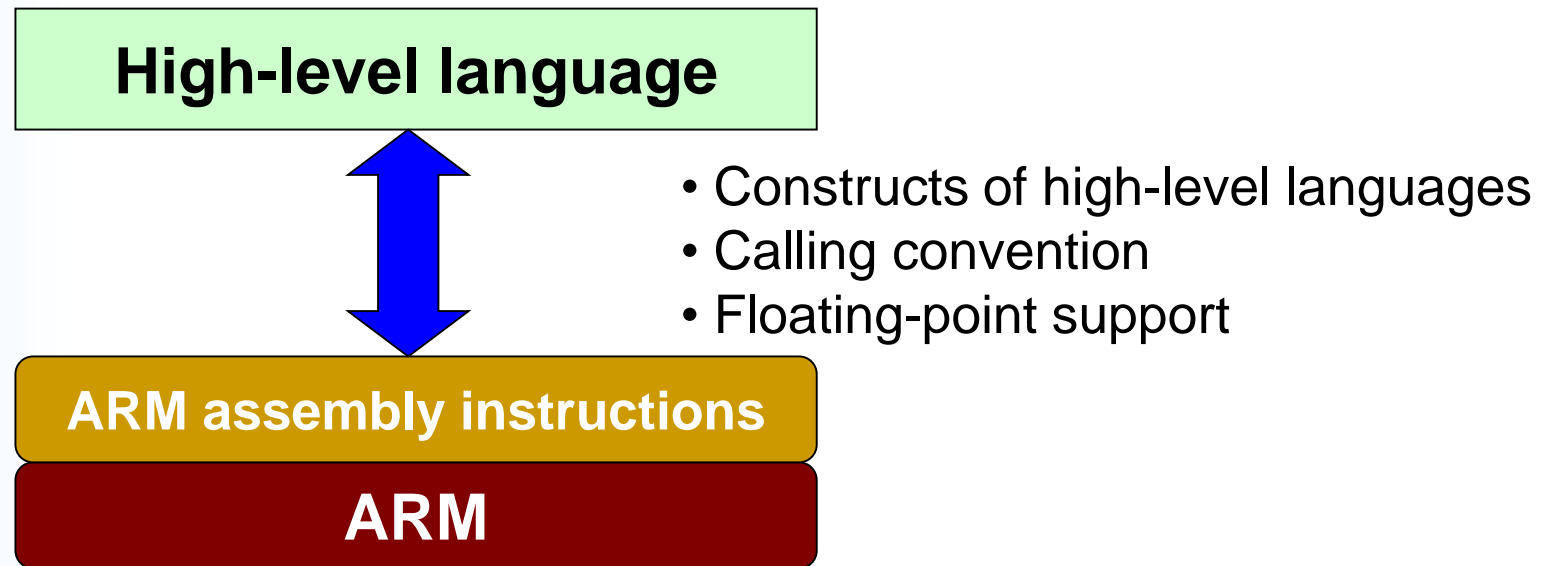


# Architectural Support for High-Level Language

Peng-Sheng Chen  
Fall, 2017

# Introduction

- Look at the requirements that a high-level language imposes on an architecture
- See how those requirements may be met



# Outline

- Abstraction in software design
- Data types
- Floating-point data types
- Expressions
- Conditional statements
- Loops
- Functions and procedures
- Use of Memory
- Run-time environment

# Outline

- **Abstraction in software design**
- Data types
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# Abstraction in Software Design

- **Determine the higher levels of abstraction**
  - Simplify the program design
  - High-level language
- **Assembly-level abstraction**
  - Work directly with the raw machine instructions
  - Express the program by instructions, addresses, registers, ...

# Outline

- Abstraction in software design
- **Data types**
- Floating-point data types
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# Data Types (1)

- Numbers
- Roman numerals
- Decimal numbers
- BCD (binary coded decimal)
- Binary notation
- Hexadecimal notation
- Number ranges
- Signed integers
- Other number sizes
- Real numbers
- Printable characters

# Data Types (2)

- ASCII
- **ARM support for character**
  - Unsigned byte load / store instructions
- Byte ordering
  - Character encode

1	9	9	5
---	---	---	---

- Read / Store a 32-bit word
- little- or big-endian



# Data Types (3)

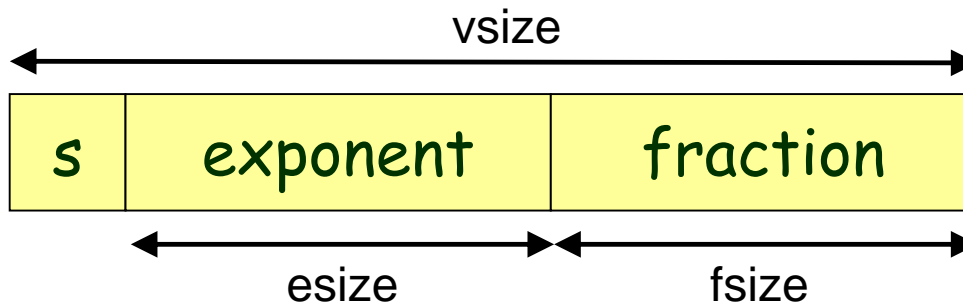
- High-level languages
- ANSI C basic data types
  - character, short integers, integer, long, ...
  - **ARM C compiler**
    - unsigned integer: 32 bits
    - unsigned long integer: 32 bits
    - unsigned short integer: 16 bits
- ANSI C derived data types
  - Array, functions, structures, ...
- ARM architectural support for C data types

# Outline

- Abstraction in software design
- Data types
- **Floating-point data types**
- The ARM floating-point architecture
- Expressions
- Conditional statements
- Loops
- Functions and procedures
- Use of Memory
- Run-time environment

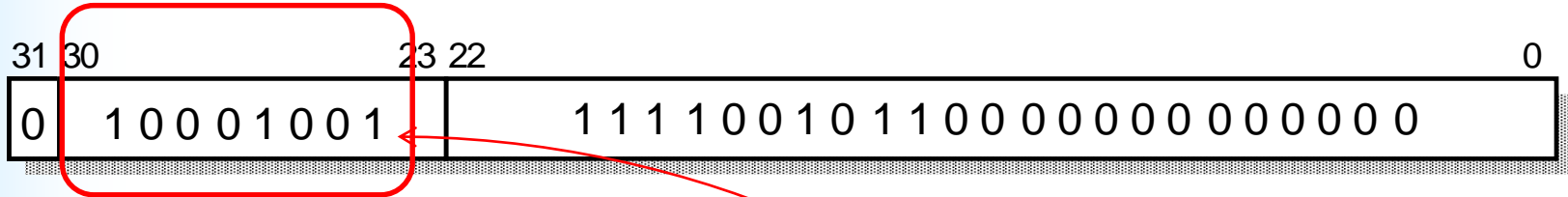
# Floating-Point Data Types

- IEEE-754



- $v = (-1)^s \times 2^{\text{exponent}} \times (1.\text{fraction})$
- Single: esize = 8, fsize = 23, vsize = 32
- Double: esize = 11, fsize = 52, vsize = 64
- Double extended, vsize > 64

# IEEE 754 Single Precision Representation of '1995'



$$\begin{aligned} 1995 &= 11111001011 \\ &= 1.\boxed{1111001011} \times 2^{1010} \end{aligned}$$

The exponent is  $127 + 10 = 137$

$$\text{value} = (-1)^S \times 1.\text{fraction} \times 2^{(\text{exponent}-127)}$$

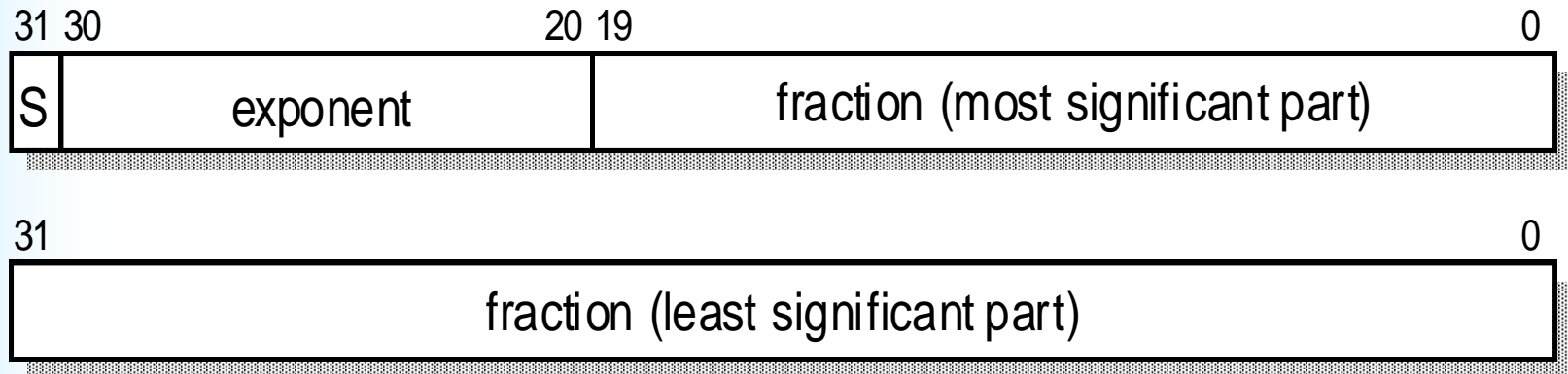
# Reserved Numbers in IEEE 754 (1)

- The exponent is either **zero** or **255**
- **Zero**
  - A zero exponent and fraction (positive zero and negative zero)
- **Plus / minus infinity**
  - The maximum exponent value
  - Zero fraction

# Reserved Numbers in IEEE 754 (2)

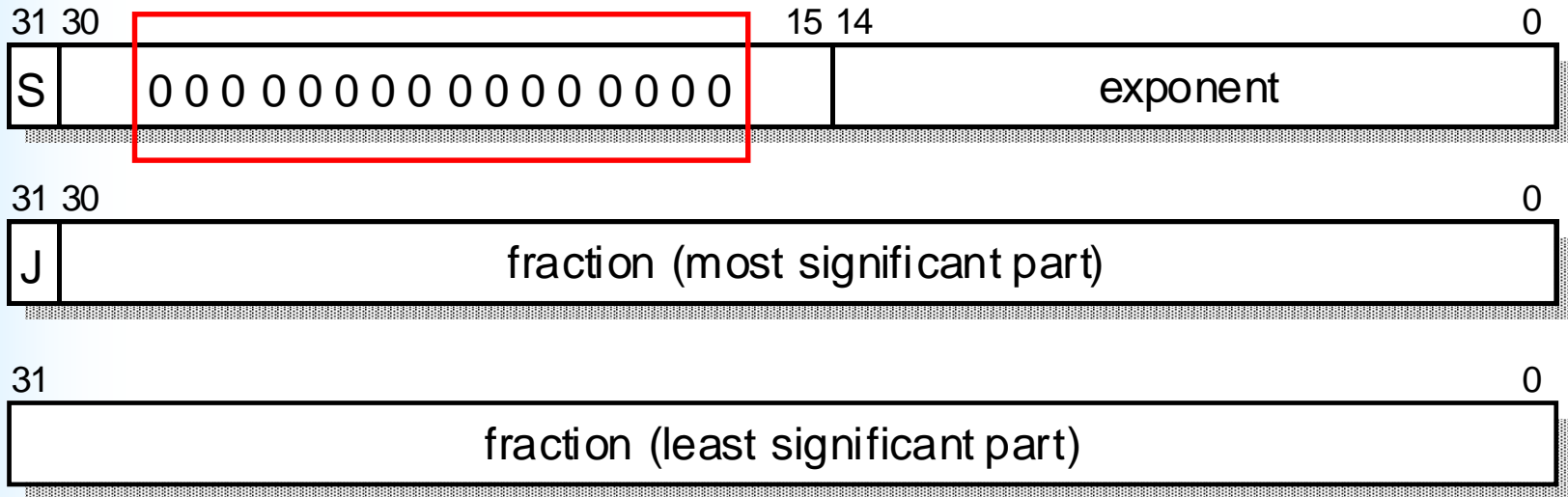
- **NaN (Not a Number)**
  - The maximum exponent value
  - Non-zero fraction
- **Denormalized number**
  - The number are too small to normalize within this format
  - Zero exponent
  - Non-zero fraction

# IEEE 754 Double Precision Floating-Point Number Format



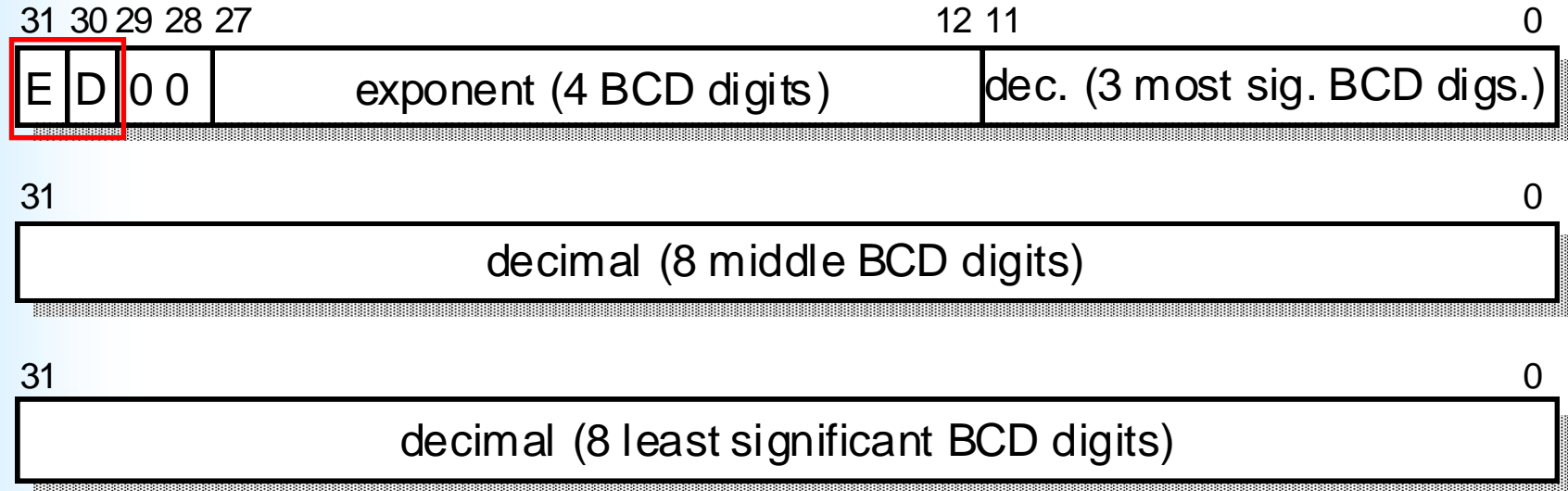
# IEEE 754 Double Extended Precision Floating-Point Number Format

**80 bits of information spread across three words**





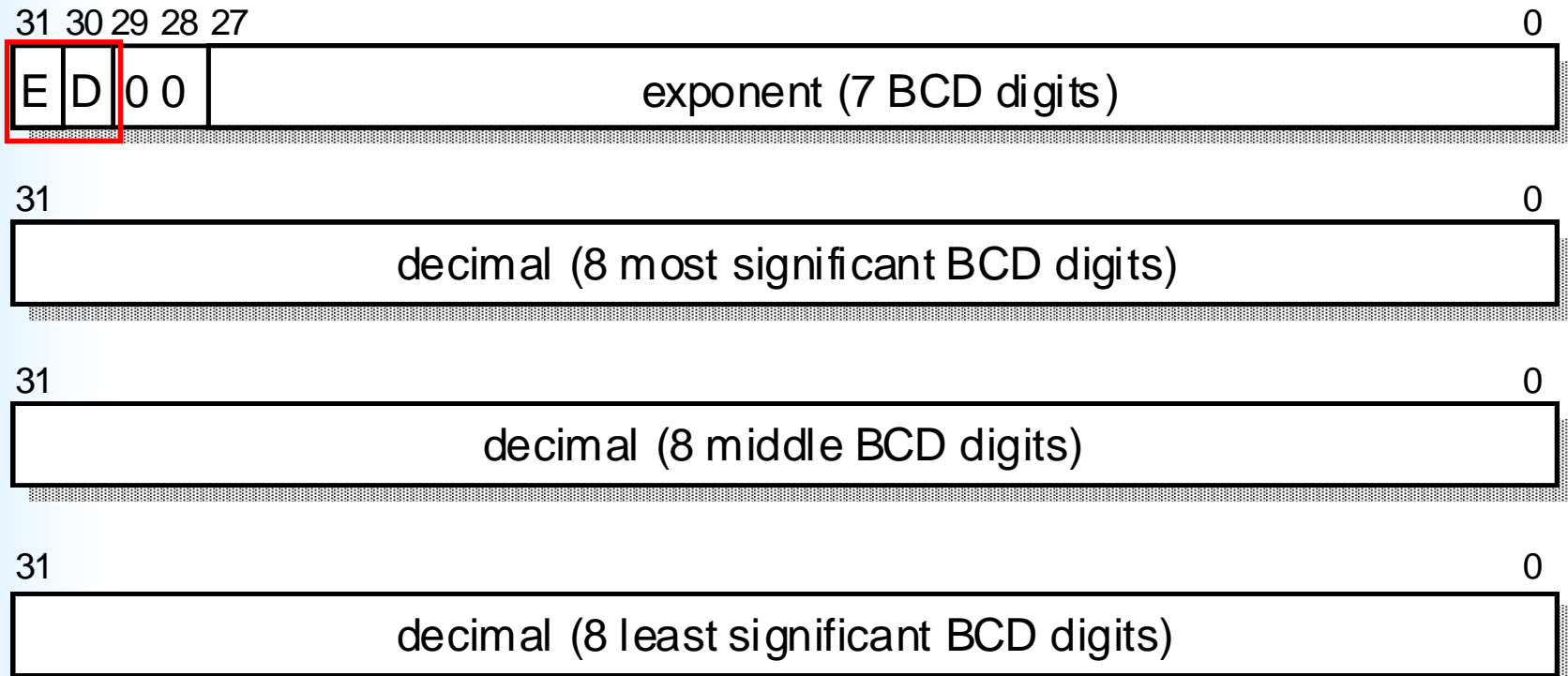
# IEEE 754 Packed Decimal Floating-Point Number Format



$$\text{value} = (-1)^D \times \text{decimal} \times 10^{((-1)^E \times \text{exponent})}$$

**3 words = 96 bits**

# IEEE 754 Extended Packed Decimal Floating-Point Number Format



**4 words = 128 bits**

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- Use of Memory
- Run-time environment

# Expressions

- Register use
  - Compilers help to allocate
- ARM support
  - 3 address format is good for compilers
- Pointer arithmetic
- Arrays

– Ex:

```
int *p;  
int i = 1;  
p = p + i;
```

Assume: p in r0, i in r1

```
ADD    r0, r0, r1, LSL #2    ; scale r1 to int
```

# Accessing Operands

- Pass an argument via a register or stack
- A constant => in the procedure's literal pool
- A local variable
  - Allocated space on the **stack**
- As a global variable
  - Allocated space in the **static area**

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# Conditional Statements (1)

- if ... else

```
if (a > b)
    c = a;
else
    c = b;
```

```
CMP      r0, r1    ; if (a>b)
MOVGT    r2, r0    ; c = a
MOVLE    r2, r1    ; c = b
```

```
MOV      r2, r0    ; c = a
CMP      r0, r1    ; if (a>b)
MOVLE    r2, r1    ; c = b
```

For the case with simple “if” statements

# Conditional Statements (2)

- A complex “if .. else” example

```
if (a > b) {
```

```
    c = a;  
    stmt 1;
```

```
    ...
```

```
} else {
```

```
    c = b;  
    stmt 2;
```

```
    ...
```

```
}
```

```
CMP      r0, r1    ; if (a>b)
```

```
BLE      ELSE
```

```
MOV      r2, r0    ; c = a
```

```
...                      ; stmt 1
```

```
...                      ; ...
```

```
B        ENDIF
```

```
ELSE MOV  r2, r1    ; c = a
```

```
...                      ; stmt 2
```

```
...                      ; ...
```

```
ENDIF
```



# Conditional Statements: switch...case (1)

- 假設所要執行之不同的動作依賴於某個變數 $x$
- $0 \leq x < N$

```
int ref_switch(int x)
{
    switch (x) {
        case 0: return method_0();
        case 1: return method_1();
        case 2: return method_2();
        case 3: return method_3();
        case 4: return method_4();
        case 5: return method_5();
        case 6: return method_6();
        case 7: return method_7();
        default: return method_d();
    }
}
```

# Conditional Statements: switch...case (2)

- A programmer sometimes wants to call one of a set of subroutines, the choice depending on a value computed by the program

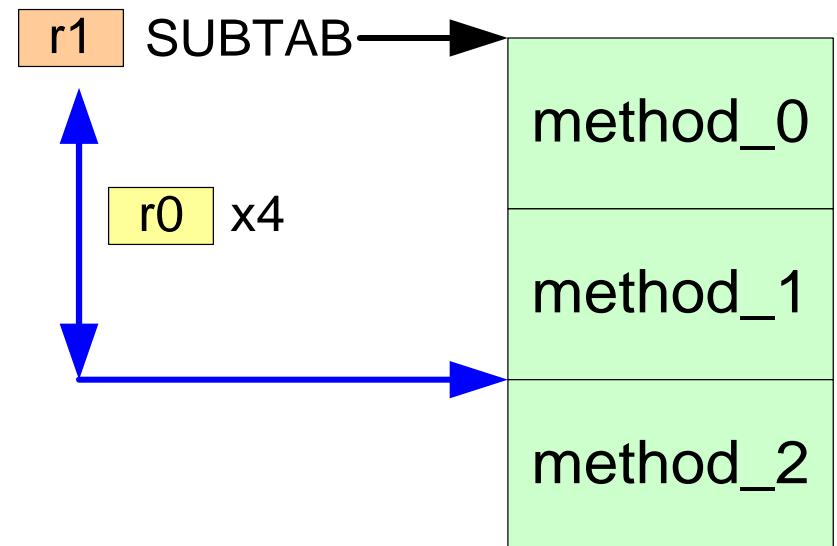
**Note:** slow when the list is long, and all subroutines are equally frequent

```
BL      JUMPTAB
..
JUMPTAB
CMP     r0, #0
BEQ     method_0
CMP     r0, #1
BEQ     method_1
CMP     r0, #2
BEQ     method_2
..
```

# Conditional Statements: switch...case (3)

- “DCD” (“**.word**”) directive instructs the assembler to reserve a word of store and to initialize it to the value of the expression in the right

```
BL    JUMPTAB
..
JUMPTAB
ADR    r1, SUBTAB
CMP    r0, #SUBMAX
LDRLS pc, [r1, r0, LSL #2]
B      method_d
SUBTAB
DCD    method_0
DCD    method_1
DCD    method_2
..
```



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# Loops

- Three forms of loop-control structure
  - for loops
  - while loops
  - do...while loops

# For Loops

```
for (i=0; i<10; i++) {  
    a[i] = 0;    /* a[i] is an integer */  
}
```

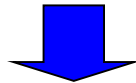
“.a” is the address of a[0]

```
MOV    r1, #0        ; The value to be stored in a[i]  
ADR    r2, .a        ; r2 points to a[0]  
MOV    r0, #0        ; i = 0  
LOOP   CMP    r0, #10 ; i < 10 ?  
       BGE    EXIT    ; if i >= 10 finish  
       STR    r1, [r2, r0, LSL #2] ; a[i] = 0  
       ADD    r0, r0, #1 ; i ++  
       B      LOOP  
EXIT   ...
```

# While Loops (1)

假設while construct繼續執行的條件是不相等

```
LOOP:  ...           ; evaluate exp
        BEQ  EXIT
        ...           ; loop body
        B    LOOP
EXIT:  ...
```

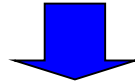


```
        B    TEST
LOOP:  ...           ; loop body
        ...
TEST:  ...           ; evaluate exp
        BNE  LOOP
EXIT:  ...
```

branch instruction  
移到最後面，loop  
body較無branch  
的干擾

# While Loops (2)

```
      B      TEST
LOOP:  ...           ; loop body
      ...
TEST:  ...           ; evaluate exp
      BNE    LOOP
EXIT:  ...
```



```
      ...           ; evaluate exp
      BEQ    EXIT    ; skip loop if necessary
LOOP:  ...           ; loop body
      ...
      ...           ; evaluate exp
      BNE    LOOP
EXIT:  ...
```



# Do... While Loops

```
LOOP:  ...           ; loop body
        ...
        ...           ; evaluate exp
        BNE  LOOP
```

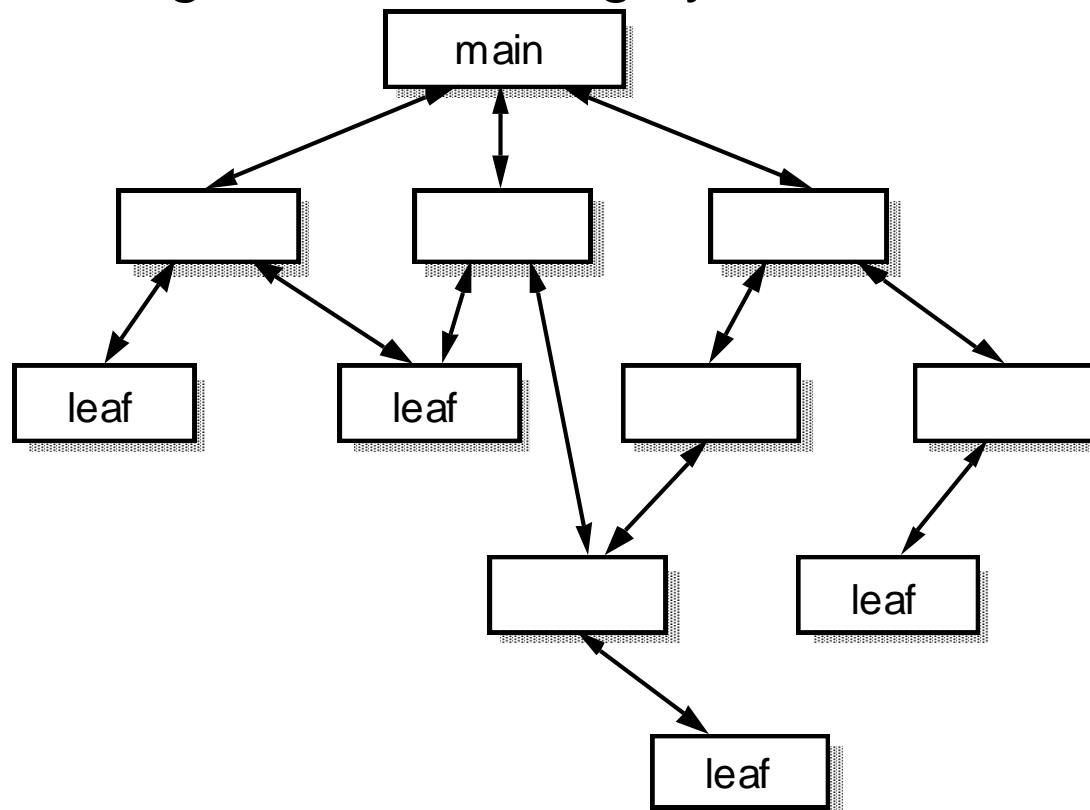
```
EXIT:  ...
```

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# Typical Hierarchical Program Structure

- Break down large programs into components that are small enough to be thoroughly tested



# Terminology (1)

- **Subroutine**

- A generic term for a routine that is called by a higher-level routine

- **Function**

- A subroutine which returns a value through its name
- Ex: `c = max(a, b);`

- **Procedure**

- A subroutine which is called to carry out some operation on specified data items
- Ex: `printf("Hello World\n");`

# Terminology (2)

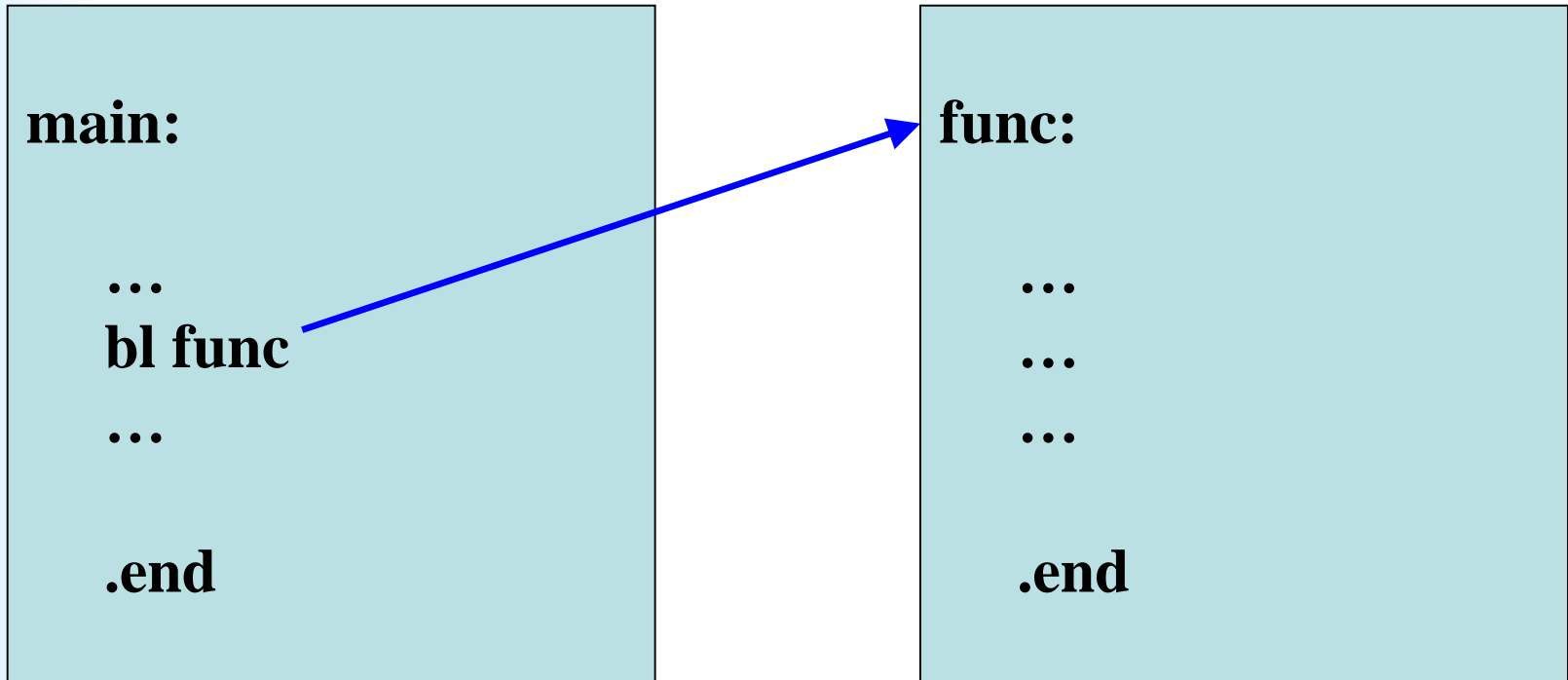
- **Arguments**
  - An expression passed to a function call
- **Parameters**
  - A value received by the function

```
void func(int a, int b)
{
    ...
}

int main(void)
{
    func(100, 200);
    return 0;
}
```

The diagram illustrates the terminology of function calls. It shows two code snippets. The first snippet is a function definition: `void func(int a, int b) { ... }`. A yellow box labeled "parameters" has a line pointing to the parameters `int a, int b` in the function signature. The second snippet is a function call: `int main(void) { func(100, 200); return 0; }`. A yellow box labeled "arguments" has a line pointing to the arguments `100, 200` in the function call.

# Situation 1

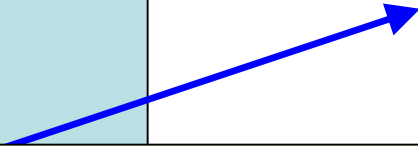


如果main function要傳遞一個integer到func function，要怎麼傳？

# Situation 1

**main:**

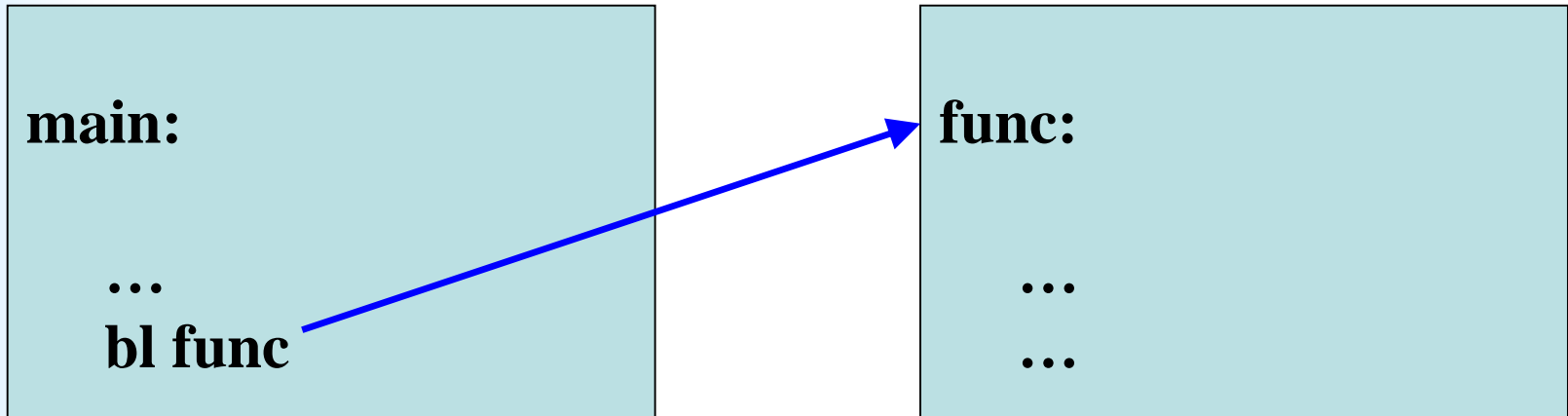
**func:**



如果main function要傳遞一個integer到func function，要怎麼傳？

- 透過register r1
- 透過register r2
- ...
- 透過stack
- 透過memory

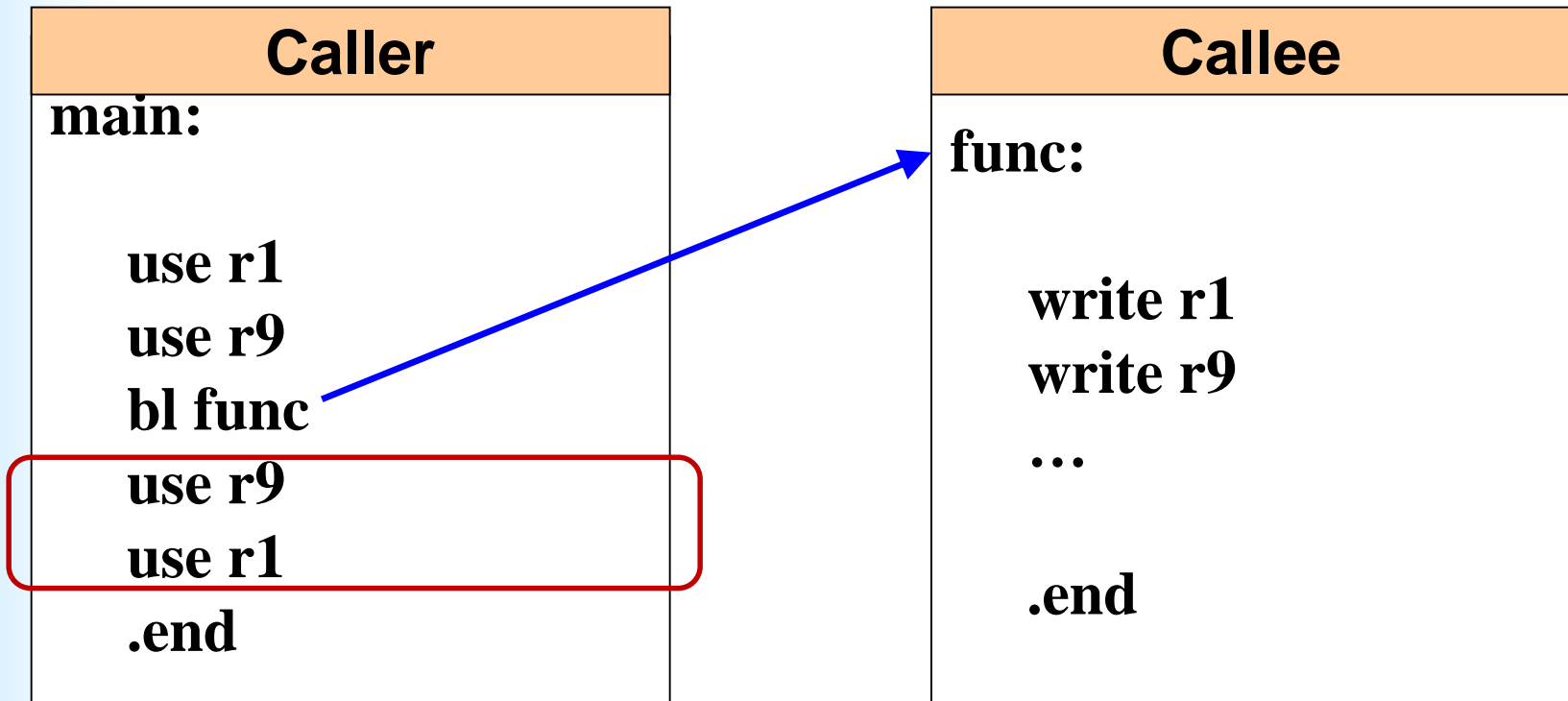
# Situation 1



- 如果main function與func function是同一個人寫的，則不會發生問題
- 如果main function與func function是不同的人寫的，則會有不知道對方是用什麼方式傳遞參數的問題
- 如果任何人都可以撰寫函式，則問題更複雜...

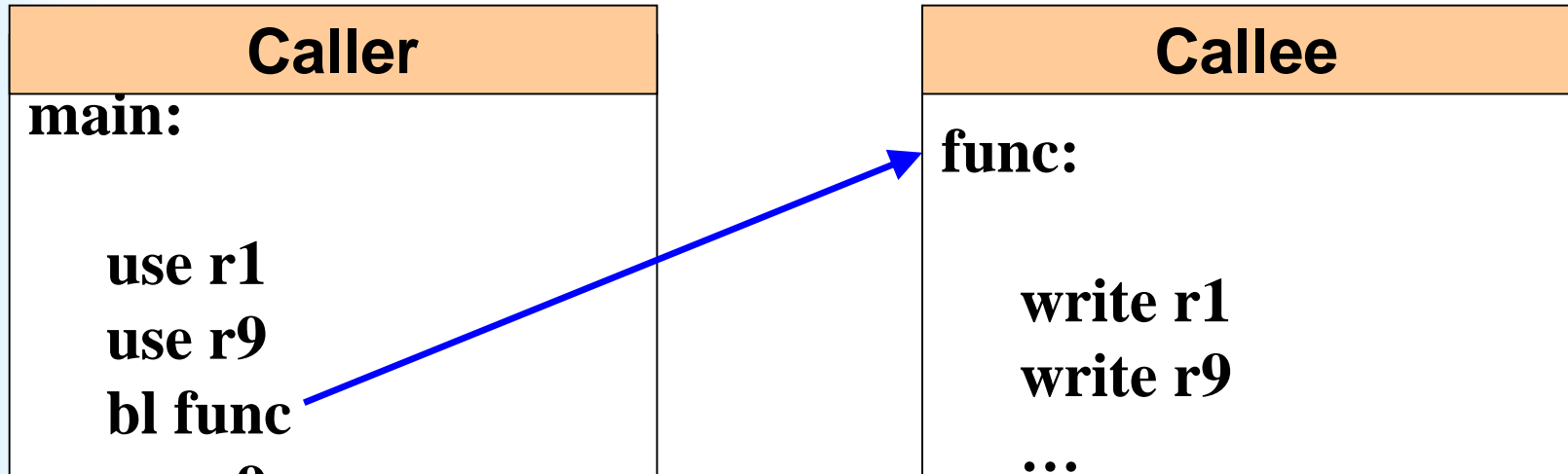


# Situation 2



如果caller在呼叫func function之後還會用到呼叫func function之前的r1與r9的值，該怎麼辦？

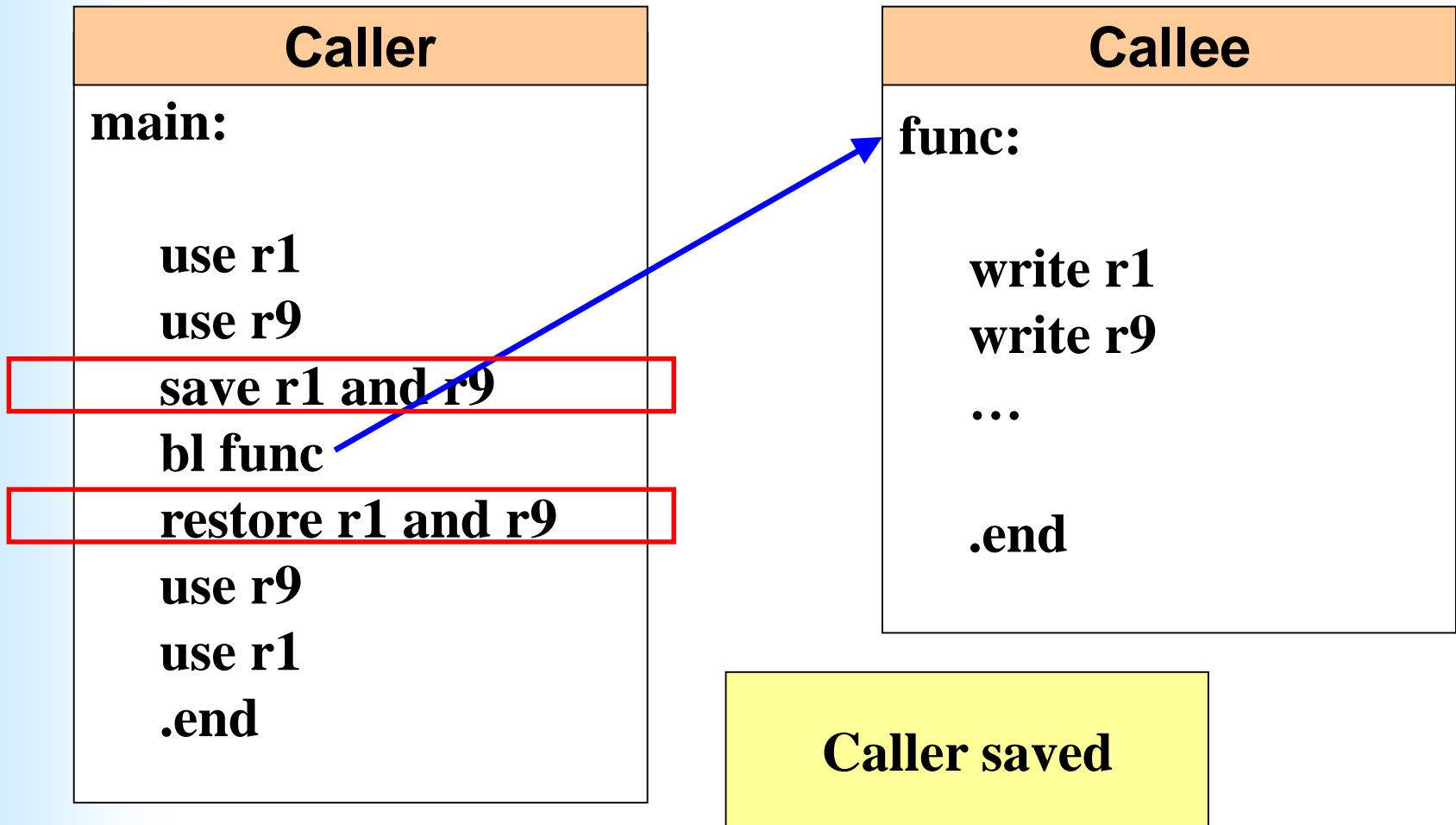
# Situation 2



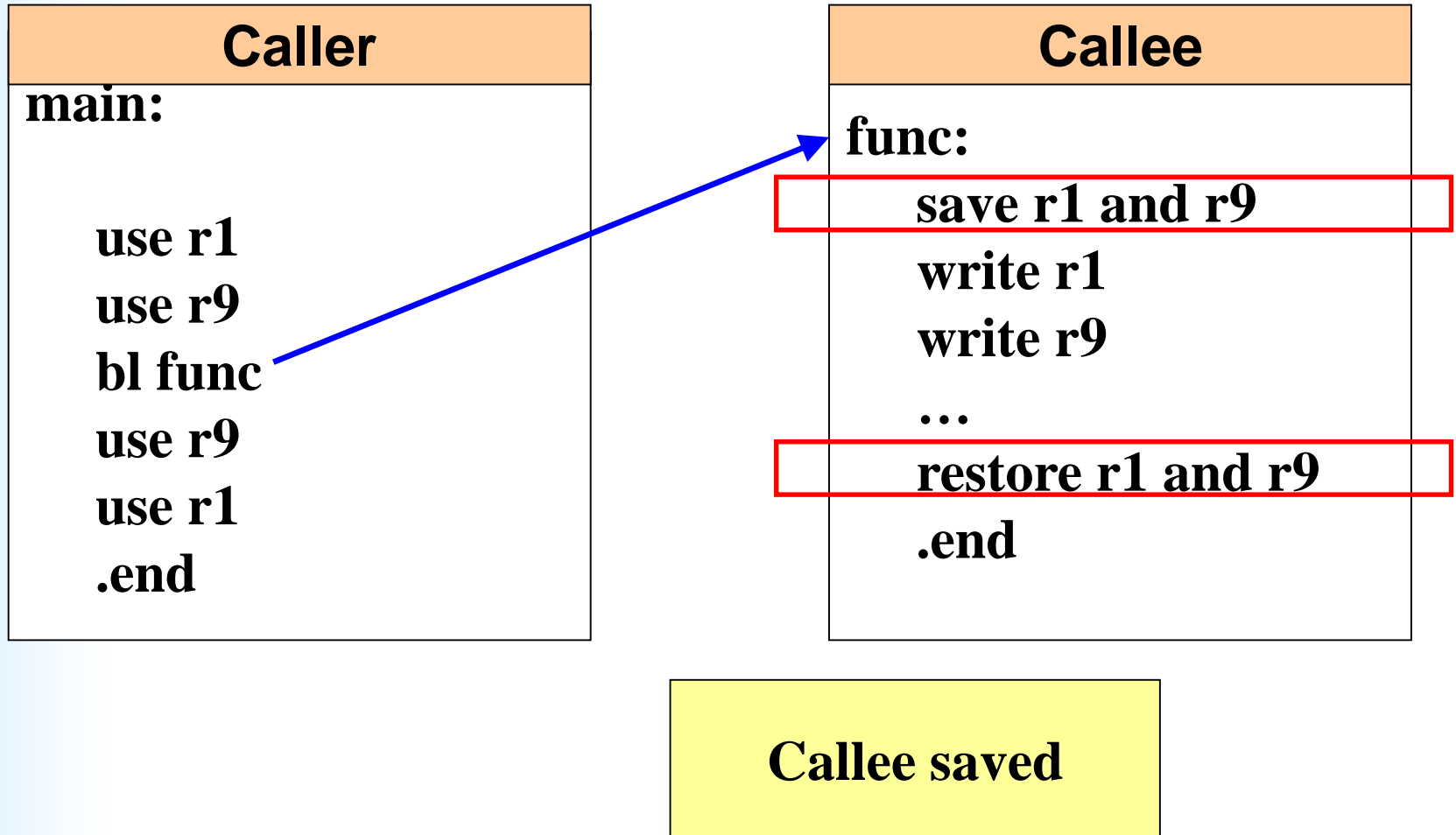
如果caller在呼叫func function之後還會用到呼叫func function之前的r1與r9的值，該怎麼辦？

- Caller幫忙save
- Callee幫忙save

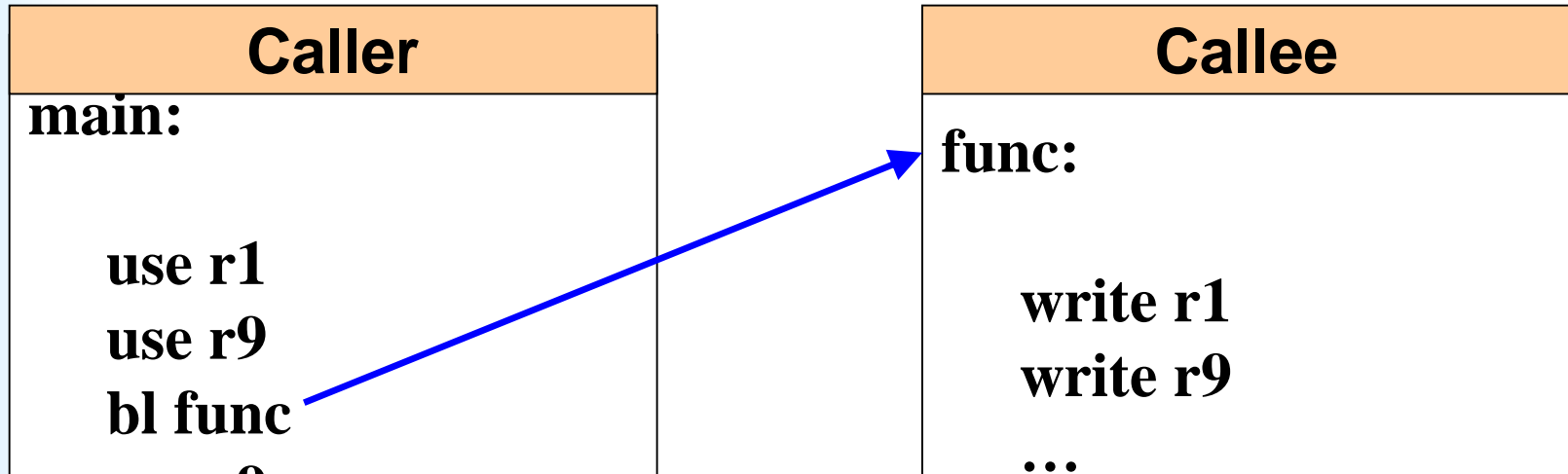
# Situation 2



# Situation 2



# Situation 2



如果caller在呼叫func function之後還會用到呼叫func function之前的r1與r9的值，該怎麼辦？

- Caller幫忙save
- Callee幫忙save

如果caller與callee是不同的人寫的，那很難知道撰寫函式的人是否有先save register

# ARM Procedure Call Standard (1)

- **Support flexible mixing of routines**

- Generated by different compilers / different assemblers
- Written in assembly language

**Calling convention**

- **ARM Limited defines a set of rules for procedure entry and exit**

- ARM Procedure Call Standard (APCS)
- 只要遵循**APCS**的規則，不同編譯器（人）所產生的**object code**，就可以相互呼叫，**link**在一起
- **Assembly code**和**C program**可以交互參照

# ARM Procedure Call Standard (2)

- Define particular use of general-purpose registers
- Define stack use from full/empty, ascending/descending choices
- Define the format of a stack-based data structure used for **back-tracing** when debugging programs
- Define the function **argument** and **result** passing mechanism to be used by all externally visible functions and procedures
- Support the ARM shared library mechanism

# APCS Register Use Convention (1)

Register	Synonym	Special	Role in the procedure call standard
r15		<b>PC</b>	The Program Counter.
r14		<b>LR</b>	The Link Register.
r13		<b>SP</b>	The Stack Pointer.
r12		IP	The Intra-Procedure-call scratch register.
r11	v8	FP	ARM-state variable-register 8. ARM-state frame pointer.
r10	v7	<b>SL</b>	ARM-state variable-register 7. Stack Limit pointer in stack-checked variants.
r9	v6	<b>SB</b>	ARM-state v-register 6. Static Base in PID,/re-entrant/shared-library variants
r8	v5		ARM-state variable-register 5.
r7	<b>v4</b>	<b>WR</b>	Variable register (v-register) 4. Thumb-state Work Register.
r6	<b>v3</b>		Variable register (v-register) 3.
r5	<b>v2</b>		Variable register (v-register) 2.
r4	<b>v1</b>		Variable register (v-register) 1.
r3	<b>a4</b>		Argument/result/scratch register 4.
r2	<b>a3</b>		Argument/result/ scratch register 3.
r1	<b>a2</b>		Argument/result/ scratch register 2.
r0	<b>a1</b>		Argument/result/ scratch register 1.



# APCS Register Use Convention (2)

Register	Synonym	Special	Role in the procedure call standard
----------	---------	---------	-------------------------------------

- Four argument registers which pass values into the function
- They must be saved across call if they contain values that are needed again
- They are **caller-saved register** variables when so used

r3	a4		Argument/result/scratch register 4.
r2	a3		Argument/result/ scratch register 3.
r1	a2		Argument/result/ scratch register 2.
r0	a1		Argument/result/ scratch register 1.

# APCS Register Use Convention (3)

r11	v8	FP	ARM-state variable-register 8. ARM-state frame pointer.
r10	v7	<b>SL</b>	ARM-state variable-register 7. Stack Limit pointer in stack-checked variants.
r9	v6	<b>SB</b>	ARM-state v-register 6. Static Base in PID,/re-entrant/shared-library variants
r8	v5		ARM-state variable-register 5.
r7	<b>v4</b>	<b>WR</b>	Variable register (v-register) 4. Thumb-state Work Register.
r6	<b>v3</b>		Variable register (v-register) 3.
r5	<b>v2</b>		Variable register (v-register) 2.
r4	<b>v1</b>		Variable register (v-register) 1.

- v1~v8, register variables which the function must return with unchanged values
- These are **callee-saved register** variables

# APCS Register Use Convention (4)

Register	Synonym	Special	Role in the procedure call standard
r15		<b>PC</b>	The Program Counter.
r14		<b>LR</b>	The Link Register.
r13		<b>SP</b>	The Stack Pointer.
r12		<b>IP</b>	The Intra-Procedure-call scratch register.
r11	v8	<b>FP</b>	ARM-state variable-register 8. ARM-state frame pointer.
r10	v7	<b>SL</b>	ARM-state variable-register 7. Stack Limit pointer in stack-checked variants.
r9	v6	<b>SB</b>	ARM-state v-register 6. Static Base in PID,/re-entrant/shared-library variants
r8	v5		ARM-state variable-register 5.
r7	<b>v4</b>	<b>WR</b>	Variable register (v-register) 4. Thumb-state Work Register.
r6	<b>v3</b>		Variable register (v-register) 3.
r5	<b>v2</b>		Variable register (v-register) 2.
r4	<b>v1</b>		Variable register (v-register) 1.
r3	<b>a4</b>		Argument/result/scratch register 4.
r2	<b>a3</b>		Argument/result/ scratch register 3.
r1	<b>a2</b>		Argument/result/ scratch register 2.
r0	<b>a1</b>		Argument/result/ scratch register 1.

# Argument Passing

- The first 4 words arguments => a1 ~ a4
- Remaining words: push into the stack in reverse order
- **Floating point**  
(If floating-point values are passed through floating-point registers)
  - The first 4 floating-point arguments => f0~f3
  - All remaining arguments: the first 4 words => a1~a4
  - The remaining words => stack in reverse order

# Effective Procedure Calls

- 四個或更少參數的函數比多於四個參數的函數執行效率要高
  - more than 4 arguments => use stack
- Caller
  - 減少對register / memory的存取動作
- Callee
  - 多了register可利用
- Inline function

# Example

```
char* queue_bytes_v1(  
    char* Q_start,  
    char* Q_end,  
    char* Q_ptr,  
    char* data,  
    unsigned int N)  
{  
    do {  
        *(Q_ptr++) = *(data++);  
        if (Q_ptr == Q_end)  
            Q_ptr = Q_start;  
    } while (--N);  
  
    return Q_ptr;  
}
```

```
typedef struct {  
    char* Q_start,  
    char* Q_end,  
    char* Q_ptr  
} Queue;
```

```
char* queue_bytes_v2(  
    Queue* queue,  
    char* data,  
    unsigned int N)  
{  
    char* Q_start = queue->Q_start;  
    char* Q_end = queue->Q_end;  
    char* Q_ptr = queue->Q_ptr;  
    do {  
        *(Q_ptr++) = *(data++);  
        if (Q_ptr == Q_end)  
            Q_ptr = Q_start;  
    } while (--N);  
  
    return Q_ptr;  
}
```

# Result Return

- 1 word value in a1
- A value of length 2-4 words
  - a1-a2, a1-a3, a1-a4
- Indirect return (Memory)
  - Ex: return a structure with 8 words

# Function Entry / Exit (1)

- A simple leaf function
  - Perform all its functions using only **a1~a4**
  - Have **minimal calling overhead**

```
                BL    leaf1
                ...
                ...

leaf1:          ...
                ...
                MOV   pc, lr    ; return
```



# Function Entry / Exit (2)

- A general function

```
        BL      leaf2
        ...
        ...

leaf2:   STMFD   sp!, {regs, lr} ; save registers
        ...
        ...
        LDMEA   sp!, {regs, pc} ; restore and return
```

# Backtrace

```
save code pointer
return link value
return sp value
return fp value
[saved v7]
[saved v6]
[saved v5]
[saved v4]
[saved v3]
[saved v2]
[saved v1]
[saved a4]
[saved a3]
[saved a2]
[saved a1]
[saved f7]
[saved f6]
[saved f5]
[saved f4]
```

```
[fp]          fp points here
[fp, #-4]
[fp, #-8]
[fp, #-12]    points to next structure
```

## 每個函式需儲存的資訊 (APCS)

The **fp register** points to the **stack backtrace structure** for the currently executing function.

```
three words
three words
three words
three words
```

## crt0.s

```
_mainCRTStartup:
```

```
...
```

```
mov r0, #0  
mov fp, r0
```

```
...
```

```
bl main
```

```
...
```

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

fp → 0

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB     fp , ip, #4  
...
```

Stack top



xxx



push

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB    fp , ip, #4  
...
```

ip

Stack top

xxx

↓  
push

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB    fp , ip, #4  
...
```

pc

ip

Stack top

xxx

pc

push

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB     fp , ip, #4  
...
```

main

ip

Stack top

xxx

main

push

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB    fp , ip, #4  
...
```

main

ip

Stack top

xxx  
main  
lr

push



```
func1 ()
{
    ...
}
```

```
main ()
{
    ...
    ...
    func1 ()
    ...
}
```

main:

```
MOV    ip , sp
STMFD  sp!, {fp, ip, lr, pc}
SUB    fp , ip, #4
...
```

main

ip

Stack top

xxx  
main  
lr  
ip

push

```
func1 ()
{
    ...
}
```

```
main ()
{
    ...
    ...
    func1 ()
    ...
}
```

main:

```
MOV    ip , sp
STMFD  sp!, {fp, ip, lr, pc}
SUB    fp , ip, #4
...
```

main

ip

Stack top

xxx  
main  
lr  
ip  
fp

push

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB     fp , ip, #4  
...
```

ip

xxx  
main  
return link  
return sp  
return fp → 0  
...

```
func1 ()  
{  
    ...  
}
```

```
main ()  
{  
    ...  
    ...  
    func1 ()  
    ...  
}
```

main:

```
MOV    ip , sp  
STMFD  sp!, {fp, ip, lr, pc}  
SUB     fp , ip, #4  
...
```

pc

fp

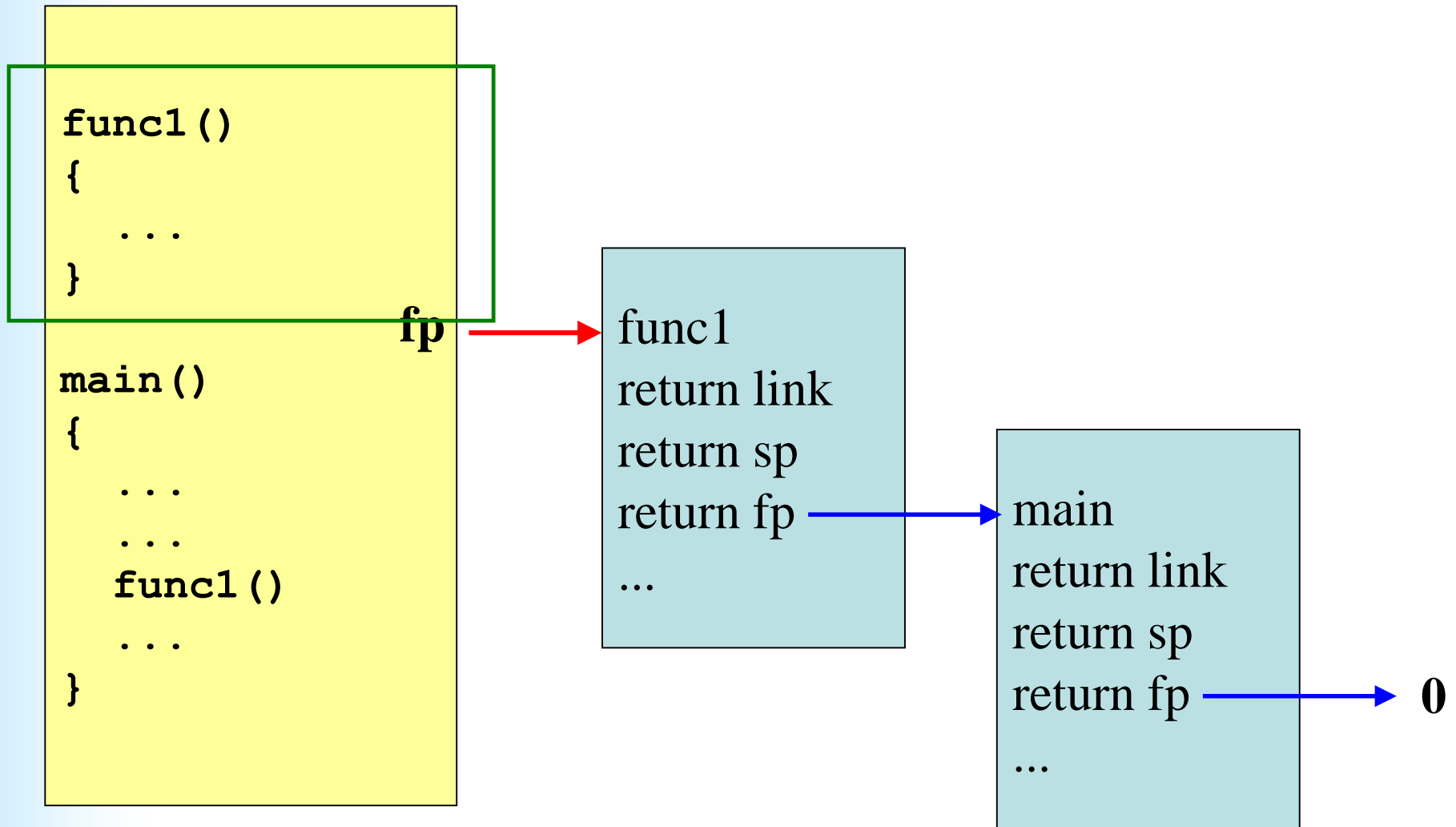
main

return link

return sp

return fp → 0

...



# Function Entry (APCS)

```
MOV ip, sp  
STMFD sp!, {fp, ip, lr, pc}  
SUB fp, ip, #4
```

OR

```
STMFD sp!, {r4-r10, fp, ip, lr, pc}
```

假如之後callee會用到r4-r10 register

# Function Exit (APCS)

**LDMEA fp, {fp, sp, pc}**

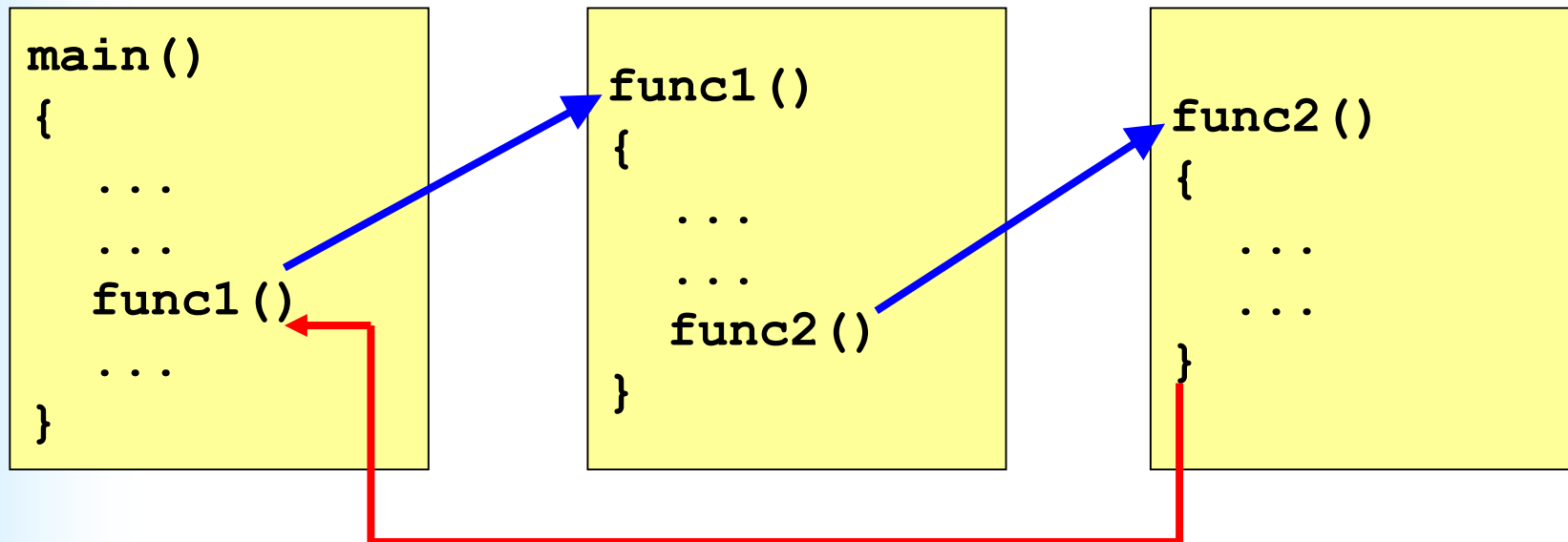
OR

**LDMEA fp, {r4-r10, fp, sp, pc}**

假如之前callee有先save r4-r10 register

# Tail Continued Functions

- The compiler will cause the code to return directly from the continuing function





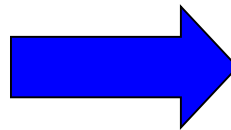
# Inline Function

- Program will execute **faster** by eliminating the function-call overhead

```
void inc(int* b)
{
    (*b)++;
}

int main()
{
    int a = 10;

    inc(&a);
    ...
}
```



```
int main()
{
    int a = 10;

    (*(&a))++;
    ...
}
```

# Inline Function in GCC

To declare a function inline, use the **inline** keyword in its declaration

```
inline void inc(int* b)
{
    (*b)++;
}

int main()
{
    int a = 10;

    inc(&a);
    ...
}
```

GCC does not inline any functions when **not optimizing** unless you specify the **always\_inline** attribute for the function

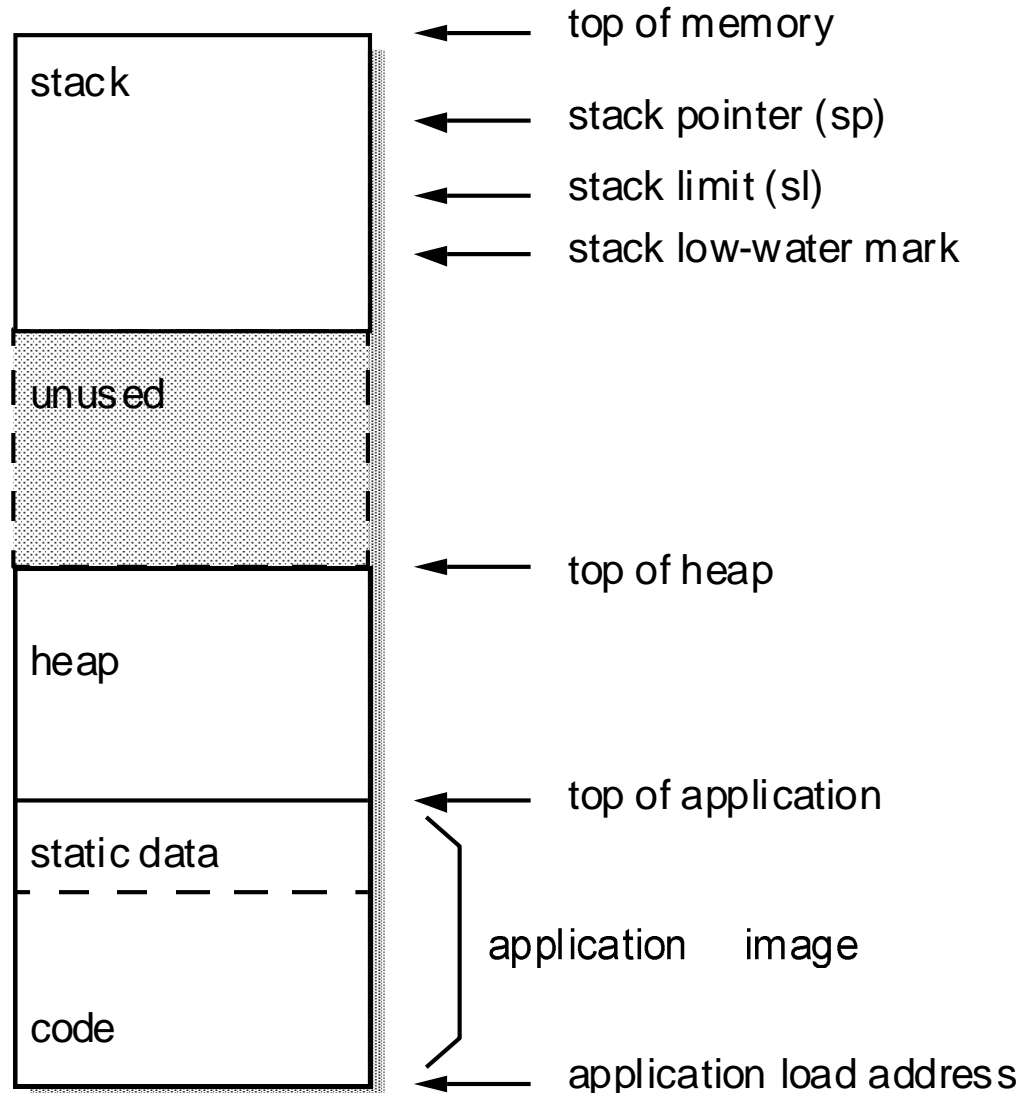


```
inline void inc(int*) __attribute__((always_inline)) ;
```

# Outline

- Abstraction in software design
- Data types
- Floating-point data types
- Expressions
- Conditional statements
- Loops
- Functions and procedures
- **Use of Memory**
- Run-time environment

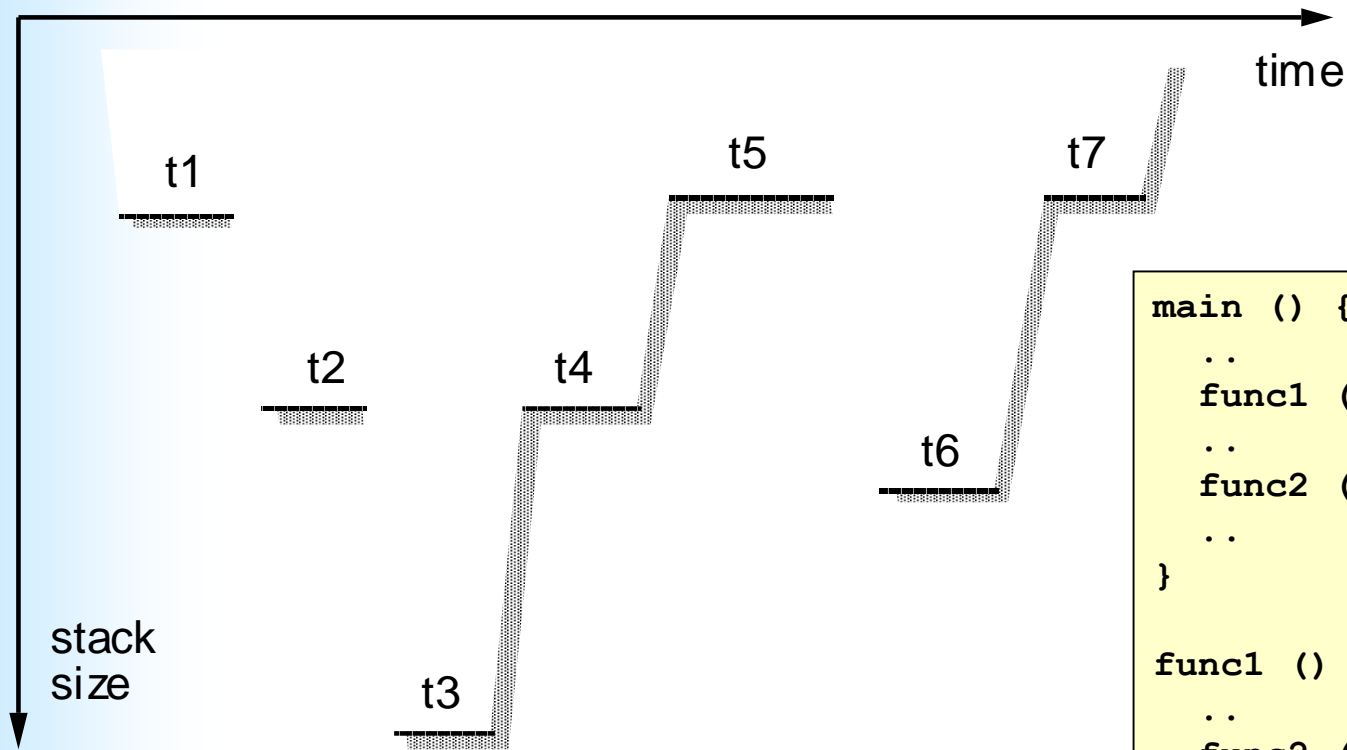
# The Standard ARM C Program Address Space Model



# A Simple Program

```
main () {  
    ..          /* t1 */  
    func1 ();  
    ..          /* t5 */  
    func2 ();  
    ..          /* t7 */  
}  
  
func1 () {  
    ..          /* t2 */  
    func2 ();  
    ..          /* t4 */  
}  
  
func2 () {  
    ..          /* t3, t6 */  
}
```

# Stack Behavior



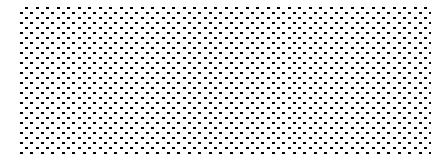
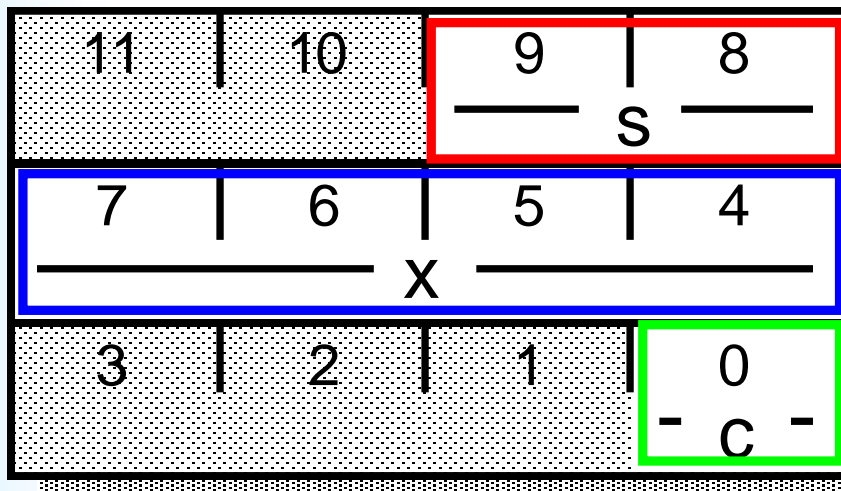
```
main () {  
    ..                /* t1 */  
    func1 ();  
    ..                /* t5 */  
    func2 ();  
    ..                /* t7 */  
}  
  
func1 () {  
    ..                /* t2 */  
    func2 ();  
    ..                /* t4 */  
}  
  
func2 () {  
    ..                /* t3, t6 */  
}
```

# Memory Issues

- **Efficient : aligned data**
- **Inefficient: non-aligned data**
- ARM C compiler generally aligns data items on appropriate boundaries
  - Bytes are stored at any **byte** address
  - Half-words are stored at **even** byte addresses
  - Words are stored on **four-byte** boundaries

# An Example: Normal Structure Memory Allocation

```
struct S1 {  
    char c;  
    int x;  
    short s;  
} example1;
```



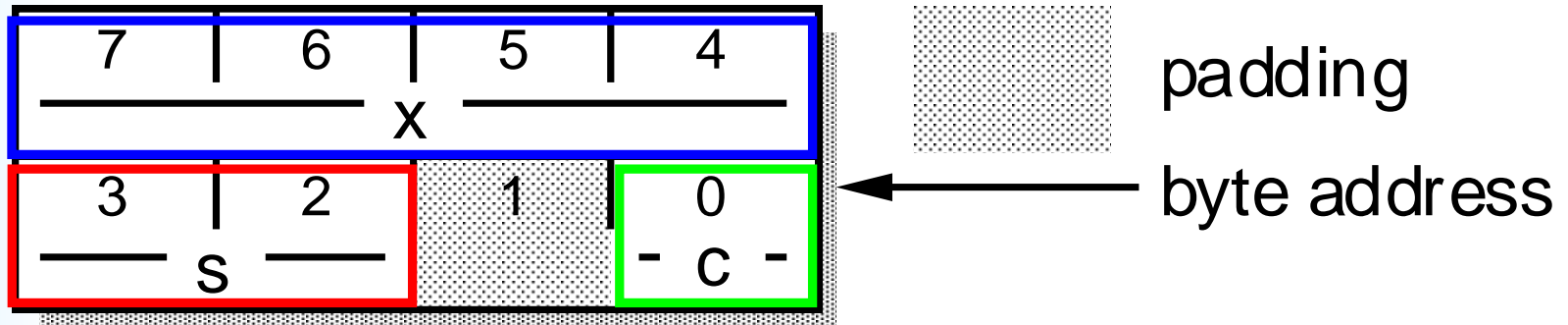
padding

byte address



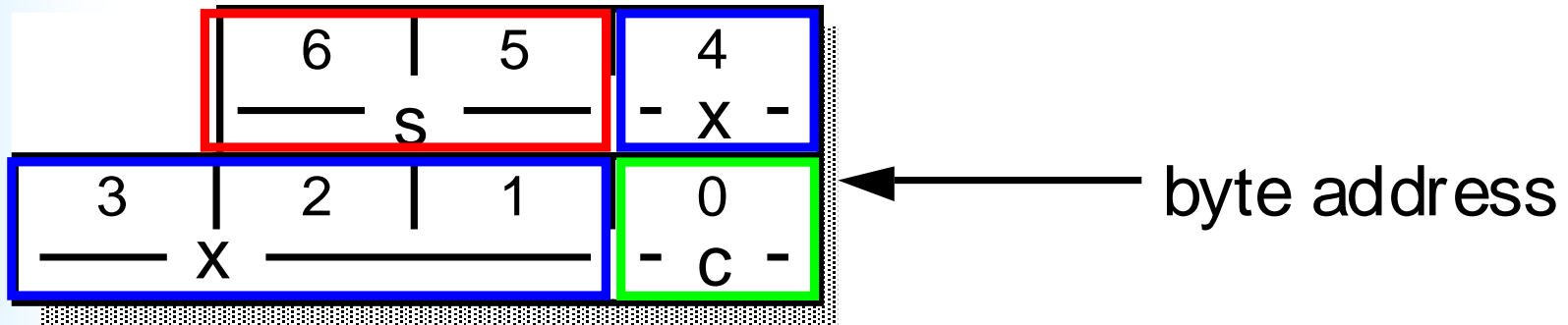
# An Example: Efficient Structure Memory Allocation

```
struct S1 {  
    char c;  
    short s;  
    int x;  
} example1;
```



# An Example: Packed Structure Memory Allocation

```
__packed struct S1 {  
    char    c;  
    int     x;  
    short   s;  
} example1;
```



# Variable Alignment in GCC (1)

- The keyword `__attribute__` allows you to specify special attributes of variables or structure fields
- This keyword is followed by an **attribute specification** inside double parentheses

Variable x is aligned on a 16-byte boundary

```
int x __attribute__ ((aligned (16)));
```

# Variable Alignment in GCC (2)

```
struct S1 {  
    char    c    __attribute__((align(1)));  
    int     x    __attribute__((align(4)));  
    short   s    __attribute__((align(2)));  
} example1;
```

```
struct S1 {  
    char    c    __attribute__((packed));  
    int     x    __attribute__((packed));  
    short   s    __attribute__((packed));  
} example1;
```

# Outline

- Abstraction in software design
- Data types
- Floating-point data types
- Expressions
- Conditional statements
- Loops
- Functions and procedures
- Use of Memory
- **Run-time environment**

# Run-time Environment

- Software development
  - Compiler, Assembler, Linker, Debugger
  - **ANSI C Library**
    - File management
    - Input / Output
    - Real-time clock
    - ...
- Embedded System
  - **Limited resources** (Cannot provide full ANSI C library)
  - Most of functions are irrelevant for different embedded systems
    - Depend on the function of the embedded system
    - Ex: Mobile phone, mp3 player, ...etc.

# Minimal Run-Time Library (1)

From ARM Limited: ~736 bytes

- **Division and remainder functions**
  - The ARM instructions set does not have divide instructions
- **Stack-limit checking functions**
  - A small embedded system has no memory management hardware
  - Ensure that programs operate safely
- **Stack and heap management**
  - C programs will use stack and heap during runtime

# Minimal Run-Time Library (2)

- **Program start up**
  - The initialization of stack and heap, ex: crt0
- **Program termination**
  - Programs call `_exit()` when
    - Termination
    - an error is detected during runtime
  - `_exit()`
    - Flush all output streams, close all open streams
    - Remove all temporary files
    - ... , finally, control is returned



# Other Issues

- Fixed Point Arithmetic
- GCC inline assembly

# Fixed Point: Idea (1)

$$1\ 2 + 3\ 5 = 4\ 7$$

$$1.\textcolor{red}{.}2 + 3.\textcolor{red}{.}5 = 4.\textcolor{red}{.}7$$

## Fixed Point: Idea (2)

$$1.2 + 3.5 = ?$$

$$1.\underset{\cdot}{2} + 3.\underset{\cdot}{5} = 4.\underset{\cdot}{7}$$

# Fixed Point: Idea

- $12 + 35 = 47$
- $1.2 + 3.5 = 4.7$
- 似乎可以用整數指令來做浮點數的運算，只要小數點都點在固定的位置就可以了
  - 假設register的值都需要把小數點點在第一位與第二位之間才是真正的數值
  - `mov r1, #12`
  - `mov r2, #35`
  - `add r2, r1, r2`

雖然r2的值是47，但是我們解讀為4.7

# Fixed Point Arithmetic (1)

- Floating point
  - IEEE-754
  - Fixed point
- A pair of integers ( $n$ ,  $e$ ) represents the fraction
  - $n$ : mantissa
  - $e$ : exponent

$$\text{Fraction} = n \times 2^{-e}$$

# Fixed Point Arithmetic (2)

Mantissa ( $n$ )	Exponent ( $e$ )	Binary	Decimal
01100100	-1	011001000.	200
01100100	0	01100100.	100
01100100	1	0110010.0	50
01100100	2	011001.00	25
01100100	3	01100.100	12.5
01100100	7	0.1100100	0.78125

- If **e is known at compile time**,  $(n, e)$  is said to a fixed point number
- Fixed point numbers can be stored in standard integer variables by storing the mantissa

# Fixed Point Arithmetic (3)

- The exponent **e** is usually denoted by the letter **q**
- Ex:  $q=14$ ,  $0x00004000$  represents ?

000000000000000000000000**1**0000000000000000

$$F = 0x00004000 \times 2^{-14} = 1$$

# Examples

- Ex:  $q=14$ ,  $0x00000001$  represents ?

$$F = 0x00000001 \times 2^{-14} = 2^{-14}$$



# Change of Exponent

- Change the exponent from  $p$  to  $r$

$$\text{Fraction} = n \times 2^{-p} = (n \times 2^{r-p}) \times 2^{-r}$$

- Mantissa =  $n \ll (r-p)$  if  $(r \geq p)$   
 $n \gg (p-r)$  if  $(p > r)$

小數點對齊，才  
可以直接做運算

Shift operation

# Addition and Subtraction

- Operation:  $c = a + b$
- Convert **a** and **b** to have the same exponent as **c**

$$a + b = n \times 2^{-r} + m \times 2^{-r} = (n + m) \times 2^{-r} = c$$

```
; a is in register r0  
; b is in register r1  
; a, b and c have the same exponent  
  
ADD r2, r0, r1
```

# Example

- $3.7 + 1.21 = ?$
- $37 * 10^{-1} + 121 * 10^{-2}$
- $(37 * 10) * 10^{-2} + 121 * 10^{-2}$
- $370 * 10^{-2} + 121 * 10^{-2}$
- $491 * 10^{-2}$
  
- $3.7 + 1.21 = 4.91$

# Fixed Point Arithmetic (4)

- If the processor does not support floating-point operations
  - Do floating-point operations by **software**
    - **Software emulation (IEEE-754)**
    - **Fixed point**
  - Fixed point computation is **faster** than software emulation (IEEE-754), but **less accuracy, informal**.

# Inline Assembly

# GNU Inline Assembly (1)

“**asm**” and “**\_\_asm\_\_**” are valid

```
asm("add r2, r1, r0");  
__asm__("add r2, r1, r0");
```

# GNU Inline Assembly (2)

- “\n” => newline
- “\t” => tab

```
__asm__ (“add r2, r1, r0\n\t”  
        “mov r3, r2\n\t”  
        “mul r0, r1, r3”);
```

# Example

```
int main(void)
```

```
{
```

```
    int a;
```

```
    a = 100;
```

```
    __asm__("add r2, r1, r0");
```

```
    printf("%d\n", a);
```

```
    return 0;
```

```
}
```





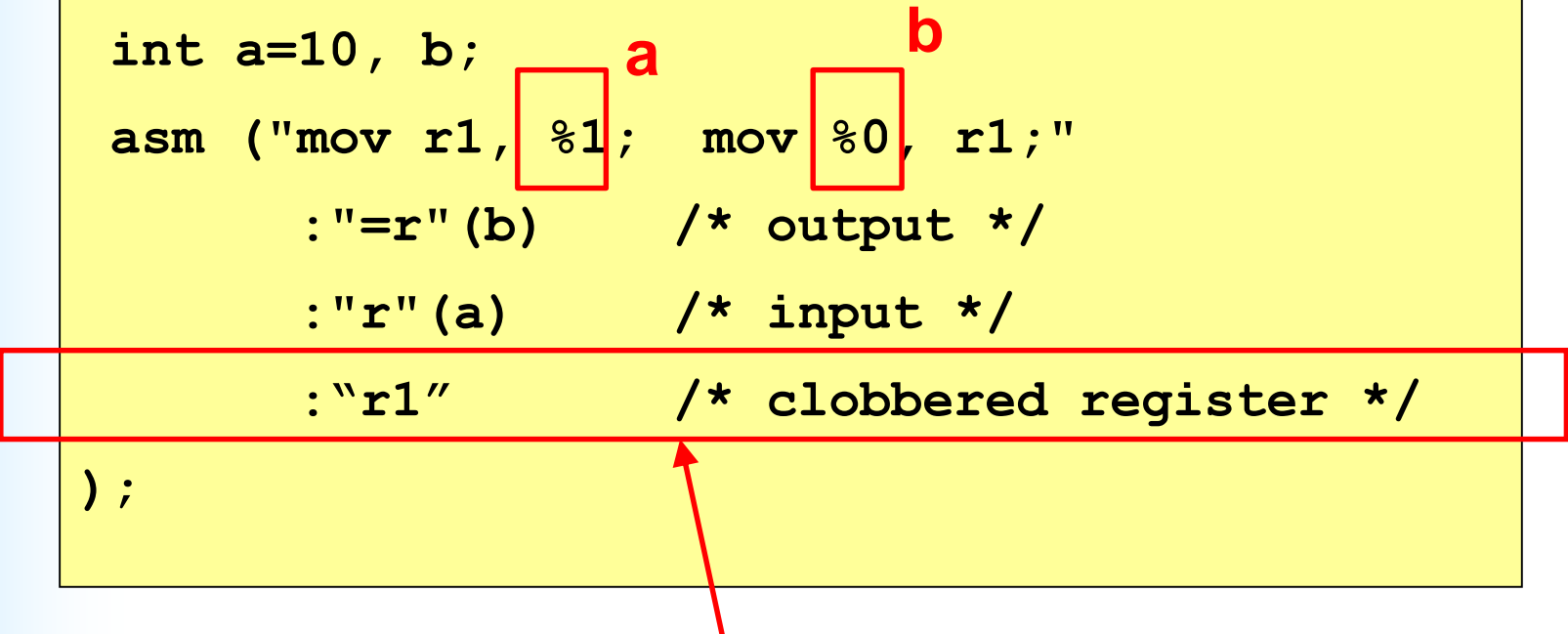
# GNU Inline Assembly (3)

- Basic format

```
asm ( assembler template
      : output operands          /* optional */
      : input operands          /* optional */
      : list of clobbered registers /* optional */
    );
```

# GNU Inline Assembly (4)

```
int a=10, b;  
asm ("mov r1, %1;  mov %0, r1;"  
    : "=r" (b)      /* output */  
    : "r" (a)        /* input */  
    : "r1"           /* clobbered register */  
);
```



Tell GCC that the value of r1 is to be modified inside "asm", so GCC won't use this register to store any other value

```
int main(void)
{
    int m=2010, n=1, k=6, p=1010;
    asm ("sub r2,%1,#10;
        add r2,r2,%3;
        add r2,r2,%2;
        mov %0,r2"
        : "=r" (p)
        : "r" (m) , "r" (n) , "r" (k)
        : "r2"          /* clobbered register */
    );
    printf("%d %d %d %d\n", m, n, k, p);
    return 0;
}
```

# Backup

# Conditional Statements: switch...case (4)

- 如果**switch**發生的條件是大範圍的**x**
- 利用**hash function**

