

1 Approximate Decision Tree

In this section the value of an empty sum is 0. Let $\varepsilon \in (0, 1) \subset \mathbb{R}$ be a real number in the open interval $(0, 1)$. Let $d, n \in \mathbb{Z}_{>0}$ be a pair of positive integers. Let $\sigma_1, \dots, \sigma_d \in \mathbb{R}_{>0}$ be positive real numbers. Let $m_1, \dots, m_d \in \mathbb{Z}_{>0}$ be positive integers. For $i \in [d]$, let

$$g_i = \{\sigma_i, (1 + \varepsilon)\sigma_i, (1 + \varepsilon)^2\sigma_i, \dots, (1 + \varepsilon)^{m_i}\sigma_i\}$$

and let $G = g_1 \times g_2 \times \dots \times g_d$.

For $i \in [d]$ and $p \in \mathbb{R}^d$ we denote the i -th coordinate of p by $p[i]$. We may treat a point $p \in \mathbb{R}^d$ as a d -tuple by writing $p = (p[1], p[2], \dots, p[d])$. For a pair of points $p, q \in \mathbb{R}^d$ we define

$$\gamma(q_1, q_2) := \left\{ p \in \mathbb{R}^d \mid \forall i \in [d] : q_1[i] < p[i] \leq q_2[i] \right\}.$$

Let

$$A = \gamma((\sigma_1, \dots, \sigma_d), ((1 + \varepsilon)^{m_1}\sigma_1, (1 + \varepsilon)^{m_2}\sigma_2, \dots, (1 + \varepsilon)^{m_d}\sigma_d)).$$

For a compact of points $P \subset A$ and an integer $i \in [d]$ we define

$$\begin{aligned} \mu(P, i) &:= \frac{1}{|P|} \cdot \sum_{p \in P} p[i] \\ \alpha(P) &:= (\mu(P, 1), \mu(P, 2), \dots, \mu(P, d)) \\ \beta(P) &:= \sum_{p \in P} \|p - \alpha(P)\|^2 \end{aligned}$$

For a point $p \in A$ we define

$$\begin{aligned} \Phi &= \{(q_1, q_2) \in G^2 \mid \forall i \in [d] : q_1[i] < q_2[i]\} \\ \Lambda &:= \{\gamma(q_1, q_2) \mid q_1, q_2 \in \Phi\} \\ \lambda(p) &:= \{C \in \Lambda \mid p \in C\} \end{aligned}$$

For a set of points $P \subseteq A$ an integer $i \in [d]$ and a real $t \in \mathbb{R}$ we define

$$\begin{aligned} \mathcal{L}(P, i, t) &:= \{p \in P \mid p[i] < t\} \\ \mathcal{R}(P, i, t) &:= P \setminus \mathcal{L}(P, i, t) \end{aligned}$$

For a positive integer h , h -tree is a tuple (t, i, L, R) where $i \in [d]$ is an integer, $t \in g_i$ is a coordinate and L, R are ℓ -tree and r -tree respectively

for integers $0 \leq \ell, r < h$ such that either $\ell = h - 1$ or $r = h - 1$; 0-tree is an empty tuple. For h -tree (t, i, L, R) and a finite non-empty set of points $P \subset A$ we define

$$\begin{aligned} \text{cost}(P, ()) &:= \beta(P) \\ \text{cost}(P, (t, i, L, R)) &:= \text{cost}(\mathcal{L}(P, i, t), L) + \text{cost}(\mathcal{R}(P, i, t), R). \end{aligned}$$

Finally, we define the function $s : 2^A \times A \rightarrow \mathbb{R}$ to be

$$s(P, p) := \sum_{C \in \lambda(p)} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())}.$$

We will use the following algorithm in the next theorem.

Algorithm 1.1: LEAF(p, T)

comment: $p \in A$ and T is an h -tree

$\ell \leftarrow (\sigma_1, \sigma_2, \dots, \sigma_d)$

$r \leftarrow ((1 + \varepsilon)^m \sigma_1, (1 + \varepsilon)^m \sigma_2, \dots, (1 + \varepsilon)^m \sigma_d)$

while $T \neq ()$

do $\left\{ \begin{array}{ll} (t, i, L, R) \leftarrow T & \\ \text{if } p[i] \leq t & \\ \quad \text{then } \begin{cases} r[i] \leftarrow t \\ T \leftarrow L \end{cases} & \\ \quad \text{else } \begin{cases} \ell[i] \leftarrow t \\ T \leftarrow R \end{cases} & \end{array} \right.$

return $(\gamma(\ell, r))$

Theorem 1. For every positive integer h , for every set of points $P \subseteq A$, for every h -tree T and for every $p \in P$:

$$\frac{\|\alpha(\text{LEAF}(p, T) \cap P) - p\|^2}{\text{cost}(P, T)} \leq s(P, p)$$

Proof. Let r, ℓ be the variables from Algorithm LEAF. These variables are points such that $r, \ell \in G$: they are initialized to be points in G and their coordinates are altered only to values from G .

Hence:

$$\text{LEAF}(p, T) = \gamma(\ell, r) \in \Lambda$$

On the other hand $p \in \text{LEAF}(p, T)$ since from the construction of Algorithm LEAF follows that for every $i \in [d] : \ell[i] \leq p[i] \leq r[i]$.

Let $C = \text{LEAF}(p, T)$. Since $C \in \Lambda$ and $p \in C$: $C \in \lambda(p)$.

Therefore, from the definition of $s(P, p)$ follows that

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} \leq s(P, p)$$

On the other hand, from the definition of cost follows that

$$\text{cost}(C \cap P, ()) \leq \text{cost}(P, T)$$

and therefore

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(P, T)} \leq \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())}.$$

Hence

$$\frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(P, T)} \leq s(P, p).$$

□

Theorem 2. For any finite set of points $P \subset A$:

$$\sum_{p \in P} s(P, p) = O(m^{2d})$$

Proof. G is a cartesian product of d sets of cardinality m and therefore $|G| = m^d$. Therefore

$$|\Lambda| \leq |G^2| = \binom{m^d}{2} = O(m^{2d})$$

and therefore

$$\begin{aligned} \sum_{p \in P} s(P, p) &= \sum_{p \in P} \sum_{C \in \lambda(p)} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} = \sum_{C \in \Lambda} \sum_{p \in P \cap C} \frac{\|\alpha(C \cap P) - p\|^2}{\text{cost}(C \cap P, ())} \\ &= \sum_{C \in \Lambda} \frac{\text{cost}(C \cap P, ())}{\text{cost}(C \cap P, ())} = \sum_{C \in \Lambda} 1 = |\Lambda| = O(m^{2d}). \end{aligned}$$

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