

$$dI = i dl = k R \sin \theta d\theta \quad (15)$$

$$dB = \frac{\mu_0 I}{2\pi R} \quad (25)$$

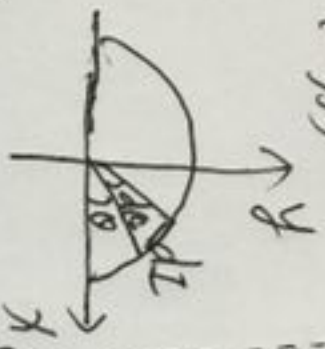
$$dB_z = dB_y = 0 \quad (28)$$

$$dB_x = dB \sin \theta = \frac{\mu_0 I \sin \theta}{2\pi} d\theta \quad (28)$$

$$B = \int dB_x = \int_0^\pi \frac{\mu_0 I \sin \theta}{2\pi} d\theta$$

$$= \frac{\mu_0 I}{4} \quad (28)$$

$$\text{360} = \pi \text{ rad} \quad (15)$$



$$\oint \vec{B} \cdot d\vec{l} = \sum I_0 \quad (28)$$

$$r < R \quad B = \frac{\mu_0 I r}{2\pi R^2} \quad (28)$$

$$r > R \quad B = \frac{\mu_0 I}{2\pi r} \quad (28)$$

$$d\Phi = \vec{B} \cdot d\vec{s} = B dr \quad (28)$$

$$\Phi = \int_0^R \frac{\mu_0 I}{2\pi R^2} r dr + \int_R^\infty \frac{\mu_0 I}{2\pi r} dr$$

$$= \frac{\mu_0 I}{4\pi} + \frac{\mu_0 I}{2\pi} \ln 2 \quad (28)$$