

Entire code and report - Assignment 3

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```
%% MyMainScript
```

```
tic;
```

```
%% Your code here
```

```
    myHarrisCornerDetector();
```

```
toc;
```

```
function [] = myHarrisCornerDetector()
```

```
S = load('../data/boat.mat');
```

```
I=S.imageOrig; %load the original image
```

```
% min(min(I)) = 0 so no need of reshifting
```

```
I = (I)/(max(max(I))); % make the intensity range from 0 to 1
```

```
% initialize parameters for tuning
```

```
sigma_1 = 1; % sigma_1 is the weight gaussian
```

```
sigma_2 = 1; % sigma_2 is the gaussian filtering for original image to get Ix,Iy
```

```
% filter the image before extracting the derivatives
```

```
I = imgaussfilt(I,sigma_2);
```

```
[Ix,Iy] = imgradientxy(I);
```

```
% compute the  $I_x^2$ ,  $I_y^2$ ,  $I_x I_y$  matrices before computing the structure
```

```
% tensor
```

```
Ix2 = Ix.^2;
```

```
figure;
```

```
imshow(mat2gray(Ix)),colorbar;
```

```
title('Ix');
```

```
Iy2 = Iy.^2;
```

```
figure;
```

```
imshow(mat2gray(Iy)),colorbar;
```

```
title('Iy');
```

```
lxly = lx.*ly;
```

```
% these lines filter lx2 ly2 lxly by another gaussian which is supposed to
```

```
% be the weights for when we construct structure tensors for pixels, thus
```

```
% after this step we don't need to worry about the weights we can just add
```

```
% the matrices at the neighbourhood of each pixel
```

```
g = fspecial('gaussian', [6 6], sigma_1);
```

```
lx2 = imfilter(lx2,g,'same');
```

```
ly2 = imfilter(ly2,g,'same');
```

```
lxly = imfilter(lxly,g,'same');
```

```
[X,Y] = size(l);
```

```
eigen1 = double(zeros(X,Y)); % smaller eigen value
```

```
eigen2 = double(zeros(X,Y)); % larger eigen value
```

```
Result = double(zeros(X,Y)); % cornerness measure
```

```
k = 0.15; % tuning parameter for measuring
```

```
for i=1:X-1
```

```
    for j=1:Y-1
```

```
        if(i == 1 || j == 1)
```

```
            reslx2 = 0;
```

```
            resly2 = 0;
```

```
            reslxly = 0;
```

```
            for a=0:1
```

```
                for b=0:1
```

```
                    reslx2 = reslx2 + lx2(a+i,b+j);
```

```
                    resly2 = resly2 + ly2(a+i,b+j);
```

```
                    reslxly = reslxly + lxly(a+i,b+j);
```

```
                end
```

```
end
```

```
tensor = double(zeros(2,2));
```

```
tensor(1,1) = reslx2;
```

```
tensor(1,2) = reslxly;
```

```
tensor(2,1) = reslxly;
```

```
tensor(2,2) = resly2;
```

```
%tensor;
```

```
e = eig(tensor);
```

```
%min(e);
```

```
%max(e);
```

```
eigen1(i,j) = min(e);
```

```
eigen2(i,j) = max(e);
```

```
Result(i,j) = (eigen1(i,j)*eigen2(i,j)) -  
k*(eigen1(i,j)+eigen2(i,j))*(eigen1(i,j)+eigen2(i,j));
```

```
else
```

```
reslx2 = 0;
```

```
resly2 = 0;
```

```
reslxly = 0;
```

```
for a=-1:1
```

```
    for b=-1:1
```

```
        reslx2 = reslx2 + lx2(a+i,b+j);
```

```
        resly2 = resly2 + ly2(a+i,b+j);
```

```
        reslxly = reslxly + lxly(a+i,b+j);
```

```
    end
```

```
end
```

```
tensor = double(zeros(2,2));
```

```
tensor(1,1) = reslx2;
```

```
tensor(1,2) = reslxly;
```

```
tensor(2,1) = reslxly;
```

```
tensor(2,2) = resly2;
```

```
%tensor;
```

```
e = eig(tensor);
```

```
%min(e);
```

```
%max(e);
```

```
eigen1(i,j) = min(e);
```

```
eigen2(i,j) = max(e);
```

```
Result(i,j) = (eigen1(i,j)*eigen2(i,j)) -
```

```
k*(eigen1(i,j)+eigen2(i,j))*(eigen1(i,j)+eigen2(i,j));
```



```
        end

    end

end

Corners = (Result > 0.35);

max(max(Result));

% display all the results

figure;

imshow(mat2gray(eigen1));

title('Minimum eigen value'),colorbar;

figure;

imshow(mat2gray(eigen2));

title('Maximum eigen value'),colorbar;

figure;
```

```
imshow(mat2gray(Result)),colorbar;
```

```
title('Cornersness measure');
```

```
figure;
```

```
imshow(mat2gray(Corners)),colorbar;
```

```
title('Thresholded Cornersness measure');
```

```
figure;
```

```
imshow(mat2gray(Corners+I)),colorbar;
```

```
title('Cornersness measure superimposed on image');
```

```
%% Mean-Shift Segmentation
```

```
%
```

```
% We implemented the Mean-Shift algorithm by first downsampling the image
```

```
% (gaussian smoothing with  $\sigma=1$  followed by resizing to half the size
```

```
% along both dimensions) and then scaling it to the range [0,1].
```

```
%

%% Parameter tuning

%

%  cntr = 0;

%  for hc=0.005:0.005:0.1

%      for hs=5:5:30

%          res = myMeanShiftSegmentation(img, hc, hs);

%          imwrite(res, ['./images/trial_',num2str(cntr),'.png']);

%          cntr = cntr+1;

%      end

%  end

%

%%
```

% All resultant images were compared visually. We chose the best output by

% looking for meaningful and distinct (i.e. less interpolation between

% segments) segments, and found the following results:

%%

% variables for displaying images

myNumOfColors = 200;

myColorScale = repmat((0:1/(myNumOfColors-1):1)',1,3);

disp('Original image');

tic;

img = im2single(imread('../data/baboonColor.png'));

% smoothen the image

img = imgaussfilt(img, 1);

% downsample image

```
img = imresize(img, 0.5);

% image has been rescaled to [0,1] range

% so hc has to be adjusted accordingly

figure; imagesc(img); title('Original image');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

toc; tic;

disp('Tuned output, h_c=0.05, h_s=20');

res = myMeanShiftSegmentation(img, 0.05, 20);

figure; imagesc(res); title('Tuned output, h_c=0.05, h_s=20');

colormap(myColorScale);

daspect ([1 1 1]);
```

```
axis tight; axis off;

% save image

save(['../images/tunedBaboon.mat'], 'res');

toc; tic;

disp('Output for h_c=0.2, h_s=20');

res = myMeanShiftSegmentation(img, 0.2, 20);

figure; imagesc(res); title('Output for h_c=0.2, h_s=20');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

toc; tic;

disp('Output for h_c=0.005, h_s=20');

res = myMeanShiftSegmentation(img, 0.005, 20);
```

```
figure; imagesc(res); title('Output for h_c=0.005, h_s=20');
```

```
colormap(myColorScale);
```

```
daspect ([1 1 1]);
```

```
axis tight; axis off;
```

```
toc; tic;
```

```
disp('Output for h_c=0.05, h_s=50');
```

```
res = myMeanShiftSegmentation(img, 0.05, 50);
```

```
figure; imagesc(res); title('Output for h_c=0.05, h_s=50');
```

```
colormap(myColorScale);
```

```
daspect ([1 1 1]);
```

```
axis tight; axis off;
```

```
toc; tic;
```

```
disp('Output for h_c=0.05, h_s=5');
```

```

res = myMeanShiftSegmentation(img, 0.05, 5);

figure; imagesc(res); title('Output for h_c=0.05, h_s=5');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

toc;

%% Observations

%

% We can clearly see (from the output images generated by using

% neighborhood parameter values) that the chosen values are optimal. High

% values of h_c and h_s favour intermixing of segments (diffused boundaries)

% whereas lower values don't produce any significant changes.

function res = myMeanShiftSegmentation(img, hc, hs)

```



```
% Parameters

% #iterations till 'assumed' convergence

num_iters = 20;

% amount by which we move towards the peak everytime

step_size = (hc*hs)^2/(hc^2+hs^2);

% prepare data structure for storing pixel-wise information

[H,W,C] = size(img);

ds = zeros([H,W,C+2]);

ds(:, :, 1:C) = img;

ds(:, :, C+1) = repmat(1:W, [H,1]);

ds(:, :, C+2) = repmat((1:H)', [1, W]);

ds = reshape(ds, [H*W, C+2]);

% allocate space for storing calculation results
```

```

num_nn = floor(sqrt(H*W));

diff = zeros([H*W, C+2, num_nn]);

fx = zeros([H*W, num_nn]);

sumfx = zeros([H*W, 1]);

grad_c = zeros([H*W, C]);

grad_s = zeros([H*W, 2]);

% waitbar for showing #iterations completed

h = waitbar(0, "Iterations completed");

for i=1:num_iters

    % find nearest neighbors

    idx = knnsearch(ds, ds, 'K', num_nn);

    % fill the diff matrix

    diff(:, :, i) = ds - permute(reshape(ds(idx', :)', [C+2, num_nn, H*W]), [3 1 2]);

```

```
% find the kernel weights for each pixel
```

```
fx(:, :) = exp(-squeeze(sum(diff(:, 1:C, :).^2/hc^2, 2))).*exp(-squeeze(sum(diff(:,  
C+1:C+2, :).^2/hs^2, 2)));
```

```
% sum up the weights for all neighbors
```

```
sumfx(:, :) = sum(fx, 2);
```

```
% find the gradient for color domain
```

```
grad_c(:, :) = -squeeze(sum(reshape(fx, [H*W, 1, num_nn]).*diff(:, 1:C, :)/hc^2, 3));
```

```
grad_c(:, :) = grad_c./sumfx;
```

```
% find the gradient for spatial domain
```

```
grad_s(:, :) = -squeeze(sum(reshape(fx, [H*W, 1, num_nn]).*diff(:, C+1:C+2, :)/hs^2, 3));
```

```
grad_s(:, :) = grad_s./sumfx;
```

```
% update the pixel data structure
```

```
ds(:, 1:C) = ds(:, 1:C) + step_size*grad_c;
```

```
ds(:,C+1:C+2) = ds(:,C+1:C+2) + step_size*grad_s;
```

```
waitbar(i/num_iters, h);
```

```
end
```

```
close(h);
```

```
res = reshape(ds(:,1:C), [H,W,C]);
```

```
end
```

Question1

August 2018

1

Findings

optimal parameters :- $\sigma_1 = \sigma_2 = 1$, $k = 0.15$ and threshold parameter = 0.35.

The tuned output is in images folder where all the asked images have been

provided in the report folder there are 4 folders. One of them corresponds to

tuned output the rest show how deviating from the tuned output the results get worse, particularly when we decrease k or threshold parameter more and more edges start showing up as corner, so we have set a high k so that we get less edges without compromising the corners.

Mean-Shift Segmentation

We implemented the Mean-Shift algorithm by first downsampling the image (gaussian smoothing with $\sigma=1$ followed by resizing to half the size along both dimensions) and then scaling it to the range [0,1]. The optimum parameter values found are:

num_iteration = 20, Gaussian kernel bandwidth for the color feature = 0.05, Gaussian kernel bandwidth for the spatial feature = 20

Contents

Parameter tuning

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Parameter tuning

```
cntr = 0;
```

```
for hc=0.005:0.005:0.1
```

```
    for hs=5:5:30
```

```
        res = myMeanShiftSegmentation(img, hc, hs);
```

```
        imwrite(res, ['./images/trial_', num2str(cntr), '.png']);
```

```
        cntr = cntr+1;
```

```
    end
```

```
end
```

All resultant images were compared visually. We chose the best output by looking for meaningful and distinct (i.e. less interpolation between segments) segments, and found the following results:

% variables for displaying images

```
myNumOfColors = 200;

myColorScale = repmat((0:1/(myNumOfColors-1):1)',1,3);

disp('Original image');

tic;

img = im2single(imread('../data/baboonColor.png'));

% smoothen the image

img = imgaussfilt(img, 1);

% downsample image

img = imresize(img, 0.5);

% image has been rescaled to [0,1] range

% so hc has to be adjusted accordingly

figure; imagesc(img); title('Original image');

colormap(myColorScale);
```

```
daspect ([1 1 1]);

axis tight; axis off;

toc; tic;

disp('Tuned output, h_c=0.05, h_s=20');

res = myMeanShiftSegmentation(img, 0.05, 20);

figure; imagesc(res); title('Tuned output, h_c=0.05, h_s=20');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

% save image

save(['../images/tunedBaboon.mat'], 'res');

toc; tic;

disp('Output for h_c=0.2, h_s=20');
```



```
res = myMeanShiftSegmentation(img, 0.2, 20);

figure; imagesc(res); title('Output for h_c=0.2, h_s=20');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

toc; tic;

disp('Output for h_c=0.005, h_s=20');

res = myMeanShiftSegmentation(img, 0.005, 20);

figure; imagesc(res); title('Output for h_c=0.005, h_s=20');

colormap(myColorScale);

daspect ([1 1 1]);

axis tight; axis off;

toc; tic;
```

```
disp('Output for h_c=0.05, h_s=50');
```

```
res = myMeanShiftSegmentation(img, 0.05, 50);
```

```
figure; imagesc(res); title('Output for h_c=0.05, h_s=50');
```

```
colormap(myColorScale);
```

```
daspect ([1 1 1]);
```

```
axis tight; axis off;
```

```
toc; tic;
```

```
disp('Output for h_c=0.05, h_s=5');
```

```
res = myMeanShiftSegmentation(img, 0.05, 5);
```

```
figure; imagesc(res); title('Output for h_c=0.05, h_s=5');
```

```
colormap(myColorScale);
```

```
daspect ([1 1 1]);
```

```
axis tight; axis off;
```

toc;

Original image

Elapsed time is 0.093338 seconds.

Tuned output, $h_c=0.05$, $h_s=20$

Elapsed time is 79.566733 seconds.

Output for $h_c=0.2$, $h_s=20$

Elapsed time is 80.835150 seconds.

Output for $h_c=0.005$, $h_s=20$

Elapsed time is 86.300257 seconds.

Output for $h_c=0.05$, $h_s=50$

Elapsed time is 82.222428 seconds.

Output for $h_c=0.05$, $h_s=5$

Elapsed time is 80.574358 seconds.

Observations

We can clearly see (from the output images generated by using neighborhood parameter values) that the chosen values are optimal. High values of h_c and h_s favour intermixing of segments (diffused boundaries) whereas lower values don't produce any significant changes.

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