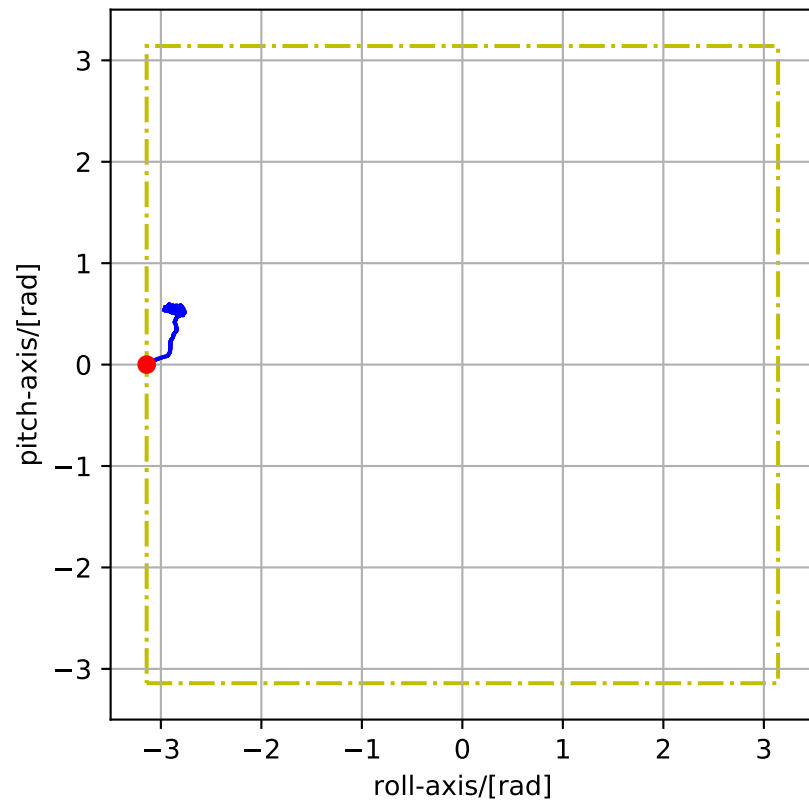


## Real time rpy while training

Orientation in roll-pitch axis



Orientation in yaw-pitch axis

