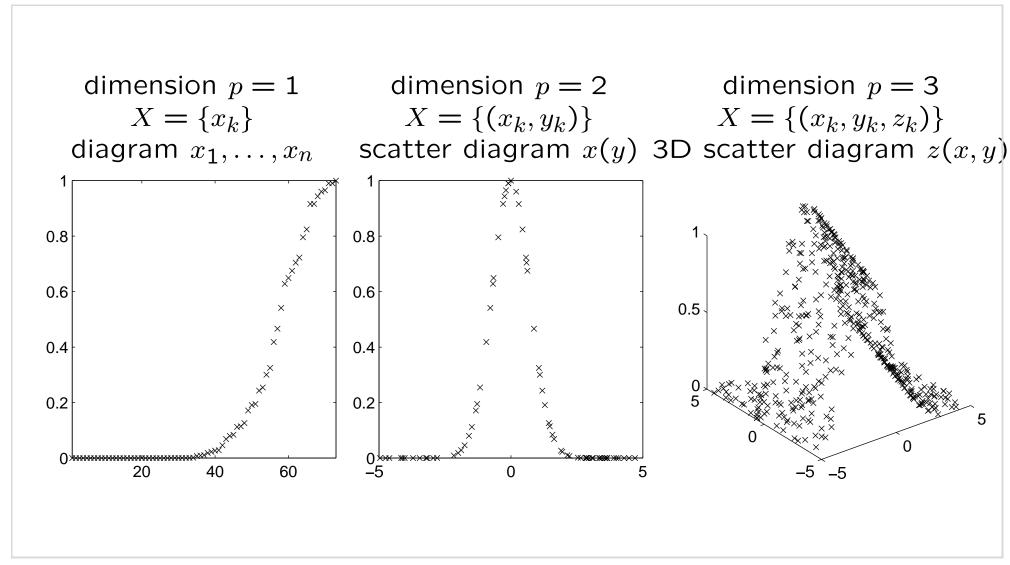
Chapter 4: Visualization

- 1. Diagrams
- 2. Principal Component Analysis
- 3. Multi Dimensional Scaling
- 4. Sammon Mapping
- 5. Auto-Encoder
- 6. Histograms
- 7. Spectral Analysis

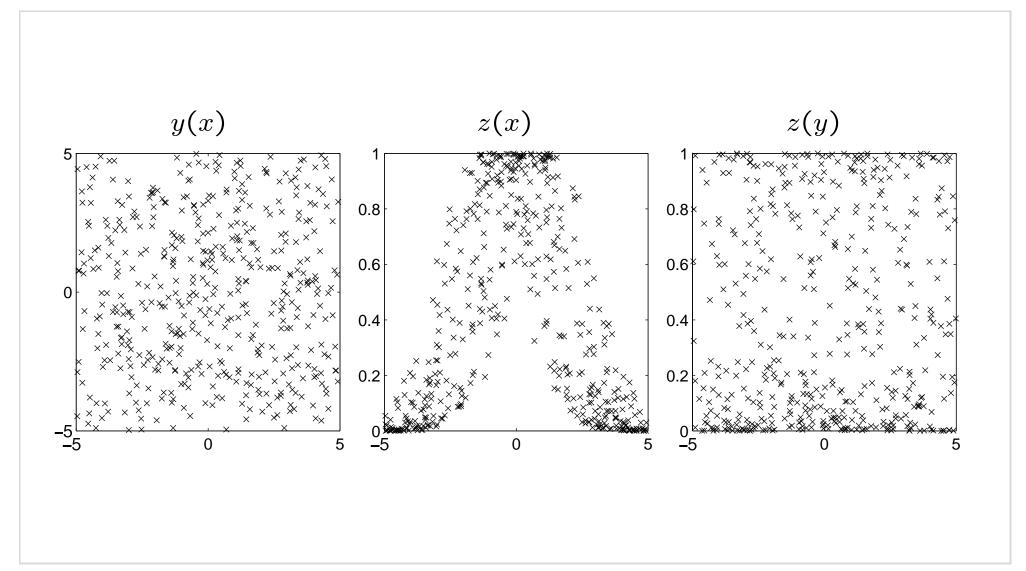
Diagrams



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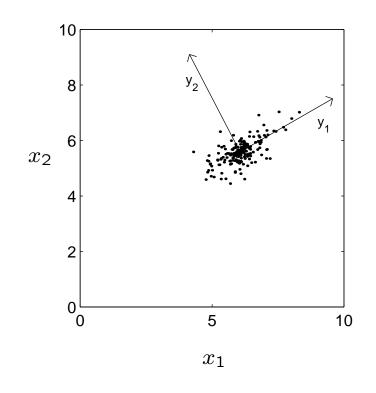
Projection



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- principal component analysis (PCA)
- Karhunen-Loève transform
- singular value decomposition (SVD)
- eigenvector projection
- Hotelling transform
- proper orthogonal decomposition



coordinate transformation: translation and rotation

transformation $IR^p \to IR^q$: $y_k = (x_k - \bar{x}) \cdot E$ inverse transformation $IR^q \to IR^p$: $x_k = y_k \cdot E^T + \bar{x}$

mean

$$\bar{x} = \frac{1}{n} \sum_{k=1}^{n} x_k$$

ullet determine rotation matrix E by maximizing the variance of Y

 \bullet variance in Y

$$v_{y} = \frac{1}{n-1} \sum_{k=1}^{n} y_{k}^{T} y_{k}$$

$$= \frac{1}{n-1} \sum_{k=1}^{n} ((x_{k} - \bar{x}) \cdot E)^{T} \cdot ((x_{k} - \bar{x}) \cdot E)$$

$$= \frac{1}{n-1} \sum_{k=1}^{n} E^{T} \cdot (x_{k} - \bar{x})^{T} \cdot (x_{k} - \bar{x}) \cdot E$$

$$= E^{T} \left(\frac{1}{n-1} \sum_{k=1}^{n} (x_{k} - \bar{x})^{T} \cdot (x_{k} - \bar{x})\right) \cdot E$$

$$= E^{T} \cdot C \cdot E$$

covariance matrix of X

$$c_{ij} = \frac{1}{n-1} \sum_{k=1}^{n} (x_k^{(i)} - \bar{x}^{(i)}) (x_k^{(j)} - \bar{x}^{(j)})$$

• constraint: rotation, no dilation

$$E^T \cdot E = I$$

• Lagrange optimization

$$L = E^{T}CE - \lambda(E^{T}E - I)$$

$$\frac{\partial L}{\partial E} = 0 \Rightarrow CE - \lambda E + E^{T}C - \lambda E^{T} = 0$$

$$\Rightarrow CE = \lambda E \text{ (eigenproblem)}$$
solution
$$(v_{1}, \dots, v_{p}, \lambda_{1}, \dots, \lambda_{p}) = \text{eig}(C)$$

solution using homogeneous equation system

$$(C - \lambda I) \cdot E = 0$$

• E is matrix of eigenvectors of C

$$E = (v_1, \dots, v_q)$$

variances in Y are eigenvalues of C

$$CE = \lambda E \quad \Leftrightarrow \quad \lambda = E^T CE = v_y$$

• suitable dimensionality q

$$\sum_{i=1}^{q} \lambda_i / \sum_{i=1}^{p} \lambda_i \ge 95\%$$

transformation error

$$e = \frac{1}{n} \sum_{k=1}^{n} (x_k - x'_k)^2 = \frac{n-1}{n} \sum_{i=q+1}^{p} \lambda_i$$

⇒ PCA yields projection with minimal quadratic error

Example Principal Component Analysis

$$X = \{(1,1), (2,1), (2,2), (3,2)\}$$

$$\bar{x} = \frac{1}{2} \cdot (4,3)$$

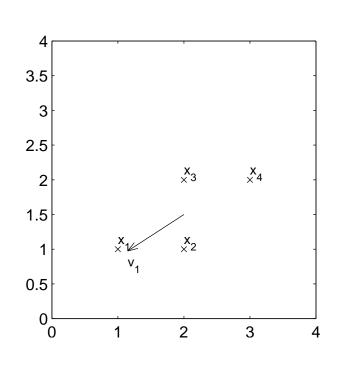
$$C = \frac{1}{3} \cdot \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\lambda_1 = 0.8727$$

$$\lambda_2 = 0.1273$$

$$v_1 = \begin{pmatrix} -0.85065 \\ -0.52573 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} 0.52573 \\ -0.85065 \end{pmatrix}$$



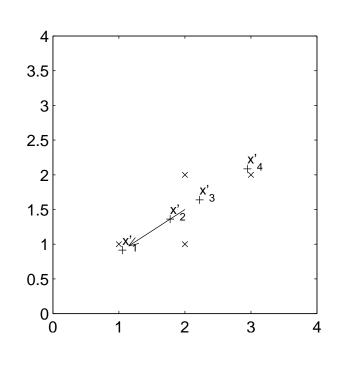
Example Principal Component Analysis

projection onto first axis:

$$E = v_1 = \begin{pmatrix} -0.85065 \\ -0.52573 \end{pmatrix}$$

$$Y = (1.1135, 0.2629, -0.2629, -1.1135)$$

$$X' = \{(1.0528, 0.91459), (1.7764, 1.3618), (2.2236, 1.6382), (2.9472, 2.0854)\}$$



Multi Dimensional Scaling

ullet eigendecomposition of the positive semi-definite matrix XX^T

$$XX^T = Q \Lambda Q^T = (Q \sqrt{\Lambda}^T) \cdot (\sqrt{\Lambda} Q^T) = (Q \sqrt{\Lambda}^T) \cdot (Q \sqrt{\Lambda}^T)^T$$

 $Q=(v_1,\ldots,v_p)$: matrix of eigenvectors of XX^T , usually p< n Λ : diagonal matrix of eigenvalues of XX^T

• estimate for X

$$Y = Q\sqrt{\Lambda}^T$$

- ullet lower dimensional projections $Y\subset R^q$, q< p
 - use only first q dimensions
 - scale eigenvectors (square norms match eigenvalues)

MDS of a Distance Matrix D

- ullet assume $ilde{X}$ and choose anchor point $ilde{x}_a$, $a\in\{1,\ldots,n\}$
- ullet transform $ilde{X}$ (origin 0) to X (origin $ilde{x}_a$)

$$x_k = \tilde{x}_k - \tilde{x}_a$$

difference vectors are invariant

$$\tilde{x}_i - \tilde{x}_j = x_i - x_j$$

scalar product of each side with itself

$$(\tilde{x}_i - \tilde{x}_j)(\tilde{x}_i - \tilde{x}_j)^T = (x_i - x_j)(x_i - x_j)^T$$

$$\Rightarrow d_{ij}^2 = x_i x_i^T - 2x_i x_j^T + x_j x_j^T = d_{ia}^2 - 2x_i x_j^T + d_{ja}^2$$

$$\Rightarrow x_i x_j^T = (d_{ia}^2 + d_{ja}^2 - d_{ij}^2)/2$$

ullet XX^T can be computed from D

Example Multi Dimensional Scaling

$$X' = \{(1,1),(2,1),(2,2),(3,2)\}$$

$$X = \left\{(-1,-\frac{1}{2}),(0,-\frac{1}{2}),(0,\frac{1}{2}),(1,\frac{1}{2})\right\} \quad \text{(mean subtracted)}$$

$$XX^{T} = \frac{1}{4} \begin{pmatrix} 5 & 1 & -1 & -5 \\ 1 & 1 & -1 & -1 \\ -1 & -1 & 1 & 1 \\ -5 & -1 & 1 & 5 \end{pmatrix}$$

$$v_{1} \approx \begin{pmatrix} -0.6882 \\ -0.1625 \\ 0.6882 \end{pmatrix}, \quad \lambda_{1} \approx 2.618$$

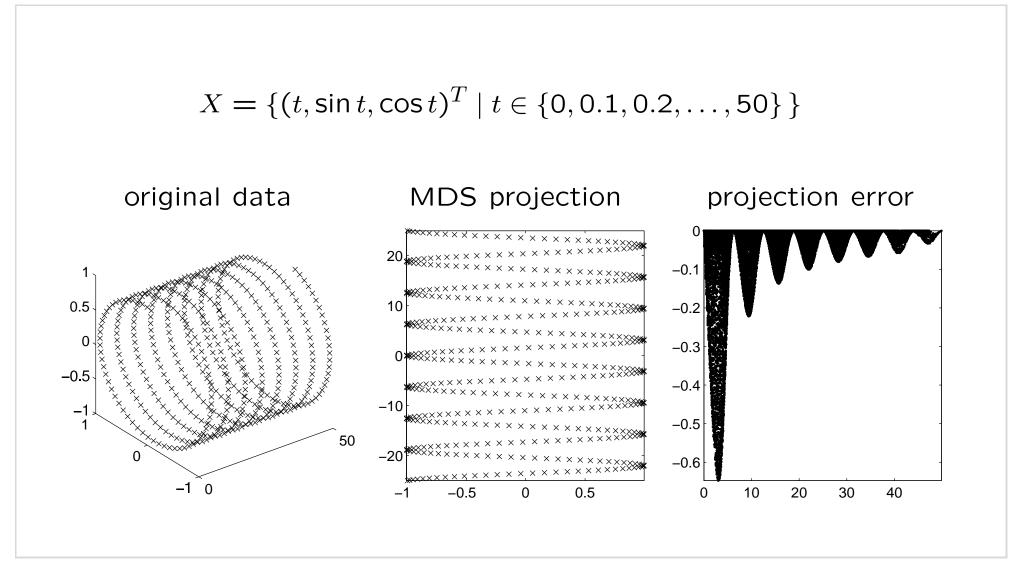
$$\Rightarrow Y \approx \begin{pmatrix} -0.6882 \\ -0.1625 \\ 0.6882 \end{pmatrix}, \quad \lambda_{1} \approx 2.618$$

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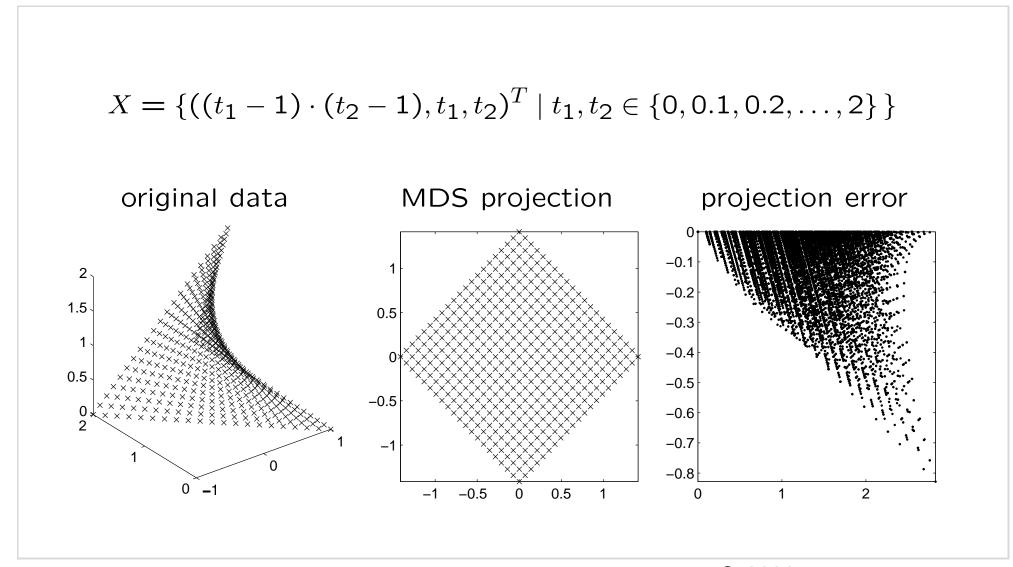
Example MDS: Helix



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Example MDS: Bent Square



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Shepard Diagram

$$D^{x} \approx \begin{pmatrix} 0 & 1 & 1.4142 & 2.2361 \\ 1 & 0 & 1 & 1.4142 \\ 1.4142 & 1 & 0 & 1 \\ 2.2361 & 1.4142 & 1 & 0 \end{pmatrix} \stackrel{2}{\begin{array}{c} 2.5 \\ 2.2361 \\ 1.3764 & 0.5257 \\ 2.2270 & 1.3764 & 0.8507 \\ 0.8507 & 0 & 0.8507 \\ 0.05257 & 0.08507 \\ 0.05257$$

- alternative criteria for multidimensional scaling
 - strict monotonicity (Torgerson)
 - points close to main diagonal (Sammon)