```
clc;
clear all;
close all;
```

generate data

```
run ("Basics.m")
```

```
sys =

              1.3 s + 1.333
  ---------------------------------------------
  s^4 + 3.967 s^3 + 8.41 s^2 + 10.62 s + 8.756

Continuous-time transfer function.
fb = 2.4327
sysd =

  0.0004236 z^3 + 0.001167 z^2 - 0.000997 z - 0.0003069
  -----------------------------------------------------
      z^4 - 3.481 z^3 + 4.58 z^2 - 2.697 z + 0.5991

Sample time: 0.12914 seconds
Discrete-time transfer function.
c = 1×5
         0     0.0004     0.0012    -0.0010    -0.0003
d = 1×5
    1.0000    -3.4807     4.5802    -2.6968     0.5991
```

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
tfinal=200;
t = 0:T_s:tfinal;
u = gensig('sine' , tfinal/20 , tfinal ,T_s);%+gensig('sine' , tfinal/50 , tfinal ,T_s)+gensig(

Noise=[1:numel(t)];
Noise(1:10) = ones(1,10)';
for i=4:1:numel(t)
    Noise(i)=+0.6*Noise(i-1)+0.75*Noise(i-2)-0.35*Noise(i-3);
end

u=u+Noise';

y = lsim(sysd  ,u ,t);
plot(t,u ,t , y ,'LineWidth',2) ;
xlabel('Time (sec)') ;
ylabel('Value') ;
title('ressponse of Question 2') ;
grid on
legend('Input' , 'OutPut') ;
```
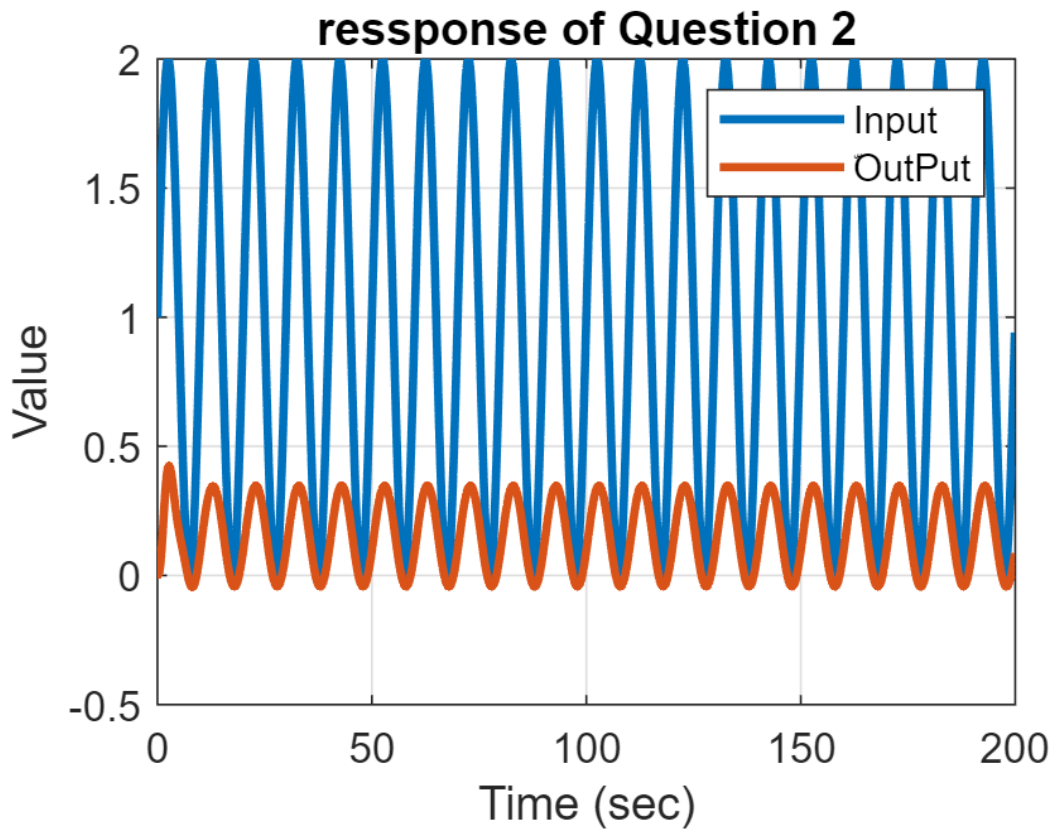
ressponse of Question 2

recursive least esquare estimation

```
N = numel(y) ;
%choose number of parameters
Parameters_in_den=4
```

```
Parameters_in_den = 4
```

```
Parameters_in_num=4
```

```
Parameters_in_num = 4
```

```
Nv=Parameters_in_num+Parameters_in_den
```

```
Nv = 8
```

```
P = 1e12*eye(Nv) ;
theta=[Nv,N]
```

```
theta = 1×2
        8        1549
```

```
theta(1:Nv,1:30) = 5*ones(Nv,30) ;

phi=[];
Eror=zeros(1,N)
```

```
Eror = 1×1549
    0    0    0    0    0    0    0    0    0    0    0    0    0 ...
```

```
tic
for i = (max(Parameters_in_num,Parameters_in_den))+1:N
    phi(:,i) = [[y(i-1:-1:i-Parameters_in_den)]' , [u(i-1:-1:i-Parameters_in_num)]']';
    K = P*phi(:,i)*(1+phi(:,i)'*P*phi(:,i))^(-1) ;
    P = (eye(Nv) - K*phi(:,i)')*P ;
    theta(:,i) = theta(:,i-1) + K*(y(i) - phi(:,i)'*theta(:,i-1));
    Eror(i)=(Eror(i-1)+(y(i)-phi(:,i)'*theta(:,i))^2);
end
```

Bode

```
ident_dis = tf(theta((Parameters_in_num+1):end,end)' ,[1 -theta(1:Parameters_in_num ,end)'], T_
```

```
ident_dis =

  0.0005414 z^3 + 0.0005013 z^2 + 5.629e-05 z - 0.0007949
  -------------------------------------------------------
      z^4 - 3.471 z^3 + 4.554 z^2 - 2.674 z + 0.5925

Sample time: 0.12914 seconds
Discrete-time transfer function.
```

```
ident_analog = d2c(ident_dis)
```

```
ident_analog =

  0.003168 s^3 - 0.02925 s^2 + 1.336 s + 1.421
  --------------------------------------------
  s^4 + 4.053 s^3 + 8.692 s^2 + 11.03 s + 9.331

Continuous-time transfer function.
```
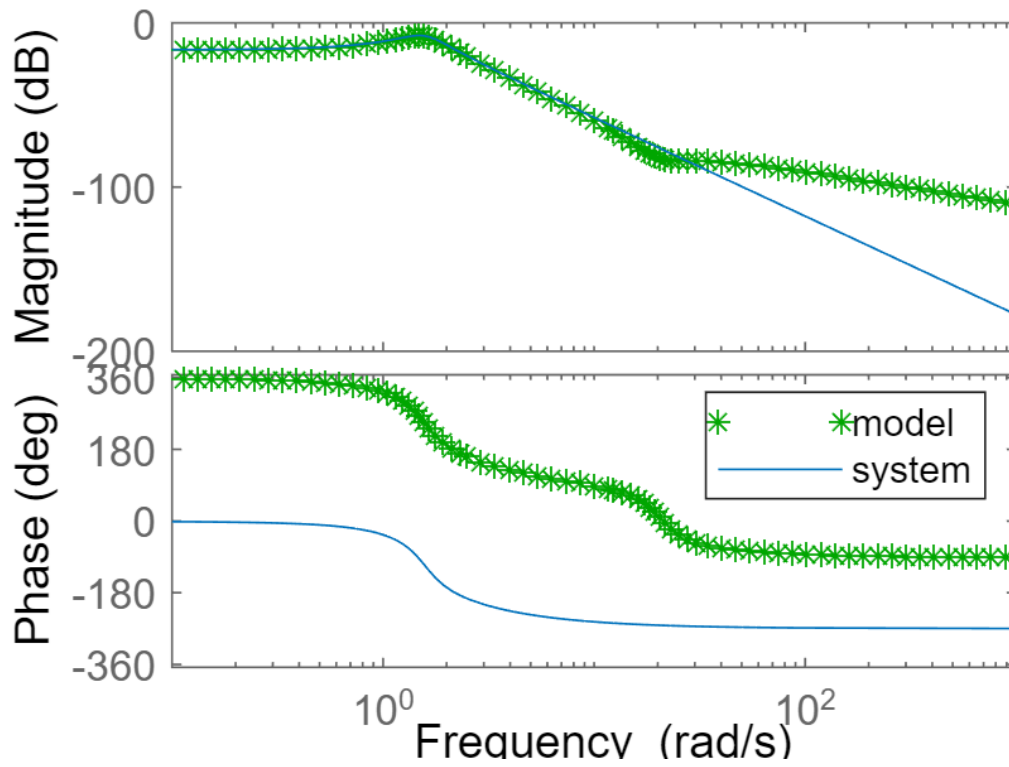
```
bode(ident_analog ,'g*',sys )
legend('model ','system')
```
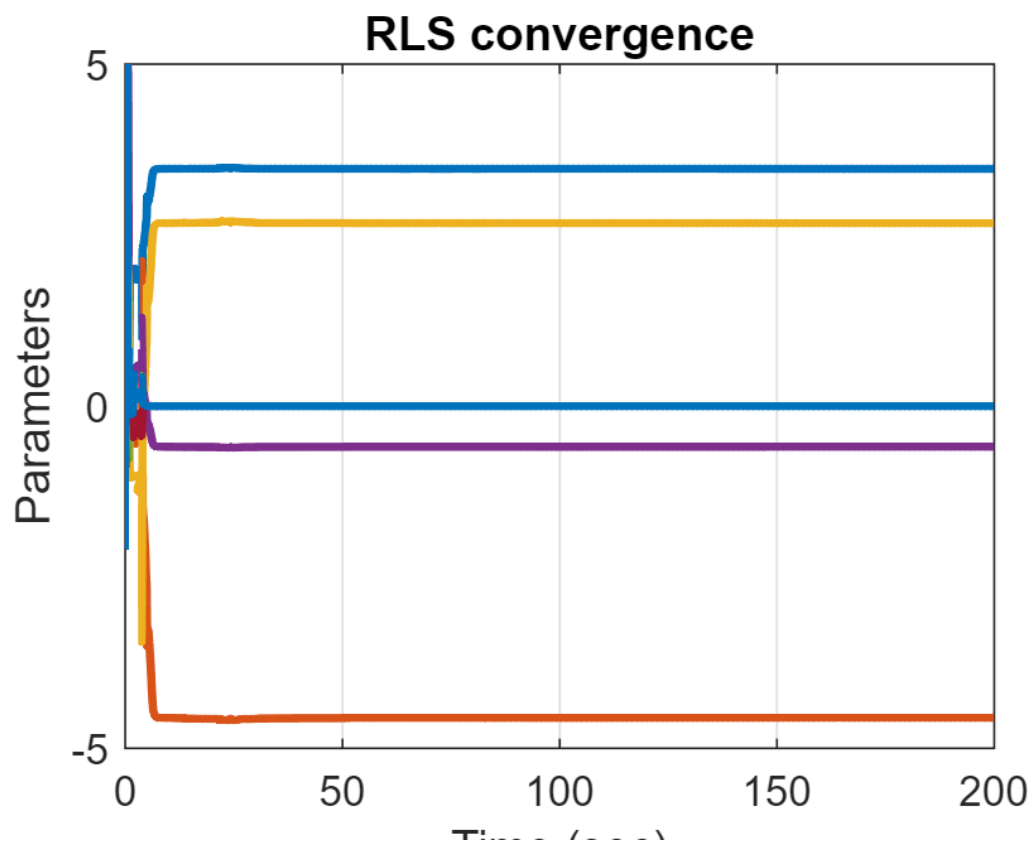
Bode Diagram
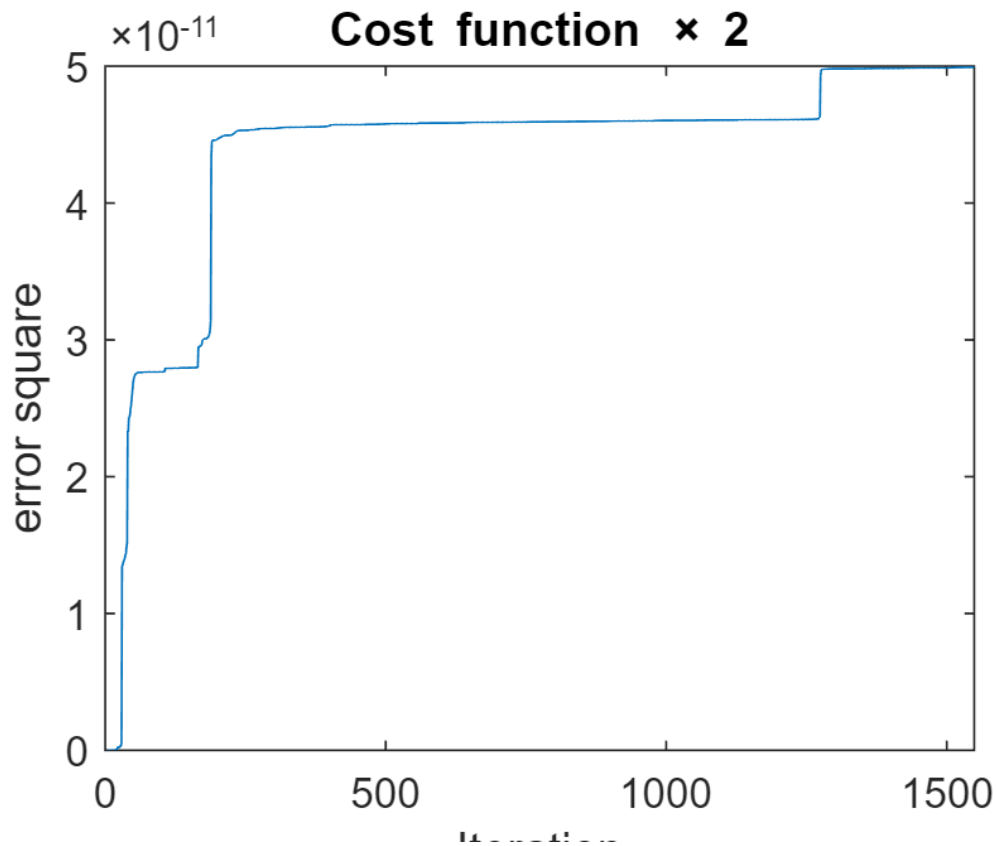

RLS Convergence

```
plot(t , theta(:,:) , 'LineWidth' , 2) ;
xlabel('Time (sec)') ;
ylabel('Parameters') ;
title('RLS convergence') ;
grid on
```

RLS convergence

Parameters

Time (sec)

```
plot(1:1:N,Eror)
xlabel('Iteration') ;
ylabel('error square') ;
title('Cost function \times 2') ;
```

Cost function × 2

(y-axis: error square, ×10⁻¹¹; x-axis: Iteration)

```
tfinal=1000;
T_s=T_s
```

T_s = 0.1291

```
t = 0:T_s:tfinal;
u = gensig('square' , tfinal/20 , tfinal ,T_s);
u = u+rand(numel(t),1);
y = lsim(sysd,u ,t);

y_model = lsim(ident_dis ,u ,t);

plot(t,y_model ,'b*',t , y ,'LineWidth',1.25) ;
xlabel('Time (sec)') ;
ylabel('Value') ;
title('ressponse of Question 2') ;
grid on
legend('Under parameter Model' , 'System') ;
```

ressponse of Question 2