

Principles of Satellite Image Processing

GNR 607

NDVI Masking and K-Means Clustering

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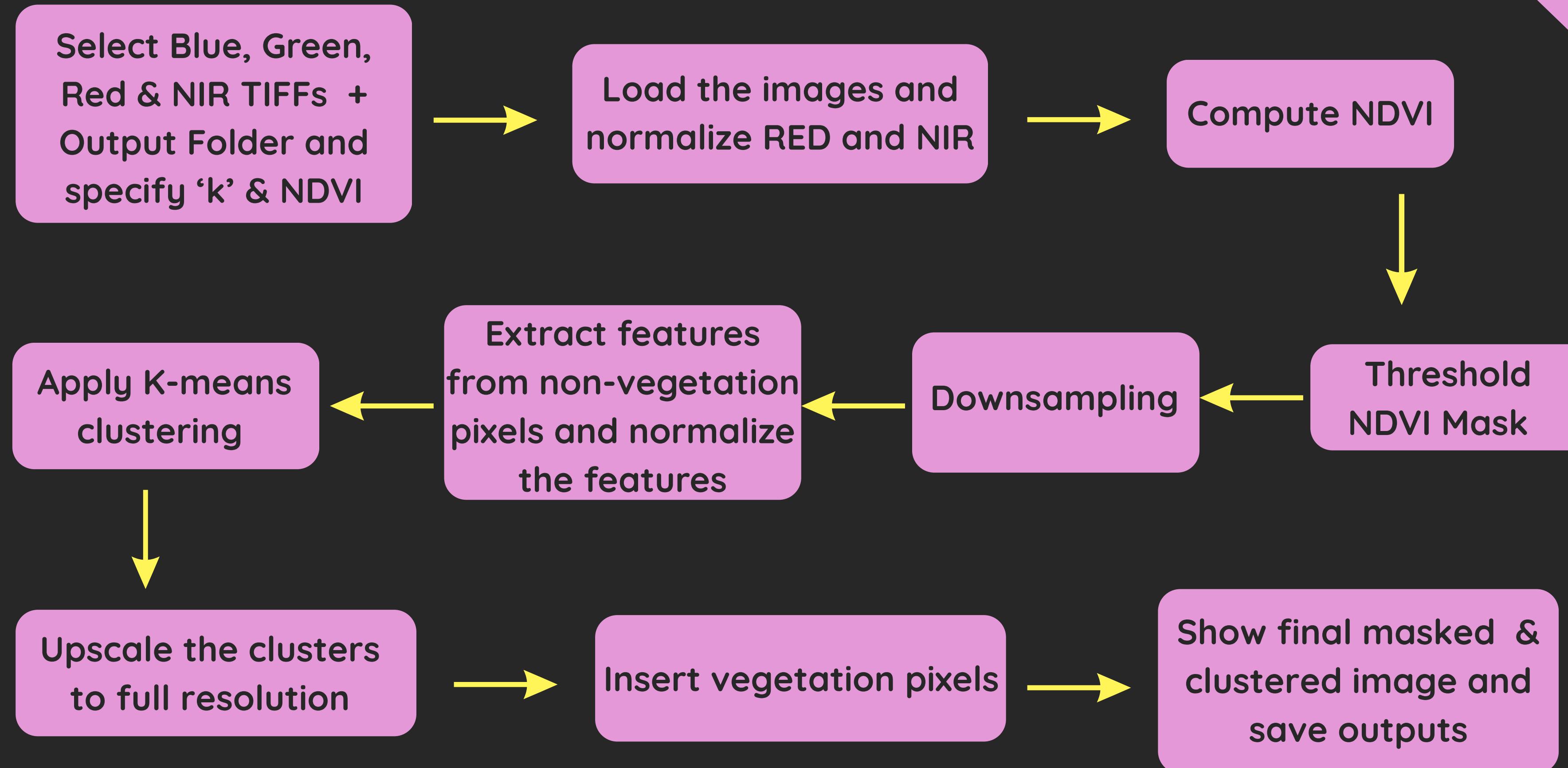


Project Objectives

Calculate NDVI and isolate vegetation using a user-defined threshold.

Apply K-Means clustering (with user-chosen K) to only the non-vegetated regions.

PROCESSING PIPELINE



NDVI ***Thresholding***

NDVI thresholding uses the Normalized Difference Vegetation Index, computed from the red and near-infrared (NIR) bands, to highlight healthy vegetation.

Plants reflect strongly in NIR and absorb red light, so high NDVI values indicate dense, healthy vegetation, while low values point to sparse or non-vegetated surfaces.

Practically, NDVI is used in agriculture, forestry, drought monitoring, and land-cover mapping to assess crop health, biomass, and vegetation stress. Typical values include ~0.3 for sparse vegetation, ~0.5-0.6 for moderate vegetation, and >0.7 for dense, healthy vegetation.

Methodology

$$\text{NDVI} = \frac{NIR - Red}{NIR + Red}$$

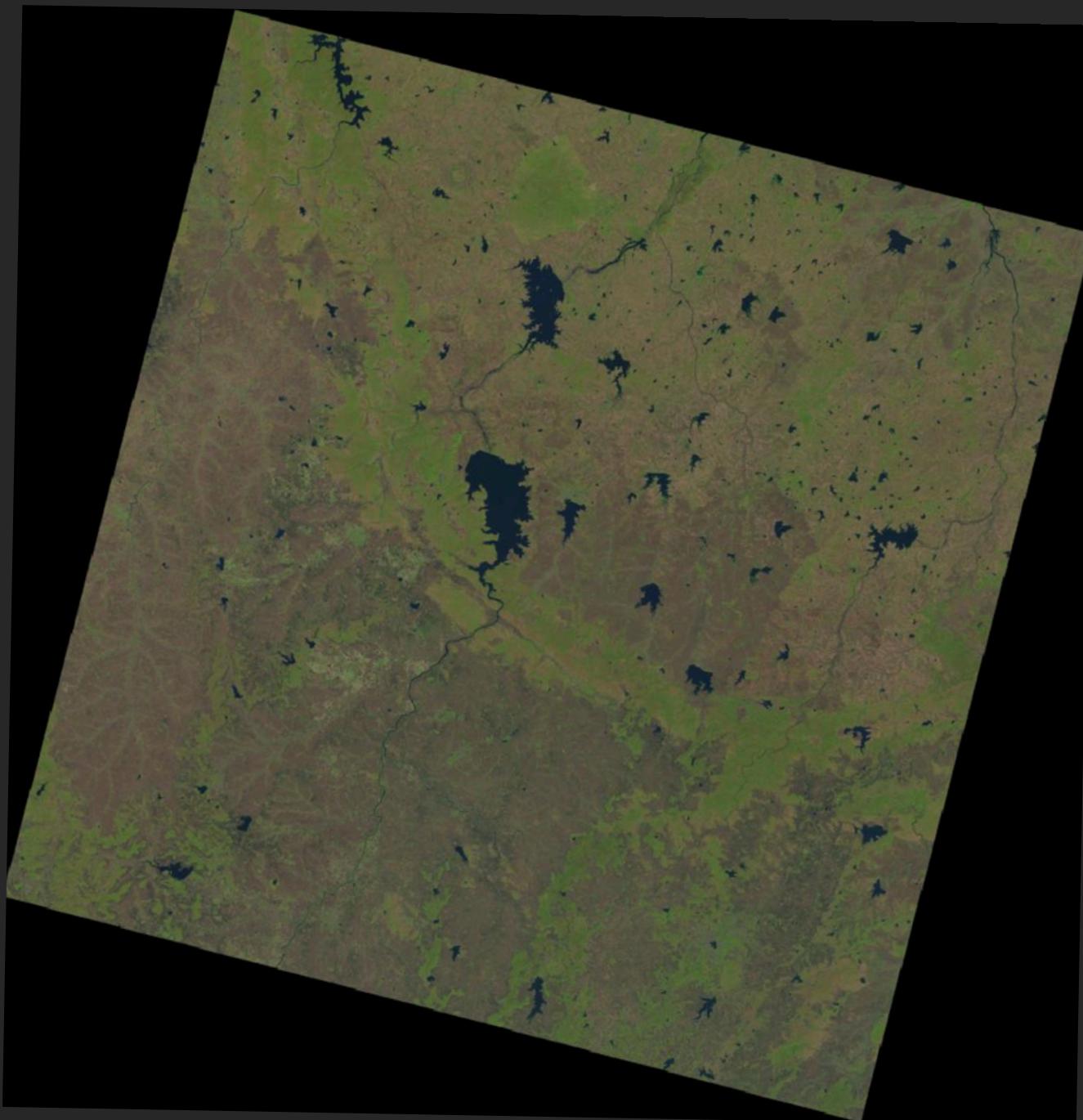
We first loaded the satellite image's NIR (b5) and Red (b4) bands.

Using the NDVI formula, we computed an NDVI image where each pixel indicates vegetation strength.

Then applied a user-defined threshold (e.g., 0.1, 0.2) to create a mask: pixels above the threshold are visible and rest are hidden.

This mask separates healthy vegetation from non-vegetated areas, and different thresholds allows us to control how strict we want the vegetation detection to be.

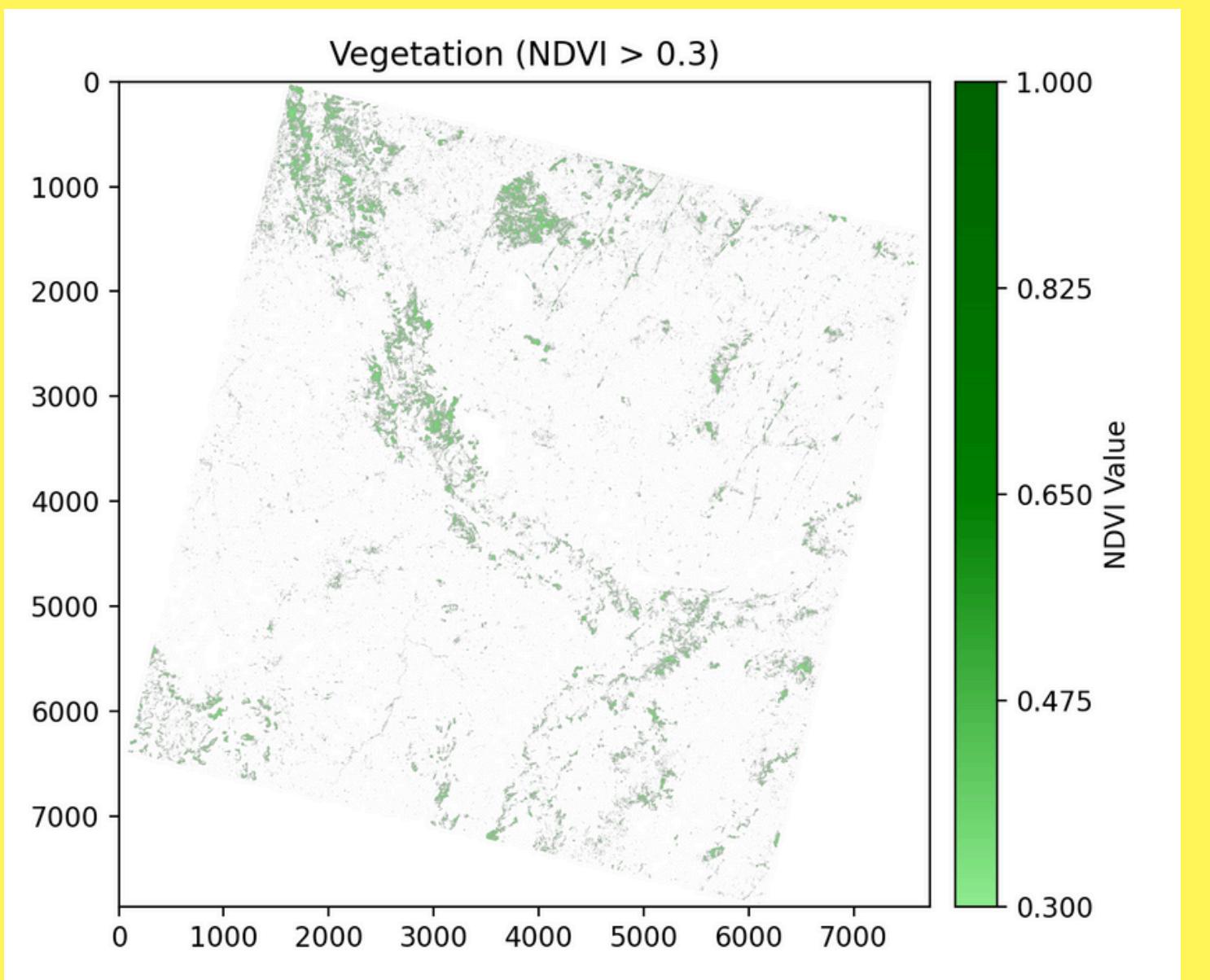
Input data



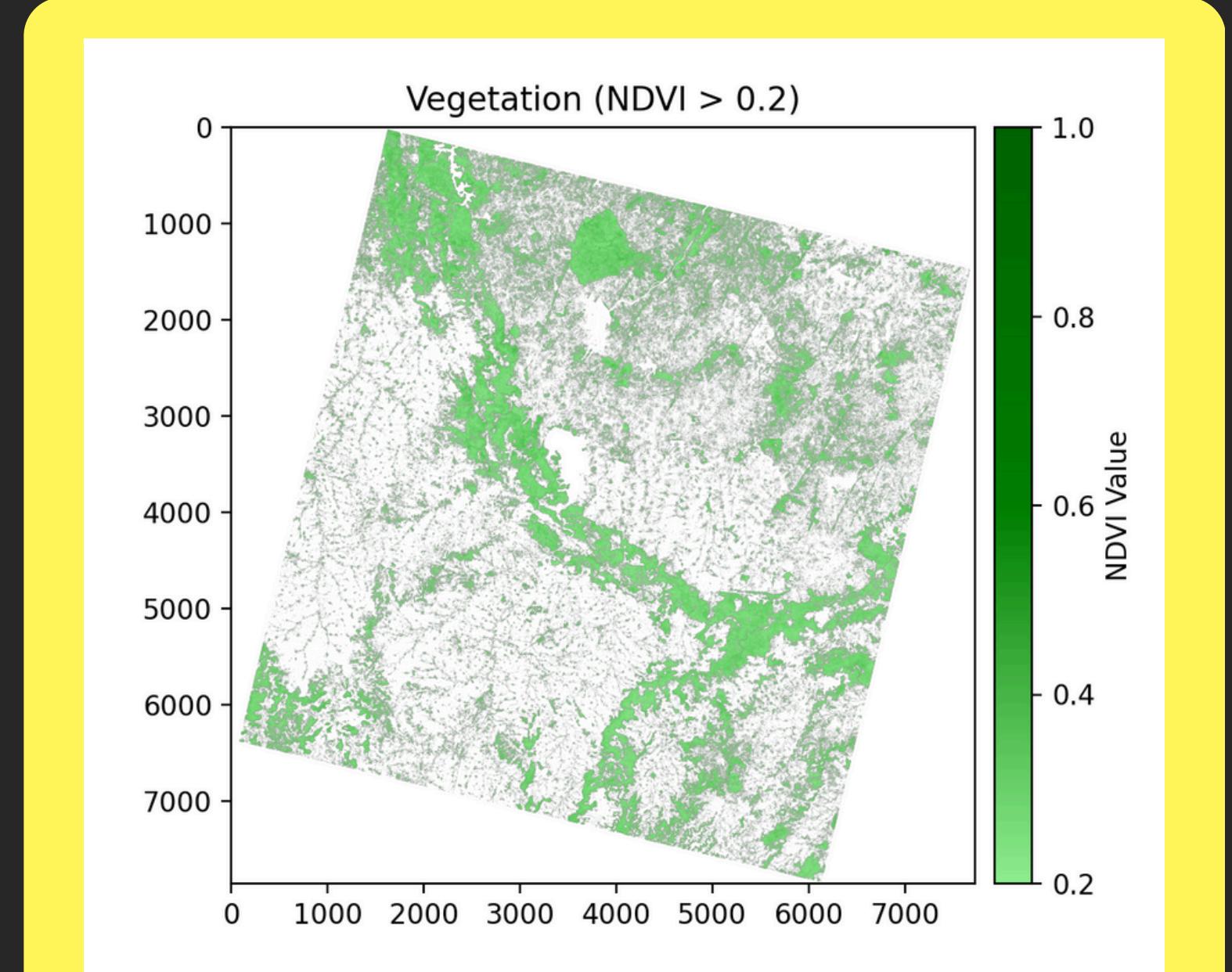
Satellite & Sensor: Landsat 9, OLI/TIRS
Acquisition Date: 7th Nov 2025
Location: ~24.55°N, 78.37°E (In Madhya Pradesh)
Cloud Cover: 0.01%
Bands Used: RGB + NIR

Results

Threshold = 0.2



Threshold = 0.3



K-means clustering

K-Means is an unsupervised machine learning algorithm that groups data into K clusters based on similarity.

It works by placing K centroids, assigning each data point to the nearest centroid, and iteratively adjusting the centroids until the clusters stabilize.

It is widely used in image segmentation, pattern recognition, remote sensing classification, customer grouping, etc because it is simple, fast, and effective for large datasets.

Each cluster represents a region where the data points share similar characteristics—for example, in images, clusters might correspond to different land-cover types, colors, textures, or intensity ranges.

Methodology

After extracting the non-vegetated pixels using the NDVI mask, Blue, Green, Red and NIR values are organized into a feature matrix and normalized for stability.

K initial centroids are chosen randomly from these feature points.

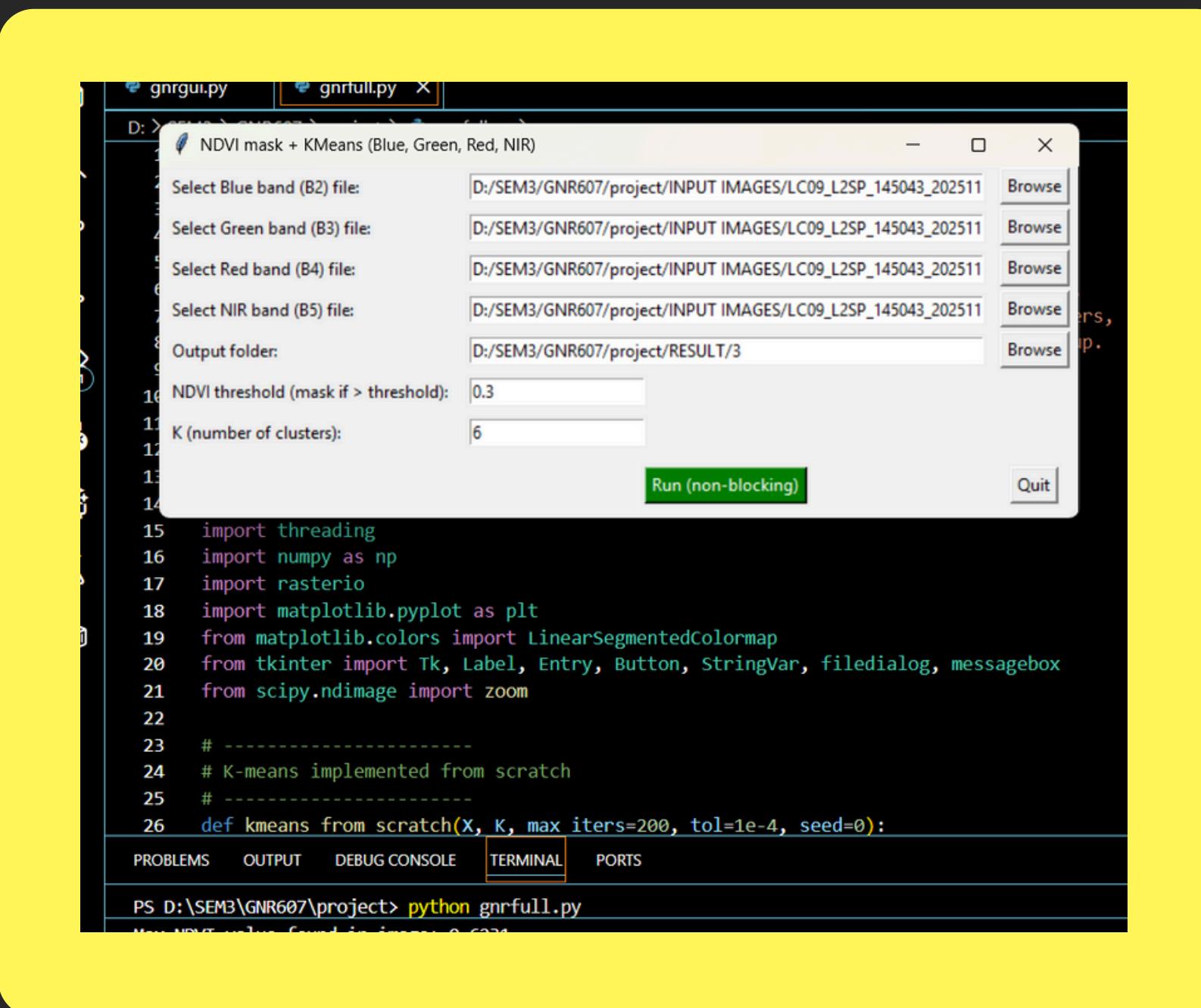
Each remaining pixel is then assigned to the nearest centroid using squared Euclidean distance, and new centroids are computed as the mean of the points in each cluster.

Empty clusters are reinitialized, and the assignment-update steps repeated until the centroids converge within a small tolerance.

The final output is a cluster label for every non-vegetation pixel, which is then mapped back to the full-resolution image, clearly separating vegetation (from the NDVI mask) and the K spectral clusters of the non-vegetated region.

Results

K=6 and NDVI threshold = 0.3



The screenshot shows the gnrgui.py application window. It displays the following parameters:

- Select Blue band (B2) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select Green band (B3) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select Red band (B4) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select NIR band (B5) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Output folder: D:/SEM3/GNR607/project/RESULT/3
- NDVI threshold (mask if > threshold): 0.3
- K (number of clusters): 6

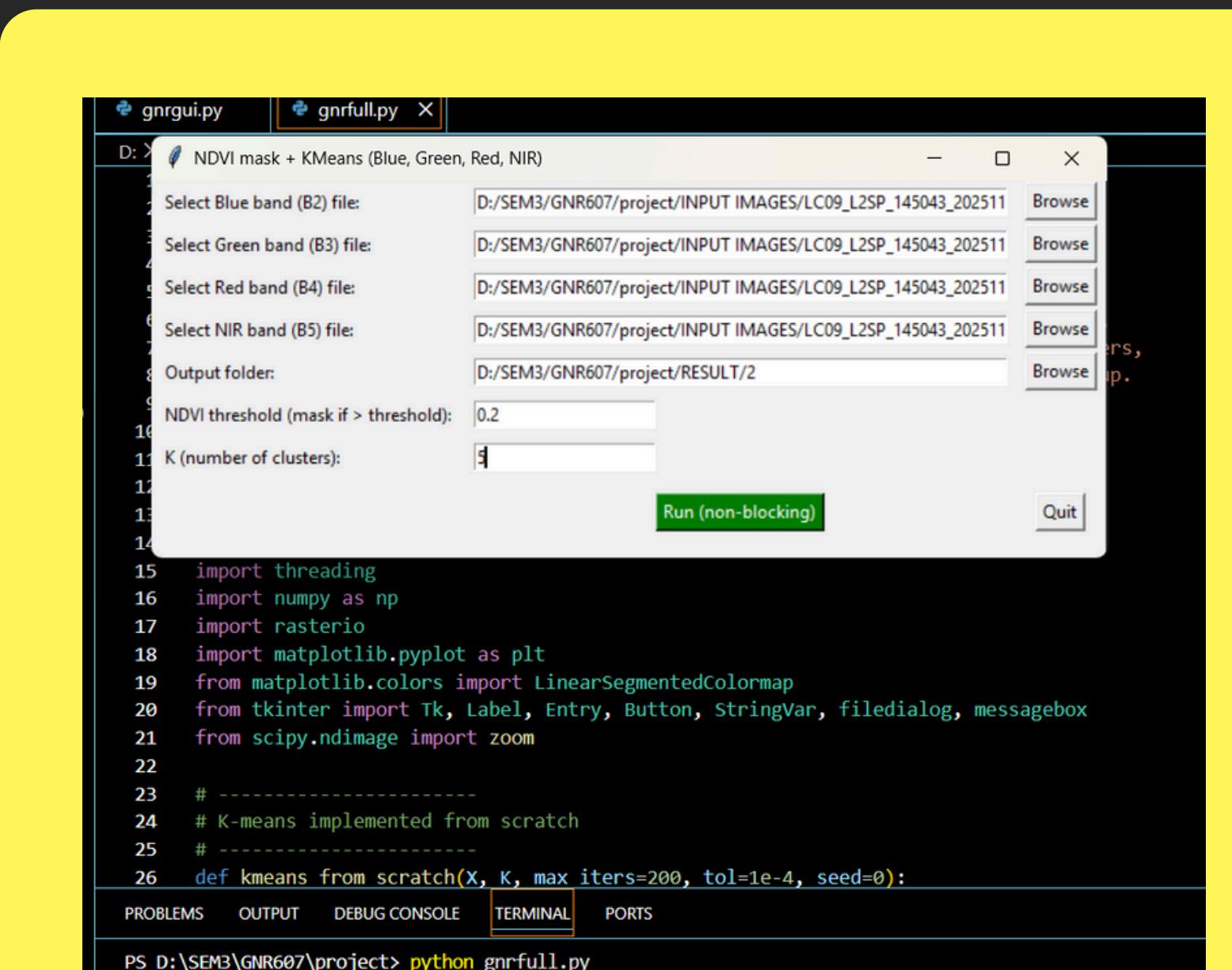
At the bottom, there is a terminal window showing the Python script code and a command prompt:

```
1  import threading
2  import numpy as np
3  import rasterio
4  import matplotlib.pyplot as plt
5  from matplotlib.colors import LinearSegmentedColormap
6  from tkinter import Tk, Label, Entry, Button, StringVar, filedialog, messagebox
7  from scipy.ndimage import zoom
8
9  # -----
10 # K-means implemented from scratch
11 # -----
12 def kmeans_from_scratch(X, K, max_iters=200, tol=1e-4, seed=0):
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```

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS

```
PS D:\SEM3\GNR607\project> python gnrfull.py
```

K=5 and NDVI threshold = 0.2



The screenshot shows the gnrgui.py application window. It displays the following parameters:

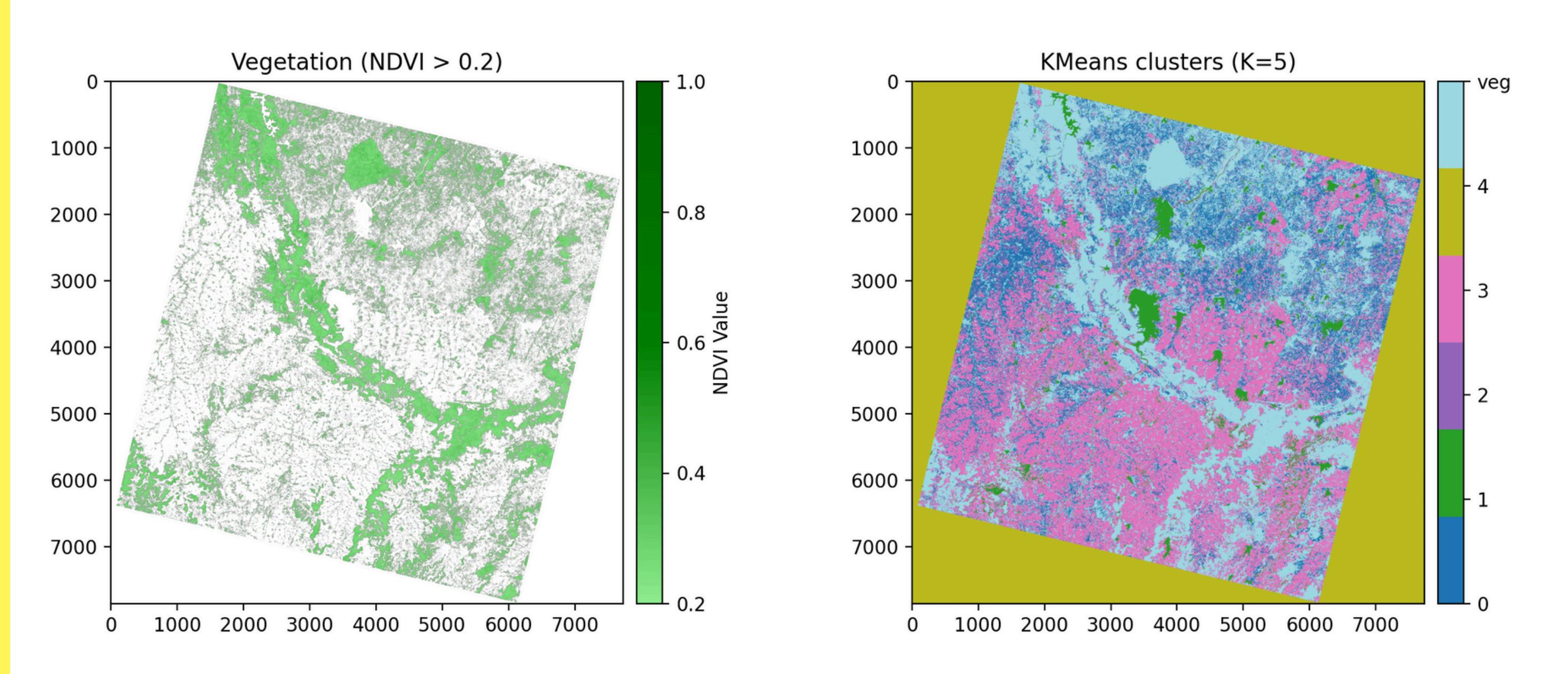
- Select Blue band (B2) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select Green band (B3) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select Red band (B4) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Select NIR band (B5) file: D:/SEM3/GNR607/project/INPUT IMAGES/LC09_L2SP_145043_202511
- Output folder: D:/SEM3/GNR607/project/RESULT/2
- NDVI threshold (mask if > threshold): 0.2
- K (number of clusters): 5

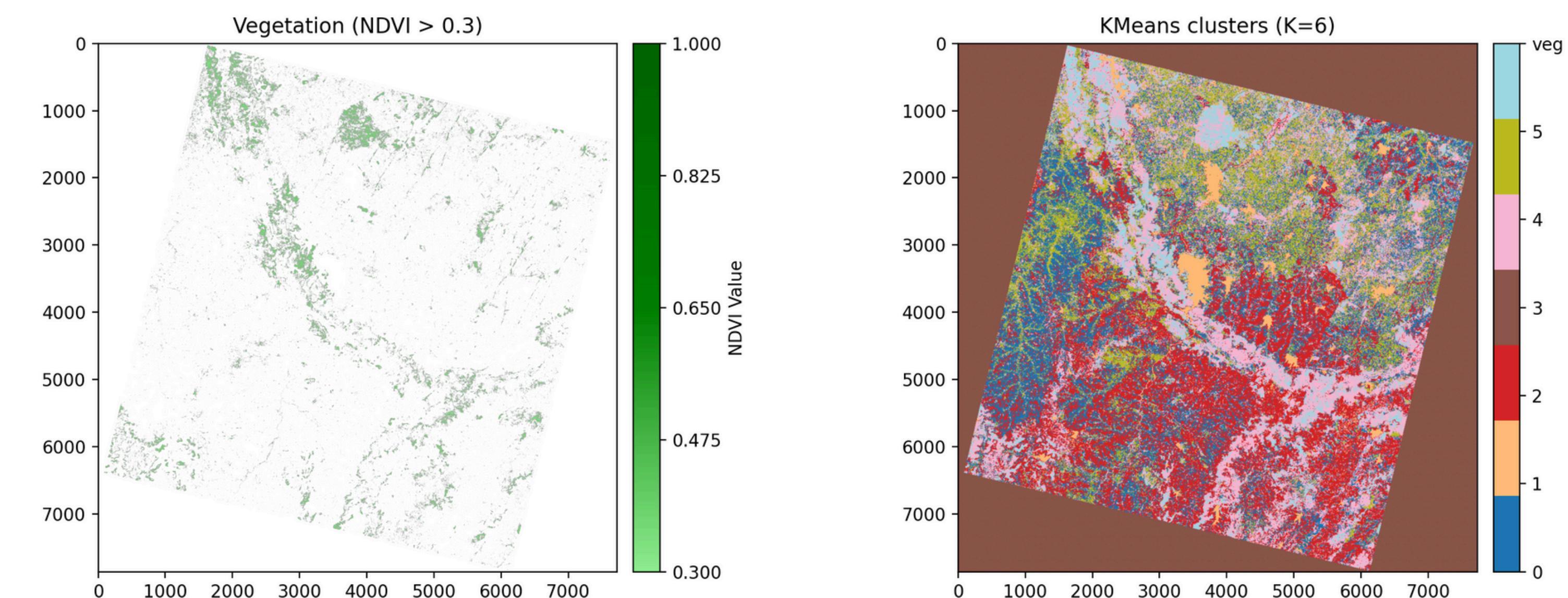
At the bottom, there is a terminal window showing the Python script code and a command prompt:

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1  import threading
2  import numpy as np
3  import rasterio
4  import matplotlib.pyplot as plt
5  from matplotlib.colors import LinearSegmentedColormap
6  from tkinter import Tk, Label, Entry, Button, StringVar, filedialog, messagebox
7  from scipy.ndimage import zoom
8
9  # -----
10 # K-means implemented from scratch
11 # -----
12 def kmeans_from_scratch(X, K, max_iters=200, tol=1e-4, seed=0):
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```

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS

```
PS D:\SEM3\GNR607\project> python gnrfull.py
```





Bibliography

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<https://medium.com/analytics-vidhya/image-segmentation-using-k-means-clustering-from-scratch-1545c896e38e> - **Image Segmentation using K-means Clustering from Scratch**

THANK YOU