







Geometry-Guided Progressive NeRF for Generalizable and Efficient Neural Human Rendering

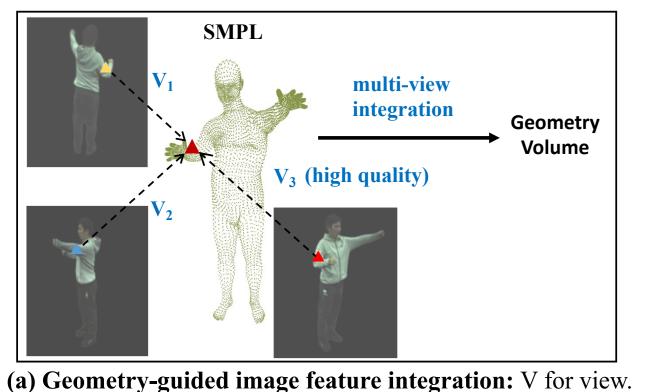
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Sea AI Lab

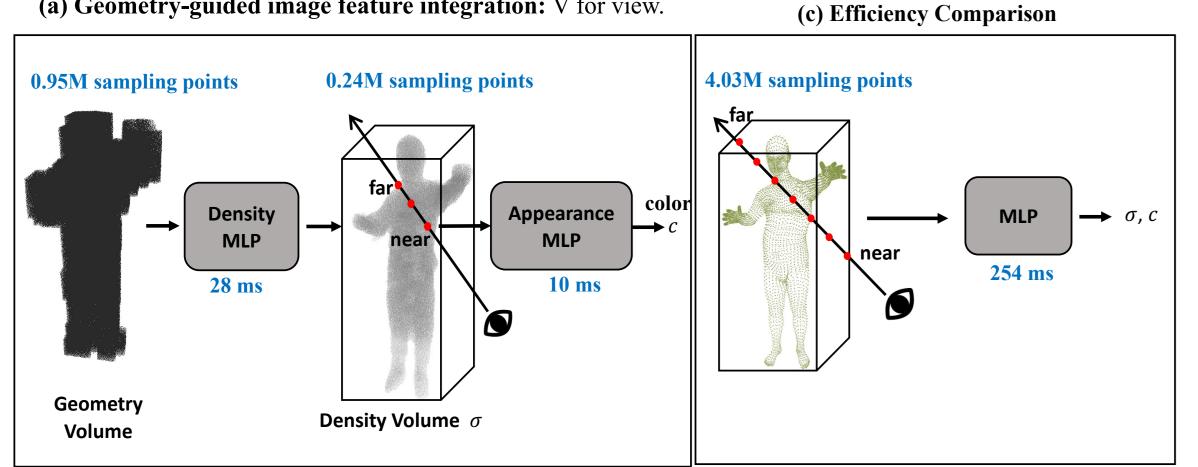
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Challenges

Free-viewpoint human body synthesis with sparse camera views

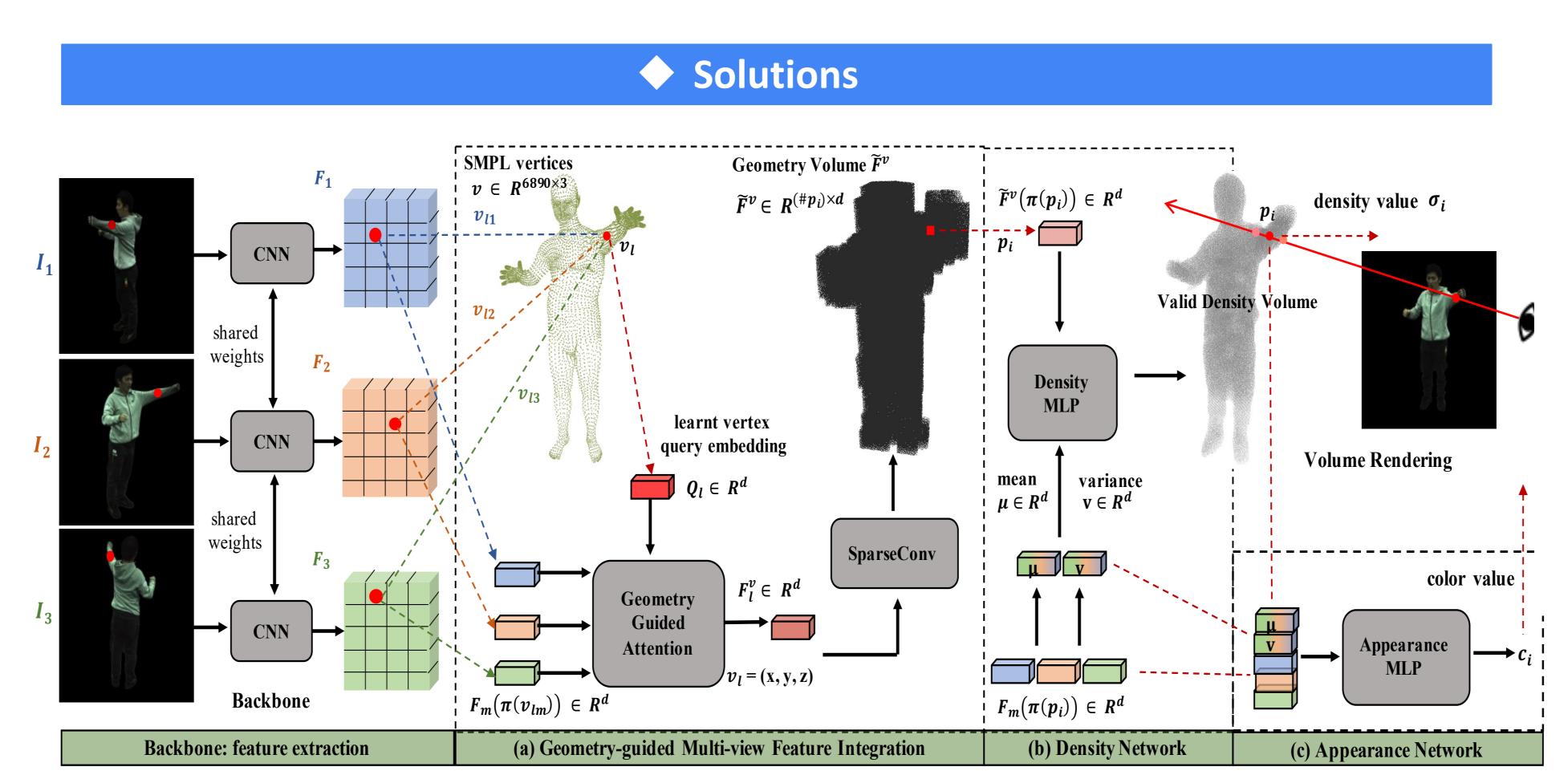


	Previous	Ours
# Density Points (↓)	4.03M	0.95M (-76%)
Density MLP T (↓)	109ms	28ms (-74%)
# Color Points (↓)	4.03M	0.24M (-94%)
Color MLP T (↓)	145ms	10ms (-93%)
Memory (↓)	20.7GB	9.9GB (-52%)



(b) Rendering pipeline: our efficient geometry-guided progressive pipeline (left) vs. previous (right). The amount of sampling points and forward time in blue are measured on the same data and model parameters.

- > The human body is highly non-rigid and commonly has selfocclusions over body parts, which may lead to ambiguous results
- High computational and memory cost of NeRF-based methods severely hinder human synthesis with accurate details in highresolution.



- > Propose a novel geometry-guided progressive NeRF (GP-NeRF) for generalizable and efficient human body rendering, which reduces the computational cost of rendering significantly and also gains higher generalization capacity simply based on the single-frame sparse views.
- > Propose an effective geometry-guided multi-view feature integration approach, where we let each view compensate the low-quality occluded information for other views with the guidance of the geometry prior.

Ours

$| PSNR (\uparrow) SSIM (\uparrow)$ Body NT [37] NHR [39] NB [28] 28.73 28.91 NHR [39] NB [28] NHP [12] 26.94 27.92 GP-NeRF (Ours) NV [19] NT [37] ZJU-3 NHR [39] PVA [30] 25.96

Quantitative Results

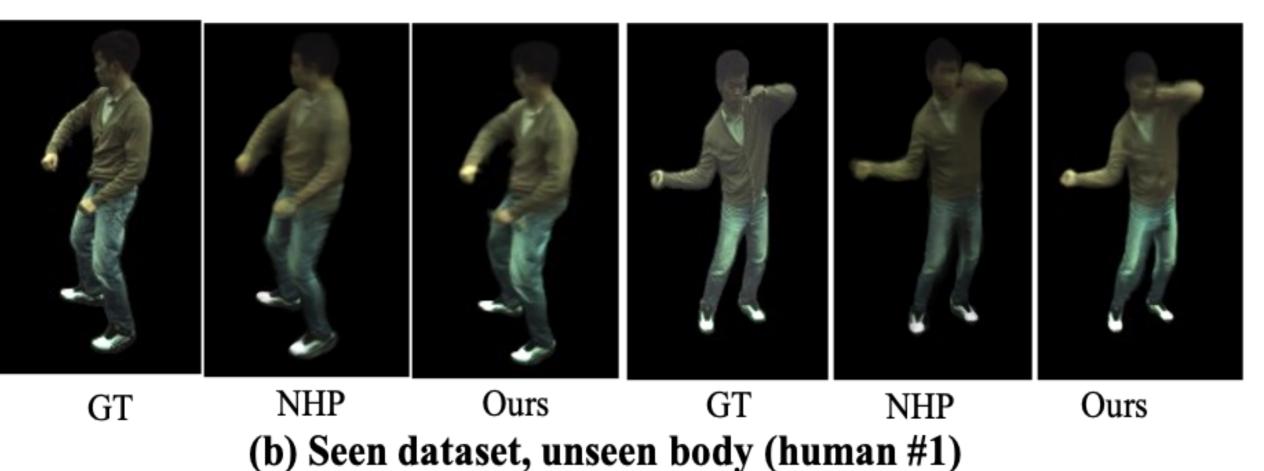
Method	$\#\mathbf{r}\left(\mathbf{M}\right)\left(\downarrow\right)$	$\mathbf{\#p}^{d}\left(\mathbf{M}\right)\left(\downarrow\right)$	$\mathbf{p}^{c}\left(\mathbf{M}\right)\left(\downarrow\right)$	Time (ms) (\downarrow)	$\text{Mem}\left(\text{GB}\right)(\downarrow)$
NHP [10]	0.063	4.03	4.03	1160	14.20
NHR [<mark>34</mark>]	0.063	4.03	4.03	636	10.20
NB [<mark>24</mark>]	0.063	4.03	4.03	611	21.80
GP-NeRF [†] 3×	0.063 (-0.0%)	4.03 (-0.0%)	4.03 (-0.0%)	589 (-3.6%)	14.53 (-33.3%)
GP-NeRF [†] 2×	0.063 (-0.0%)	4.03 (-0.0%)	4.03 (-0.0%)	567 (-7.2%)	20.74 (-4.9%)
GP-NeRF 2×	0.039 (-38.1%)	0.95 (-76.4%)	0.24 (-94.0%)	243 (-60.2%)	9.88 (-54.7%)
GP-NeRF 1×	0.039 (-38.1%)	0.95 (-76.4%)	0.24 (-94.0%)	175 (-71.4%)	14.25 (-34.6%)

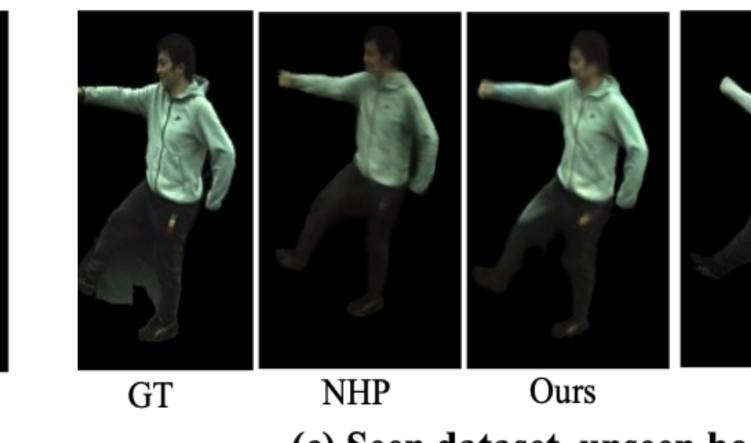
Method	T^a -MLP (ms) (\downarrow)	T^a -total (ms) (\downarrow)	T^c -MLP (ms) (\downarrow)	T^c -total (ms) (\downarrow)	PSNR (↑)
GP-NeRF [†] 2×	108.58	226.56	145.38	146.39	26.56
GP-NeRF 2×	28.08 (-74.1%)	83.65 (-63.1%)	10.02 (-93.1%)	11.4 (-92.2%)	26.67 (+0.4%)
GP-NeRF 1×	23.55 (-78.3%)	74.07 (-67.3%)	9.50 (-93.5%)	10.27 (-93.0%)	26.67 (+0.4%)

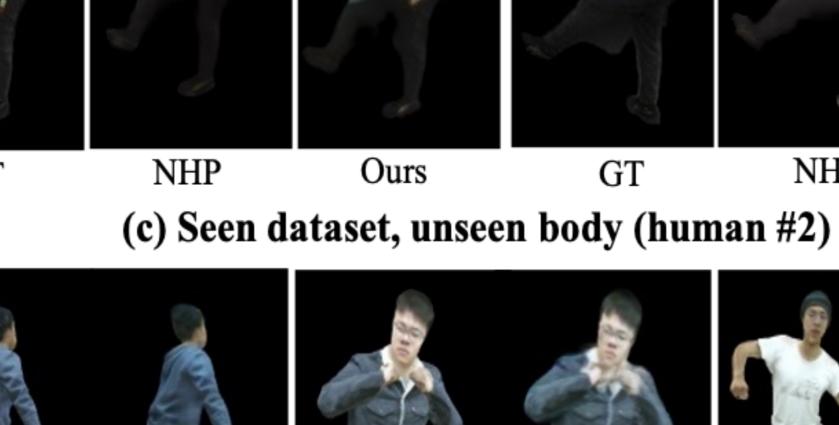
Our GP-NeRF has achieved state-of-the-art performance on the ZJU-MoCap dataset, taking only 175ms on RTX 3090 and reducing time for rendering per image by over 70.

Qualitative Results

NB Ours GT NHR (a) Seen dataset, seen body, unseen pose



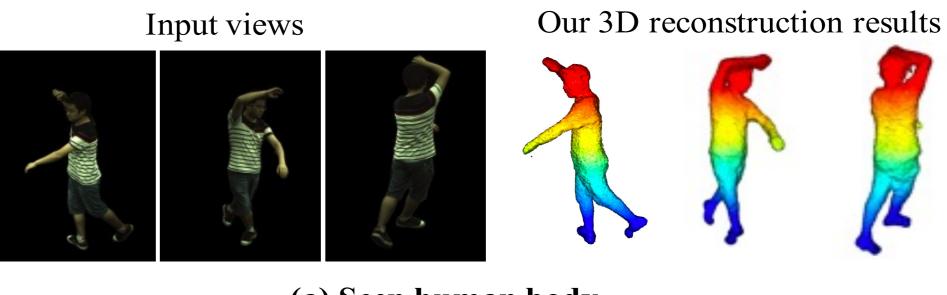




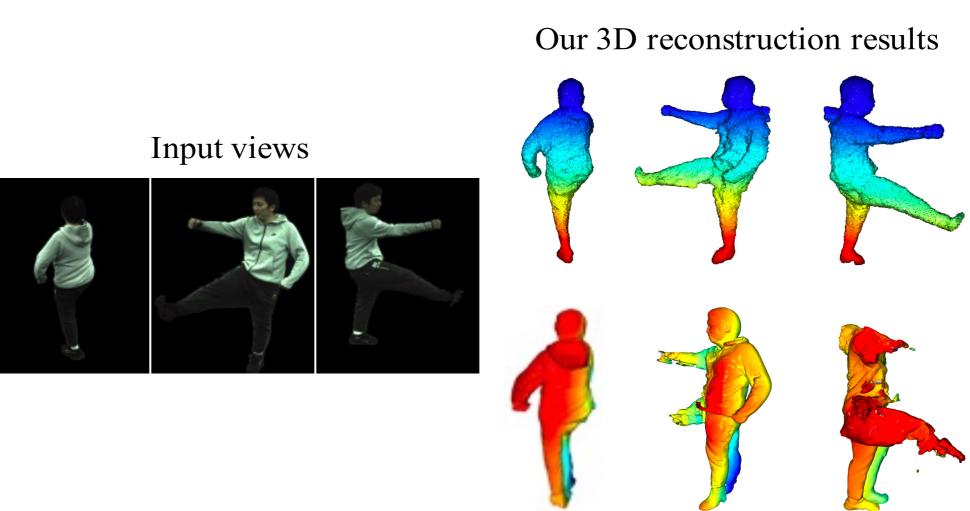


(d) Seen dataset, unseen body on THUman dataset (for each image pair, GT in the left, our results in the right)

Reconstructed 3D Results



(a) Seen human body



Our synthesis can reconstruct very close human body shape and clothes details like hoods and folds on unseen human bodies.

without geometry priors and can reconstruct more accurate lighting conditions.

Ours can stick to the normal human

body geometry better than methods

PIFuHD reconstruction results

(b) Unseen human body