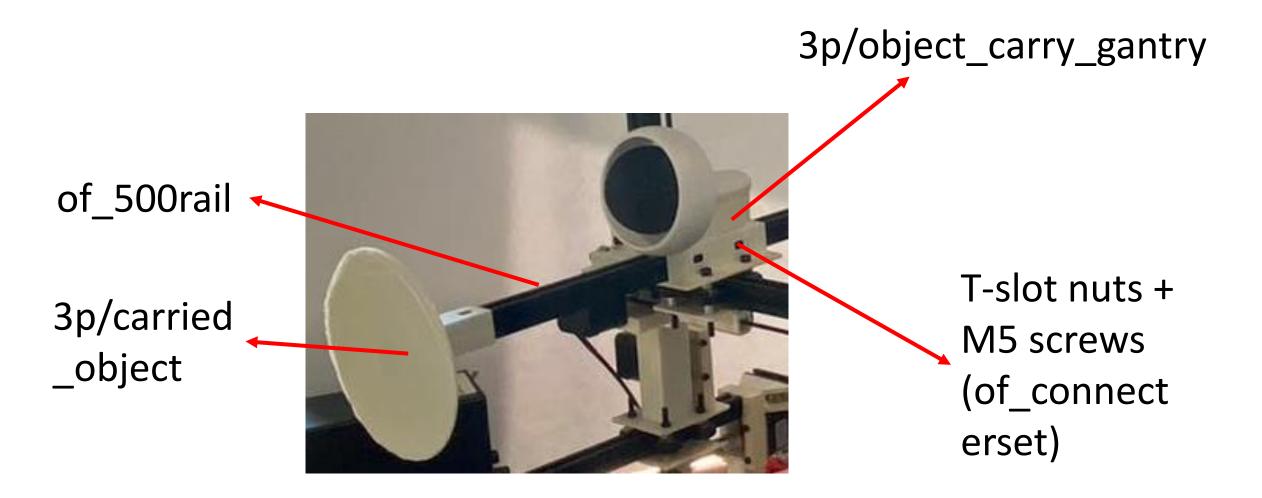
3p/x\_idler\_gantry

Idler (of\_beltset)



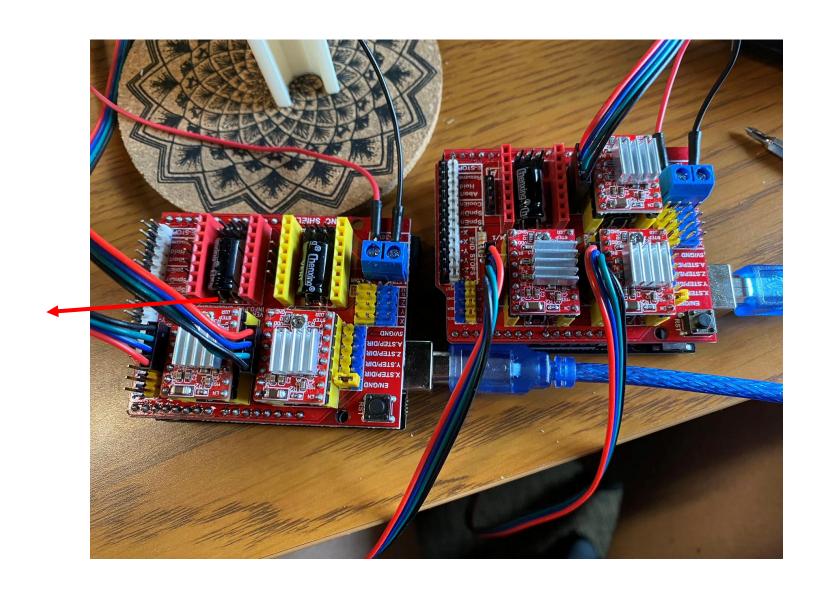
M5 screw + nuts

## b: object carrier (x axis)



#### C: boards

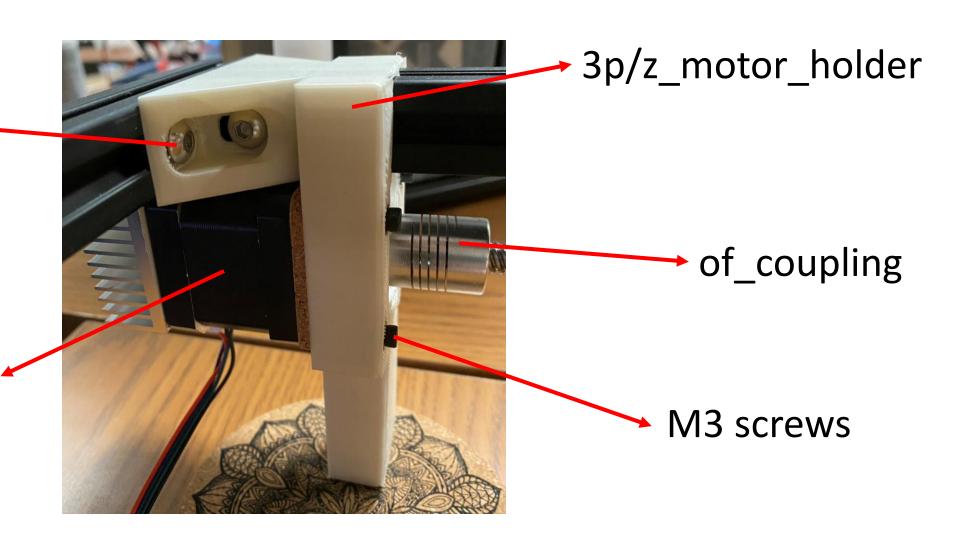
of\_Arduino + of\_CNCV3 + of\_A4988



## d: z axis (motor holder)

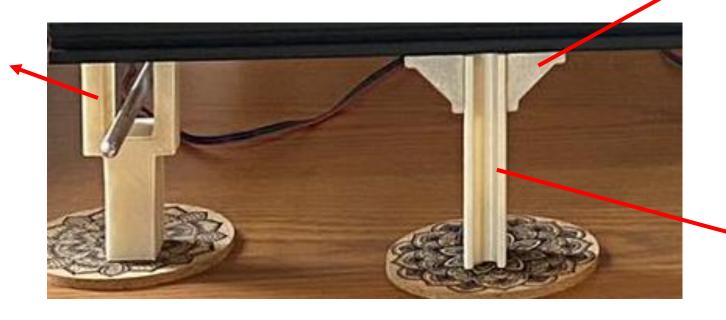
T-slot nuts + M5 screws (of\_connect erset)

of\_motor + of\_heatsink



## f: other supports

3p/support\_corner



corner bracket (of\_connecter set)

3p/support\_side