


# On Faster Model Checking of First-Order Graph Properties and Tarski's Calculus of Relations

Yo: Tentative

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## Abstract

This is a SUPER-STRONG-PAPER and brings a NEW ERA to the field of FO.

**2012 ACM Subject Classification** Theory of computation → Logic

**Keywords and phrases** First-order Logic, Fine-grained Complexity

**Digital Object Identifier** 10.4230/LIPIcs...

## 1 Notation

(メモ: LIPICSとpLaTeXは異常に組み合わせが悪いので、コメントなどで日本語を書く時はこのようにします。)

Cute round-corner box

コメントを付ける時には、screenで囲うとこういう感じになります

Yo: コメントテスト

Yo: コメントテスト 2

We write  $\mathbb{FO}^k$  to denote the set of formulas of First-order predicate logic with  $k$ -variables.

## Important Remark (Unary and Binary Predicates)

We allow unary and binary predicates in our  $\mathbb{FO}^3$ . Therefore, we do not allow terms involving ternary predicates such as  $\forall x. \exists y. \forall z. P(x, y, z)$ .<sup>1</sup>

On this remark, we can identify each model  $\mathcal{M}$  as color graphs as follows:

- Each element corresponds a node (vertex).
- Each unary predicate  $U_i$  means “color- $i$ ” node.
- Each binary predicate  $P_j$  is “color- $j$ ” edge.
- For example, on two nodes  $x, y$ , a term  $(U_i(x) \wedge U_j(y) \wedge P_k(x, y))$  means that  $x$  has the color  $i$ ,  $y$  has the color  $j$ , and there is a color  $k$  edge from  $x$  to  $y$ .

<sup>1</sup> For each unary predicate  $U$ , we can simulate it by a diagonal binary predicate  $B_U(x, y) := x = y \wedge U(x)$ . However, in our later construction, we use some unary predicates; thus, we also allow unary predicates explicitly.



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Leibniz International Proceedings in Informatics

LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany

## 28 Quantifier width

Quantifier widthという謎の指標を導入します。

与えられた式の部分項  $\forall/\exists x.(\dots)$  について  $\dots$  部分に「直接」出てくる quantifier の個数を、この部分項の quantifier width と呼ぶことにします。

たとえば、次の部分項

$$\forall x. \left( \left( \underline{\forall} y. P(y) \right) \vee \left( \underline{\forall} z. (\underline{\forall} x. P(z, x)) \wedge Q(z) \right) \right)$$

については、内部に3つの quantifier の出現（下線）があるのですが、直接の出現は赤くした2つだけなので、この部分項の quantifier width は「2」です。

そして、式の quantifier width というのは、最大の quantifier width を持つ部分項における、その数として定義します。

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30 **2** Introduction

31 The *model checking problem* is the following problem:

32 given both a *sentence*  $\varphi$  and a *structure*  $\mathfrak{A}$ , does  $\mathfrak{A} \models \varphi$  hold?

33 The *model checking problem* for  $\mathbb{FO}$  is complete in PSPACE, unfortunately. Nevertheless, the  
34 *model checking problem* for  $\mathbb{FO}^k$  can be decided in  $\mathcal{O}(\|\varphi\| \cdot n^k)$  time [4, Proposition 3.1] by  
35 a naive bottom-up evaluation algorithm, where  $\|\varphi\|$  is the length of  $\varphi$  and  $n$  is the number  
36 of *vertices* in  $\mathfrak{A}$ .

37 A natural question is, whether the complexity  $\mathcal{O}(\|\varphi\| \cdot n^k)$  time can be improved. Williams  
38 [5] gave a positive answer to the question. He showed that the complexity can be improved  
39 to  $\mathcal{O}(n^\omega)$  time for  $\mathbb{FO}^3$ ,<sup>2</sup> where  $\omega$  is the exponent of matrix multiplication.

40 Namely, the problem

Yo: On data complexity (formula is fixed and structure is given) [5]

- For  $\mathbb{FO}^3$ ,  $\mathcal{O}(n^\omega)$  time,
- For  $\mathbb{FO}^k$  (where  $k \geq 3$ ),  $\mathcal{O}(n^{\omega+k-3})$  time,
- For  $\mathbb{FO}^k$  (where  $k \geq 9$ ),  $\mathcal{O}(n^{k-4})$  time.

On combined complexity ()

Parameterized complexity

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42 We shed a light the

43 Related work:

- 44 ■ [1]: Space complexity for  $\mathbb{FO}^k$ .

45

46 **3** Preliminaries

47 <sup>r</sup> We write  $\models$

<sup>2</sup> More precisely, [2, Theorem 7]

## 4 from

[5]

## 5 Conclusion

## 6 FPT on FO3

We write  $\text{FO}_{k,w}^3$  to denote the set of formulas of  $\text{FO}^3$  with  $k$ -predicates and  $w$ -quantifier-width.

► **Theorem 1** ( $\text{FO}_{k,w}^3$  model checkig is FPT).

Let  $\varphi : \text{FO}_{k,w}^3$ .

For a given model (graph)  $\mathcal{G}$ , we can decide if  $\mathcal{G} \models \varphi$  in  $O(2^{k+w} \cdot |\varphi| \cdot N^\omega)$  where

- $N$  is the number of vertices in  $\mathcal{G}$ ; and
- $\omega$  is a complexity constant for the boolean matrix multiplication (BMM): i.e.,  $O(N^\omega)$ -time is the time complexity for BMM of two  $(N, N)$  matrices.<sup>3</sup>

► **Corollary 2.** If we fix the number of predicates  $k$  and width  $w$ , the model checking problem  $\mathcal{G} \models \varphi$  in  $O(|\varphi| \cdot N^\omega)$  time-complexity where  $N$  is the number of nodes in  $\mathcal{G}$ .

$k$ をfixしない、素朴な  $\{(x, y, z)\}$  構築アルゴリズムだと  $O(|\varphi| \cdot N^3)$  になって、その設定だと Theorem 1 は 係数 が大きくなりすぎて遅いということを、意味のある形で言及した方が良い。

以降、Theorem 1 の証明をやっていきます。

### 6.1 Proof of Theorem 1

Here we use  $P, Q, R \dots$  to denote binary predicates and  $U, \dots$  for unary predicates.

For a given graph (model)  $\mathcal{G}$ , we write  $N_{\mathcal{G}}$  or simply  $N$  to denote the number of vertices of  $\mathcal{G}$ .

#### Our idea: Quantifier elimination (Simple case)

Our query evaluation strategy is evaluating the innermost (quantifier-free formula) to the outermost along with quantifier eliminating.

Let us consider the following situation:

$$Qx \dots (Qy \dots (Qz \dots (Qx \dots (Qy \dots (\exists x. (P(y, x) \wedge R(x, z)))))))$$

To eliminate  $\exists z. P(y, x) \wedge R(x, z)$ , we introduce a new predicate defined as follows:

$$S(x, y) := \exists z. P(x, z) \wedge Q(z, y).$$

It is worth noting that  $S$  is just the composed predicate of  $P$  and  $Q$ . So, we write  $P \odot Q$  instead of  $S$ .

Using this predicate, we can rewrite the above one to the following one:

$$Qx \dots (Qy \dots (Qz \dots (Qx. (Qy. (P \odot R)(y, z))))))$$

<sup>3</sup> 何らかの論文をciteして、今の記録がどれくらいか書いておくと分かりやすい

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Continuing this process, if we eventually enter  $\forall x.\exists y.T(x, y)$ :

73

1. building a unary predicate  $T_y(x) := \exists y.T(x, y)$  in  $O(N^2)$ -time, we rewrite it to  $\forall x.T_y(x)$ .

74

2. we then simply evaluate  $\forall x.T_y(x)$  as  $\bigwedge_{1 \leq i \leq N} T_y(i)$  in  $O(N)$ -time.

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## 76 Time-complexity of basic operations

Here we enumerate the time-complexity of our basic operations, which will be used later:

77

■ Building a new predicate  $Q(x, y) := P(x, y) \bowtie R(x, y)$  ( $\bowtie \in \{\wedge, \vee\}$ ) needs  $O(N^2)$ -time.

78

■ Transposing a predicate  $P^T(x, y) := P(y, x)$  needs  $O(N^2)$ -time.

79

■ Evaluating unary predicates  $Qx.P(x)$  ( $Q \in \{\forall, \exists\}$ ) needs  $O(N)$ -time.

80

■ Building a new predicate  $Q(x) := Qy.P(x, y)$  ( $Q \in \{\exists, \forall\}$ ) needs  $O(N^2)$ -time.

81

So, the remaining operator is predicate composing  $(P \odot Q)(x, y) := \exists z.P(x, z) \wedge Q(z, y)$  from predicates  $P$  and  $Q$ . Although a very simple matrix multiplication requires  $O(N^3)$ -time, we can build such  $P \odot Q$  using fast matrix multiplication algorithms.

82

83 from predicates  $P$  and  $Q$ . Although a very simple matrix multiplication requires  $O(N^3)$ -time,  
84 we can build such  $P \odot Q$  using fast matrix multiplication algorithms.

85 ► **Proposition 3 (Fact).** *From two predicates  $P$  and  $Q$ , we can build the composited predicate*  
86  *$P \odot Q$  in  $O(N^\omega)$ -time.*

## 87 6.2 Quantifier elimination: General case

88 If we encounter terms of the very restricted form like  $\exists z.P(x, z) \wedge Q(z, y)$ , we can replace it  
89 by  $(P \odot Q)(x, y)$  with eliminating the quantifier occurrence  $\exists z$ .

In other words, if we encounter more general form of  $\exists z.\dots$ , we need to translate it to some adequate form for quantifier elimination. Let us consider the following term:

$$\exists z. \left( (P(x, z) \vee P(y, z) \vee P(x, y)) \wedge (Q(x, z) \vee Q(x, y)) \wedge (R(y, z) \vee R(x, y)) \right).$$

90 We cannot directly apply our quantifier elimination strategy because  $\exists$ -quantifiers do not  
91 distribute on  $\wedge$ : i.e.,  $(\exists z.\varphi_1 \wedge \varphi_2) \neq (\exists z.\varphi_1) \wedge (\exists z.\varphi_2)$ .

To apply our quantifier elimination procedure, DNF is an adequate form. However, as well-known, converting-to-DNF translation generates an exponential-large expression in the worst case. For our example, we first translate the first  $(\dots) \wedge (\dots)$  subterm as follows:

$$\begin{aligned} & (P(x, z) \vee P(y, z) \vee P(x, y)) \wedge (Q(x, z) \vee Q(x, y)) \\ & \Rightarrow \\ & (P(x, z) \wedge Q(x, z)) \vee (P(y, z) \wedge Q(x, z)) \vee (P(x, y) \wedge Q(x, z)) \\ & \vee (P(x, z) \wedge Q(x, y)) \vee (P(y, z) \wedge Q(x, y)) \vee (P(x, y) \wedge Q(x, y)). \end{aligned}$$

92 We continue to normalize this term with  $R(y, z) \vee R(x, y)$  and it generates DNF with 12  
93 bases of the form  $P(\_, \_) \wedge Q(\_, \_)$ .

94 Since our goal is to design an  $O(F(k, w) \cdot |\varphi| \cdot N^\omega)$ -time algorithm, we cannot adopt  
95 converting-to-DNF transformations.

## 96 6.3 Tseytin-like (?) transformation for General Cases

97 As we have seen above, explicit translations to DNF does not work well since it may explode  
98 given expression to an exponential size.

99 We here develop a translation inspired by Tseytin's transformation.<sup>4</sup>

実際はインスパイアされたという程でもないんですが、とはいえよく知られた構成  
な気もするので、何かciteできるものがあればしたいという感じ。

100

Let us revisit the above example:

$$\exists z. \left( (P(x, z) \vee P(y, z) \vee P(x, y)) \wedge (Q(x, z) \vee Q(x, y)) \wedge (R(y, z) \vee R(x, y)) \right).$$

First, we generate all possible *assignments* to predicates. For our example, we have the following assignments:

	$P(x, z)$	$P(y, z)$	$P(x, y)$	$Q(x, z)$	$Q(x, y)$	$R(y, z)$	$R(x, y)$
$\alpha_1$	0	0	0	0	0	0	0
$\alpha_2$	0	0	0	0	0	0	1
$\alpha_3$	0	0	0	0	0	1	0
$\vdots$							
$\alpha$	1	0	1	0	1	0	0
$\vdots$							
$\alpha_\star$	1	1	1	1	1	1	1

101 Let  $\mathcal{A}$  be the set of all assignments.

102 Let  $\llbracket \Psi \rrbracket_\alpha$  be a boolean value obtained by evaluating  $\Psi$  under an assignment  $\alpha$ .

103 For our example expression  $\psi$ ,  $\llbracket \psi \rrbracket_\alpha = 0$  using  $\alpha$  appearing in the above table.

104 If we change  $\alpha$  as  $\alpha(R(y, z)) \leftarrow 1$ , then  $\llbracket \psi \rrbracket_\alpha = 1$ .

105 Introducing assignment leads to the following useful proposition.

► **Proposition 4.**

$$\Psi(x, y, z) \iff \bigvee_{\alpha \in \mathcal{A}} (\alpha \wedge \llbracket \Psi \rrbracket_\alpha).$$

*Especially, let  $\mathcal{V} = \{\alpha \in \mathcal{A} : \llbracket \Psi \rrbracket_\alpha\}$ , then we have:*

$$\Psi(x, y, z) \iff \bigvee_{\alpha \in \mathcal{V}} \alpha(x, y, z). \quad (\star)$$

By the definition of assignments,  $\alpha$  takes the following form:

$$\alpha(x, y, z) \equiv P_1(x, y) \wedge P_1(x, z) \wedge P_2(y, z) \wedge \cdots \wedge P_k(x, z).$$

It means that the right-hand side of  $(\star)$  takes DNF. Therefore,

$$\exists z. \Psi(x, y, z) \iff (\exists z. \alpha_1(x, y, z)) \vee (\exists z. \alpha_2(x, y, z)) \vee \cdots \vee (\exists z. \alpha_{|\mathcal{V}|}(x, y, z)).$$

106 It suffices to eliminating an  $\exists$ -quantifier from  $\exists z. \alpha(x, y, z)$  for an assignment  $\alpha$ .

We first divide  $\alpha(x, y, z)$  into two parts  $\alpha_z$  and  $\alpha_{-z}$  as follows:

$$\alpha(x, y, z) \equiv \underbrace{(P_1(x, z) \wedge P_2(z, x) \wedge P_1(y, z) \wedge \cdots)}_{\alpha_z: z\text{-involving-terms}} \wedge \underbrace{(P_1(x, y) \wedge P_1(y, x) \wedge P_2 \wedge \cdots)}_{\alpha_{-z}: z\text{-non-involving-terms}}$$

<sup>4</sup> [https://en.wikipedia.org/wiki/Tseytin\\_transformation](https://en.wikipedia.org/wiki/Tseytin_transformation)

We now have the following:

$$\left( \exists z. \alpha(x, y, z) \right) \iff \left( \alpha_{-z}(x, y) \wedge (\exists z. \alpha_z(x, y, z)) \right).$$

107 Finally, we transform  $\alpha_z$  in the following steps (order):

- 108 1. If  $\alpha_z$  has a term  $P(z, x)$ , we replace it with  $\tilde{P}(x, z)$  where  $\tilde{P}(a, b) = P(b, a)$ .  
 109 2. Similarly, we change terms of the form  $P(y, z)$  to  $\tilde{P}(z, y)$ .  
 3. At this point,

$$\alpha_z(x, y, z) \equiv \underbrace{(P_1(x, z) \wedge P_3(x, z) \wedge P_4(x, z) \wedge \dots)}_{\Psi_x} \wedge \underbrace{(P_2(z, y) \wedge P_3(z, y) \wedge P_5(z, y) \wedge \dots)}_{\Psi_y}.$$

- 110 4. Let  $\Psi_x$  (resp.  $\Psi_y$ ) be the set of predicates appearing in the above former (resp. latter)  
 111 part.  
 5. Let us introduce two new predicates:

$$\pi(x, z) := \bigwedge_{P \in \Psi_x} P(x, z), \quad \lambda(z, y) := \bigwedge_{Q \in \Psi_y} Q(z, y).$$

6. We reach our goal:

$$\alpha_z(x, y, z) = \pi(x, z) \wedge \lambda(z, y).$$

Using the final form, we obtain the following:

$$\begin{aligned} \left( \exists z. \alpha(x, y, z) \right) &\iff \left( \alpha_{-z}(x, y) \wedge (\exists z. \pi(x, z) \wedge \lambda(z, y)) \right) \\ &\iff \left( \alpha_{-z}(x, y) \wedge (\pi \odot \lambda)(x, y) \right) \\ &\iff (\alpha_{-z} \wedge (\pi \odot \lambda))(x, y) \end{aligned}$$

## 112 6.4 Considering Complexity

113 To eliminate an  $\exists$ -quantifier from an assignment  $\alpha$ , we introduce a new single predicate  
 114  $\alpha_{-z} \wedge (\pi \odot \lambda)$ .

Now we have a question: To eliminate the  $\exists$ -quantifier from  $\exists z. \Psi(x, y, z)$ , from the following characterization

$$\left( \exists z. \Psi(x, y, z) \right) \iff \left( \exists z. \bigvee_{\alpha \in \mathcal{V}} \alpha(x, y, z) \right) \iff \bigvee_{\alpha \in \mathcal{V}} \left( \exists z. \alpha(x, y, z) \right) \iff \bigvee_{\alpha \in \mathcal{V}} (\alpha_{-z} \wedge (\pi \odot \lambda))(x, y)$$

can we avoid to introduce  $O(2^k)$  predicates if we have  $k$ -predicates?? Please recall that each assignment is a choice from  $9k$ -literals from  $\mathcal{L}$  where

$$\mathcal{L} = \{Q(a, b) : a, b \in \{x, y, z\}, Q \in \{P_1, P_2, \dots, P_k\}\}.$$

**Yes. We can avoid introducing a large number of predicates** because we just need to introduce the following single (but large) predicate:

$$(\alpha_{-z}^1 \wedge (\pi^1 \odot \lambda^1)) \vee (\alpha_{-z}^2 \wedge (\pi^2 \odot \lambda^2)) \vee \dots \vee (\alpha_{-z}^n \wedge (\pi^n \odot \lambda^n))$$

115 for  $\mathcal{V} = \{\alpha^1, \alpha^2, \dots, \alpha^n\}$ .

Let us consider what happens when repeatedly eliminating quantifiers from the innermost to the outermost:

$$\begin{aligned}
 & \exists y. \left( (\exists z. \dots) \bowtie (\exists z. \dots) \bowtie \dots \bowtie (\exists z. \dots) \right) \\
 & \Rightarrow \\
 & \exists y. \left( \begin{array}{l} \text{Q. how many predicates appear in this scope?} \\ \text{A. } k + w \text{ where } w \text{ is the quantifier width of } \psi \end{array} \right) \\
 & \Rightarrow \\
 & \text{Eliminating } (\exists y.) \text{ introduces a single new predicate.}
 \end{aligned}$$

Since the required number of quantifier elimination (= the quantifier depth) is bounded by the size of a given expression  $|\psi|$ , we obtain the following our theorem in the end.

► **Theorem 1 (Restatement).** *Let  $\varphi : \mathbb{FO}_{k,w}^3$ .  
For a given model (graph)  $\mathcal{G}$ , we can decide if  $\mathcal{G} \models \varphi$  in  $O(2^{k+w} \cdot |\varphi| \cdot N^w)$ .*

## 7 FO2 model checking

$\mathbb{FO}^2$ の論理式  $\psi$  と、グラフ  $\mathcal{G}$  について  $\mathcal{G} \models \psi$  のモデル検査問題は  $O(|\psi| \cdot |\mathcal{G}|)$  で解ける気がします。ただし、 $|\mathcal{G}|$ は頂点数ではなく、述語（つまり辺）の定義の記述長も合わせたものです。面白そうなら書いても良いかと思うのですが、 $\mathbb{FO}^3$ の話だけにしたほうが、話がぼやけないならなくても良いかなという気がします。

Dense graphについては  $(x, y)$  の値の集合を構築する方法で  $O(|\psi| \cdot N^2)$  になります。この  $N$  は  $\mathcal{G}$  の頂点数の方です。ただ、sparse graphの時には  $N^2$  は  $|\mathcal{G}|$  について線形ではないので、そこを改良したいという感じです。

アイディアは、 $\mathbb{FO}^3$ の時と比べると、 $\exists y. P(x, y) \wedge Q(y, x) \simeq (P \odot Q)$  の計算について  $(P \odot Q)(x, x)$  の diagonal な形しか要求しないので、行列積を全部やる必要が多分なさそうとかそういう感じです。

Sparse graphの話なので、もしかすると Impagliazzo たちがやっているかもしれません。

Yo: [3] Lemma 9.1 Base Case は  $O(|\psi| \cdot |\mathcal{G}|)$  ??

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