

線性代數 + Julia + $LAT_{E}X$ 的學習筆記

Date: 2020-10-02

整個學習過程將以如下「線性代數」課程為主軸學習：

線性代數 台灣大學電機系 蘇柏青

本課程是線性代數的入門課程。線性代數係以「向量空間」(Vector Space)為核心概念之數學工具，擁有極廣泛之應用，非常值得理工商管等科系大學部同學深入修習，作為日後專業應用之基礎。

課程來源：<http://ocw.aca.ntu.edu.tw/ntu-ocw/index.php/ocw/cou/102S207>

學習目標

如下為幾個學習的子目標：

學科

- 線性代數 - 重新學習線性代數，了解重要概念的中文及英文詞彙及應用。

工具

- Julia - 深入學習，了解重要套件的應用及使用。
- Pluto - 隨之成長，作為撰寫學習記錄的工具。
- LaTeX - 隨緣學習，作為撰寫學習記錄的工具。
- Markdown - 隨緣學習，作為撰寫學習記錄的工具。

服務

- GitHub - 學習使用 GitHub 服務，並記錄學習歷程及分享學習內容。

單元 I · Basic Concepts on Matrices and Vectors

Matrix

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} = [a_{ij}] = M_{mn}$$

Matrix Addition

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} + \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 4 & 5 \\ 6 & 8 \end{bmatrix}$$

```
3x2 Array{Int64,2}:  
 2  3  
 4  5  
 6  8  
  
· [1 2; 3 4; 5 6]+[1 1; 1 1; 1 2]
```

Scalar Multiplication

$$cA$$
$$3 \cdot \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$$

```
3x2 Array{Int64,2}:  
 3  6  
 9 12  
15 18  
  
· 3 * [1 2; 3 4; 5 6]
```

```
3x2 Array{Int64,2}:  
 3  6  
 9 12  
15 18  
  
· 3 .* [1 2; 3 4; 5 6]
```

Transpose

$$C = \begin{bmatrix} 7 & 9 \\ 18 & 31 \\ 52 & 68 \end{bmatrix} \Rightarrow C^T = \begin{bmatrix} 7 & 18 & 52 \\ 9 & 31 & 68 \end{bmatrix}$$

```
2x3 LinearAlgebra.Adjoint{Int64,Array{Int64,2}}:  
 7 18 52  
 9 31 68  
  
· let  
·   C=[7 9; 18 31; 52 68]  
·   C'  
· end
```

Vectors

Row Vector:

$$\begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}$$

Column Vector:

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}^T$$

The i th component of \mathbf{v}

$$v_i$$

```
1x4 Array{Int64,2}:  
 1  2  3  4
```

```
· [ 1 2 3 4]
```

```
► Int64[1, 2, 3, 4]
```

```
· [1; 2; 3; 4;]
```

```
4x1 LinearAlgebra.Adjoint{Int64,Array{Int64,2}}:  
 1  
 2  
 3  
 4
```

```
· [ 1 2 3 4]'
```

Linear Combination

A *linear combination* of vectors $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ is a vector of the form

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k$$

where c_1, c_2, \dots, c_k are scalars. These scalars are called the *coefficients* of the linear combination.

Standard Vectors

The standard vectors of R^n are defined as

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, e_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

Matrix-Vector Product

$$Av = v_1a_1 + v_2a_2 + \cdots + v_na_n$$

► Int64[23, 53, 83]

```

. let
.   A=[1 2; 3 4; 5 6]
.   v=[7;8]
.   A*v
. end

```

Identity Matrix

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Stochastic Matrix

$$A = \begin{bmatrix} 0.85 & 0.03 \\ 0.15 & 0.97 \end{bmatrix}$$

Slide to set number of **years**:  40

Slide to set population of **city**:  1200

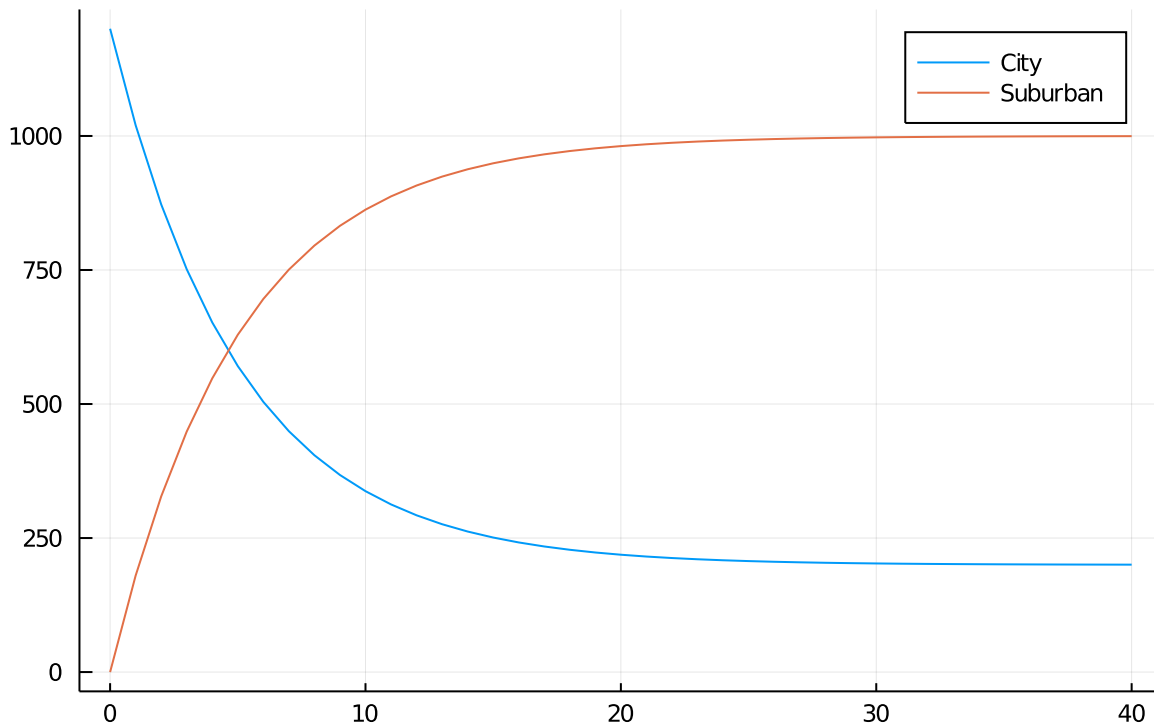
Slide to set population of **suburban**:  0

```

. begin
.   u01xslider = @bind u01x Slider(1:100; default=40, show_value=true)
.   u01cslider = @bind u01c Slider(0:1200; default=1200, show_value=true)
.   u01sslider = @bind u01s Slider(0:1200; default=0, show_value=true)
.   md"""
.   Slide to set number of **years**: $(u01xslider)
.
.   Slide to set population of **city**: $(u01cslider)
.
.   Slide to set population of **suburban**: $(u01sslider)
.   """
. end

```

Population Trend



```

. let
.   x=u01x # Number of Years (x)
.   pc=u01c # Population of City
.   ps=u01s # Population of Suburban
.   A=[0.85 0.03; 0.15 0.97]
.   #=
.   # p0 Population in year 0
.   p0=[500; 700]
.   p1=A*p0
.   p2=A*(p1)
.   p3=A*(p2)
.   p4=A*(p3)
.   p5=A*(p4)
.   x=0:5
.   Y=hcat(p0, p1, p2, p3, p4, p5)
.   plot(x, Y', title = "Population", label = ["City" "Suburban"])
.   =#
.   p=[pc; ps]
.   Y=p
.   for i in 1:x
.     p=A*p
.     Y=hcat(Y, p)
.   end
.   plot(0:x, Y', title = "Population Trend", label = ["City" "Suburban"])
. end

```

單元 2 · System of Linear Equations

System of Linear Equations

$$A = \begin{bmatrix} 1 & -2 & -1 \\ 3 & -6 & -5 \\ 2 & -1 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 3 \\ 3 \\ 0 \end{bmatrix}$$

$$Ax = b$$

Solves $Ax = b$ by (essentially) Gaussian elimination (Julia \ Operator):

$$x = A \setminus b$$

```
[-4.000000000000001, -5.000000000000001, 3.000000000000001]
[3.0, 3.0, 0.0]
true
```

```
· # Solve System of Linear Equations
· let
·     with_terminal() do
·         A=[1 -2 -1; 3 -6 -5; 2 -1 1]
·         b=[3; 3; 0]
·         x=A \ b
·         println(x)
·         println(A*x)
·         println(A*x == b)
·     end
· end
```

Row Echelon Form & Reduced Row Echelon Form

```
[0.4037433155080213, -1.2112299465240637, 0.11229946524064169, 1.4812834224598934, 2.0]
[6.999999999999998, 9.000000000000002, 2.0, 0.0]
false
```

```
· # Solve System of Linear Equations
· let
·     with_terminal() do
·         A=[1 -3 0 2 0; 0 0 1 6 0; 0 0 0 0 1; 0 0 0 0 0]
·         b=[7; 9; 2; 0]
·         x=A \ b
·         println(x)
·         println(A*x)
·         println(A*x == b)
·     end
· end
```

單元 3 · Gaussian Elimination

實作參考：

[Gaussian-elimination.pdf](#)

[Numerical Analysis by Julia Series 1 — Gauss Elimination | by Treee July | Medium](#)

對列及行的參照：

```
3x3 Array{Int64,2}:
```

```
1  2  3
4  5  6
7  8  9
```

```
• let
•     A=[ 1 2 3; 4 5 6; 7 8 9]
• end
```

```
Array{Any}((7,))
1: String "A: [1 2 3; 4 5 6; 7 8 9]"
2: String "A[1, 1]: 1"
3: String "A[end, end]: 9"
4: String "r1: [1, 2, 3]"
5: String "ΣAi: [12, 15, 18]"
6: String "c1: [1, 4, 7]"
7: String "ΣAj: [6, 15, 24]"
```

```
• let
•     o=[]
•     # Matrix
•     A=[ 1 2 3; 4 5 6; 7 8 9]
•     push!(o, @sprintf("A: %s", A))
•     # Elements
•     push!(o, @sprintf("A[1, 1]: %s", A[1, 1]))
•     push!(o, @sprintf("A[end, end]: %s", A[end, end]))
•     # Row
•     r1=A[1,:]
•     push!(o, @sprintf("r1: %s", r1))
•     ΣAi=A[1,:]+A[2,:]+A[3,:]
•     push!(o, @sprintf("ΣAi: %s", ΣAi))
•     # Column
•     c1=A[:,1]
•     push!(o, @sprintf("c1: %s", c1))
•     ΣAj=A[:,1]+A[:,2]+A[:,3]
•     push!(o, @sprintf("ΣAj: %s", ΣAj))
•     with_terminal(dump, o)
• end
```

👍 選定之輸出方案： 1) 容易以 do ... end 區塊包裝 3) 轉貼程式碼到他處不用修改

```
2020年10月 2日 週五 17時24分43秒 CST
A: Array{Int64}((3, 3)) [1 2 3; 4 5 6; 7 8 9]
A[1, 1]: Int64 1
A[end, end]: Int64 9
r1: Array{Int64}((3,)) [1, 2, 3]
ΣAi: Array{Int64}((3,)) [12, 15, 18]
c1: Array{Int64}((3,)) [1, 4, 7]
ΣAj: Array{Int64}((3,)) [6, 15, 24]
```

```
10月 2020
日 一 二 三 四 五 六
      1  2  3
  4  5  6  7  8  9 10
11 12 13 14 15 16 17
18 19 20 21 22 23 24
25 26 27 28 29 30 31
```

```

· let
·   with_terminal() do
·       println("👉 選定之輸出方案： 1) 容易以 do ... end 區塊包裝 3) 轉貼程式碼到他處不用修改\n")
·       # Get Current Time
·       command=`date`
·       run(command)
·       # Matrix
·       A=[ 1 2 3; 4 5 6; 7 8 9]
·       print("A: "); dump(A)
·       # Elements
·       print("A[1, 1]: "); dump(A[1, 1])
·       print("A[end, end]: "); dump(A[end, end])
·       # Row
·       r1=A[1, :]
·       print("r1: "); dump(r1)
·       ΣAi=A[1, :]+A[2, :]+A[3, :]
·       print("ΣAi: "); dump(ΣAi)
·       # Column
·       c1=A[:, 1]
·       print("c1: "); dump(c1)
·       ΣAj=A[:, 1]+A[:, 2]+A[:, 3]
·       print("ΣAj: "); dump(ΣAj)
·       println()
·       run(`cal -h`)
·   end
· end

```

```

A: Array{Int64}{(3, 3)} [1 2 3; 4 5 6; 7 8 9]
A[1, 1]: Int64 1
A[end, end]: Int64 9
r1: Array{Int64}{(3,)} [1, 2, 3]
ΣAi: Array{Int64}{(3,)} [12, 15, 18]
c1: Array{Int64}{(3,)} [1, 4, 7]
ΣAj: Array{Int64}{(3,)} [6, 15, 24]

```

```

· let
·   Text() do io
·       # Matrix
·       A=[ 1 2 3; 4 5 6; 7 8 9]
·       print(io, "A: "); dump(io, A)
·       # Elements
·       print(io, "A[1, 1]: "); dump(io, A[1, 1])
·       print(io, "A[end, end]: "); dump(io, A[end, end])
·       # Row
·       r1=A[1, :]
·       print(io, "r1: "); dump(io, r1)
·       ΣAi=A[1, :]+A[2, :]+A[3, :]
·       print(io, "ΣAi: "); dump(io, ΣAi)
·       # Column
·       c1=A[:, 1]
·       print(io, "c1: "); dump(io, c1)
·       ΣAj=A[:, 1]+A[:, 2]+A[:, 3]
·       print(io, "ΣAj: "); dump(io, ΣAj)
·   end
· end

```

```
A: [1 2 3; 4 5 6; 7 8 9]
```

```
A[1, 1]: 1
```

```
A[end, end]: 9
```


r: [1, 2, 3]

ΣA_i : [12, 15, 18]

c1: [1, 4, 7]

ΣA_j : [6, 15, 24]

```

. let
.     # Matrix
.     A=[ 1 2 3; 4 5 6; 7 8 9]
.     # Row
.     r1=A[1, :]
.      $\Sigma A_i$ =A[1, :]+A[2, :]+A[3, :]
.     # Column
.     c1=A[:, 1]
.      $\Sigma A_j$ =A[:, 1]+A[:, 2]+A[:, 3]
.     md"""
.     A: $(Text(A))
.
.     A[1, 1]: $(Text(A[1, 1]))
.
.     A[end, end]: $(Text(A[end, end]))
.
.     r1: $(Text(r1))
.
.      $\Sigma A_i$ : $(Text( $\Sigma A_i$ ))
.
.     c1: $(Text(c1))
.
.      $\Sigma A_j$ : $(Text( $\Sigma A_j$ ))
.     """
. end

```

單元 4 · The language of set theory

Subset

Let $S_1 = \{a, b, c, d, e\}$, $S_2 = a, b, e$

$S_2 \subset S_1$ means

$\forall x \in S_2, x \text{ is also } \in S_1.$

👉 Give Me Five, 原來集合在 Julia 裏頭是長這樣子喔！☺

```
Set{String}
```

```
dict: Dict{String,Nothing}
```

```
slots: Array{UInt8}((16,)) UInt8[0x00, 0x00, 0x00, 0x01, 0x01, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00]
```

```
keys: Array{String}((16,))
```

```
1: #undef
```

```
2: #undef
```

```
3: #undef
```

```
4: String "c"
```

```
5: String "e"
```

```
...
```

```
12: #undef
```

```

13: #undef
14: String "a"
15: #undef
16: String "d"
vals: Array{Nothing}((16,))
1: Nothing nothing
2: Nothing nothing
3: Nothing nothing
4: Nothing nothing
5: Nothing nothing
...
12: Nothing nothing
13: Nothing nothing
14: Nothing nothing
15: Nothing nothing
16: Nothing nothing
ndel: Int64 0
count: Int64 5
age: UInt64 0x0000000000000005
idxfloor: Int64 1
maxprobe: Int64 0
Set(["c", "e", "b", "a", "d"])
Set(["e", "b", "a"])
true
Set(["c", "e", "b", "a", "d"])
Set(["e", "b", "a"])
Set(["c", "d"])
Set{String}()

```

```

• let
•     with_terminal() do
•         s1=Set(["a", "b", "c", "d", "e"])
•         println("👋 Give Me Five, 原來集合在 Julia 裏頭是長這樣子喔!👉")
•         dump(s1)
•         println(s1)
•         s2=Set(["a", "b", "e"])
•         println(s2)
•         # subset
•         println(⊆(s2, s1))
•         # union set
•         println(∪(s1, s2))
•         # intersection set
•         println(∩(s1, s2))
•         # difference set
•         println(setdiff(s1, s2))
•         println(setdiff(s2, s1))
•     end
• end

```

單元 5 · Span of a Set of Vectors

```

• md"""
• ## 單元 5 · Span of a Set of Vectors
• """

```

實作參考：

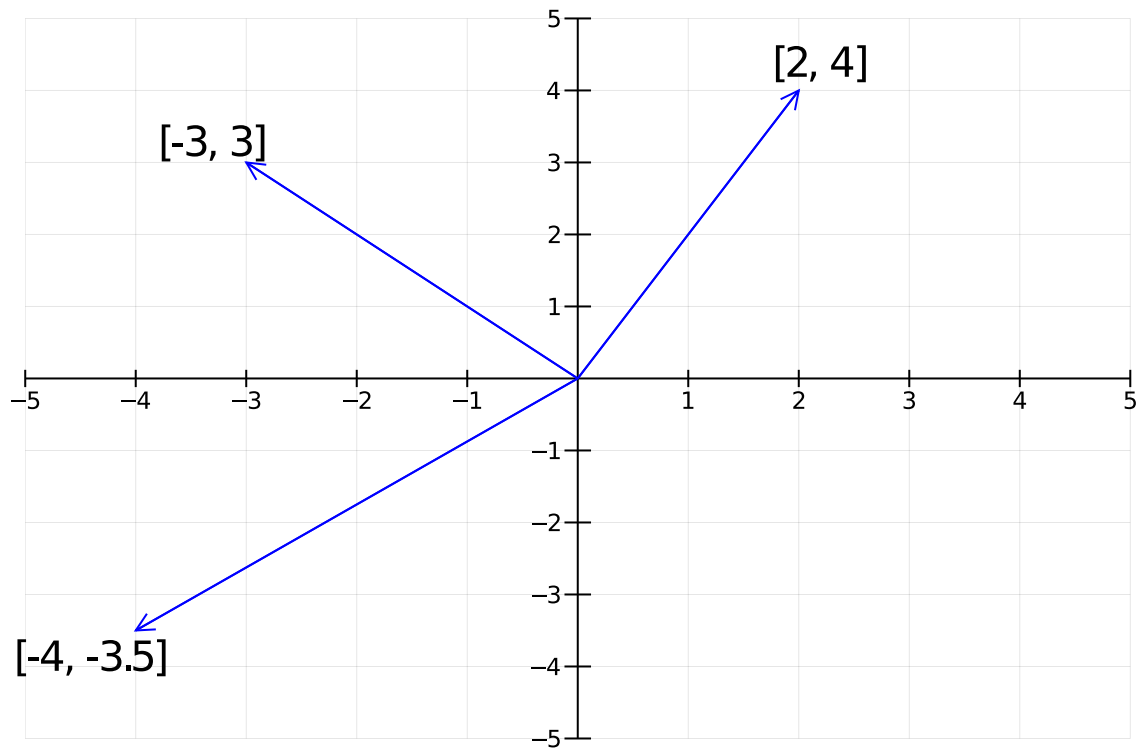
[Linear Algebra – Quantitative Economics with Julia](#)

```
• md"""
```

```

· 實作參考：
·
· [Linear Algebra – Quantitative Economics with Julia]
· (https://julia.quantecon.org/tools\_and\_techniques/linear\_algebra.html)
· """

```



```

· let
·     x_vals = [0 0 0 ; 2 -3 -4]
·     y_vals = [0 0 0 ; 4 3 -3.5]
·
·     plot(x_vals, y_vals, arrow = true, color = :blue,
·          legend = :none, xlims = (-5, 5), ylims = (-5, 5),
·          annotations = [(2.2, 4.4, "[2, 4]"),
·                        (-3.3, 3.3, "[-3, 3]"),
·                        (-4.4, -3.85, "[-4, -3.5]")],
·          xticks = -5:1:5, yticks = -5:1:5,
·          framestyle = :origin)
· end

```

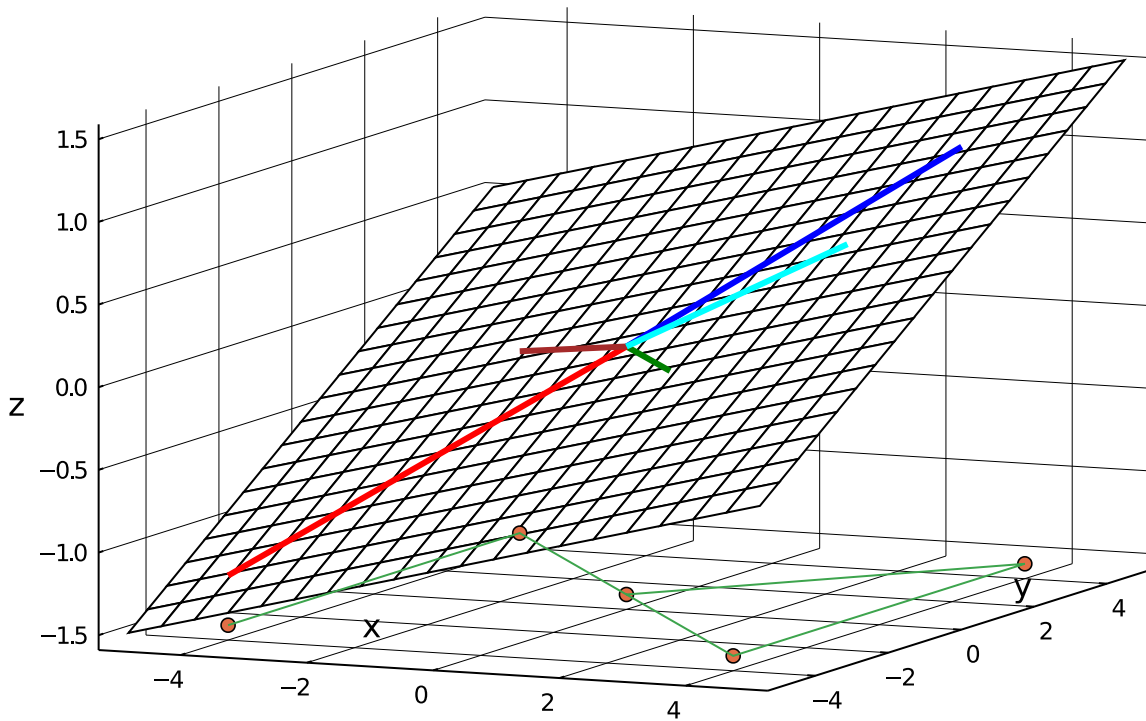
Slide to set i: 1

Slide to set j: 5

```

· begin
·     u05islidr = @bind u05i Slider(1:5; default=1, show_value=true)
·     u05jslidr = @bind u05j Slider(1:5; default=5, show_value=true)
·     md"""
·     Slide to set **i**: $(u05islidr)
·
·     Slide to set **j**: $(u05jslidr)
·     """
· end

```



```

. let
.   i=u05i
.   j=u05j
.   # fixed linear function, to generate a plane
.   f(x, y) = 0.2x + 0.1y
.
.   # lines to vectors
.   x_vec = [0 0 0 0 0; 3 3 -4 -4 3.5]
.   y_vec = [0 0 0 0 0; 4 -4 -4 4 0]
.   z_vec = [0 0 0 0 0; f(3, 4) f(3, -4) f(-4, -4) f(-4, 4) f(3.5, 0)]
.   color = [:blue :green :red :brown :cyan]
.
.   # draw the plane
.   n = 20
.   grid = range(-5, 5, length = n)
.   z2 = [ f(grid[row], grid[col]) for row in 1:n, col in 1:n ]
.   # wireframe(grid, grid, z2, fill = :blues, gridalpha = 1 )
.   plot(grid, grid, z2, fill = :blues, gridalpha = 1, linewidth = 0.5, seriotype =
:wireframe)
.   # plot(grid, grid, z2, fill = :blues, gridalpha = 1, linewidth = 0.5, seriotype =
:surface)
.   # Dots
.   # plot!([0; 4; 4; -4; -4], [0; 4; -4; 4; -4], [-1.5; -1.5; -1.5; -1.5; -1.5], labels =
"", seriotype = :scatter3d)
.   p = [ 0 0 -1.5; 4 4 -1.5; 4 -4 -1.5; -4 4 -1.5; -4 -4 -1.5]' # Transpose
.   plot!(p[1, i:j], p[2, i:j], p[3, i:j], labels = "", seriotype = :scatter3d)
.   plot!(p[1, i:j], p[2, i:j], p[3, i:j], labels = "", seriotype = :path3d)
.   # Vectors
.   plot!(x_vec[:, i:j], y_vec[:, i:j], z_vec[:, i:j], color = color[:, i:j], linewidth = 3,
xlabel = "x", ylabel = "y", zlabel = "z", labels = "", colorbar = false)
.   # plot!(x_vec, y_vec, z_vec, color = color[:, i:j], linewidth = 3, xlabel = "x", ylabel =
"y", zlabel = "z", labels = "", colorbar = false)
. end

```

單元 6 · Linear Dependence and Linear Independence

```
[-0.09523809523809523, -0.1295238095238095, -0.08761904761904767]
[-0.26666666666666666, 0.6666666666666671, -1.2000000000000006, -0.6666666666666671]
false
```

```
• let
•   with_terminal() do
•       A=[1 2 -1; -1 1 -8; 2 -1 13; 1 -1 8]
•       b=[0; 1; -2; 1]
•       x=A \ b
•       println(x)
•       println(A*x)
•       println(A*x == b)
•   end
• end
```

```
[0.0, 0.0, 0.0, -0.0, 0.0]
[0.0, 0.0]
true
```

```
• let
•   with_terminal() do
•       A=[1 -4 2 -1 2; 2 -8 3 2 1]
•       b=[0; 0]
•       x=A \ b
•       println(x)
•       println(A*x)
•       println(A*x == b)
•   end
• end
```

單元 7 · Matrix Multiplication

Matrix Multiplication

Let $v, x, y \in R^n$. Suppose A and B are $n \times n$ matrices.

$$x = Bv$$

$$y = Ax$$

$$\Downarrow$$

$$y = Cv = A(Bv) = (AB)v$$

```
Array{Int64}{(2, 2)} [3 -1; 2 0]
Array{Int64}{(2, 2)} [2 3; 0 1]
```

```
• let
•   with_terminal() do
•       A=[1 2; 1 1]
•       B = [ 1 1; 1 -1]
```

```

.      dump(A * B)
.      dump(B * A)
.      end
. end

```

單元 8 · Invertibility and Elementary Matrices

Inverse

An $n \times n$ matrix A is called invertible if there exists an $n \times n$ matrix B such that $AB = BA = I_n$. In this case, B is called an inverse of A .

$$\begin{aligned}
 A &= \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} & \Rightarrow & AB = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2 \\
 B &= \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} & & BA = \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2
 \end{aligned}$$

```

Array{Int64}((2, 2)) [1 2; 3 5]
Array{Float64}((2, 2)) [-4.999999999999997 1.9999999999999999; 2.9999999999999987 -0.9999
999999999996]
Array{Float64}((2, 2)) [-5.0 2.0; 3.0 -1.0]
Float64 1.0
Float64 0.0
Float64 -0.0
Float64 1.0
Float64 1.0
Float64 0.0
Float64 0.0
Float64 1.0

```

```

. let
.     with_terminal() do
.         A=[1 2; 3 5]
.         B=inv(A)
.         dump(A)
.         dump(B)
.         dump(round.(B))
.         dump.(round.(A*B))
.         dump.(round.(B*A))
.     end
. end

```

疑：為什麼只是近似的值？因為 3?

單元 9 · Column Correspondence Theorem

實作參考：

[blegat/RowEchelon.jl](#): Small package containing the `rref` function for computing the reduced row echelon form of the matrix **A**

可做為 module 及 RREF 計算實作參考。提供的 function 為 `rref`, `rref!`, `rrefwithpivots`, `rrefwithpivots!`,

Reduced Row Echelon Form (RREF)

```
Using RREF:
Array{Int64}((4, 6)) [1 2 ... 1 2; -1 -2 ... 3 6; 2 4 ... 0 3; -3 -6 ... 3 9]
[1 2 -1 2 1 2; -1 -2 1 2 3 6; 2 4 -3 2 0 3; -3 -6 2 0 3 9]
Array{Float64}((4, 6)) [1.0 2.0 ... -1.0 -5.0; 0.0 0.0 ... 0.0 -3.0; 0.0 0.0 ... 1.0 2.0; 0.0
0.0 ... 0.0 0.0]
[1.0 2.0 0.0 0.0 -1.0 -5.0; 0.0 0.0 1.0 0.0 0.0 -3.0; 0.0 0.0 0.0 1.0 1.0 2.0; 0.0 0.0
0.0 0.0 0.0 0.0]
Using \:
Array{Float64}((5,)) [-1.0, -1.0, -3.0, 1.0, 1.0]
[-1.0, -1.0, -3.0, 1.0, 1.0]
[2.0, 6.0, 3.0, 9.0]
Using \ with RREF:
Array{Float64}((5,)) [-1.0, -1.0, -3.0, 1.0, 1.0]
[-1.0, -1.0, -3.0, 1.0, 1.0]
[-5.0, -3.0, 2.0, 0.0]
```

```
• let
•     with_terminal() do
•         println("Using RREF:")
•         A=[ 1 2 -1 2 1 2; -1 -2 1 2 3 6; 2 4 -3 2 0 3; -3 -6 2 0 3 9]
•         dump(A)
•         println(Text(A))
•         B=rref(A)
•         dump(round.(B))
•         println(Text(round.(B)))
•
•         println("Using \\:")
•         A1=A[:, 1:5]
•         b1=A[:, 6]
•         x=A1 \ b1
•         dump(round.(x))
•         println(Text(round.(x)))
•         println(Text(round.(A1*x)))
•
•         println("Using \\ with RREF:")
•         A2=B[:, 1:5]
•         b2=B[:, 6]
•         y=A2 \ b2
•         dump(round.(y))
•         println(Text(round.(y)))
•         println(Text(round.(A2*y)))
•     end
• end
```

單元 10 · The Inverse of a Matrix

Matrix Inversion

$$[A \quad I_3] = \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 6 & 0 & 1 & 0 \\ 3 & 4 & 8 & 0 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -16 & 4 & 3 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 0 & 1 & 7 & -2 & -1 \end{array} \right] = [I_3 \quad B]$$

```
[1 2 3 1 0 0; 2 5 6 0 1 0; 3 4 8 0 0 1]
[1.0 0.0 0.0 -16.0 4.0 3.0; 0.0 1.0 0.0 -2.0 1.0 -0.0; 0.0 0.0 1.0 7.0 -2.0 -1.0]
[-16.0 4.0 3.0; -2.0 1.0 -0.0; 7.0 -2.0 -1.0]
[-16.0 4.0 3.0; -2.0 1.0 0.0; 7.0 -2.0 -1.0]
```

```
• let
•     with_terminal() do
•         AI=[ 1 2 3 1 0 0; 2 5 6 0 1 0; 3 4 8 0 0 1]
•         println(AI)
•         IB=round.(rref(AI))
•         println(IB)
•         C=IB[:, 4:6]
•         println(C)
•         D=round.(inv(AI[:, 1:3]))
•         println(D)
•     end
• end
```

<<<

```
• md"""
• ### <<<
• """
```

參考資料

Linear Algebra

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- [] [Introduction to Applied Linear Algebra – Vectors, Matrices, and Least Squares](#)

[Julia language companion](#)

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- [] [Introduction to Julia](#)

[] [Advanced topics](#)

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- [] [18.S191 Introduction to Computational Thinking](#)

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[QuantEcon.cheatsheet/julia-cheatsheet.pdf](#)

[cheatsheets/plotsjl-cheatsheet.pdf](#)

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