```
clc;
clear all;
close all;
```

```
run("Q310_Basic.mlx")
sys_dis_open =
   0.1604 \text{ z}^2 - 0.1958 \text{ z} + 0.07861
  z^3 - 1.937 z^2 + 1.122 z - 0.1421
Sample time: 0.24388 seconds
Discrete-time transfer function.
c = 1 \times 4
            0.1604 -0.1958 0.0786
d = 1 \times 4
    1.0000 -1.9367 1.1220 -0.1421
sys_cont_close =
     7.8 \text{ s}^3 + 205.7 \text{ s}^2 + 601.4 \text{ s} + 1276
  s^4 + 15.8 s^3 + 212.7 s^2 + 608.4 s + 1276
Continuous-time transfer function.
sys dis close =
  0.1328 \ z^3 - 0.3505 \ z^2 + 0.3048 \ z - 0.08705
  z^4 - 3.73 z^3 + 5.24 z^2 - 3.288 z + 0.778
Sample time: 0.015887 seconds
Discrete-time transfer function.
c1 = 1 \times 5
             0.1328 -0.3505 0.3048 -0.0871
d1 = 1 \times 5
    1.0000 -3.7296 5.2395 -3.2878
                                              0.7780
```

generate data

```
tfinal=100;
t = 0:T_s_close:tfinal;

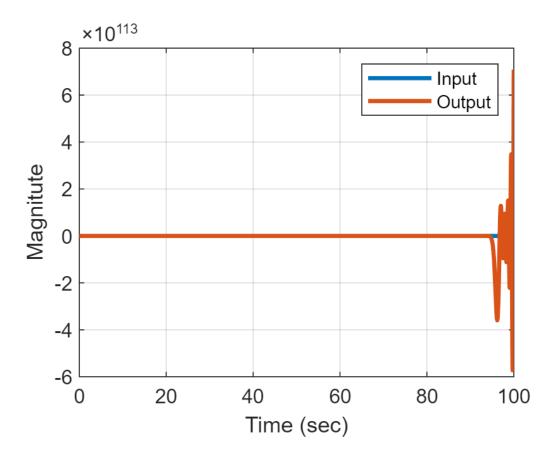
Priemss=primes(100);
u=zeros(numel(t),1);
for i=20:numel(Priemss)
    input_dummy=gensig('sine' , tfinal/Priemss(1,i) , tfinal ,T_s_close);
    u=u+input_dummy;
end

var_e=0.7;
e=sqrt(var_e);
Noise=(-e+(e+e)*rand(numel(t),1));
u=u+Noise;
y = lsim(sys_dis_close ,u ,t);
```

smooth parameter variation

legend('Input','Output');

```
paras=[];
uu=400
uu = 400
for temp=uu:numel(y)
     paras(:,temp)=[d1(2:end)+d1(2:end)*.001*(sin(.005*(temp-uu))),(c1+c1*.001*(sin(.005*(temp-uu)))]
    y(temp)=[-(y(temp-1:-1:temp-4))',(u(temp:-1:temp-4))']*paras(:,temp);
end
     sys_dis = tf(c1+c1*.0001*(sin(.05*(temp-uu))-1)', [1 -d1(2:end)+d1(2:end)*.0001*(sin(.05*(temp-uu))-1)']
sys_dis =
 0.1328 z^3 - 0.3504 z^2 + 0.3048 z - 0.08704
 z^4 + 3.73 z^3 - 5.24 z^2 + 3.288 z - 0.7781
Sample time: 0.24388 seconds
Discrete-time transfer function.
     ident_analog = d2c(sys_dis)
Warning: The model order was increased to handle real negative poles.
ident_analog =
   -0.4281 \text{ s}^4 + 6.619 \text{ s}^3 + 1.974 \text{ s}^2 - 29.16 \text{ s} + 0.443
  s^5 - 5.515 s^4 + 141.1 s^3 + 1229 s^2 + 5790 s + 1.238e04
Continuous-time transfer function.
plot(t,u ,t , y ,'LineWidth',2);
xlabel('Time (sec)');
ylabel('Magnitute');
grid on
```



Kalman Filter

```
N = numel(y);
% %-----%
%choose number of parameters
Parameters_in_den=3

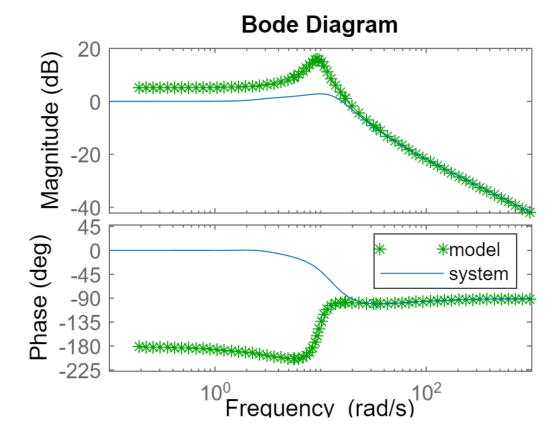
Parameters_in_den = 3

Parameters_in_num=3

Parameters_in_num = 3

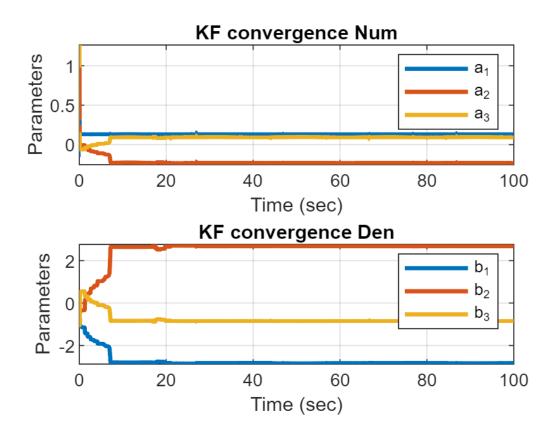
% %------%
Nv=Parameters_in_num+Parameters_in_den;
```

Bode



KF Convergence

```
subplot(2,1,1)
plot(t , theta_hat_KF((Parameters_in_num+1):end,:) , 'LineWidth' , 2);
xlabel('Time (sec)');
ylabel('Parameters');
title('KF convergence Num');
grid on
legend('a_1','a_2','a_3')
% xlim([0 6])
% ylim([-1 1])
subplot(2,1,2)
plot(t , -theta_hat_KF(1:Parameters_in_num ,:) , 'LineWidth' , 2);
xlabel('Time (sec)');
ylabel('Parameters');
title('KF convergence Den');
grid on
legend('b_1','b_2','b_3')
```



```
% xlim([0 6])
% ylim([-7 7])
```