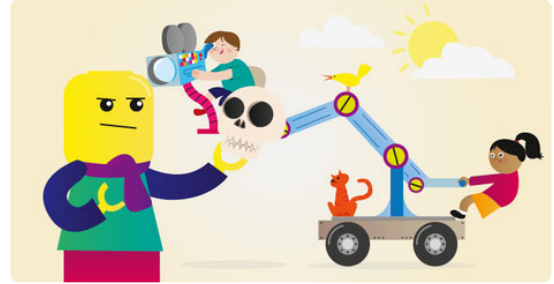




Projects

Push Button Stop Motion

Make your own stop motion animation rig with a push button using Python Picamera and GPIO



Step 1 What you will make

Make your own stop motion animation video using a Raspberry Pi, Python and a camera module to take pictures, controlled by a push button connected to the Pi's GPIO pins.

You can use LEGO to animate a tower being built, figures acting out a scene, or anything else you can think of



What you will learn

By creating a push button stop motion machine with your Raspberry Pi you will learn

- How to set up and use the Raspberry Pi camera module
- How to use the Python picamera library to capture photograph
- How to connect a button to the GPIO pins on a Raspberry Pi
- How to control the camera with a button using GPIO Zero
- How to generate a video from the command line using `avconv`

This resource covers elements from the following strands of the **Raspberry Pi Digital Making Curriculum** (<https://www.raspberrypi.org/curriculum/>):

- **Combine programming constructs to solve a problem** (<https://www.raspberrypi.org/curriculum/programming/builder>)
- **Combine inputs and/or outputs to create projects or solve a problem** (<https://www.raspberrypi.org/curriculum/physical-computing/builder>)



What you will need

Hardware

- Raspberry Pi camera module
- 1 x Full size breadboard
- 2 x Male-to-female jumper leads
- 1 x Tactile button

Software

You'll need to make sure you have the following packages installed.

- libav-tools

You'll need to be online to install packages.

First update and upgrade your system. Enter the following commands in to the terminal:

```
sudo apt-get update
sudo apt-get upgrade
```

Now install the packages you'll need:

```
sudo apt-get install libav-tools
```

- Test you have **libav-tools** installed by entering **avconv** at the command line. You should see some information about the **avconv** version.



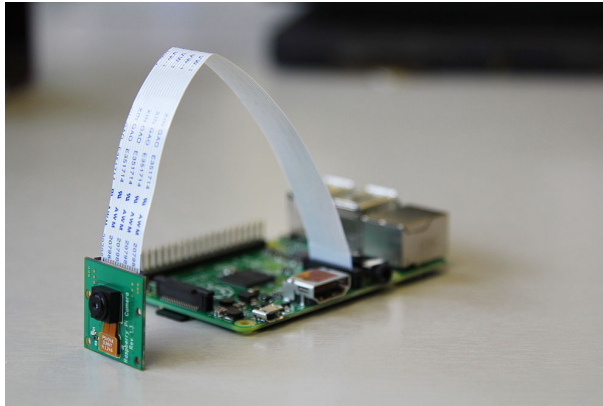
Additional information for educators

If you need to print this project, please use the **printer-friendly version** (<https://projects.raspberrypi.org/en/projects/push-button-stop-motion/print>).

You can find the finished code for this project **here** (<http://rpf.io/p/en/push-button-stop-motion-get>).

Step 2 Connect the camera

Before booting your Pi, you'll need to connect the camera



Locate the camera port next to the Ethernet port. Lift the tab on the to



Place the strip in the connector, with the blue side facing the Ethernet port. While holding the strip in place, push down the t



Turn the power on to boot the Pi.



Step 3 Test the camera

Open a terminal window from the application menu. Enter the following command:



```
raspistill -k
```

You should see a preview appear on the screen. It doesn't matter if the picture is upside-down; you can configure this later. Press **Ctrl + C** to exit the preview.

Run the command **ls** to see the files in your home directory; you should see **image1.jpg** listed.

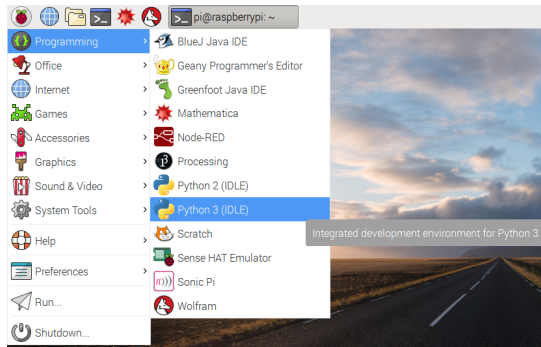


Click the file manager icon in the taskbar and you should see some folders and files. Double-click **image1.jpg** to preview it.



Step 4 Take a picture with Python

Open **Python 3 (IDLE)** from the main menu:



Select **File > New window** from the menu to open a Python file editor



Carefully enter the following code into the new window (case is important!)



```
from picamera import PiCamera
from time import sleep

camera = PiCamera()

camera.start_preview()
sleep(3)
camera.capture('/home/pi/Desktop/image.jpg')
camera.stop_preview()
```

Select **File > Save** from the menu (or press **Ctrl + S**) and save as **animation.py**.



Press **F5** to run your program.



You should see **image.jpg** saved on your Desktop. Double-click the icon to open the image



If the picture is upside-down you can either reposition your camera using a mount, or leave it as it is and tell Python to flip the image. To do this, add the following lines:



```
camera.rotation = 180
```

after `camera = PiCamera()`, so it becomes:

```
from picamera import PiCamera
from time import sleep

camera = PiCamera()

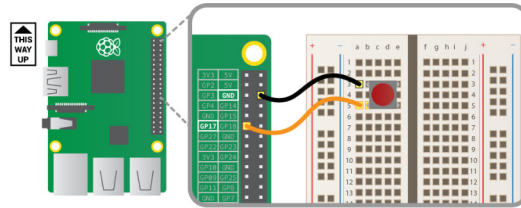
camera.rotation = 180
camera.start_preview()
sleep(3)
camera.capture('/home/pi/Desktop/image.jpg')
camera.stop_preview()
```

Run the file again and it will overwrite `image.jpg` with a new image in the correct orientation. Remember to keep these lines in your code while you alter it in the next few steps



Step 5 Connect a hardware button

Using your breadboard and jumper leads, connect the Pi to the button as shown in the diagram below



Import **Button** from the **gpiozero** module at the top of the code, create up **Button** connected to pin 17, and change the **sleep** line to use **button.wait_for_press** like so:



```
from picamera import PiCamera
from time import sleep
from gpiozero import Button

button = Button(17)
camera = PiCamera()

camera.start_preview()
button.wait_for_press()
camera.capture('/home/pi/image.jpg')
camera.stop_preview()
```

Save and run your program.



Once the preview has started, press the button connected to your Pi to capture an image



Return to the file manager window and you should see your **image.jpg**. Again, double-click to view.



Step 6 Take a selfie

If you want to take a photograph of yourself with the camera board, you are going to have to add in a delay to enable you to get into position. You can do this by modifying your program

Add a line to your code to tell the program to sleep briefly before capturing an image, as below



```
camera.start_preview()
button.wait_for_press()
sleep(3)
camera.capture('/home/pi/Desktop/image.jpg')
camera.stop_preview()
```

Save and run your program.

Press the button and try to take a selfie. Be sure to keep the camera still! Ideally, it should be mounted in position



Again, feel free to check the image in the file manager. You can run the program again to take another selfie



Step 7 Stop motion animation

Now that you have successfully taken individual photographs with your camera, it's time to try combining a series of still images to make stop motion animation.

IMPORTANT You must create a new folder to store your stills. In the terminal window, enter `mkdir animation`.



Modify your code to add a loop to keep taking pictures every time the button is pressed



```
camera.start_preview()
frame = 1
while True:
    try:
        button.wait_for_press()
        camera.capture('/home/pi/animation/frame%03d.jpg' % frame)
        frame += 1
    except KeyboardInterrupt:
        camera.stop_preview()
        break
```

Because `while True` goes on forever, you have to be able to make it exit gracefully. Using `try` and `except` means it can deal with an exceptional circumstance - if you force it to stop with `Ctrl + C` it will close the camera preview and exit the loop.

`frame%03d` means the file will be saved as the name "frame" followed by a 3-digit number with leading zeroes - 001, 002, 003 etc. This allows them to be easily sorted into the correct order for the video.

Now set up your animation subject (e.g. LEGO), ready to start the stop motion animation



Press the button to capture the first frame, then rearrange the animation subject and press the button again to capture each subsequent frame.



Once all the frames have been captured, press `Ctrl + C` to terminate the program.



Open the `animation` folder in the file manager to see your stills collection



Step 8 Generate the video

To generate the video, begin by returning to the terminal window



Run the video rendering command:



```
avconv -r 10 -i animation/frame%03d.jpg -qscale 2 animation.h264
```

*Note you're using **%03d** again - this is a common format which both Python and **avconv** understand, and means the photos will be passed in to the video in order.*

Play your video using **omxplayer**.



```
omxplayer animation.h264
```

You can adjust the frame rate by editing the rendering command. Try changing **-r 10** (10 frames per second) to another number.

You can also change the filename of the rendered video to stop it from overwriting your first attempt. To do this, change **animation.h264** to something else.

Step 9 What next?

- Why not share your video? Try uploading it to YouTube!
- Now you know how to wire up a button to take a picture with the camera module, what else could you use this for?
- Could you do something similar for a time-lapse video?
- What could you use instead of a button? A motion sensor?
- Instead of making a video, what else could you do with photos taken with the camera module? You could post them to Twitter, or another social media site.

Published by **Raspberry Pi Foundation** (<https://www.raspberrypi.org>) under a **Creative Commons license** (<https://creativecommons.org/licenses/by-sa/4.0/>).

View project & license on GitHub (<https://github.com/RaspberryPiLearning/push-button-stop-motion>)