

Motion Planning

*Good For Long
Horizon Planning;*

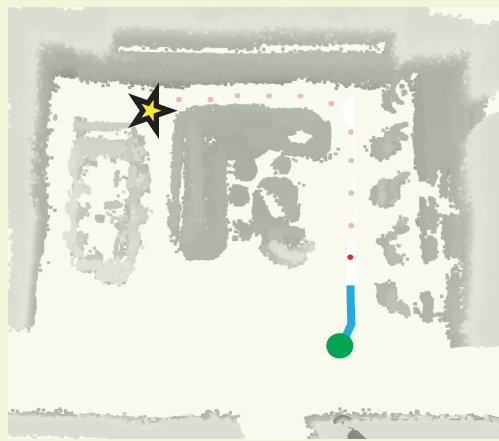
Needs Dynamics Model;



PoPi

Motion Planning suggests waypoints;

*“Local” diffusion policy does manipulation
in between;*



Diffusion

No explicit dynamics;

Needs a lot of data
for global scale;

Doesn't generalize to
new environments;

