Chapter 5. Problems.

Problem 1

y-x-u, y-x-v-u, y-x-w-u, y-x-w-v-u,
y-w-u, y-w-v-u, y-w-x-u, y-w-x-v-u, y-w-v-x-u,
y-z-w-u, y-z-w-v-u, y-z-w-x-u, y-z-w-x-v-u, y-z-w-v-x-u,

Problem 2

x to z:
x-y-z, x-y-w-z,
x-w-z, x-w-y-z,
x-v-w-z, x-v-w-y-z,
x-u-w-z, x-u-w-y-z,
x-u-v-w-z, x-u-v-w-y-z

z to u:
z-w-u,
z-w-v-u, z-w-x-u, z-w-v-x-u, z-w-x-v-u, z-w-y-x-u, z-w-y-x-v-u,
z-y-x-u, z-y-x-v-u, z-y-x-w-u, z-y-x-w-y-u, z-y-x-v-w-u,
z-y-w-v-u, z-y-w-x-u, z-y-w-v-x-u, z-y-w-x-v-u, z-y-w-y-x-u, z-y-w-y-x-v-u

z to w:
z-w, z-y-w, z-y-x-w, z-y-x-v-w, z-y-x-u-w, z-y-x-u-v-w, z-y-x-v-u-w

Problem 3

Step	*N'*	*D(t),p(t)*	*D(u),p(u)*	*D(v),p(v)*	*D(w),p(w)*	*D(y),p(y)*	*D(z),p(z)*
0	x	∞	∞	3,x	6,x	6,x	8,x
1	xv	7,v	6,v	3,x	6,x	6,x	8,x
2	xvu	7,v	6,v	3,x	6,x	6,x	8,x
3	xvuw	7,v	6,v	3,x	6,x	6,x	8,x
4	xvuwy	7,v	6,v	3,x	6,x	6,x	8,x
5	xvuwyt	7,v	6,v	3,x	6,x	6,x	8,x
6	xvuwytz	7,v	6,v	3,x	6,x	6,x	8,x

Problem 4

a)

Step	N'	D(x), p(x)	D(u),p(u)	D(v),p(v)	D(w),p(w)	D(y),p(y)	D(z),p(z)
0	t	∞	2,t	4,t	∞	7,t	∞
1	tu	∞	2,t	4,t	5,u	7,t	∞
2	tuv	7,v	2,t	4,t	5,u	7,t	∞
3	tuvw	7,v	2,t	4,t	5,u	7,t	∞
4	tuvwx	7,v	2,t	4,t	5,u	7,t	15,x
5	tuvwxy	7,v	2,t	4,t	5,u	7,t	15,x
6	tuvwxyz	7,v	2,t	4,t	5,u	7,t	15,x

b)

Step	N'	D(x), p(x)	D(t),p(t)	D(v),p(v)	D(w),p(w)	D(y),p(y)	D(z),p(z)
	u	∞	2,u	3,u	3,u	∞	∞
	ut	∞	2,u	3,u	3,u	9,t	∞
	utv	6,v	2,u	3,u	3,u	9,t	∞
	utvw	6,v	2,u	3,u	3,u	9,t	∞
	utvwx	6,v	2,u	3,u	3,u	9,t	14,x
	utvwxy	6,v	2,u	3,u	3,u	9,t	14,x
	utvwxyz	6,v	2,u	3,u	3,u	9,t	14,x

c)

Step	N'	D(x), p(x)	D(u),p(u)	D(t),pt)	D(w),p(w)	D(y),p(y)	D(z),p(z)

	v	3,v	3,v	4,v	4,v	8,v	∞
	vx	3,v	3,v	4,v	4,v	8,v	11,x
	vxu	3,v	3,v	4,v	4,v	8,v	11,x
	vxut	3,v	3,v	4,v	4,v	8,v	11,x
	vxutw	3,v	3,v	4,v	4,v	8,v	11,x
	vxutwy	3,v	3,v	4,v	4,v	8,v	11,x
	vxutwyz	3,v	3,v	4,v	4,v	8,v	11,x

d)

Step	*N'*	*D(x), p(x)*	*D(u),p(u)*	*D(v),p(v)*	*D(t),p(t)*	*D(y),p(y)*	*D(z),p(z)*
	w	6,w	3,w	4,w	∞	∞	∞
	wu	6,w	3,w	4,w	5,u	∞	∞
	wuv	6,w	3,w	4,w	5,u	12,v	∞
	wuvt	6,w	3,w	4,w	5,u	12,v	∞
	wuvtx	6,w	3,w	4,w	5,u	12,v	14,x
	wuvtxy	6,w	3,w	4,w	5,u	12,v	14,x
	wuvtxyz	6,w	3,w	4,w	5,u	12,v	14,x

e)

Step	*N'*	*D(x), p(x)*	*D(u),p(u)*	*D(v),p(v)*	*D(w),p(w)*	*D(t),p(t)*	*D(z),p(z)*
	y	6,y	∞	8,y	∞	7,y	12,y
	yx	6,y	∞	8,y	12,x	7,y	12,y
	yxt	6,y	9,t	8,y	12,x	7,y	12,y
	yxtv	6,y	9,t	8,y	12,x	7,y	12,y
	yxtvu	6,y	**9,t**	8,y	12,x	7,y	12,y

	yxtvuw	6,y	9,t	8,y	12,x	7,y	12,y
	yxtvuwz	6,y	9,t	8,y	12,x	7,y	12,y

f)

Step	N'	D(x), p(x)	D(u),p(u)	D(v),p(v)	D(w),p(w)	D(y),p(y)	D(t),p(t)
	z	8,z	∞	∞	∞	12,z	∞
	zx	8,z	∞	11,x	14,x	12,z	∞
	zxv	8,z	14,v	**11,x**	14,x	12,z	15,v
	zxvy	8,z	14,v	11,x	14,x	**12,z**	15,v
	zxvyu	8,z	**14,v**	11,x	14,x	12,z	15,v
	zxvyuw	8,z	14,v	11,x	**14,x**	12,z	15,v
	zxvyuwt	8,z	14,v	11,x	**14,x**	12,z	15,v

Problem 5

		Cost to u	v	x	y	z
	v	∞	∞	∞	∞	∞
From	x	∞	∞	∞	∞	∞
	z	∞	6	2	∞	0

Cost to

		u	v	x	y	z
	v	1	0	3	∞	6
From	x	∞	3	0	3	2
	z	7	5	2	5	0

Cost to

		u	v	x	y	z
	v	1	0	3	3	5
From	x	4	3	0	3	2
	z	6	5	2	5	0

		Cost to				
		u	v	x	y	z
	v	1	0	3	3	5
From	x	4	3	0	3	2
	z	6	5	2	5	0

Problem 6

The wording of this question was a bit ambiguous. We meant this to mean, "the number of iterations from when the algorithm is run for the first time" (that is, assuming the only information the nodes initially have is the cost to their nearest neighbors). We assume that the algorithm runs synchronously (that is, in one step, all nodes compute their distance tables at the same time and then exchange tables).

At each iteration, a node exchanges distance tables with its neighbors. Thus, if you are node A, and your neighbor is B, all of B's neighbors (which will all be one or two hops from you) will know the shortest cost path of one or two hops to you after one iteration (i.e., after B tells them its cost to you).

Let d be the "diameter" of the network - the length of the longest path without loops between any two nodes in the network. Using the reasoning above, after $d-1$ iterations, all nodes will know the shortest path cost of d or fewer hops to all other nodes. Since any path with greater than d hops will have loops (and thus have a greater cost than that path with the loops removed), the algorithm will converge in at most $d-1$ iterations.

ASIDE: if the DV algorithm is run as a result of a change in link costs, there is no a priori bound on the number of iterations required until convergence unless one also specifies a bound on link costs.

Problem 7

a) Dx(w) = 2, Dx(y) = 4, Dx(u) = 7

b) First consider what happens if c(x,y) changes. If c(x,y) becomes larger or smaller (as long as c(x,y) >=1) , the least cost path from x to u will still have cost at least 7. Thus a change in c(x,y) (if c(x,y)>=1) will not cause x to inform its neighbors of any changes.

If $c(x,y) = \delta < 1$, then the least cost path now passes through y and has cost $\delta+6$.

Now consider if c(x,w) changes. If $c(x,w) = \varepsilon \leq 1$, then the least-cost path to u continues to pass through w and its cost changes to $5 + \varepsilon$; x will inform its neighbors of this new cost. If $c(x,w) = \delta > 6$, then the least cost path now passes through y and has cost 11; again x will inform its neighbors of this new cost.

c) Any change in link cost c(x,y) (and as long as c(x,y) >=1) will not cause x to inform its neighbors of a new minimum-cost path to u .

Problem 8

Node x table

		Cost to		
		x	y	z
	x	0	3	4
From	y	∞	∞	∞
	z	∞	∞	∞

		Cost to		
		x	y	z
	x	0	3	4
From	y	3	0	6
	z	4	6	0

Node y table

		Cost to		
		x	y	z
	x	∞	∞	∞
From	y	3	0	6
	z	∞	∞	∞

		Cost to		
		x	y	z
	x	0	3	4
From	y	3	0	6
	z	4	6	0

Node z table

		Cost to		
		x	y	z
	x	∞	∞	∞
From	y	∞	∞	∞

z	4	6	0

		Cost to		
		x	y	z
	x	0	3	4
From	y	3	0	6
	z	4	6	0

Problem 9

NO, this is because that decreasing link cost won't cause a loop (caused by the next-hop relation of between two nodes of that link). Connecting two nodes with a link is equivalent to decreasing the link weight from infinite to the finite weight.

Problem 10

At each step, each updating of a node's distance vectors is based on the Bellman-Ford equation, i.e., only decreasing those values in its distance vector. There is no increasing in values. If no updating, then no message will be sent out. Thus, D(x) is non-increasing. Since those costs are finite, then eventually distance vectors will be stabilized in finite steps.

Problem 11

a)

Router z	Informs w, $D_z(x)=\infty$
	Informs y, $D_z(x)=6$
Router w	Informs y, $D_w(x)=\infty$
	Informs z, $D_w(x)=5$
Router y	Informs w, $D_y(x)=4$
	Informs z, $D_y(x)=4$

b)

b) Yes, there will be a count-to-infinity problem. The following table shows the routing converging process. Assume that at time t0, link cost change happens. At time t1, y updates its distance vector and informs neighbors w and z. In the following table, "→" stands for "informs".

time	t0	t1	t2	t3	t4

Z	→ w, $D_z(x)=\infty$ → y, $D_z(x)=6$		No change	→ w, $D_z(x)=\infty$ → y, $D_z(x)=11$	
W	→ y, $D_w(x)=\infty$ → z, $D_w(x)=5$		→ y, $D_w(x)=\infty$ → z, $D_w(x)=10$		No change
Y	→ w, $D_y(x)=4$ → z, $D_y(x)=4$	→ w, $D_y(x)=9$ → z, $D_y(x)=\infty$		No change	→ w, $D_y(x)=14$ → z, $D_y(x)=\infty$

We see that w, y, z form a loop in their computation of the costs to router x. If we continue the iterations shown in the above table, then we will see that, at t27, z detects that its least cost to x is 50, via its direct link with x. At t29, w learns its least cost to x is 51 via z. At t30, y updates its least cost to x to be 52 (via w). Finally, at time t31, no updating, and the routing is stabilized.

time	t27	t28	t29	t30	t31
Z	→ w, $D_z(x)=50$ → y, $D_z(x)=50$				via w, ∞ via y, 55 via z, 50
W		→ y, $D_w(x)=\infty$ → z, $D_w(x)=50$	→ y, $D_w(x)=51$ → z, $D_w(x)=\infty$		via w, ∞ via y, ∞ via z, 51
Y		→ w, $D_y(x)=53$ → z, $D_y(x)=\infty$		→ w, $D_y(x)=\infty$ → z, $D_y(x)=52$	via w, 52 via y, 60 via z, 53

c) cut the link between y and z.

Problem 12

Since full AS path information is available from an AS to a destination in BGP, loop detection is simple – if a BGP peer receives a route that contains its own AS number in the AS path, then using that route would result in a loop.

Problem 13

The chosen path is not necessarily the shortest AS-path. Recall that there are many issues to be considered in the route selection process. It is very likely that a longer loop-free path is preferred over a shorter loop-free path due to economic reason. For example, an AS might prefer to send traffic to one neighbor instead of another neighbor with shorter AS distance.

Problem 14

a) eBGP

b) iBGP

c) eBGP

d) iBGP

Problem 15

a) I1 because this interface begins the least cost path from 1d towards the gateway router 1c.

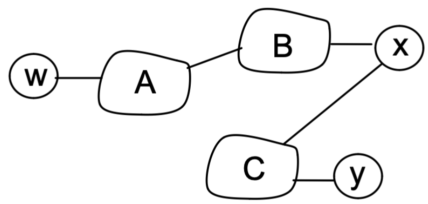
b) I2. Both routes have equal AS-PATH length but I2 begins the path that has the closest NEXT-HOP router.

c) I1. I1 begins the path that has the shortest AS-PATH.

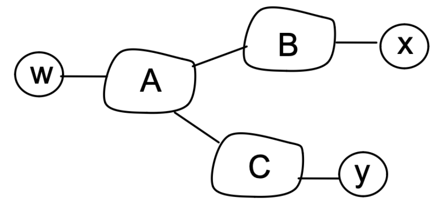
Problem 16

One way for C to force B to hand over all of B's traffic to D on the east coast is for C to only advertise its route to D via its east coast peering point with C.

Problem 17



X’s view of the topology



W’s view of the topology

In the above solution, X does not know about the AC link since X does not receive an advertised route to w or to y that contain the AC link (i.e., X receives no advertisement containing both AS A and AS C on the path to a destination.

Problem 18

BitTorrent file sharing and Skype P2P applications.
Consider a BitTorrent file sharing network in which peer 1, 2, and 3 are in stub networks W, X, and Y respectively. Due the mechanism of BitTorrent’s file sharing, it is quire possible that peer 2 gets data chunks from peer 1 and then forwards those data chunks to 3. This is equivalent to B forwarding data that is finally destined to stub network Y.

Problem 19

A should advise to B two routes, AS-paths A-W and A-V.
A should advise to C only one route, A-V.
C receives AS paths: B-A-W, B-A-V, A-V.

Problem 20

Since Z wants to transit Y's traffic, Z will send route advertisements to Y. In this manner, when Y has a datagram that is destined to an IP that can be reached through Z, Y will have the option of sending the datagram through Z. However, if Z advertizes routes to Y, Y can re-advertize those routes to X. Therefore, in this case, there is nothing Z can do from preventing traffic from X to transit through Z.

Problem 21

Request response mode will generally have more overhead (measured in terms of the number of messages exchanged) for several reasons. First, each piece of information received by the manager requires two messages: the poll and the response. Trapping generates only a single message to the sender. If the manager really only wants to be notified when a condition occurs, polling has more overhead, since many of the polling messages may indicate that the waited-for condition has not yet occurred. Trapping generates a message only when the condition occurs.

Trapping will also immediately notify the manager when an event occurs. With polling, the manager needs will need to wait for half a polling cycle (on average) between when the event occurs and the manager discovers (via its poll message) that the event has occurred.

If a trap message is lost, the managed device will not send another copy. If a poll message, or its response, is lost the manager would know there has been a lost message (since the reply never arrives). Hence the manager could repoll, if needed.

Problem 22

Often, the time when network management is most needed is in times of stress, when the network may be severely congested and packets are being lost. With SNMP running over TCP, TCP's congestion control would cause SNMP to back-off and stop sending messages at precisely the time when the network manager needs to send SNMP messages.