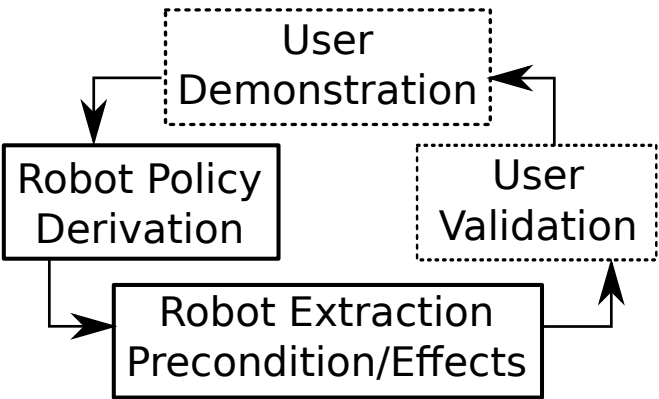


1) Programming by Demonstration



2) Automated Planning

Planning Problem

Planning Domain
created using PbD

Initial State
recognised by Robot

Final Goal State
set by User

Planner

Robot
Execution

action1
action2
...

3) Retro-active Loop

