

# 1 Approximate Decision Tree

In this section the value of an empty sum is 0. Let  $d, n \in \mathbb{N} \setminus \{0\}$ . Let  $\sigma_1, \dots, \sigma_d \in \mathbb{R}$  be real numbers. Let  $m_1, \dots, m_d \in \mathbb{N} \setminus \{0\}$  be positive integers. For  $i \in [d]$ , let  $g_i = \{\sigma_i, (1 + \varepsilon)\sigma_i, (1 + \varepsilon)^2\sigma_i, \dots, (1 + \varepsilon)^{m_i}\sigma_i\}$ . Let  $G = g_1 \times g_2 \times \dots \times g_d$ .

For  $i \in [d]$  and  $p \in \mathbb{R}^d$  we denote the  $i$ -th coordinate of  $p$  by  $p[i]$ . We may treat a point  $p \in \mathbb{R}^d$  as a  $d$ -tuple by writing  $p = (p[1], p[2], \dots, p[d])$ . For a pair of points  $p, q \in \mathbb{R}^d$  we define

$$\gamma(q_1, q_2) := \left\{ p \in \mathbb{R}^d \mid \forall i \in [d] : q_1[i] < p[i] \leq q_2[i] \right\}.$$

Let

$$A = \gamma((\sigma_1, \dots, \sigma_d), ((1 + \varepsilon)^{m_1}\sigma_1, (1 + \varepsilon)^{m_2}\sigma_2, \dots, (1 + \varepsilon)^{m_d}\sigma_d)).$$

For a compact of points  $P \subset A$  and an integer  $i \in [d]$  we define

$$\begin{aligned} \mu(P, i) &:= \frac{1}{|P|} \cdot \sum_{p \in P} p[i] \\ \alpha(P) &:= (\mu(P, 1), \mu(P, 2), \dots, \mu(P, d)) \\ \beta(P) &:= \sum_{p \in P} \|p - \alpha(P)\|^2 \end{aligned}$$

For a point  $p \in A$  we define

$$\begin{aligned} \Phi &= \{(q_1, q_2) \in G^2 \mid \forall i \in [d] : q_1[i] < q_2[i]\} \\ \Lambda &:= \{\gamma(q_1, q_2) \mid q_1, q_2 \in \Phi\} \\ \lambda(p) &:= \{C \in \Lambda \mid p \in C\} \end{aligned}$$

For a set of points  $P \subseteq A$  an integer  $i \in [d]$  and a real  $t \in \mathbb{R}$  we define

$$\begin{aligned} \mathcal{L}(P, i, t) &:= \{p \in P \mid p[i] \leq t\} \\ \mathcal{R}(P, i, t) &:= P \setminus \mathcal{L}(P, i, t) \end{aligned}$$

For positive integer  $h$ ,  $h$ -tree is a tuple  $(t, i, L, R)$  when  $t \in G$ ,  $i \in [d]$  is an integer and  $L, R$  are  $\ell$ -tree and  $r$ -tree respectively for integers  $0 \leq \ell, r < h$  such that either  $\ell = h - 1$  or  $r = h - 1$ ; 0-tree is an empty tuple. For  $h$ -tree  $(t, i, L, R)$  and a finite non-empty set of points  $P \subset A$  we define

$$\begin{aligned}\text{cost}(P, ()) &:= \beta(P) \\ \text{cost}(P, (t, i, L, R)) &:= \text{cost}(\mathcal{L}(P, i, t), L) + \text{cost}(\mathcal{R}(P, i, t), R).\end{aligned}$$

Finally, we define the function  $s : 2^A \times A \rightarrow \mathbb{R}$  to be

$$s(P, p) := \sum_{C \in \lambda(p)} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())}.$$

We will use the following algorithm in the next theorem.

**Algorithm 1.1:** LEAF( $p, T$ )

**comment:**  $p \in A$  and  $T$  is an  $h$ -tree

$\ell \leftarrow (\sigma_1, \sigma_2, \dots, \sigma_d)$

$r \leftarrow ((1 + \varepsilon)^m \sigma_1, (1 + \varepsilon)^m \sigma_2, \dots, (1 + \varepsilon)^m \sigma_d)$

**while**  $T \neq ()$

**do**  $\left\{ \begin{array}{ll} (t, i, L, R) \leftarrow T & \\ \text{if } p[i] \leq t & \\ \quad \text{then } \begin{cases} r[i] \leftarrow t \\ T \leftarrow L \end{cases} & \\ \quad \text{else } \begin{cases} \ell[i] \leftarrow t \\ T \leftarrow R \end{cases} & \end{array} \right.$

**return**  $(\gamma(\ell, r))$

**Theorem 1.** For every positive integer  $h$ , for every set of points  $P \subseteq A$ , for every  $h$ -tree  $T$  and for every  $p \in P$ :

$$\frac{\|\alpha(\text{LEAF}(p, T) \cap P) - p\|^2}{\text{cost}(P, T)} \leq s(P, p)$$

*Proof.* Let  $r, \ell$  be the variables from Algorithm LEAF. These variables are points such that  $r, \ell \in G$ : they are initialized to be points in  $G$  and their coordinates are altered only to values from  $G$ .

Hence:

$$\text{LEAF}(p, T) = \gamma(\ell, r) \in \Lambda$$

On the other hand  $p \in \text{LEAF}(p, T)$  since from the construction of Algorithm LEAF follows that for every  $i \in [d] : \ell[i] \leq p[i] \leq r[i]$ .

Let  $C = \text{LEAF}(p, T)$ . Since  $C \in \Lambda$  and  $p \in C$ :  $C \in \lambda(p)$ .

Therefore, from the definition of  $s(P, p)$  follows that

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} \leq s(P, p)$$

On the other hand, from the definition of  $\text{cost}$  follows that

$$\text{cost}(C \cap P, ()) \leq \text{cost}(P, T)$$

and therefore

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(P, T)} \leq \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())}.$$

Hence

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(P, T)} \leq s(P, p).$$

□

**Theorem 2.** *For any finite set of points  $P \subset A$ :*

$$\sum_{p \in P} s(P, p) = O(m^{2d})$$

*Proof.*  $G$  is a cartesian product of  $d$  sets of cardinality  $m$  and therefore  $|G| = m^d$ . Therefore

$$|\Lambda| \leq |G^2| = \binom{m^d}{2} = O(m^{2d})$$

and therefore

$$\begin{aligned} \sum_{p \in P} s(P, p) &= \sum_{p \in P} \sum_{C \in \lambda(p)} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} = \sum_{C \in \Lambda} \sum_{p \in P \cap C} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} \\ &= \sum_{C \in \Lambda} \frac{\text{cost}(C \cap P, ())}{\text{cost}(C \cap P, ())} = \sum_{C \in \Lambda} 1 = |\Lambda| = O(m^{2d}). \end{aligned}$$

□