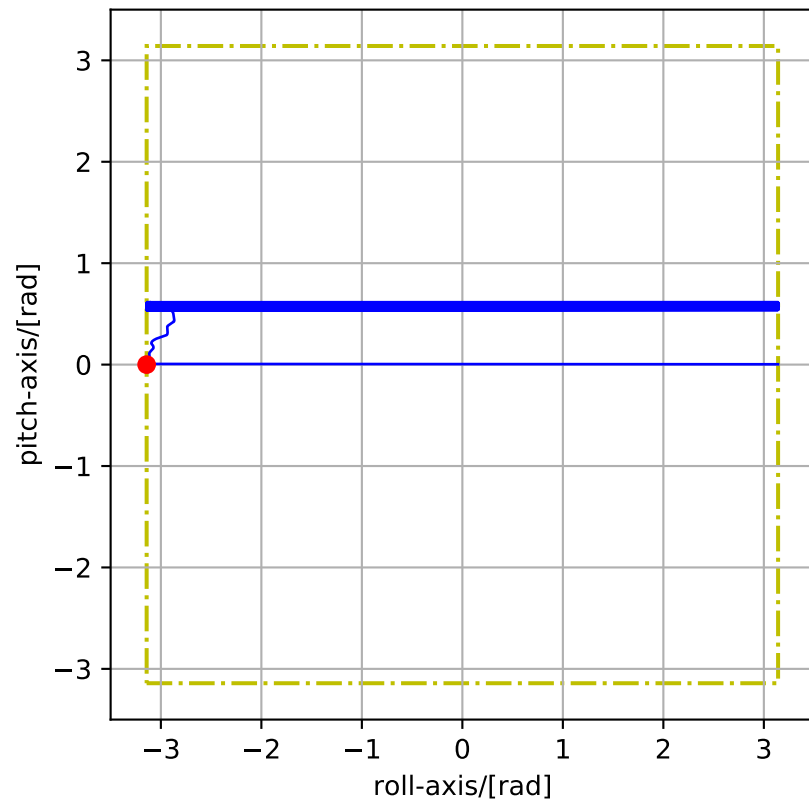Real time rpy while training

Orientation in roll-pitch axis

Orientation in yaw-pitch axis