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Trees

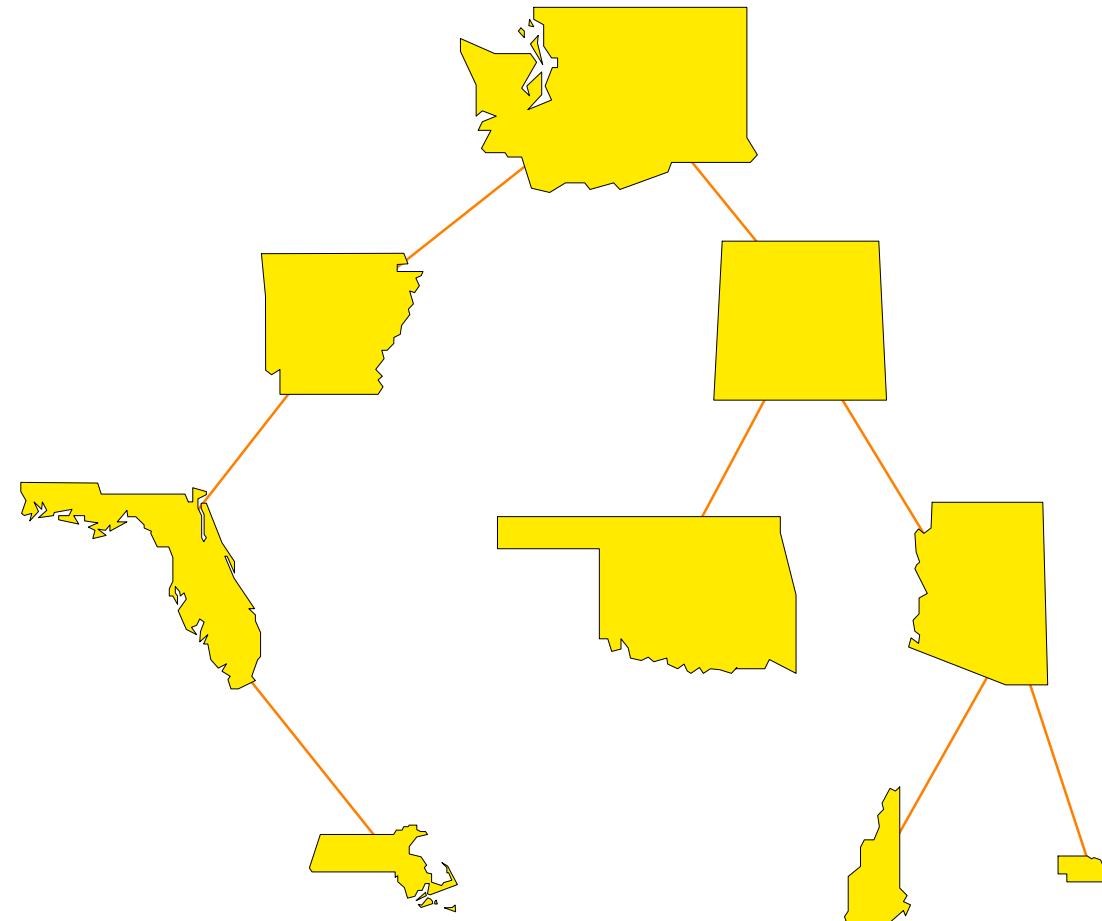
Binary Trees

- ❖ A binary tree has **nodes**, similar to nodes in a linked list structure.
- ❖ **Data** of one sort or another may be stored at each node.
- ❖ But it is the **connections** between the nodes which characterize a binary tree.



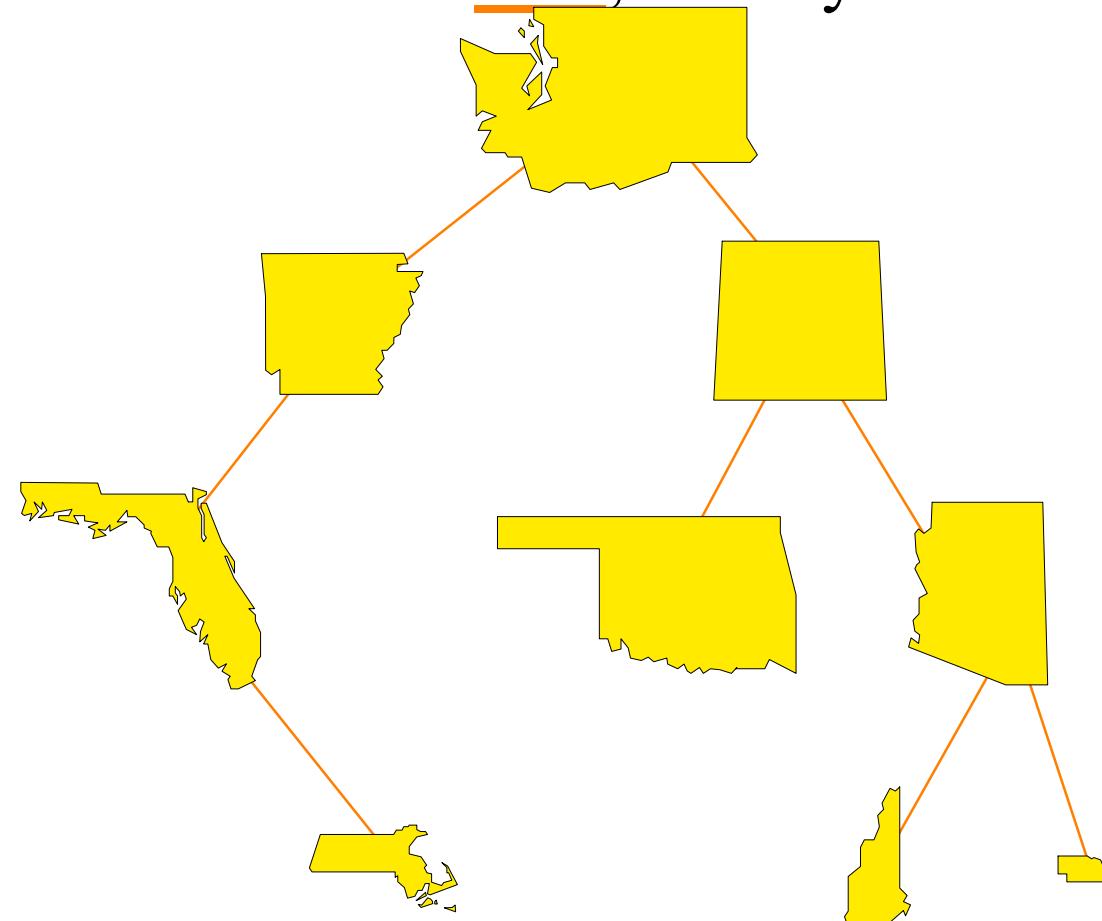
A Binary Tree of States

In this example, the data contained at each node is one of the 50 states.



A Binary Tree of States

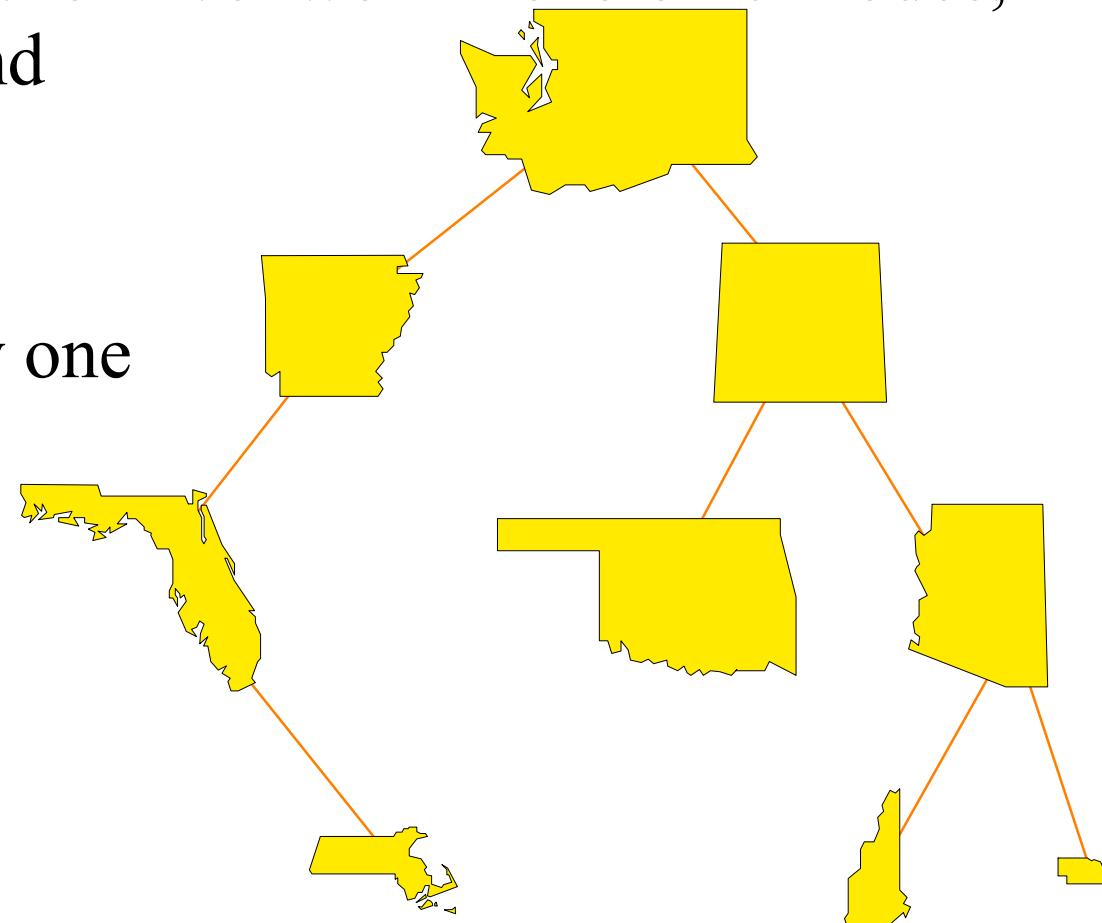
Each tree has a special node called its root, usually drawn at the top.



A Binary Tree of States

Each node is permitted to have two links to other nodes, called the left child and the right child.

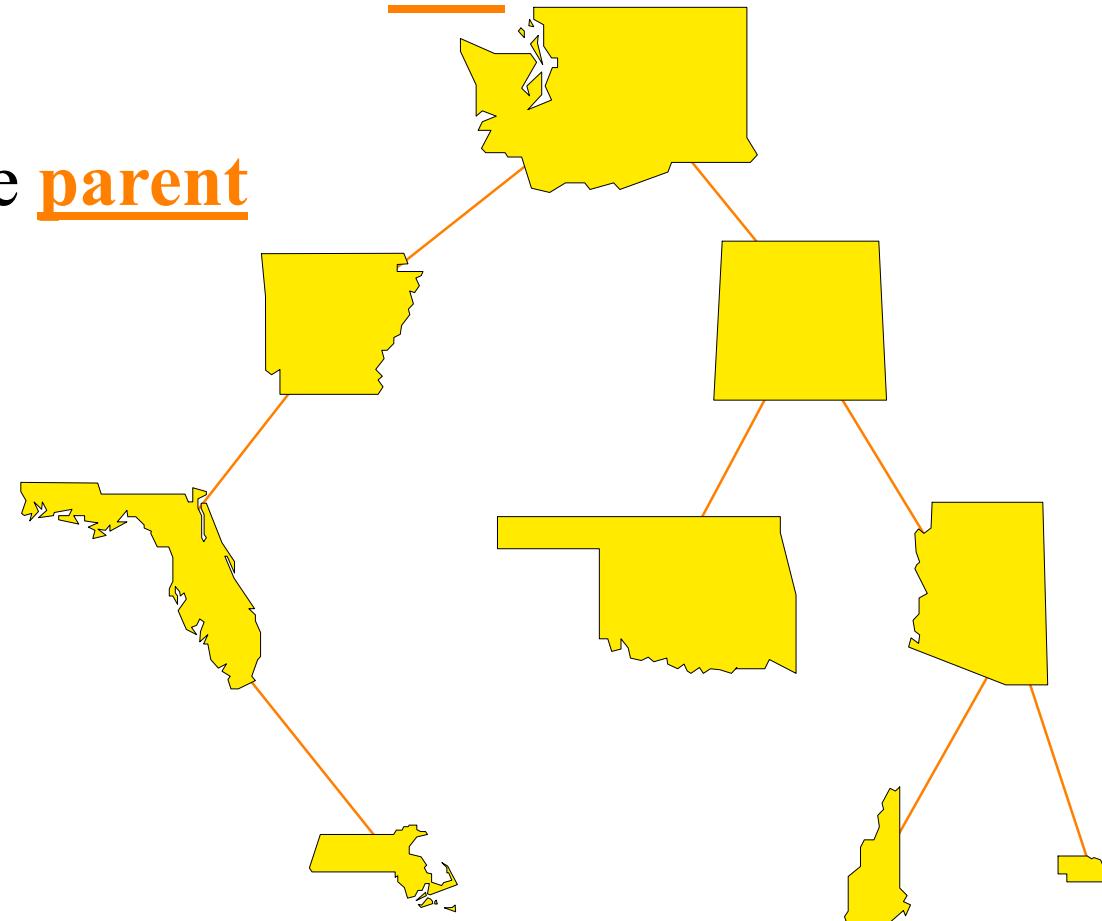
Some nodes have only one child.



A Binary Tree of States

A node with no children is called a leaf.

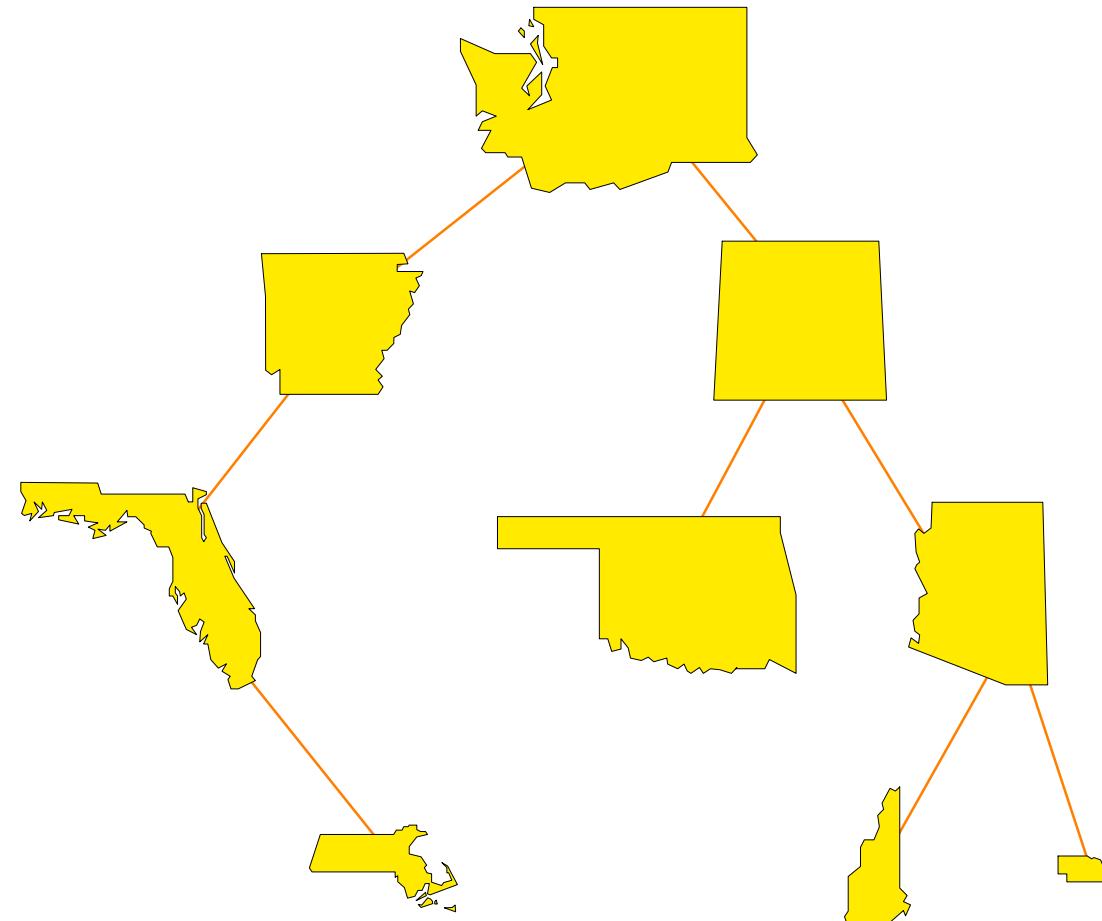
Each node is called the parent of its children.



A Binary Tree of States

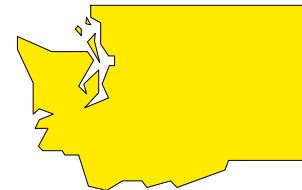
Two rules about parents:

- The root has no parent.
- Every other node has exactly one parent.



Complete Binary Trees

A complete binary tree is a special kind of binary tree which will be useful to us.



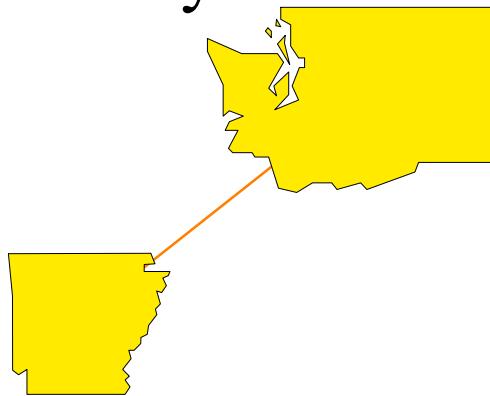
When a complete binary tree is built, its first node must be the root.



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Complete Binary Trees

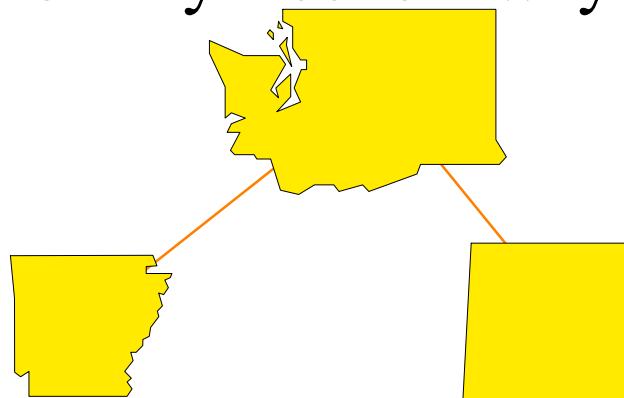
The second node of a complete binary tree is always the left child of the root...



Complete Binary Trees

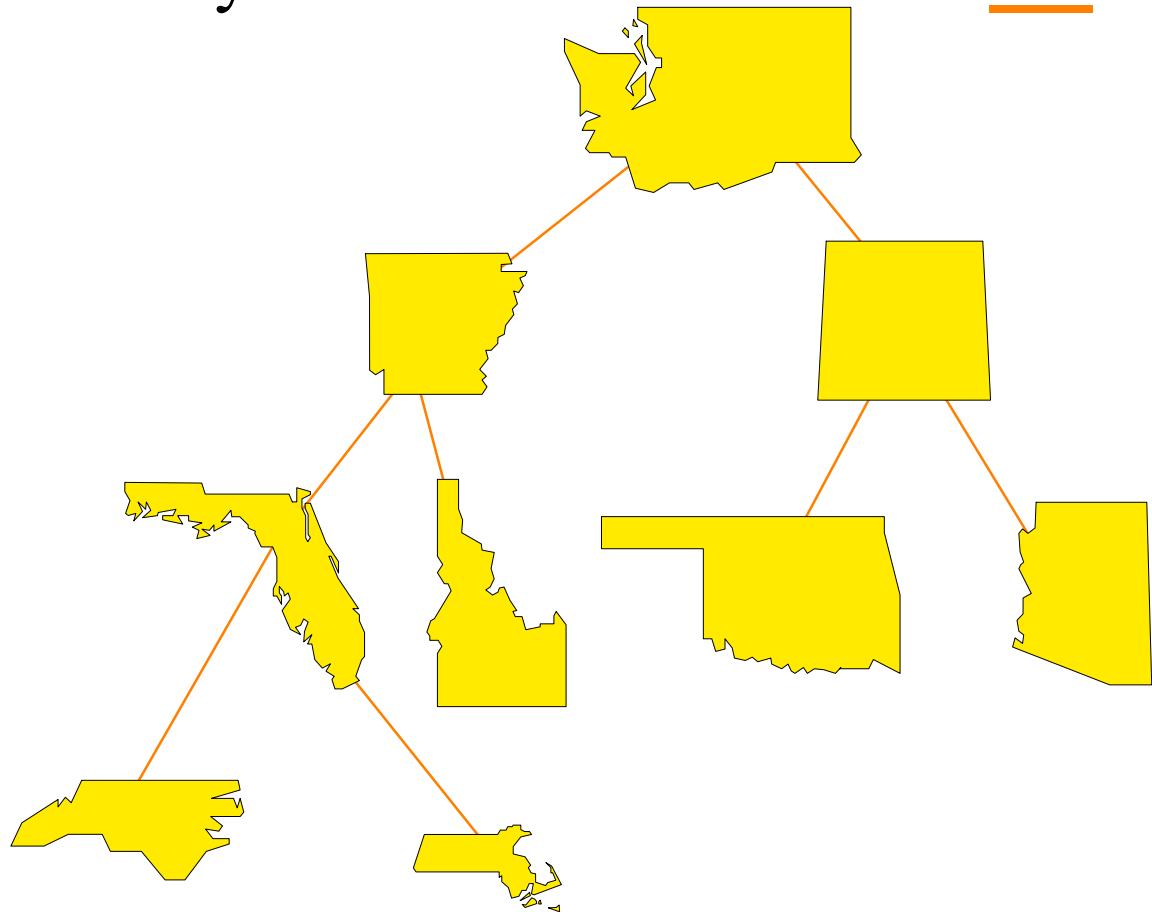
The second node of a complete binary tree is always the left child of the root...

... and the third node is always the right child of the root.

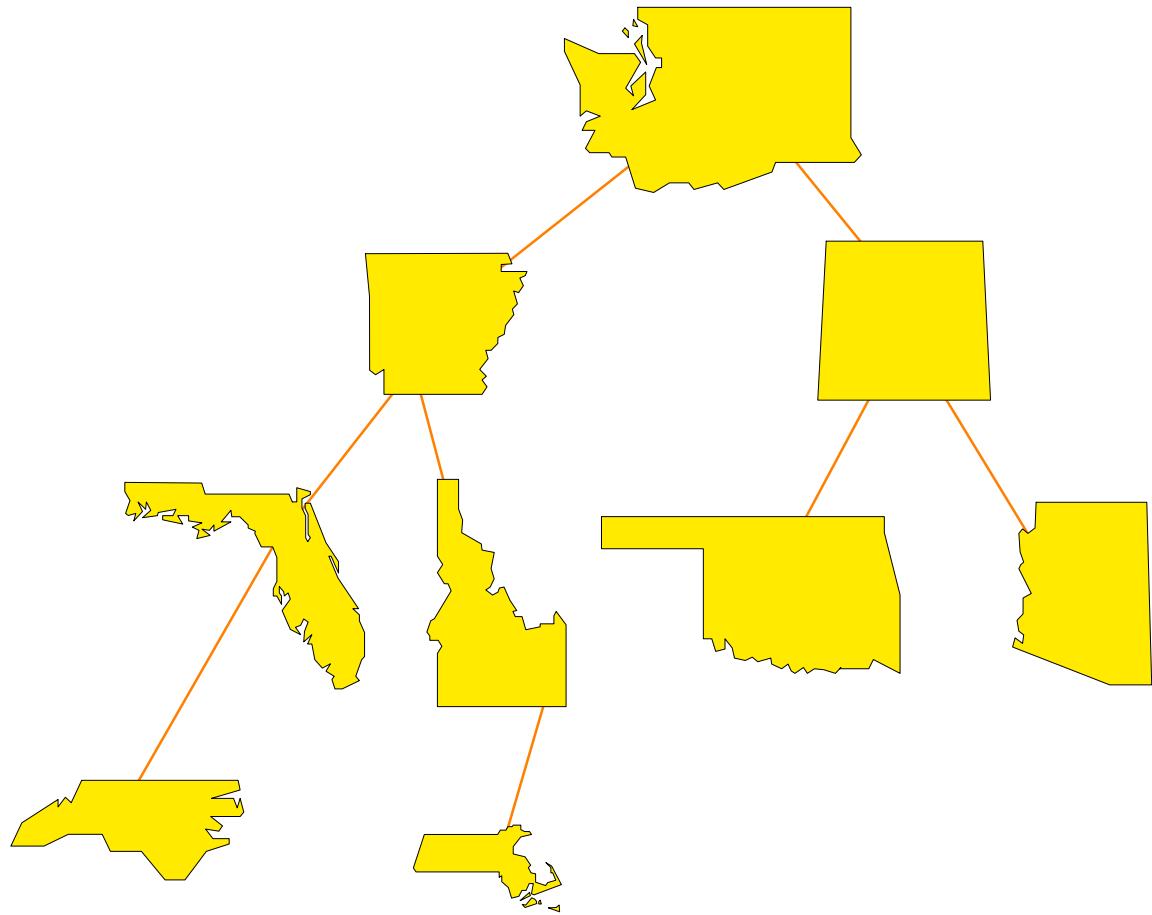


Complete Binary Trees

The next nodes must always fill the next level from left to right.



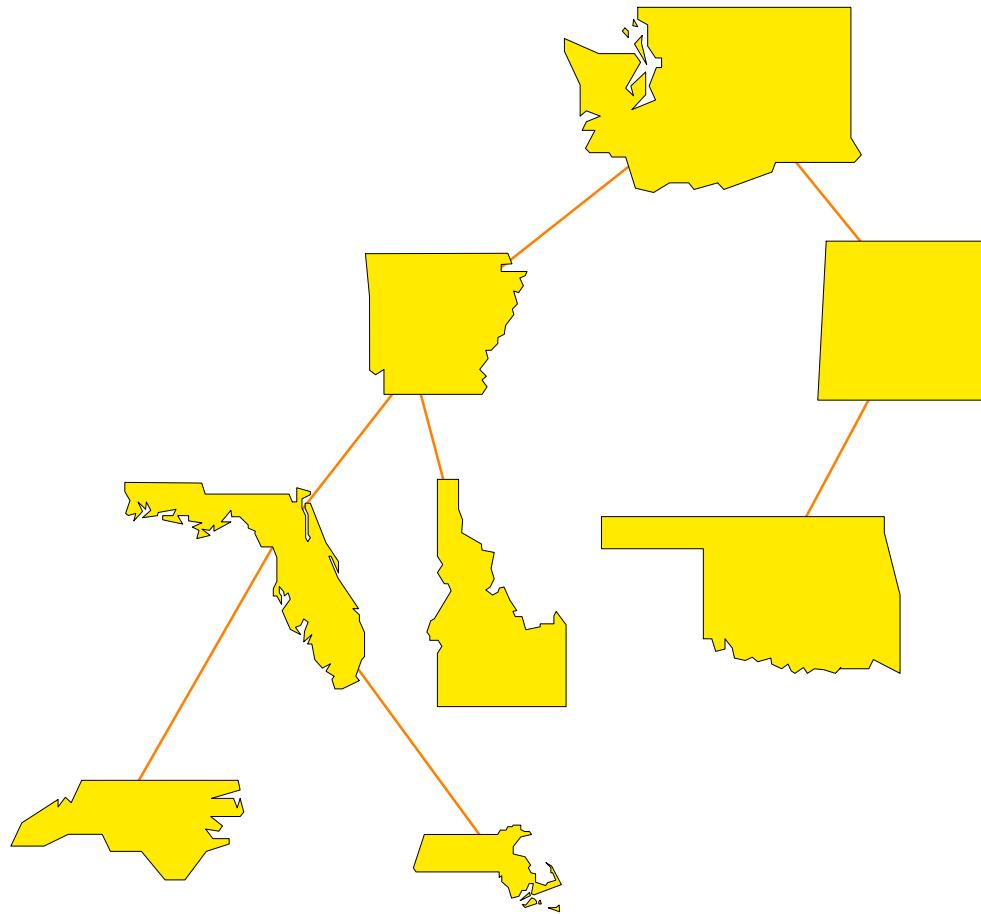
Is This Complete?



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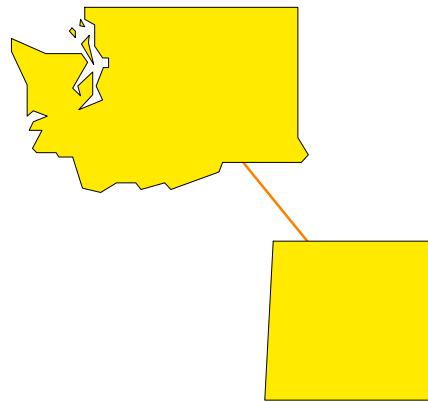
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Is This Complete?



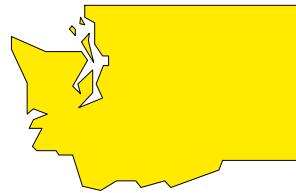
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Is This Complete?



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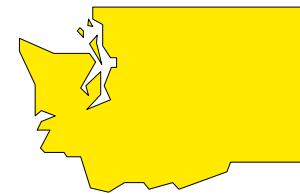
Is This Complete?



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Full Binary Trees

A full binary tree
is a special kind
of complete
binary tree



FULL

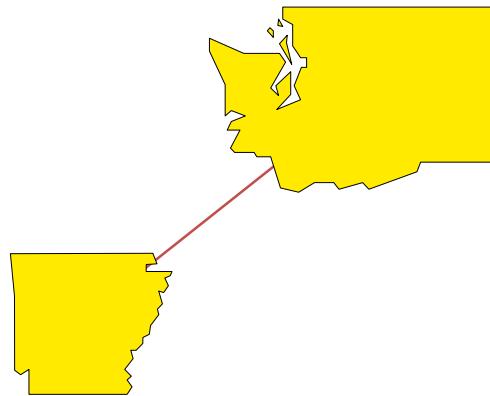
When a full
binary tree is built,
its first node must be
the root.



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Full Binary Trees

The second node of a full binary tree is always the left child of the root...



not FULL yet

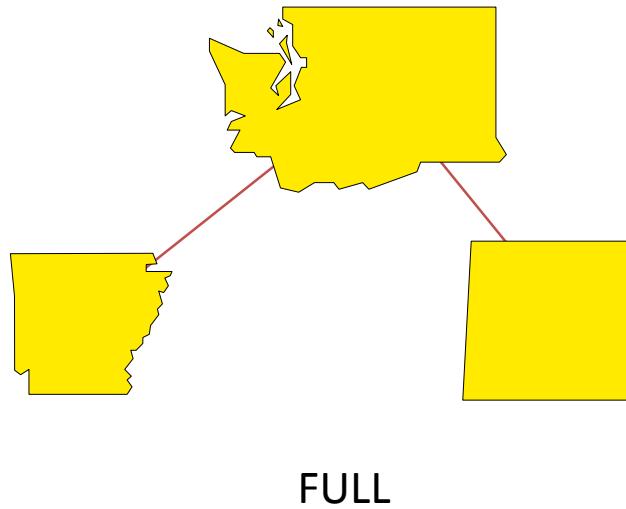


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Full Binary Trees

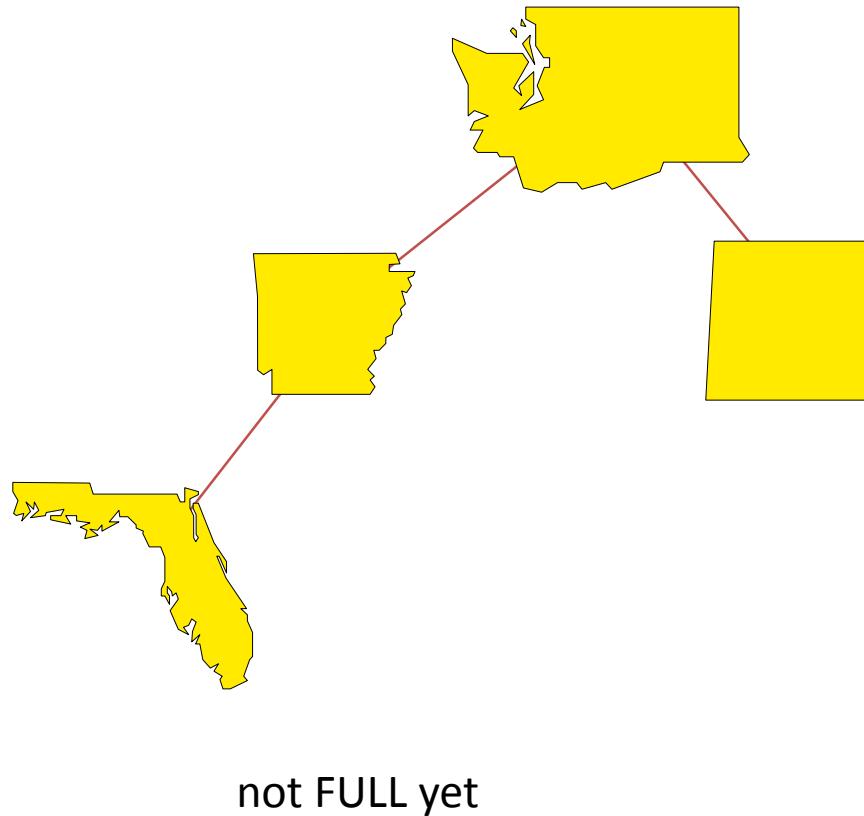
The second node of a full binary tree is always the left child of the root...

... and you MUST have the third node which always the right child of the root.



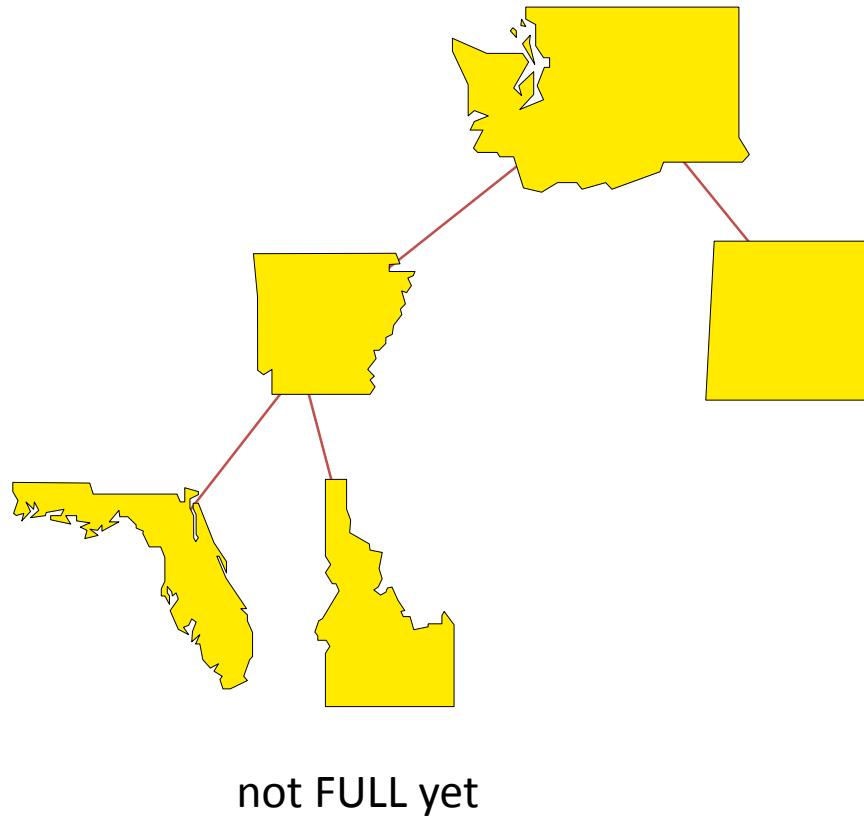
Full Binary Trees

The next nodes
must always fill
the next level
from left to
right.



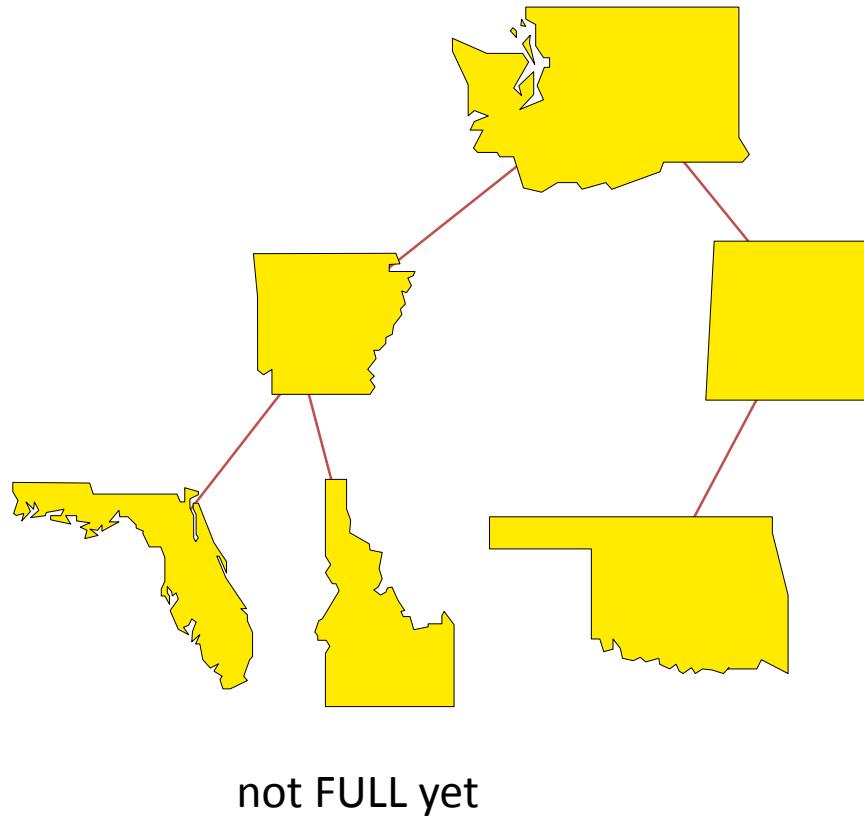
Full Binary Trees

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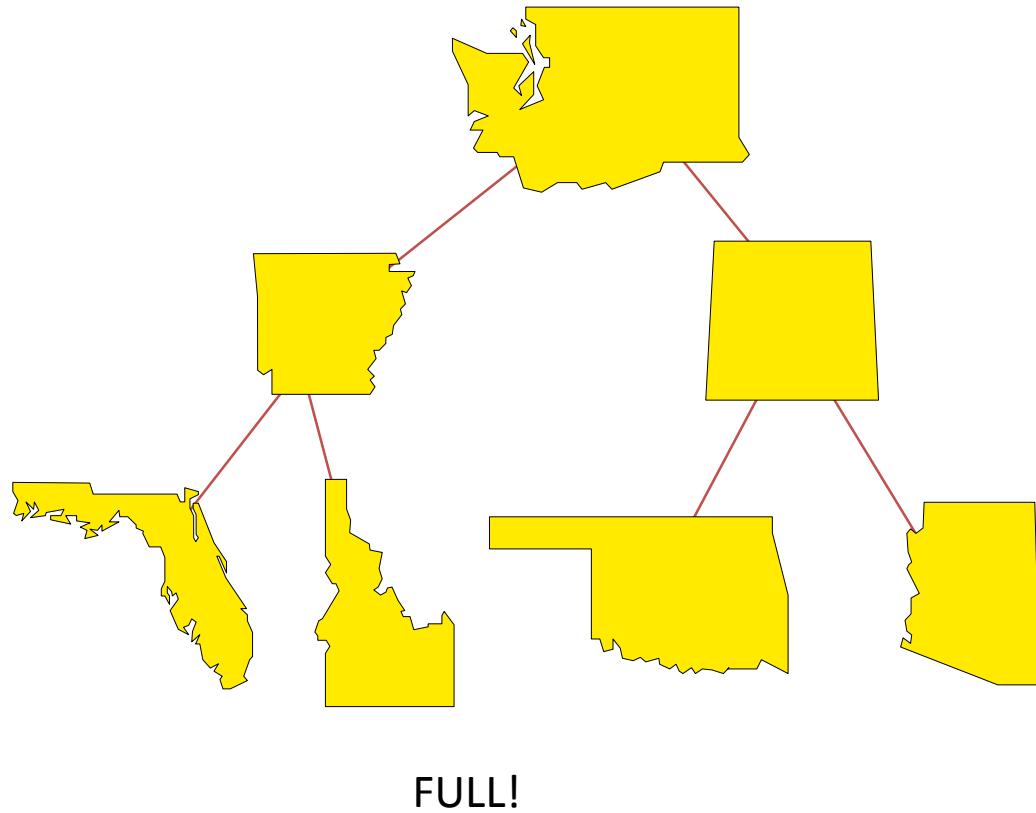
Full Binary Trees

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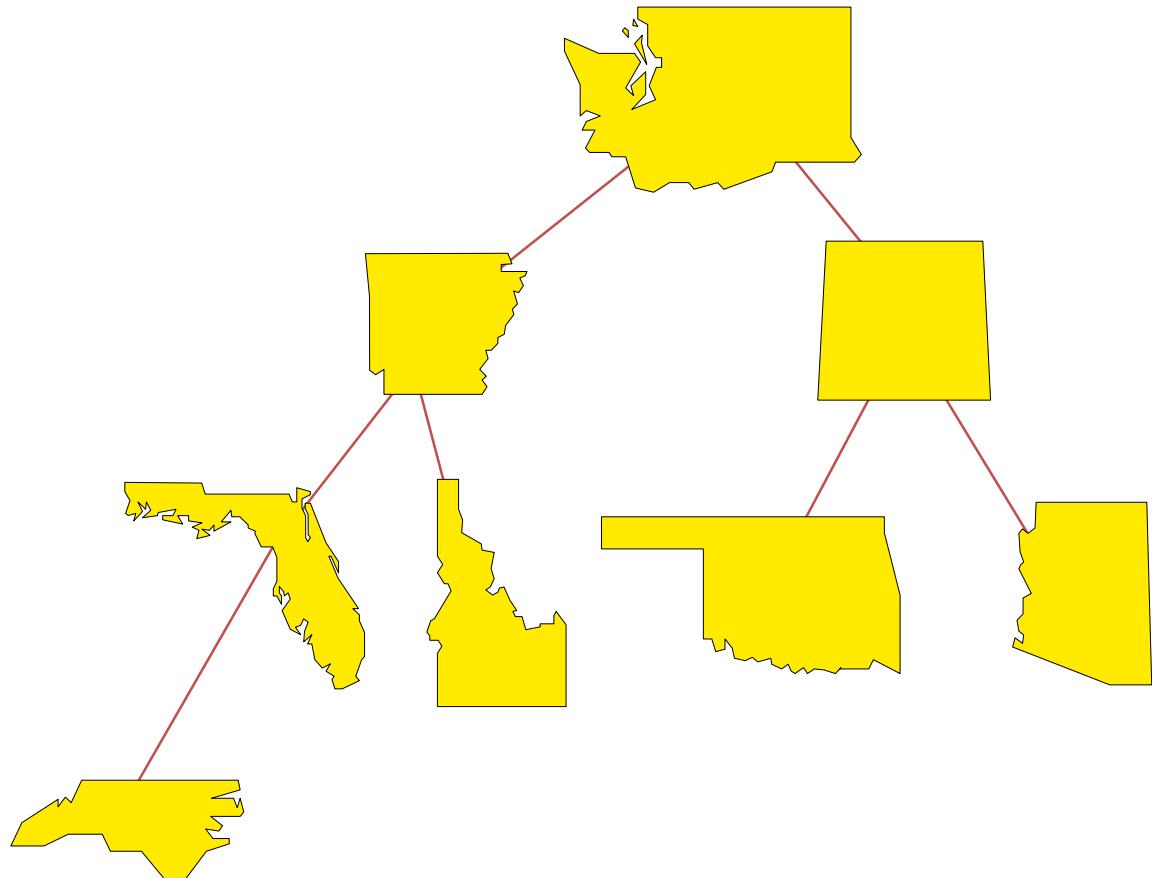
Full Binary Trees

The next nodes
must always fill
the next level
from left to
right...until
every leaf has
the same depth
(2)



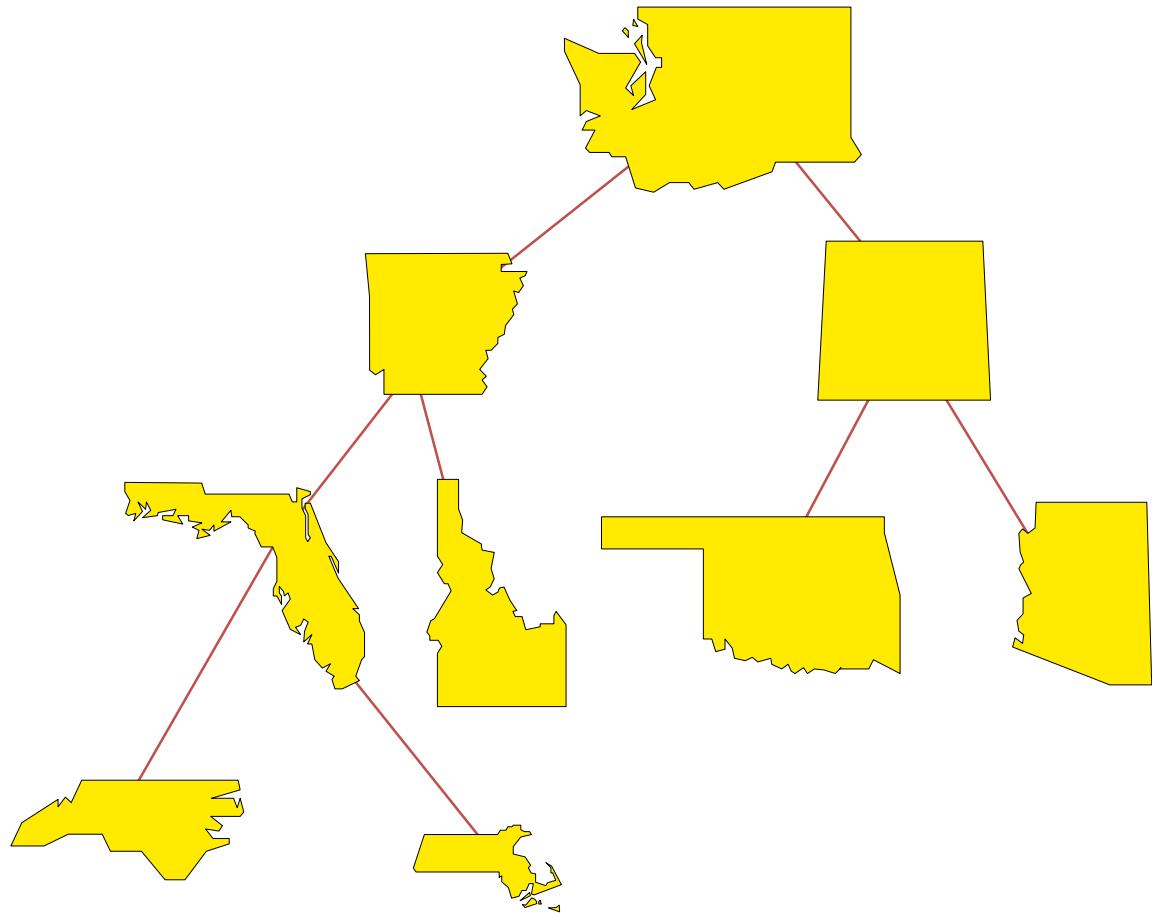
Full Binary Trees

The next nodes
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right.

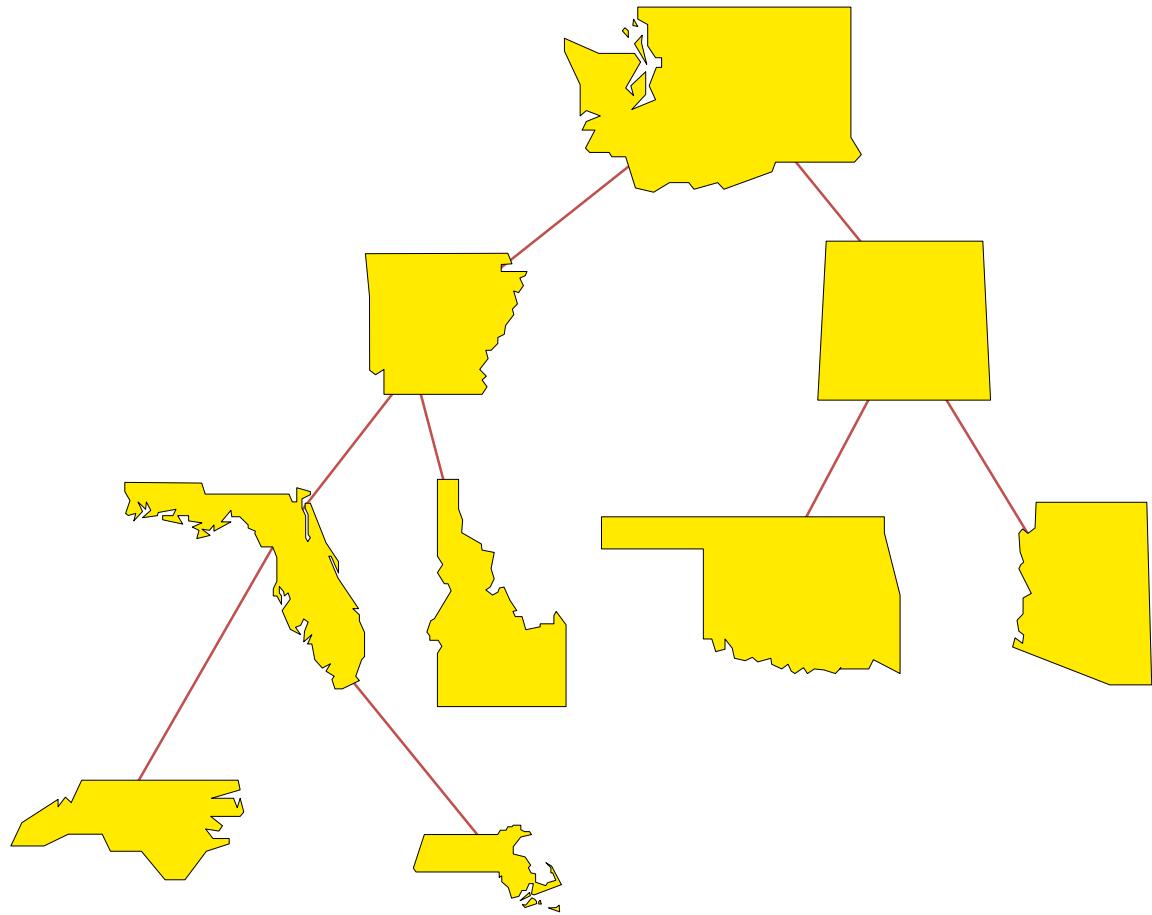


Full Binary Trees

The next nodes
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right.

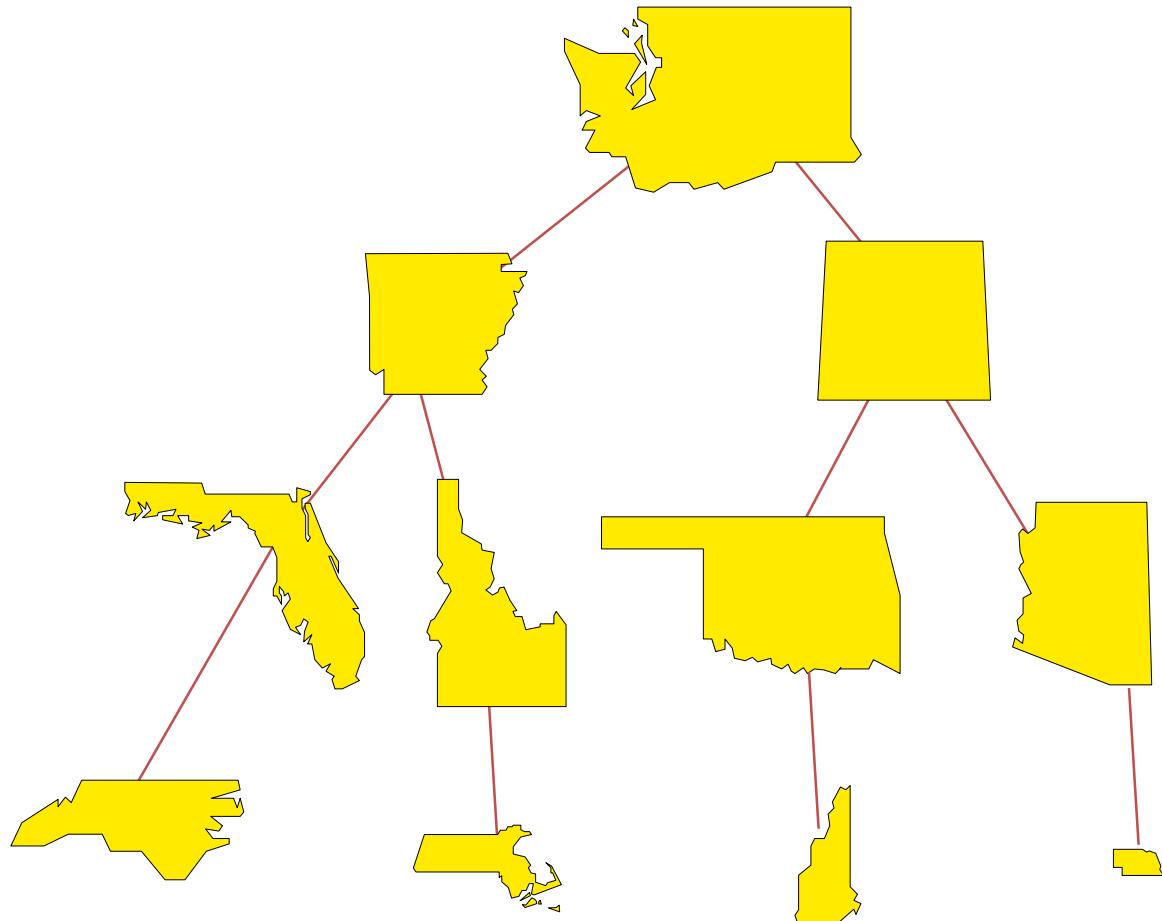


Is This Full?



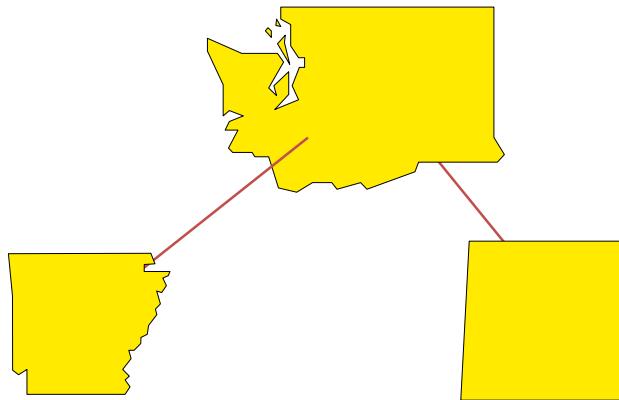
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Is This Full?



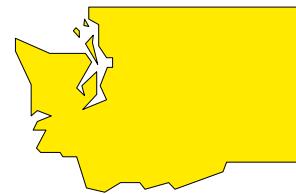
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Is This Full?



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Is This Full?



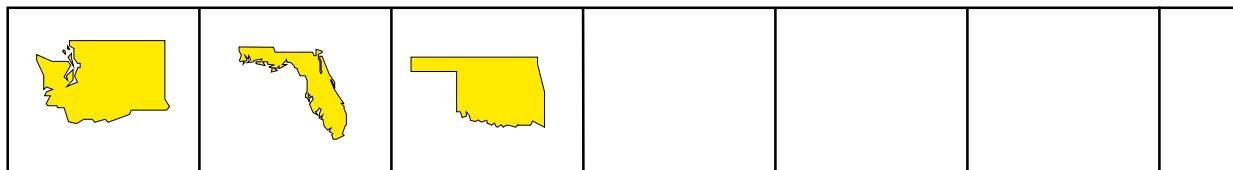
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Array implementation of a Complete Binary Tree

- ❖ We will store the data from the nodes in a partially-filled array.



An integer to keep track of how many nodes are in the tree



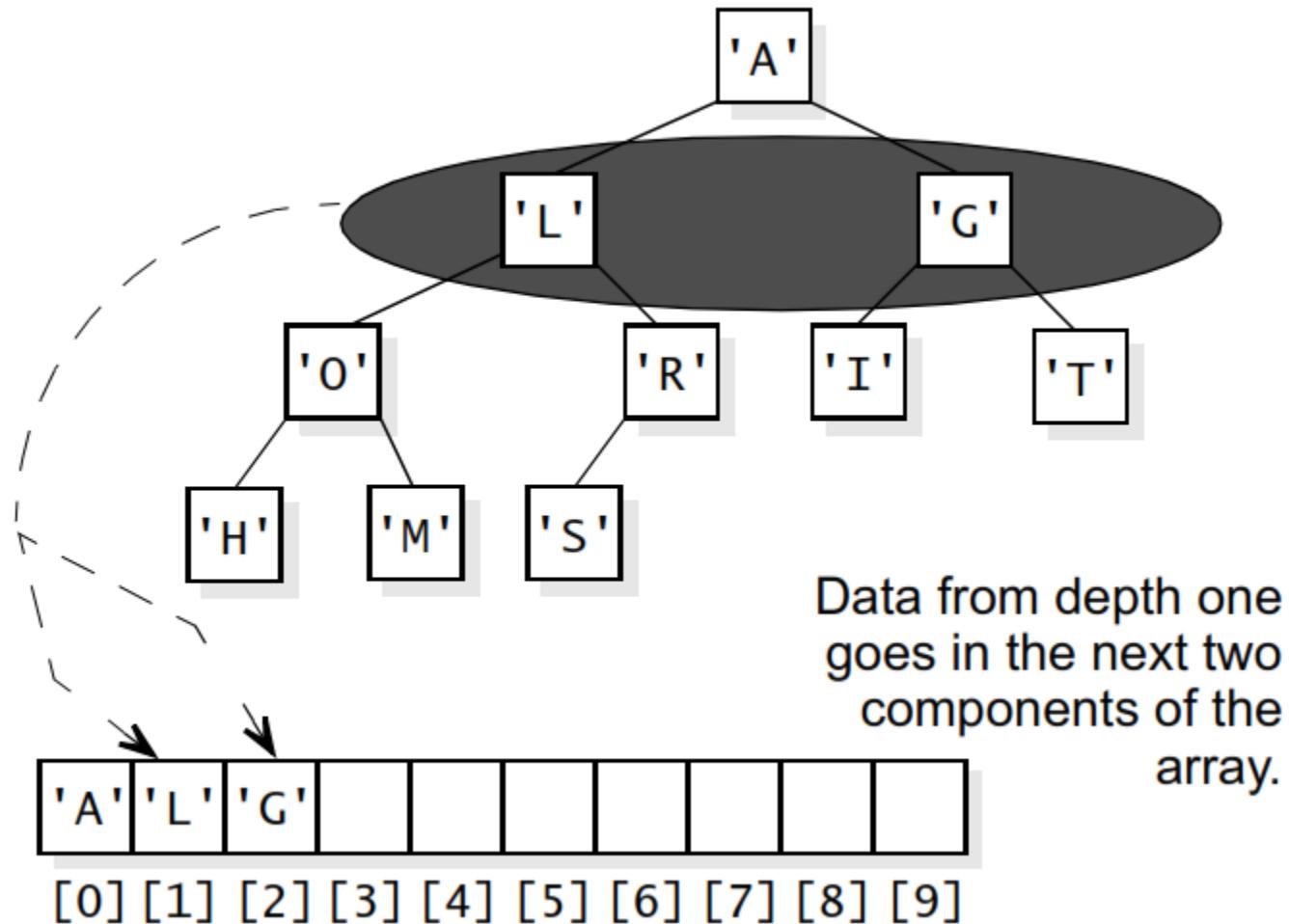
An array of data

We don't care what's in this part of the array.



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Array implementation of a Complete Binary Tree



Array implementation of a Complete Binary Tree

- ❖ Root is at [0]
- ❖ Parent of node in [i] is at $[(i-1)/2]$
- ❖ Children (if exist) of node [i] is at $[2i+1]$ and $[2i+2]$
- ❖ Total node number
 - $2^0+2^1+2^2+\dots+2^{d-1}+r, r \leq 2^d$, d is the depth

*In a complete binary tree with 10,000 nodes,
suppose that a node has its value stored in location 4999.*

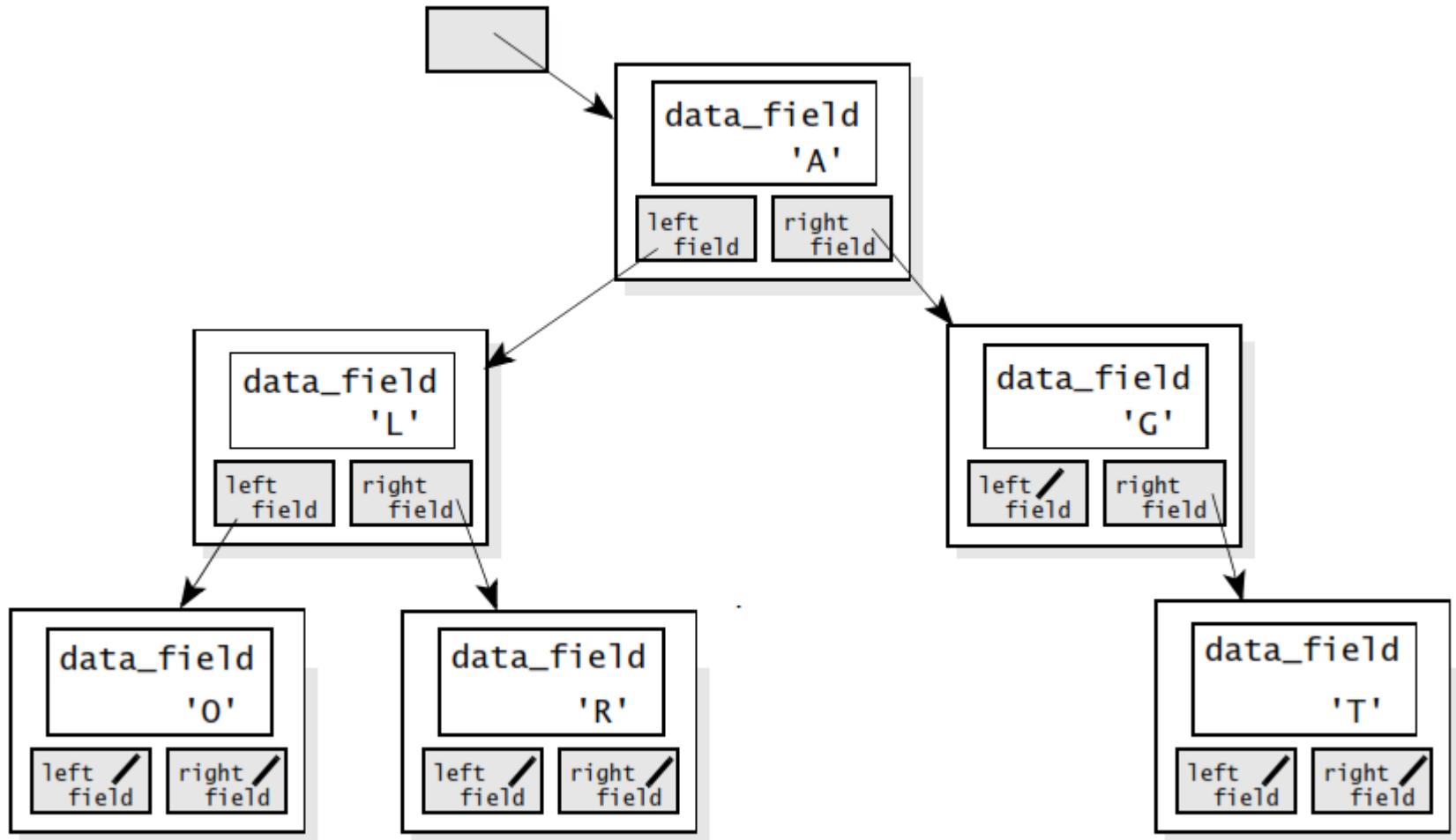
Where is the value stored for this node's parent?

Where are the values stored for its left child and right child?



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Binary Tree implementation with a Class for Nodes



Binary Tree Nodes

- ❖ Each node of a binary tree is stored in an object of a new *binary_tree_node* class
- ❖ Each node contains data as well as pointers to its children
- ❖ An entire tree is represented as a pointer to the root node



binary_tree_node Class

```
template <class Item>
class binary_tree_node
{
private:
    Item data_field;
    binary_tree_node *left_field;
    binary_tree_node *right_field;
```



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```
public:
```

```
// TYPEDEF
typedef Item value_type;

// CONSTRUCTOR
binary_tree_node(
    const Item& init_data = Item( ),
    binary_tree_node* init_left = NULL,
    binary_tree_node* init_right = NULL
)
{
    data_field = init_data;
    left_field = init_left;
    right_field = init_right;
}
```



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```
// MODIFICATION MEMBER FUNCTIONS
Item& data( ) { return data_field; }
binary_tree_node* left( ) { return left_field; }
binary_tree_node* right( ) { return right_field; }
void set_data(const Item& new_data) { data_field = new_data; }
void set_left(binary_tree_node* new_left) { left_field = new_left; }
void set_right(binary_tree_node* new_right)
                           { right_field = new_right; }

// CONST MEMBER FUNCTIONS
const Item& data( ) const { return data_field; }
const binary_tree_node* left( ) const { return left_field; }
const binary_tree_node* right( ) const { return right_field; }
bool is_leaf( ) const
{ return (left_field == NULL) && (right_field == NULL); }
```

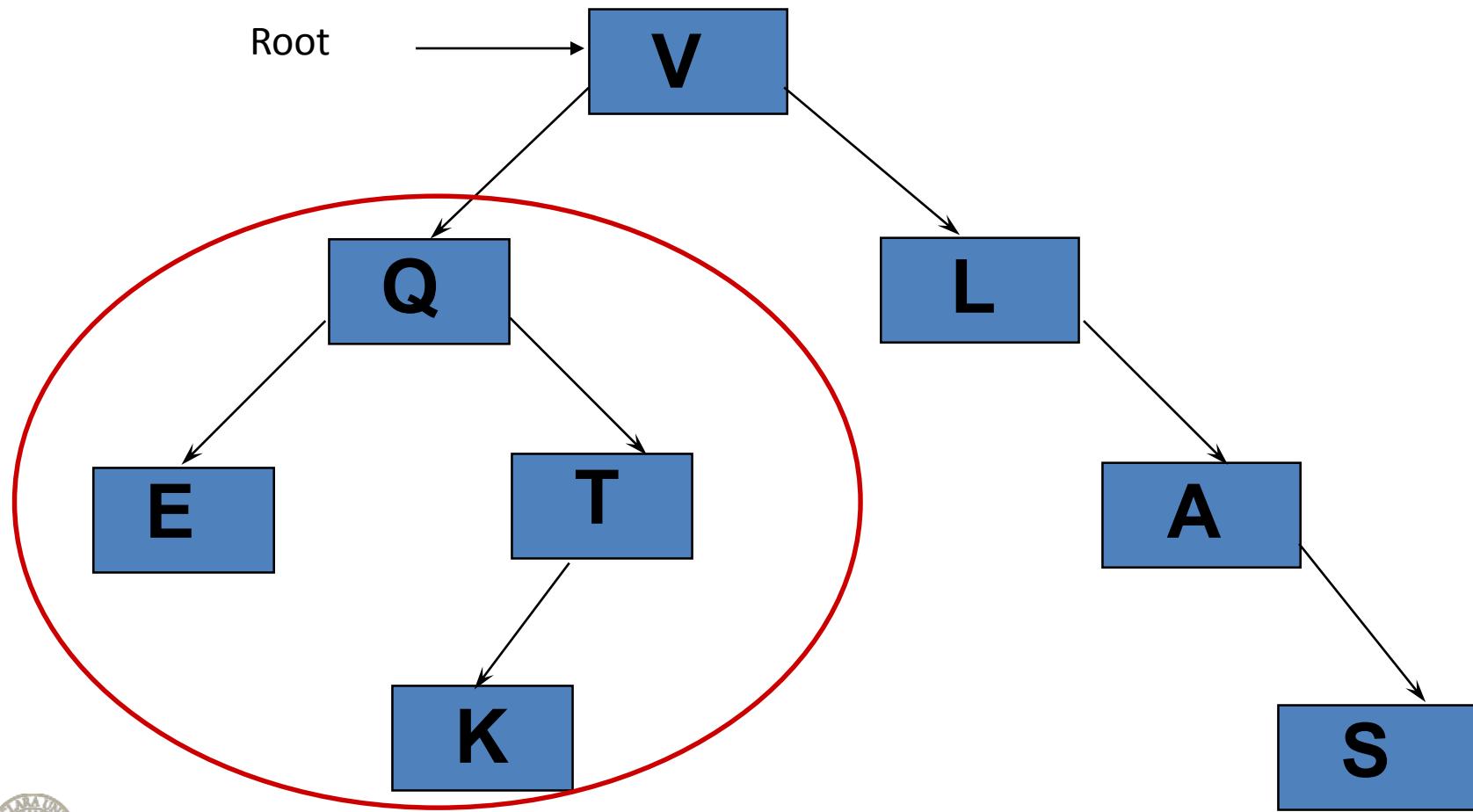


Creating and Manipulating Trees

- ❖ Consider two functions
 - Clearing a tree
 - ✓ Return nodes of a tree to the heap
 - Copying a tree
- ❖ The Implementation is easier than it seems
 - if we use recursive thinking



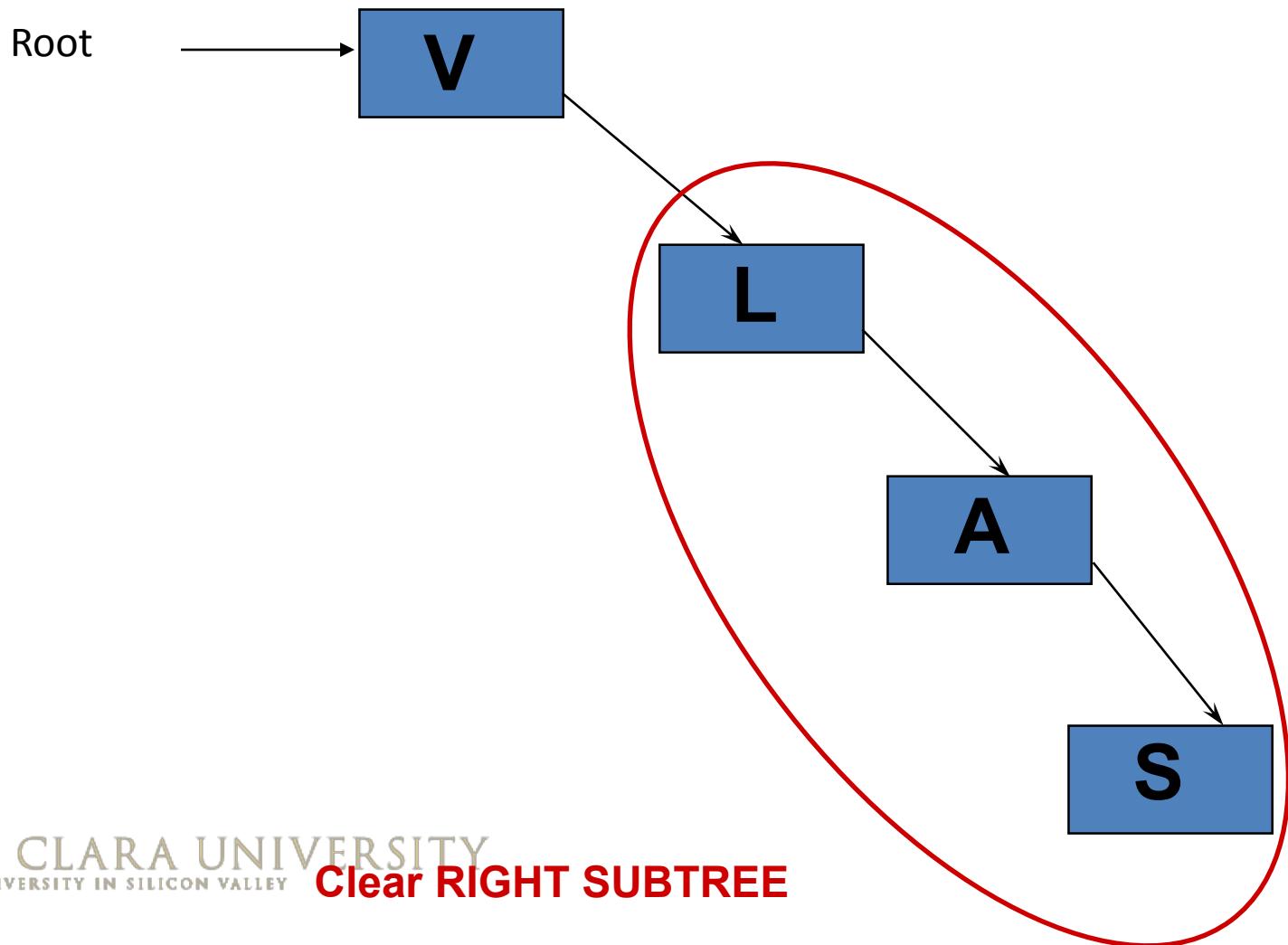
Clearing a Tree



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Clear LEFT SUBTREE

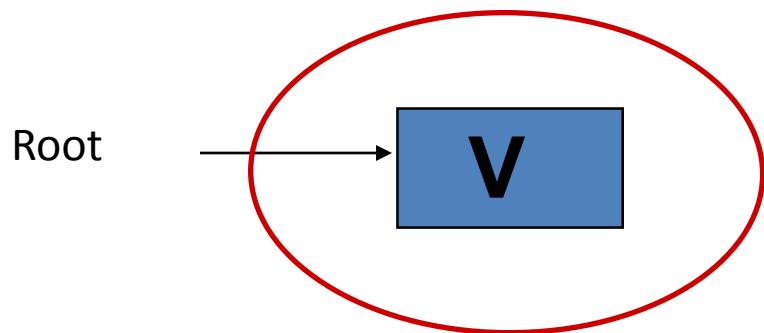
Clearing a Tree



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Clear **RIGHT SUBTREE**

Clearing a Tree

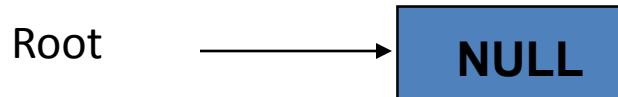


Return root node to the heap



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Clearing a Tree



Set the root pointer to NULL



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Clear a Tree

- ❖ key: recursive thinking

```
template <class Item>
void tree_clear(binary_tree_node<Item>*& root_ptr)
// Library facilities used: cstdlib
{
    if (root_ptr != NULL)
    {
        tree_clear( root_ptr->left( ) ); // clear left subtree
        tree_clear( root_ptr->right( ) ); // clear right subtree
        delete root_ptr; // return root node to the heap
        root_ptr = NULL; // set root pointer to the null
    }
}
```



Copy a Tree

```
template <class Item>
binary_tree_node<Item>* tree_copy
    (const binary_tree_node<Item>* root_ptr)
// Library facilities used: cstdlib
{
    binary_tree_node<Item> *l_ptr;
    binary_tree_node<Item> *r_ptr;

    if (root_ptr == NULL)
        return NULL;
    else
    {
        // copy the left sub_tree
        l_ptr = tree_copy( root_ptr->left( ) );
        // copy the right sub_tree
        r_ptr = tree_copy( root_ptr->right( ) );
        return new binary_tree_node<Item>
            (root_ptr->data( ), l_ptr, r_ptr);
    } // copy the root node and set the root pointer
}
```



Binary Tree Traversals

❖ pre-order traversal

- root (left sub_tree) (right sub_tree)

❖ in-order traversal

- (left sub_tree) root (right sub_tree)

❖ post-order traversal

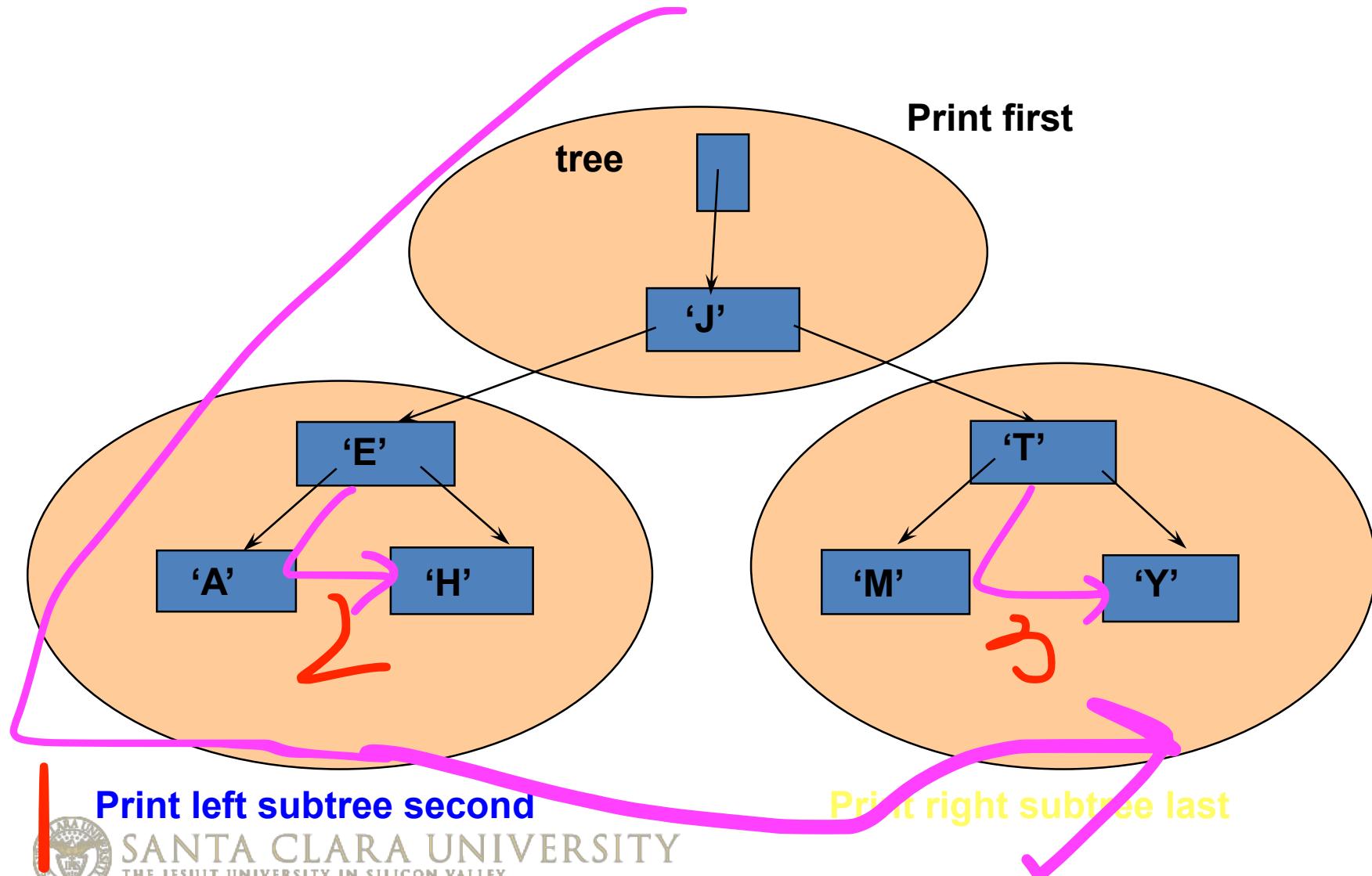
- (left sub_tree) (right sub_tree) root

❖ backward in-order traversal

- (right sub_tree) root (left sub_tree)



Preorder Traversal: J E A H T M Y



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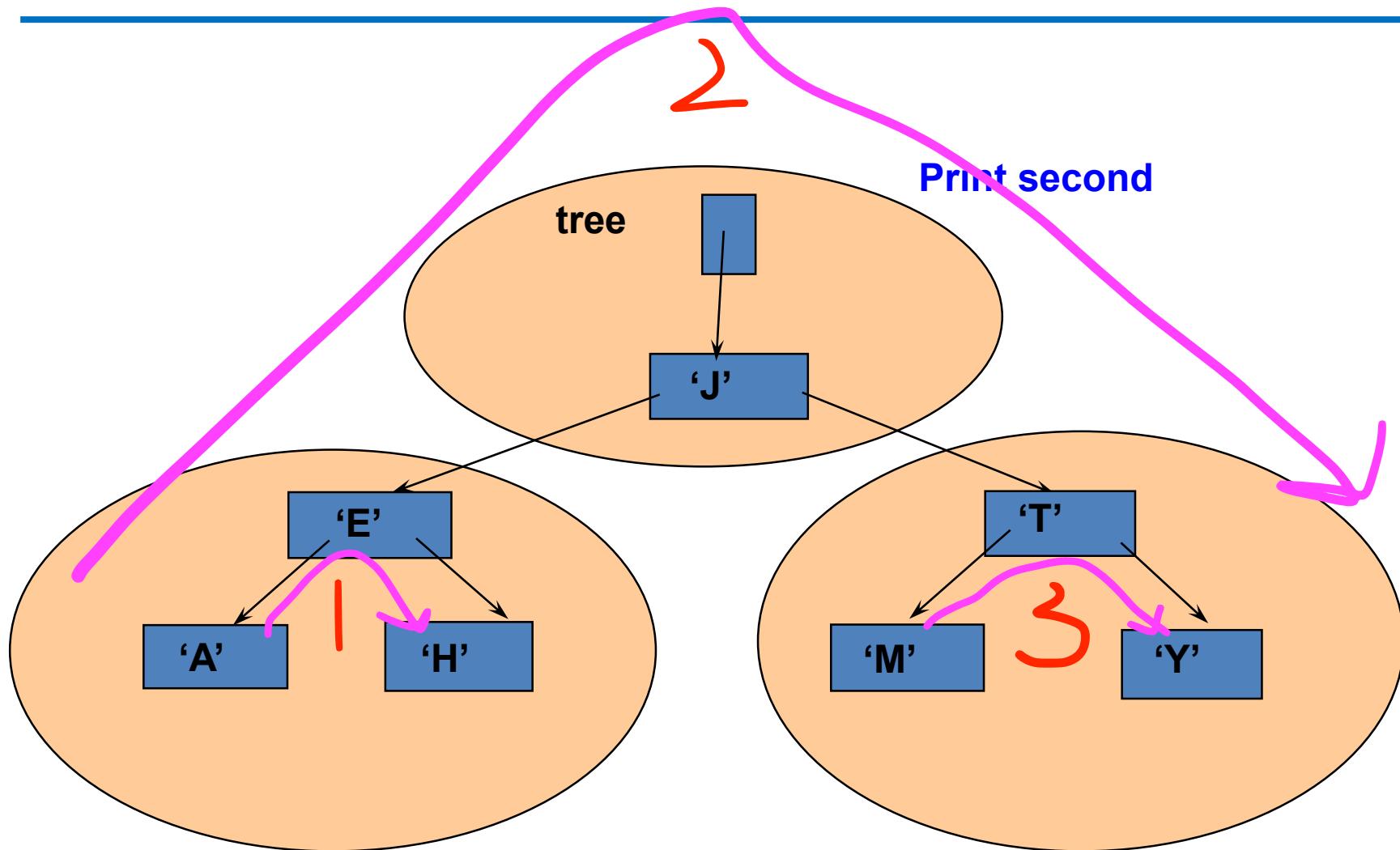
Preorder Traversal

- ❖ Example: print the contents of each node

```
template <class Item>
void preorder_print(const binary_tree_node<Item>* node_ptr)
// Library facilities used: cstdlib, iostream
{
    if (node_ptr != NULL)
    {
        std::cout << node_ptr->data( ) << std::endl;
        preorder_print(node_ptr->left( ));
        preorder_print(node_ptr->right( ));
    }
}
```



Inorder Traversal: A E H J M T Y



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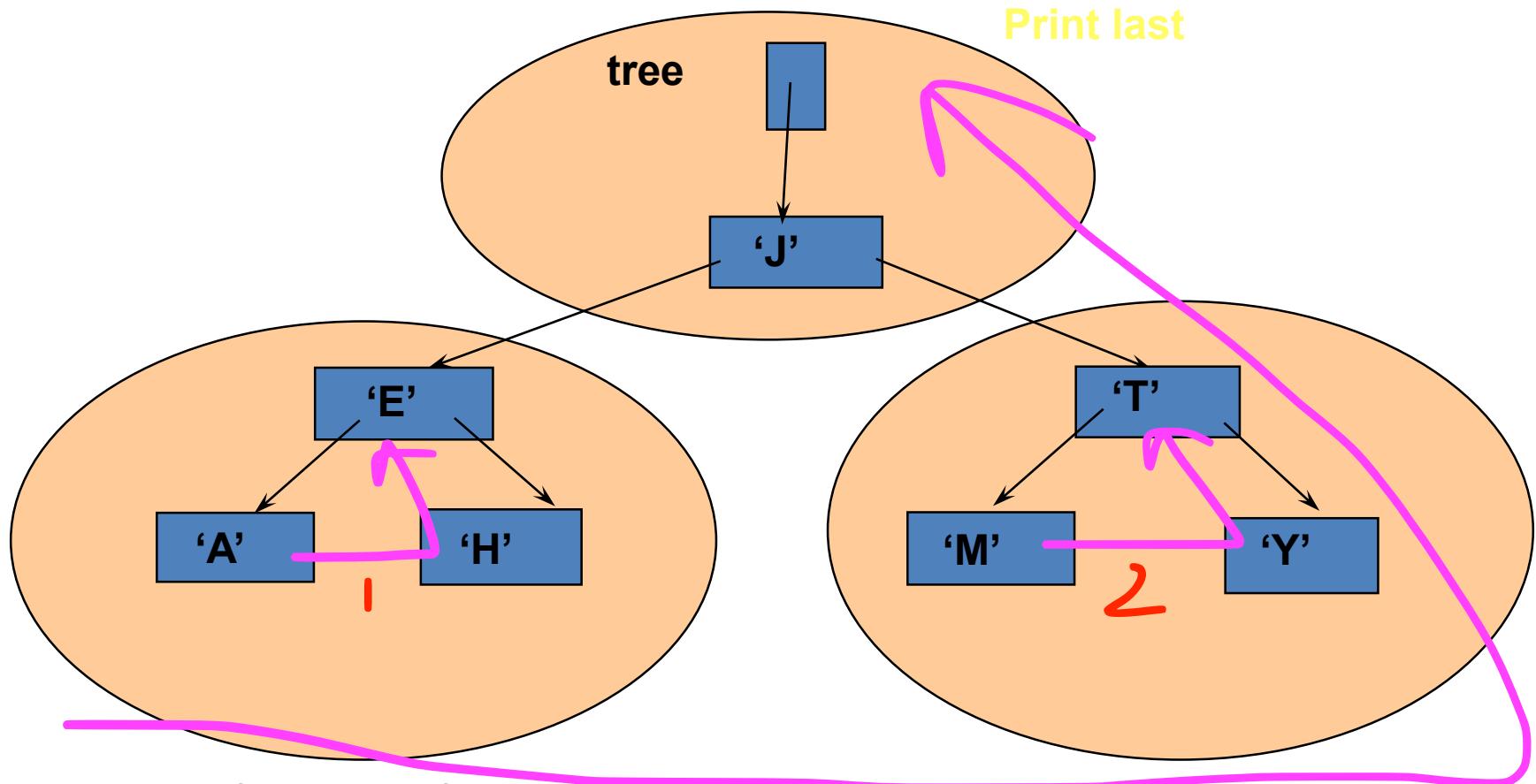
Inorder Traversal

- ❖ Example: print the contents of each node

```
template <class Item>
void inorder_print(const binary_tree_node<Item>* node_ptr)
// Library facilities used: cstdlib, iostream
{
    if (node_ptr != NULL)
    {
        inorder_print(node_ptr->left( ));
        std::cout << node_ptr->data( ) << std::endl;
        inorder_print(node_ptr->right( ));
    }
}
```



Postorder Traversal: A H E M Y T J



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3

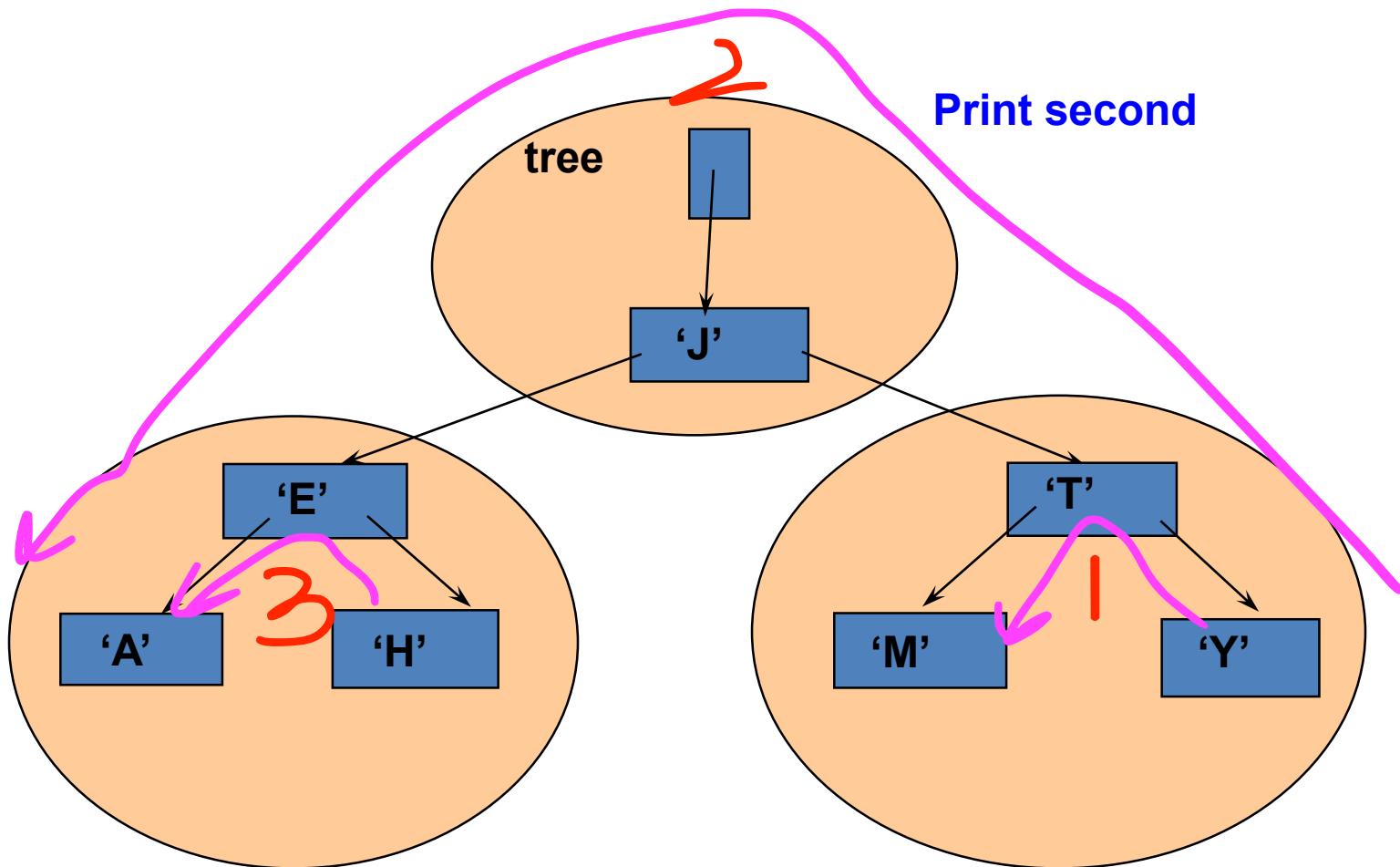
Postorder Traversal

- ❖ Example: print the contents of each node

```
template <class Item>
void postorder_print(const binary_tree_node<Item>* node_ptr)
// Library facilities used: cstdlib, iostream
{
    if (node_ptr != NULL)
    {
        postorder_print(node_ptr->left( ));
        postorder_print(node_ptr->right( ));
        std::cout << node_ptr->data( ) << std::endl;
    }
}
```



Backward Inorder Traversal: Y T M J H E A



A Useful Backward Inorder Traversal

- ❖ Indent each letter according its depth

```
template <class Item, class sizeType>
void print(binary_tree_node<Item>* node_ptr, sizeType depth)
// Library facilities used: iomanip, iostream, stdlib
{
    if (node_ptr != NULL)
    {
        print(node_ptr->right( ), depth+1);
        std::cout << std::setw(4*depth) << "";
        std::cout << node_ptr->data( ) << std::endl;
        print(node_ptr->left( ), depth+1);
    }
}
```



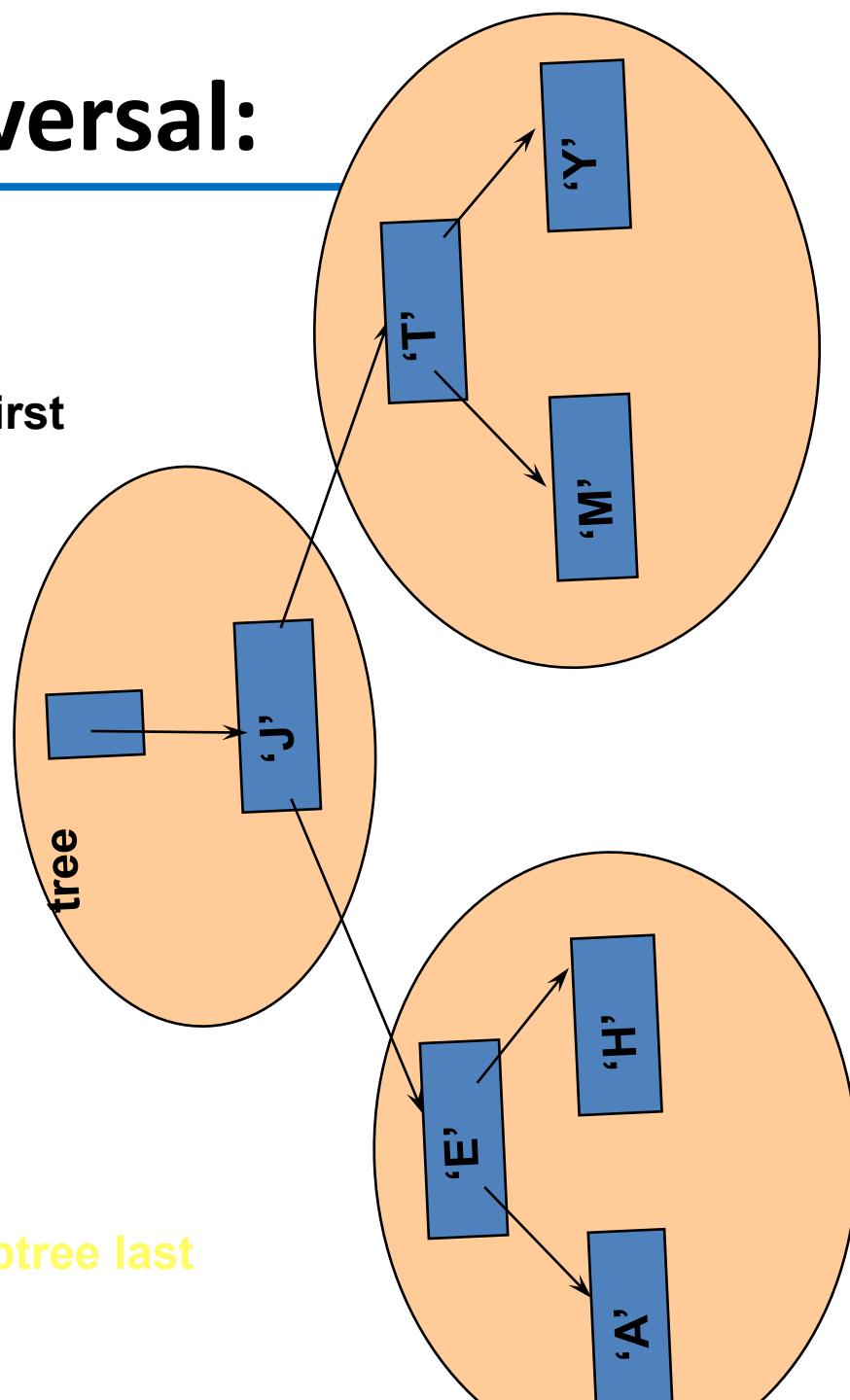
Backward Inorder Traversal:

Y T M J H E A

Print right subtree first

Print second

Print left subtree last



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A Challenging Question:

- ❖ For the traversals we have seen, the “processing” was simply printing the values of the node
- ❖ But we’d like to do any kind of processing
 - We can replace “cout” with some other form of “processing”
- ❖ But how about 1000 kinds of processing?
 - Can template be helpful?



A parameter can be a function

- ❖ write one function capable of doing anything
- ❖ A parameter to a function may be a function. Such a parameter is declared by
 - the name of the function's return type (or void),
 - then the name of the parameter (i.e. the function),
 - and finally a pair of parentheses ().
 - Inside () is a list of parameter types of that parameter function
- ❖ Example
 - `int sum (void f (int&, double), int i,...);`



Preorder Traversal – print only

- ❖ Example: print the contents of each node

```
template <class Item>
void preorder_print(const binary_tree_node<Item>* node_ptr)
// Library facilities used: cstdlib, iostream
{
    if (node_ptr != NULL)
    {
        std::cout << node_ptr->data() << std::endl;
        preorder_print(node_ptr->left());
        preorder_print(node_ptr->right());
    }
}
```



Preorder Traversal – general form

- ❖ A template function for tree traversals

```
template <class Item>
void preorder(void f(Item&), binary_tree_node<Item>* node_ptr)
// Library facilities used: cstdlib
{
    if (node_ptr != NULL)
    {
        // node_ptr->data() return reference !
        f( node_ptr->data( ) );
        preorder(f, node_ptr->left( ) );
        preorder(f, node_ptr->right( ) );
    }
}
```



Preorder Traversal – how to use

- ❖ Define a real function before calling

```
void printout(int & it)
    // Library facilities used: iostream
{
    std::cout << it << std::endl;
}
```

- Can you print out all the node of a tree pointed by root ?

```
binary_tree_node<int> *root;
....
preorder(printout, root);
```



Preorder Traversal – another functions

- ❖ Can define other functions...

```
void assign_default(int& it)
    // Library facilities used: iostream
{
    it = 0;
}
```

- You can assign a default value to all the node of a tree pointed by root:

```
binary_tree_node<int> *root;
....
preorder(assign_default, root);
```



Preorder Traversal – a more general form

- ❖ An extremely general implementation

```
template <class Process, class BTNode>
void preorder(Process f, BTNode* node_ptr)
// Note: BTNode may be a binary_tree_node or a const
// binary tree node.
// Process is the type of a function f that may be
// called with a single Item argument (using the Item
// type from the node), as determined by the actual f
// in the following.
// Library facilities used: cstdlib
{
    if (node_ptr != NULL)
    {
        f( node_ptr->data( ) );
        preorder(f, node_ptr->left( ) );
        preorder(f, node_ptr->right( ) );
    }
}
```



Functions as Parameters

- ❖ We can define a template function X with functions as parameters – which are called *function parameters*
- ❖ A function parameter can be simply written as $\text{Process } f$ (where Process is a template), and the forms and number of parameters for f are determined by the actual call of f inside the template function X
- ❖ The function argument for f when calling the template function X cannot be a template function, it must be instantiated in advance or right in the function call



Summary

- ❖ Tree, Binary Tree, Complete Binary Tree
 - child, parent, sibling, root, leaf, ancestor,...
- ❖ Array Representation for Complete Binary Tree
 - Difficult if not complete binary tree
- ❖ A Class of `binary_tree_node`
 - each node with two link fields
- ❖ Tree Traversals
 - recursive thinking makes things much easier
- ❖ A general Tree Traversal
 - A Function as a parameter of another function



BINARY SEARCH TREES

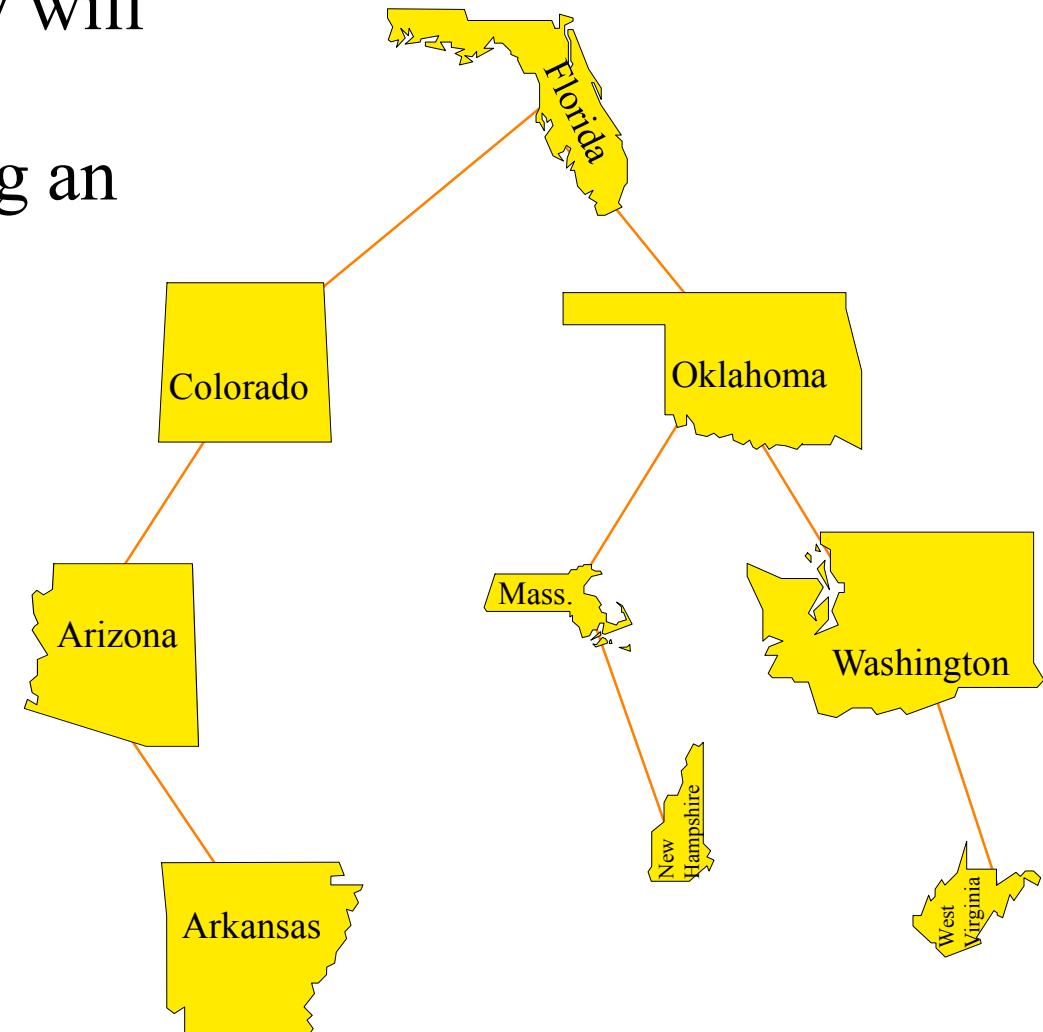
Binary Search Tree Definition

- ❖ In a binary search tree, the entries of the nodes can be compared with a strict weak ordering. Two rules are followed for every node n :
 - The entry in node n is NEVER less than an entry in its left subtree
 - The entry in the node n is less than every entry in its right subtree.



A Binary Search Tree of States

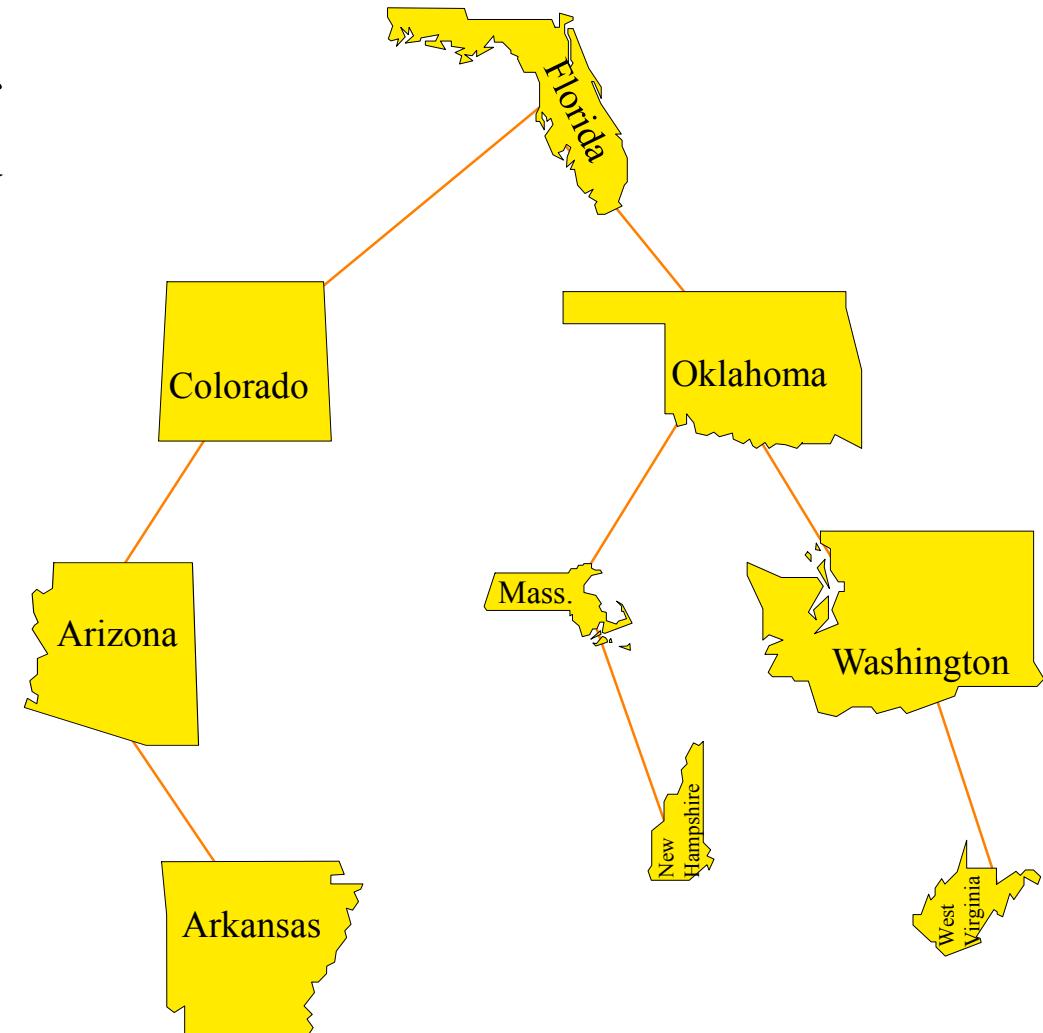
The data in the dictionary will be stored in a binary tree, with each node containing an item and a key.



A Binary Search Tree of States

❖ Storage rules:

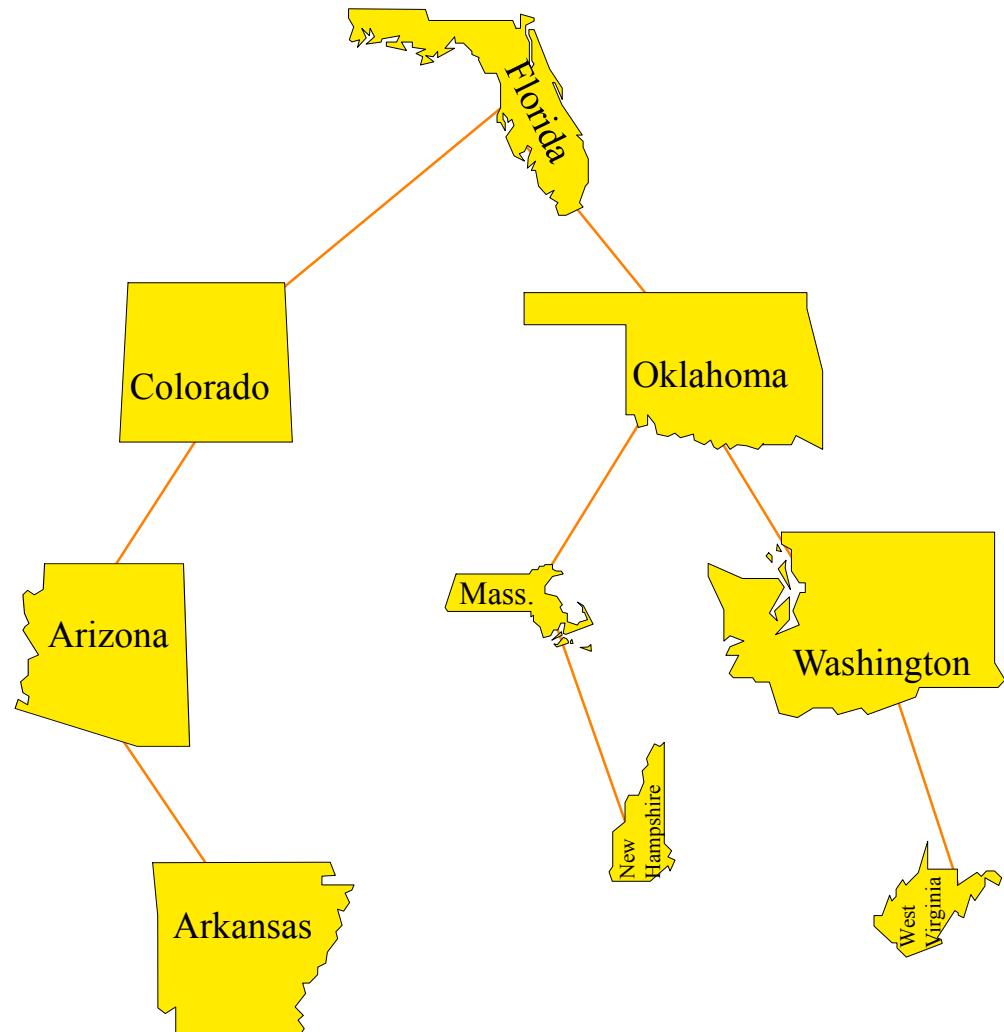
- Every key to the left of a node is alphabetically before the key of the node.
- Every key to the right of a node is alphabetically after the key of the node.



Retrieving Data

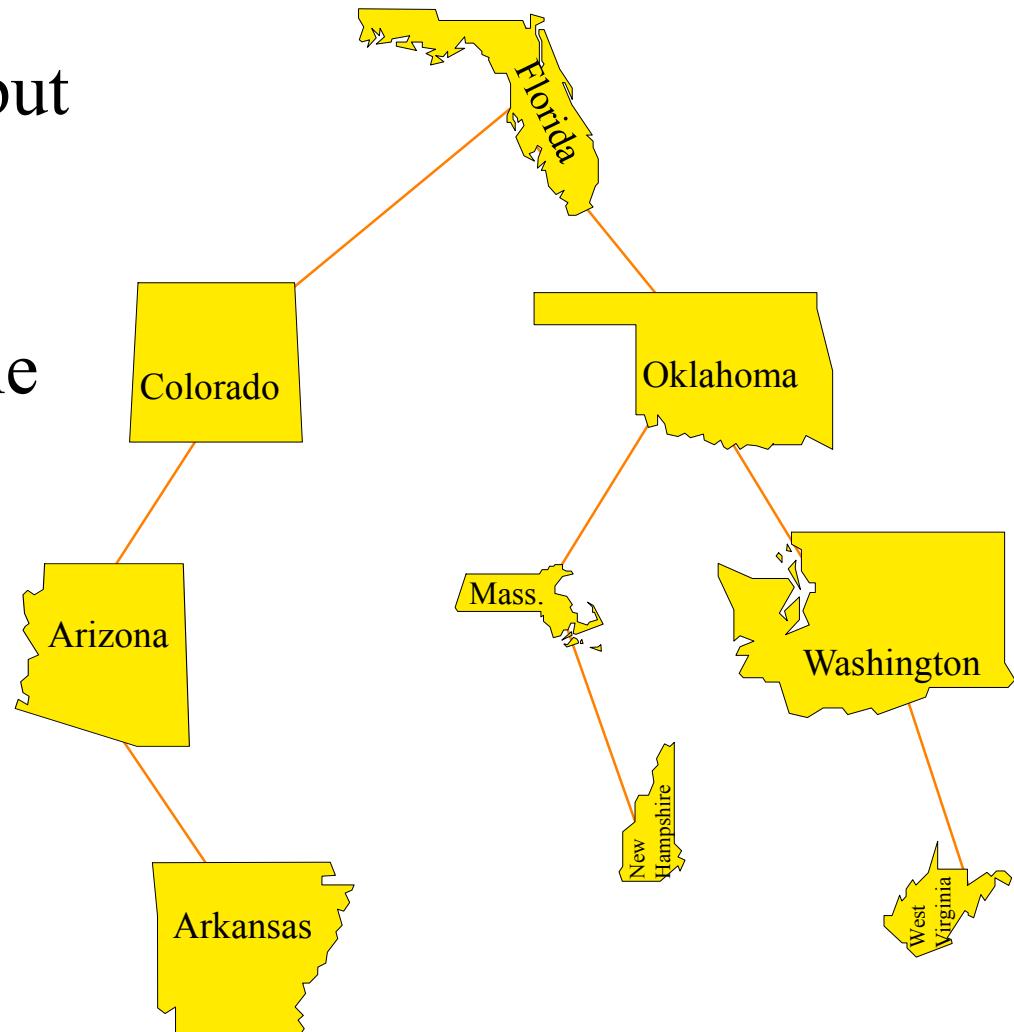
Start at the root.

- If the current node has the key, then stop and retrieve the data.
- If the current node's key is too **large**, move **left**.
- If the current node's key is too **small**, move **right**.



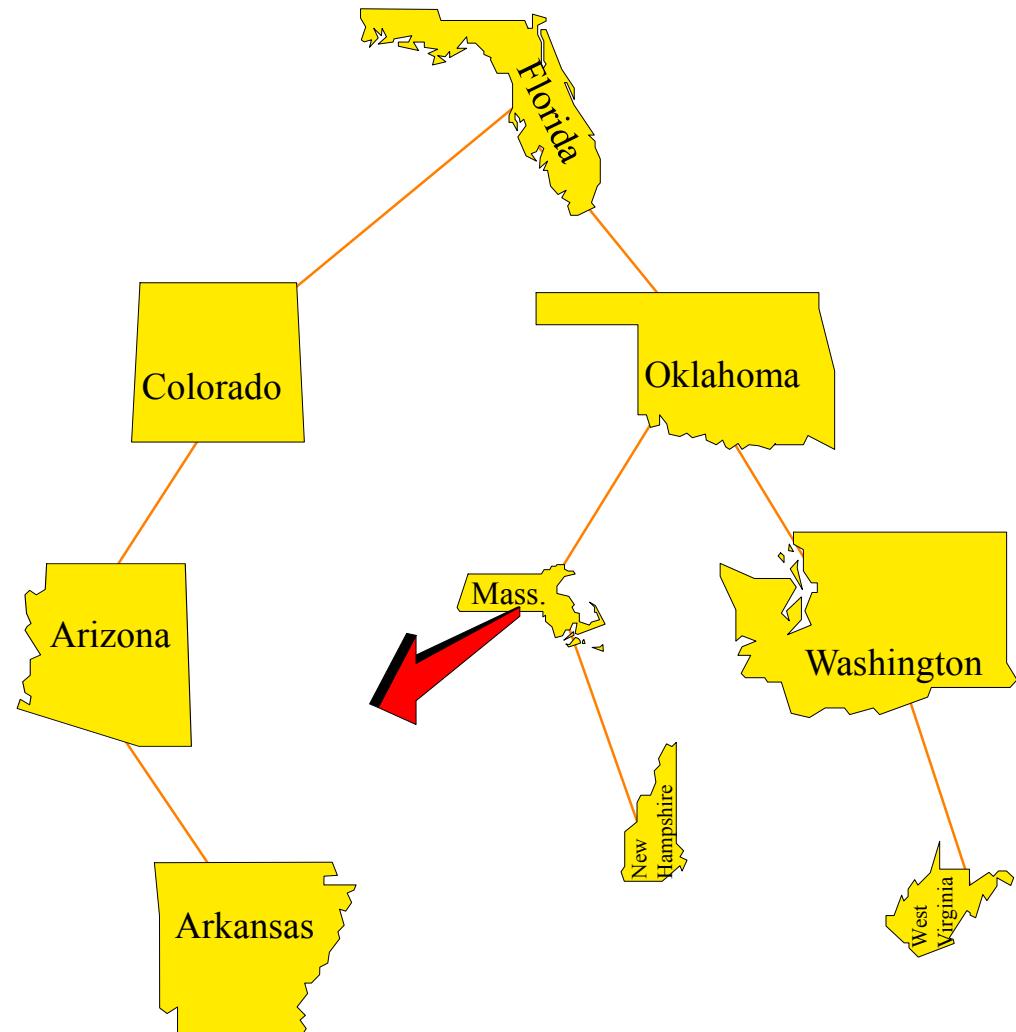
Adding a New Item with a Given Key

- ❑ Pretend that you are trying to find the key, but stop when there is no node to move to.
- ❑ Add the new node at the spot where you would have moved to if there had been a node.



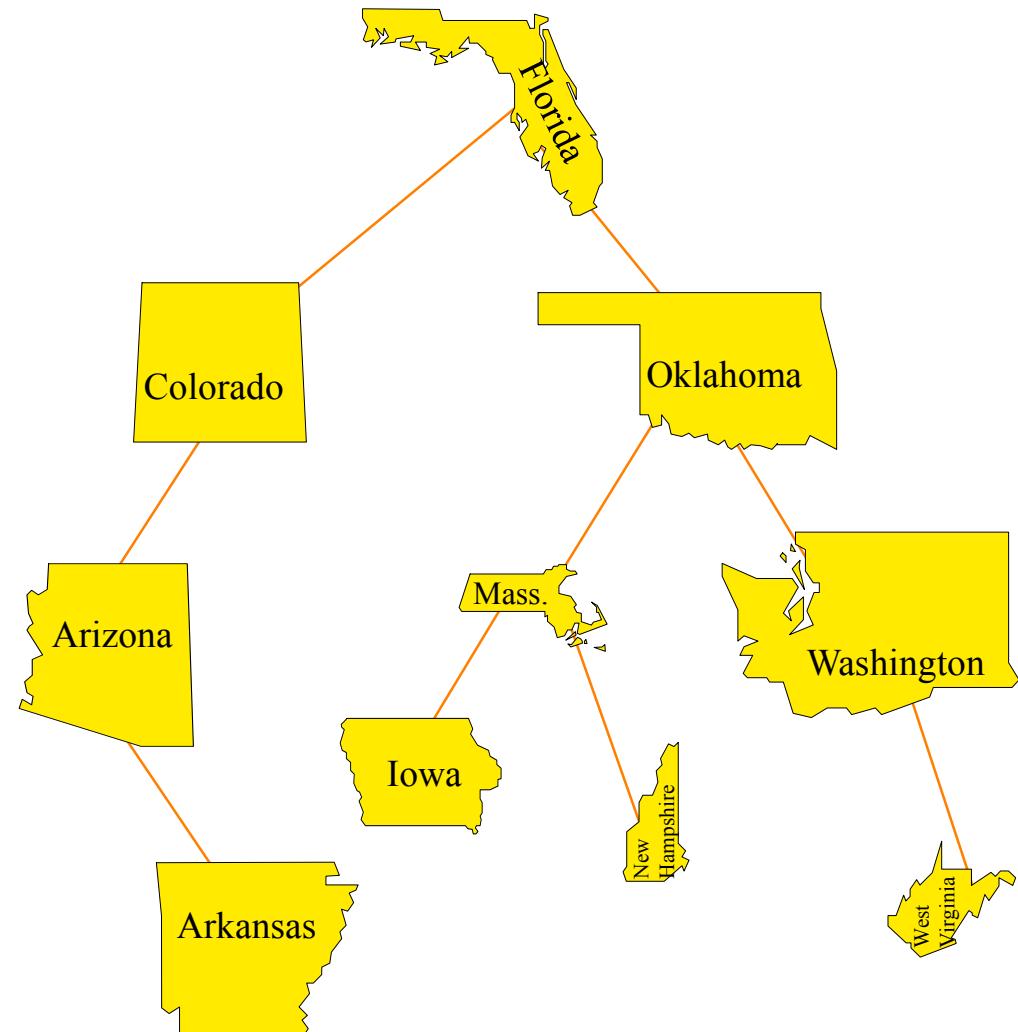
Adding

- Pretend that you are trying to find the key, but stop when there is no node to move to.
- Add the new node at the spot where you would have moved to if there had been a node.



Adding

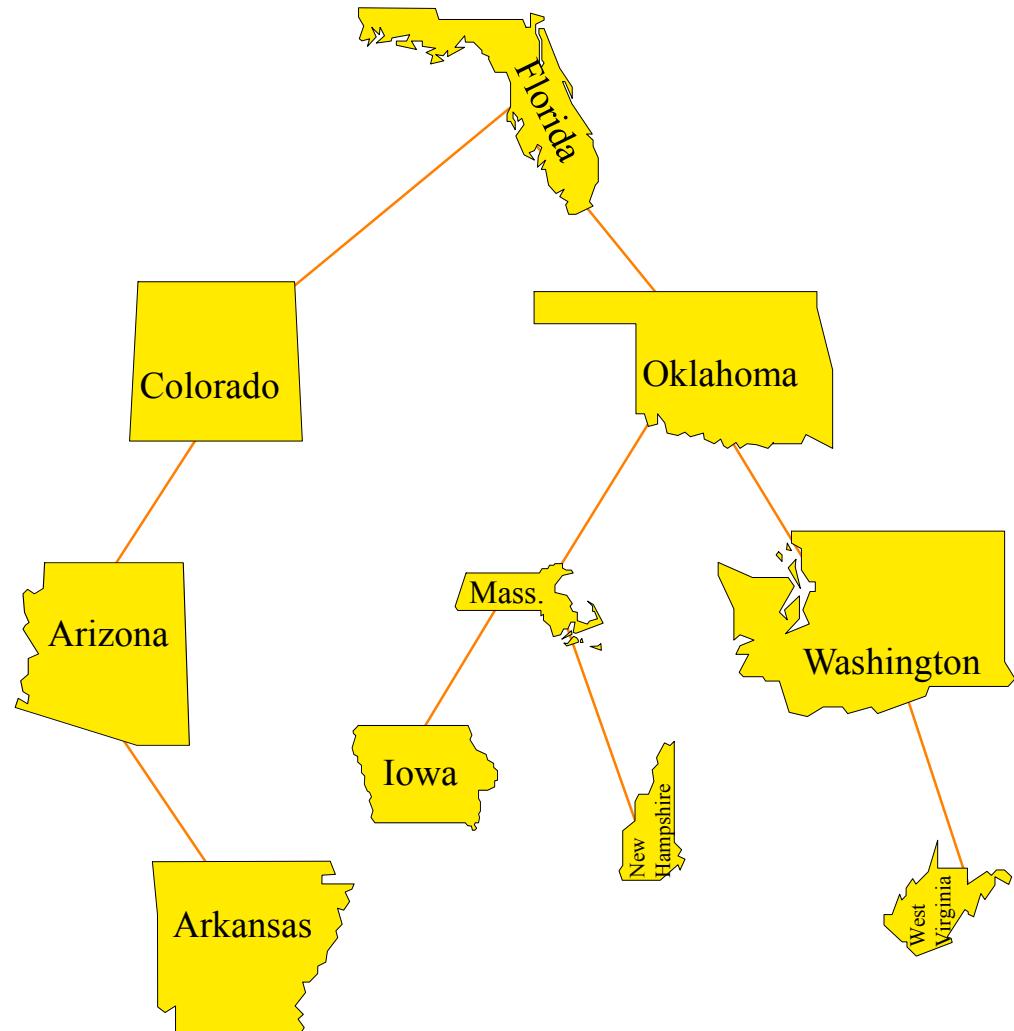
- Pretend that you are trying to find the key, but stop when there is no node to move to.
- Add the new node at the spot where you would have moved to if there had been a node.



Adding



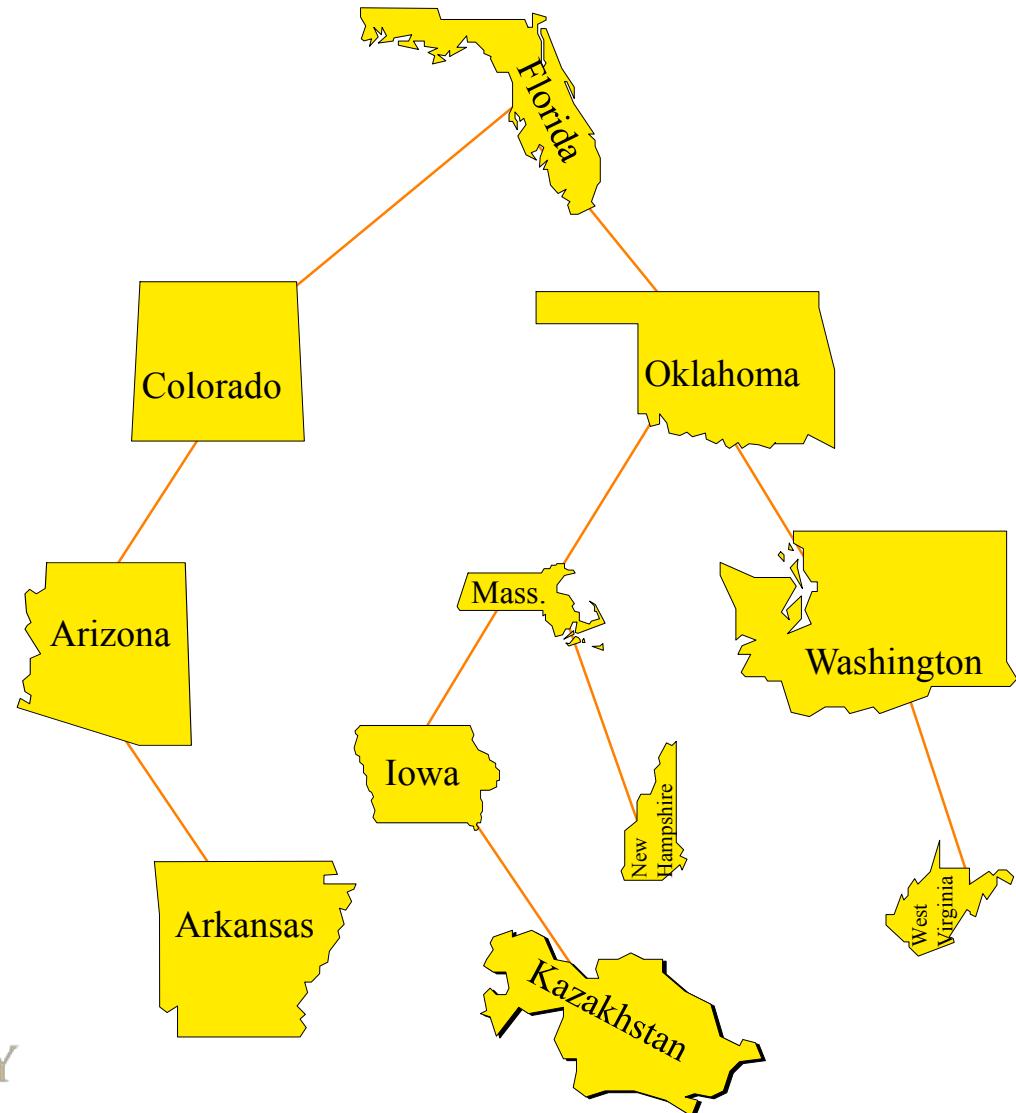
*Where would you
add this state?*



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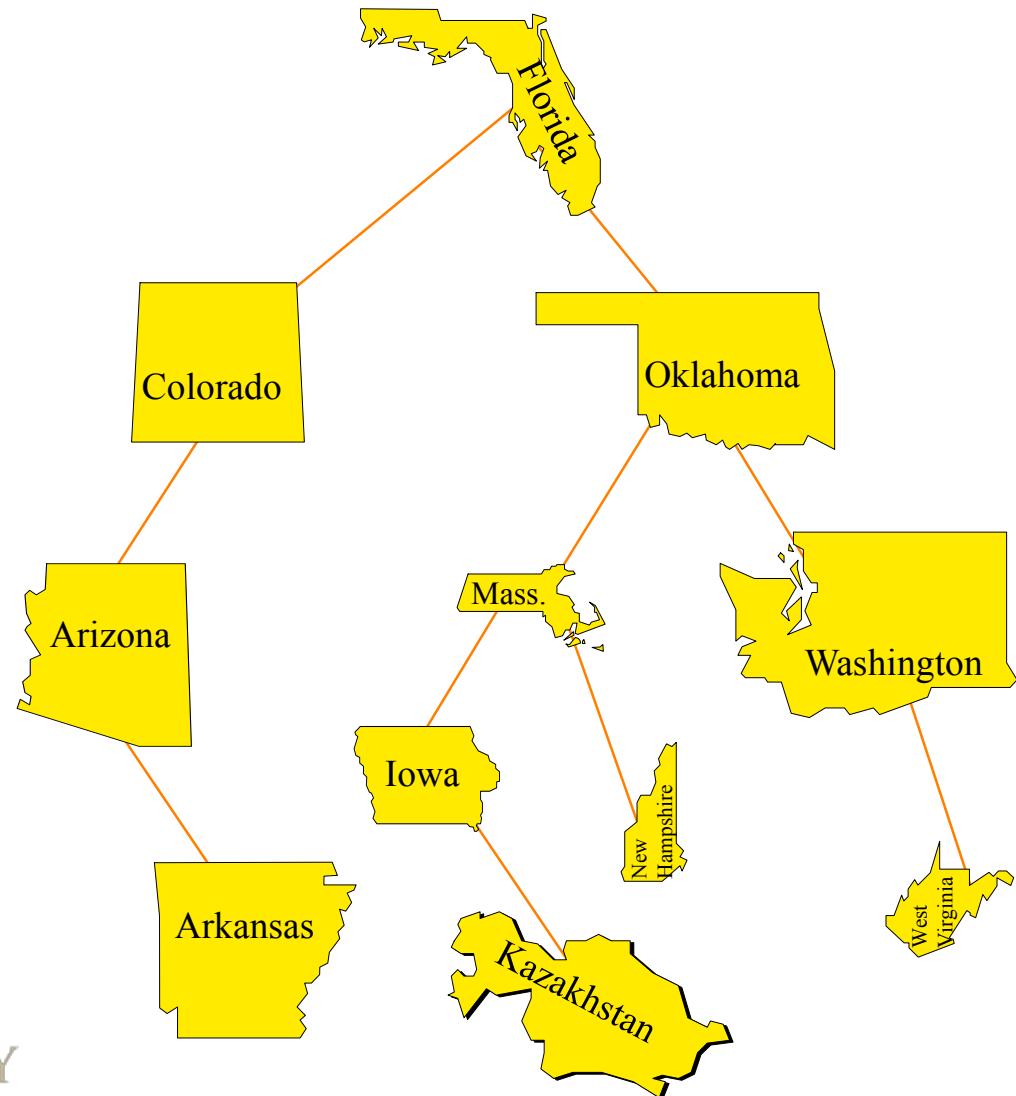
Adding

Kazakhstan is the
new right child
of Iowa?



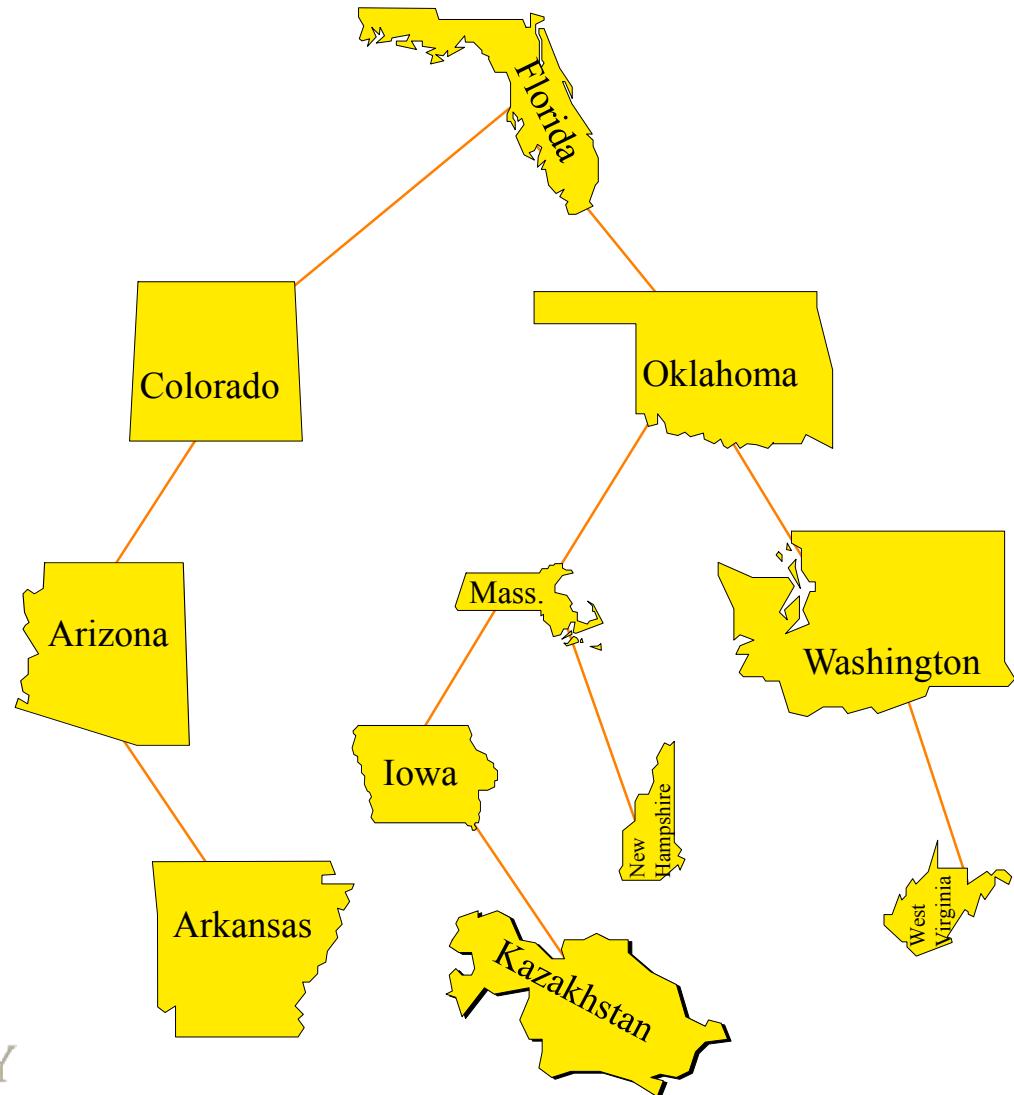
Removing an Item with a Given Key

- ❑ Find the item.
- ❑ If necessary, swap the item with one that is easier to remove.
- ❑ Remove the item.



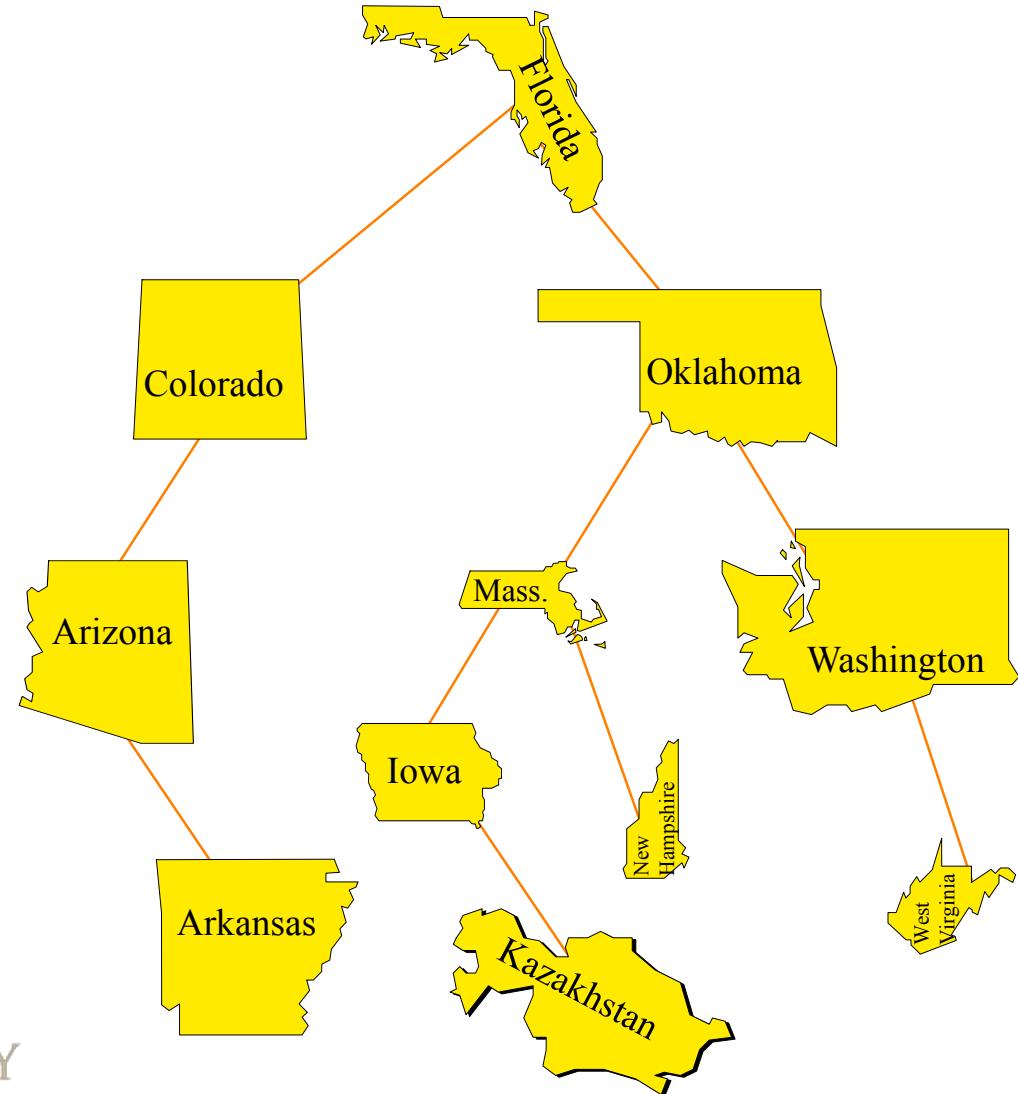
Removing "Florida"

- Find the item.



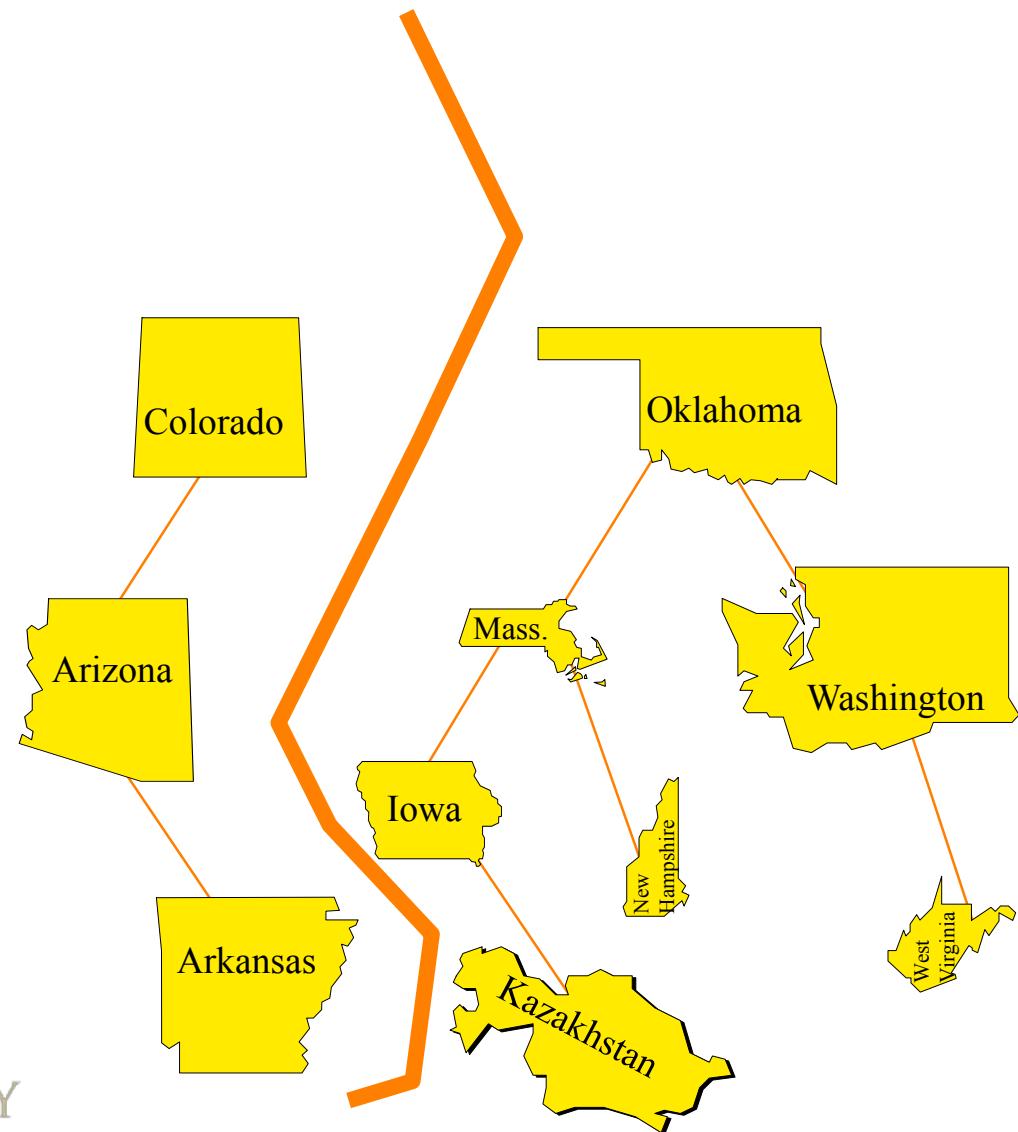
Removing "Florida"

Florida cannot be removed at the moment...



Removing "Florida"

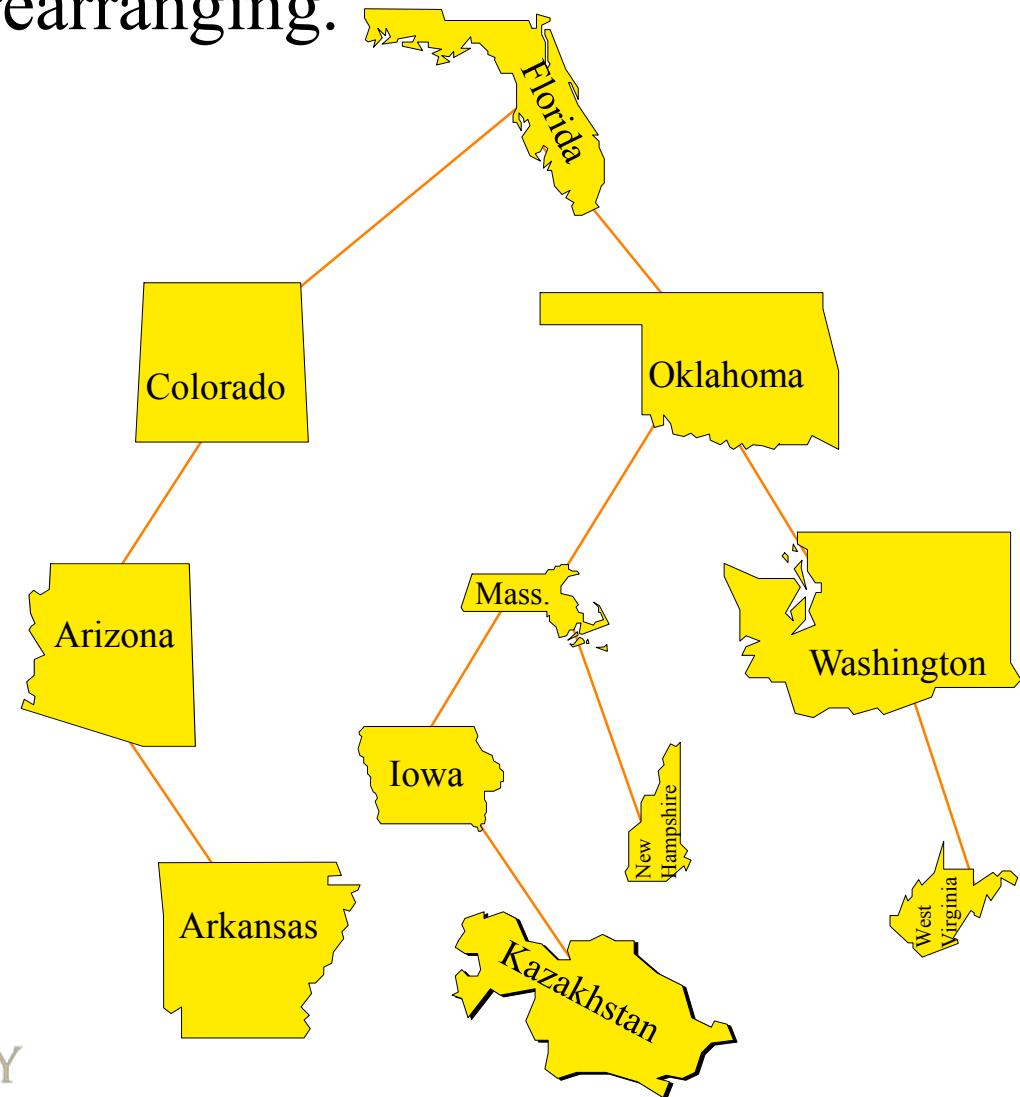
... because removing Florida would break the tree into two pieces.



Removing "Florida"

- If necessary, do some rearranging.

The problem of breaking the tree happens because Florida has 2 children.



Removing "Florida"

- If necessary, do some rearranging.

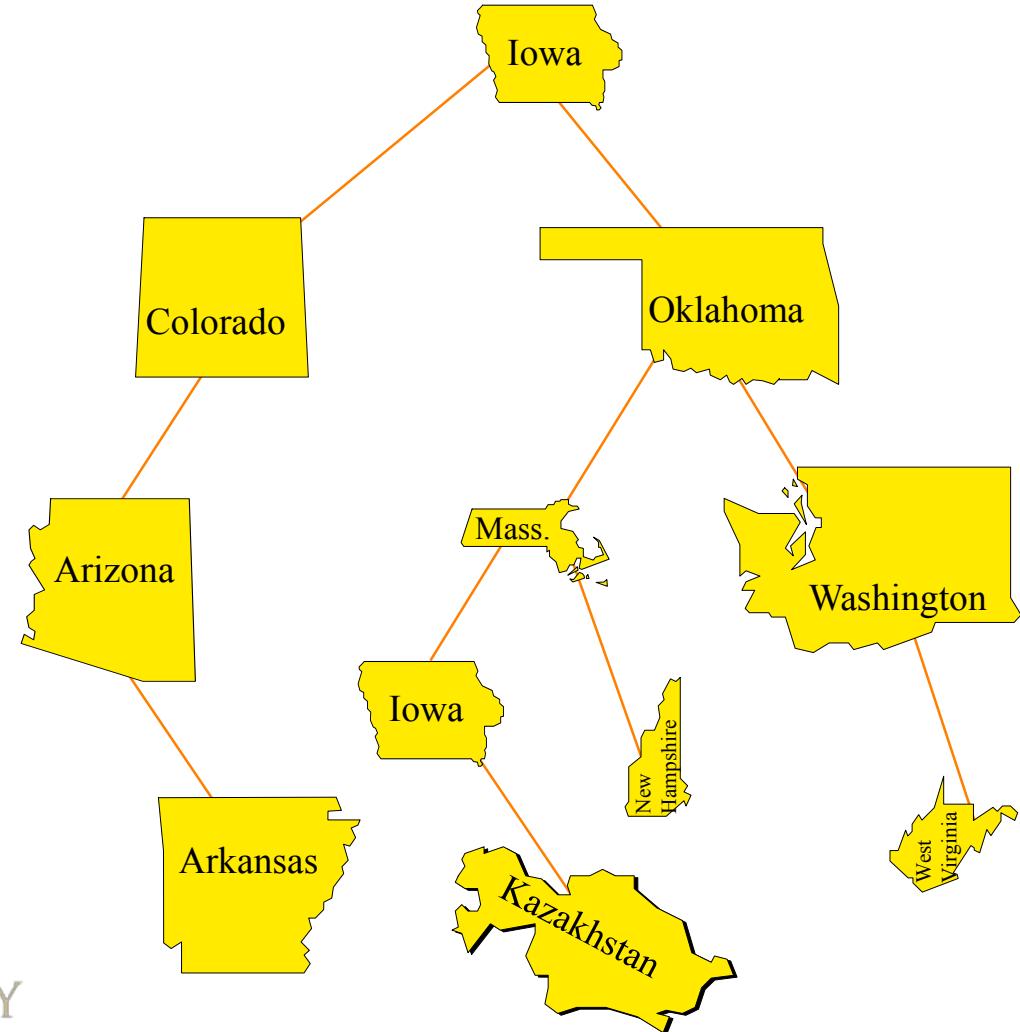
For the rearranging,
take the smallest item
in the right subtree...



Removing "Florida"

- If necessary, do some rearranging.

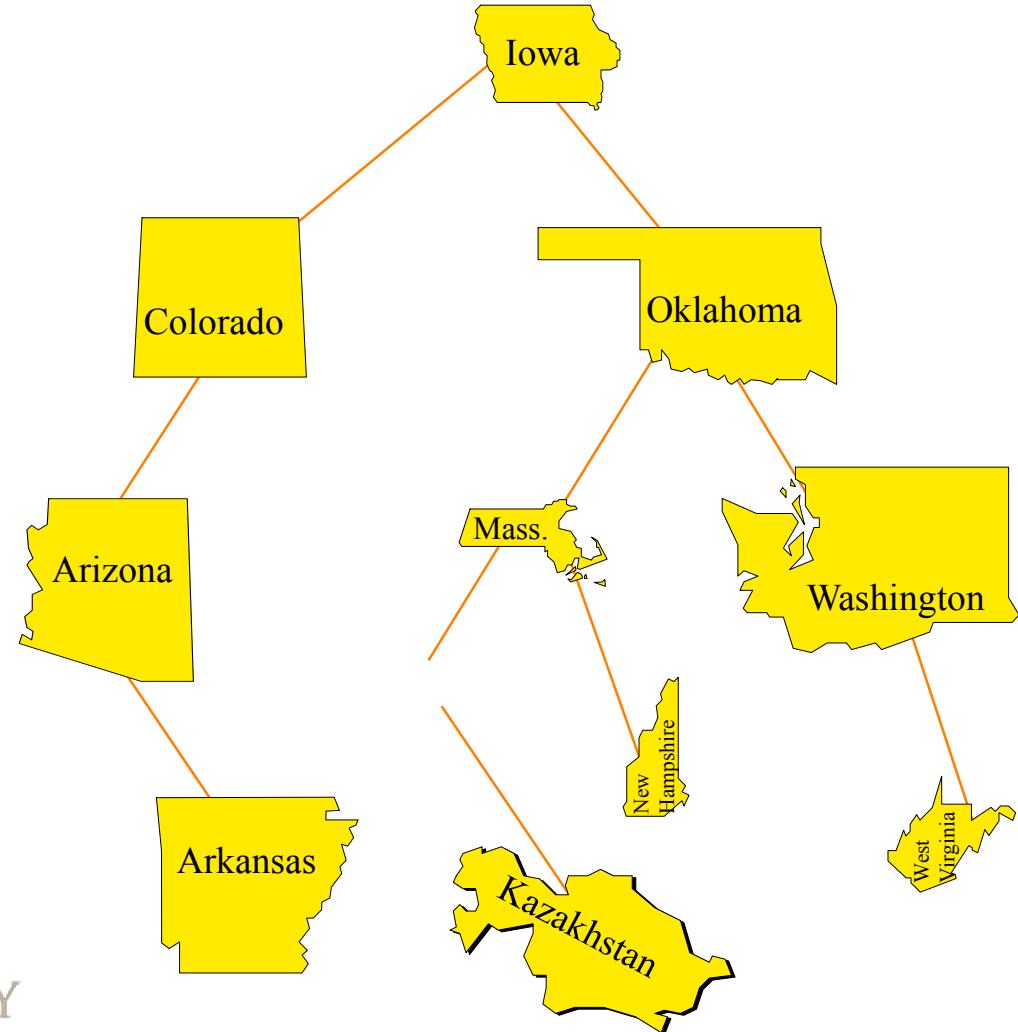
...copy that smallest item onto the item that we're removing...



Removing "Florida"

- If necessary, do some rearranging.

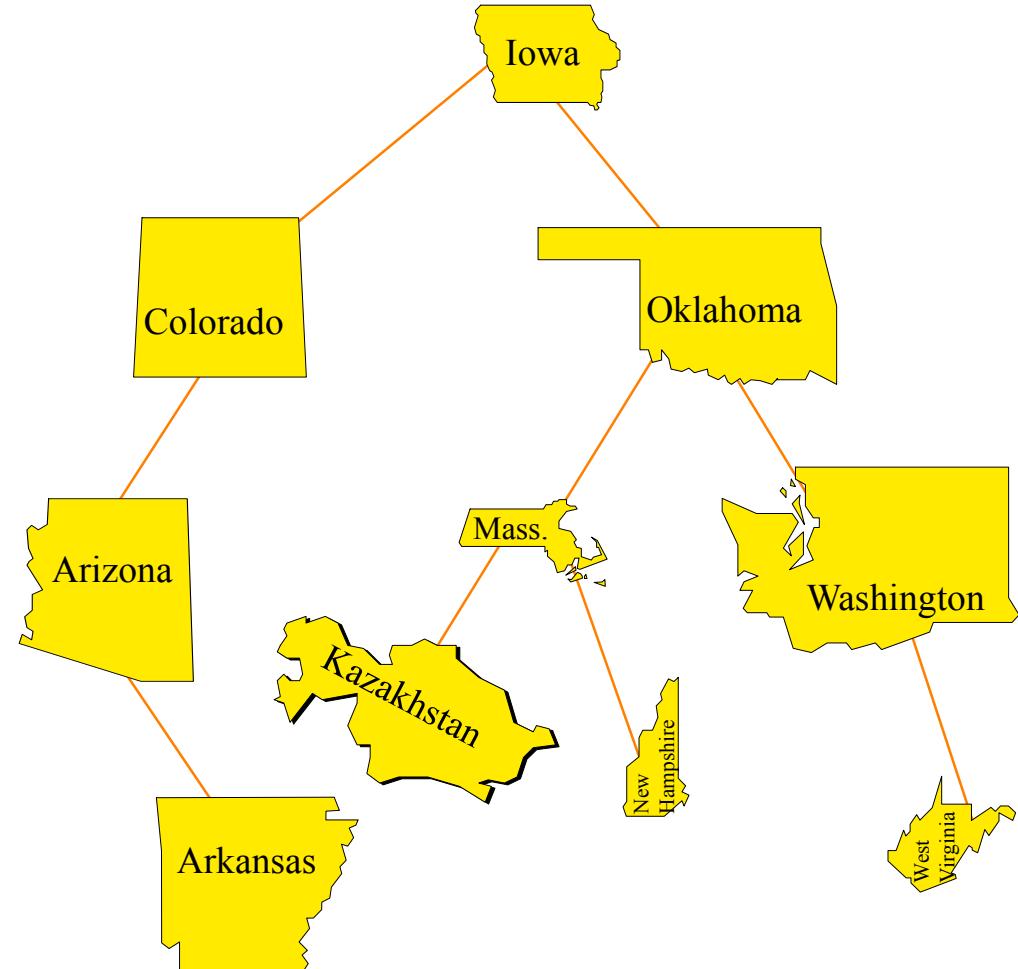
... and then remove
the extra copy of the
item we copied...



Removing "Florida"

- If necessary, do some rearranging.

... and reconnect
the tree



Removing an Item with a Given Key

- Find the item.
 - If the item has a right child, rearrange the tree:
 - Find smallest item in the right subtree
 - Copy that smallest item onto the one that you want to remove
 - Remove the extra copy of the smallest item (making sure that you keep the tree connected)
- else just remove the item.



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