

# Zunzhi You

youzunzhi@gmail.com | [github.com/youzunzhi](https://github.com/youzunzhi) | <https://youzunzhi.github.io>

## EDUCATION

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### The University of Sydney

Ph.D. in Computer Science

Sydney, Australia

*Mar. 2023 –*

### Sun Yat-sen University

B.E. in Software Engineering, School of Computer Science and Engineering

Guangzhou, China

*Aug. 2017 – June 2021*

Overall Average: 90.25%, Ranking: 13/174, Outstanding Graduate

### National Chiao Tung University

Exchange Student in the Department of Computer Science

Hsinchu, Taiwan

*Sep. 2019 – Jan. 2020*

Overall Average: 92.5%

## PUBLICATIONS AND TRANSCRIPTS

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Zunzhi You, Daochang Liu, Bohyung Han, Chang Xu. Beyond Pretrained Features: Noisy Image Modeling Provides Adversarial Defense. NeurIPS, 2023. [\[Paper\]](#) [\[Code\]](#)

Zunzhi You, Yi-Hsuan Tsai, Wei-Chen Chiu, Guanbin Li. Towards Interpretable Deep Networks for Monocular Depth Estimation. ICCV, 2021. [\[Paper\]](#) [\[Code\]](#)

Chung-Sheng Lai, Zunzhi You, Ching-Chun Huang, Yi-Hsuan Tsai, Wei-Chen Chiu. Colorization of Depth Map via Disentanglement. ECCV, 2020. [\[Paper\]](#) [\[Code\]](#)

Ricong Huang, Haofeng Li, Zunzhi You, Weikai Chen, Yizhou Yu, Guanbin Li. SENSE: Self-Evolving learning for Self-Supervised Monocular Depth Estimation.

## RESEARCH HIGHLIGHTS

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### Adversarial Defense from Noisy Image Modeling Pretraining

*Aug. 2022 – May 2023*

Advisors: Dr [Chang Xu](#), Dr [Daochang Liu](#), Professor [Bohyung Han](#)

- Proposed a self-supervised pretraining framework that brings adversarial robustness to downstream models
- Recognized that replacing masking in the mask image modeling framework by adding noise can learn strong noise-invariant features
- Exploit the reconstruction ability of the NIM model from noisy images to remove adversarial perturbations
- Showed that the proposed method improves the adversarial robustness with little sacrifice of the clean accuracy

### Interpretability of DNNs for Monocular Depth Estimation

*Apr. 2020 – Mar. 2021*

Advisors: Dr [Wei-Chen Chiu](#), Dr [Yi-Hsuan Tsai](#), Dr [Guanbin Li](#)

- Quantified and enhanced the interpretability of DNNs for monocular depth estimation
- Observed some neural units are selective to certain ranges of depth based on the qualitative and quantitative behavior of each unit
- Identified that selective units are more meaningful to the estimation performance by ablating units successively in different orders
- Proposed to assign a depth range for each unit to select to tackle issues caused by batch-wise optimization, resulting in more interpretable and accurate DNNs for monocular depth estimation
- Validated the proposed method's reliability and applicability, e.g. providing cues to explain models' mistakes

### Depth Colorization and its Applications

*Sep. 2019 – Mar. 2020*

Advisors: Dr [Wei-Chen Chiu](#), Dr [Yi-Hsuan Tsai](#)

- Verified the applicability of our proposed depth colorization model
- Defined a metric of consistency upon the prediction difference of RGB-based vision models to address the problem of unavailable ground truth
- Conducted experiments on two datasets with an object detection model YOLOv3, showing our method was able to maintain the vision model's performance in ill-lighted situations