# Data Augmentation using VAE for enhancing Classification with various Dataset

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Background of research

Variational auto encoder

simulation

Future study

References

Background of research

- n=100000, traindata=80000, testdata=20000
- $x_1, x_2, x, \cdots, x_{10} \sim U(0, 1)$
- $\beta = (1, 1.5, 2, 2.5, 0, -1, -1.5, -2, -2.5, 0)$
- $p(y|x) = \frac{e^{x_1+1.5x_2+2x_3+2.5x_4+0x_5-1x_6-1.5x_7-2x_8-2.5x_9+0x_{10}}}{1+e^{x_1+1.5x_2+2x_3+2.5x_4+0x_5-1x_6-1.5x_7-2x_8-2.5x_9+0x_{10}}}$
- Fit the train data to the logistic regression model and measure the accruacy of the test data.

	False	True
0	7356	2536
1	2720	7388

73.09062%

## Logistic model

- Downsampling data with category 1 at a rate of 0.05%.
- Oversampling by the original number of data with category 1.
- Fit the Oversampling data to the logistic regression model and measure the accuracy of the test data.

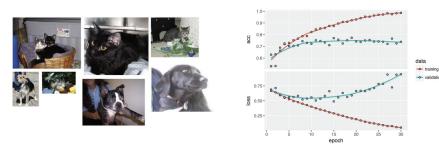
	False	True
0	7900	1992
1	4257	5851

57.88484%

• It is confirmed that the performance of the model has decreased as the information of the data with category 1 is reduced.

#### CNN model

Background of research

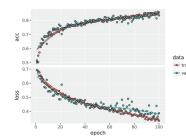


- training accuracy is higher than validation accuracy training loss is lower than validation loss.
- An overfitting problem has occurred.



### **Data Augmentation**





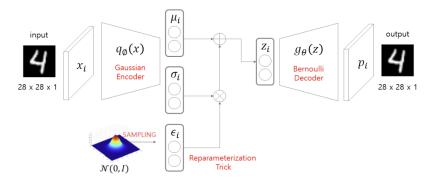
sparse data  $\rightarrow$  augmentation data

- The validation accuracy is improved.
- The problem of overfitting has improved to a certain extent.

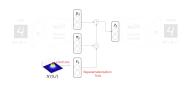
[Deep Learning with R (Francis Chollet with J.J. Allaire)]

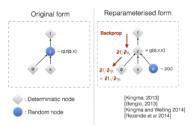
### Data Augmentation

- Cherry Khosla (2020) suggested that image data augmentation can improve the performance of the CNN model.
- Zubayer Islam, Mohamed Abdel-Aty (2021) suggested that the performance of SVM and logistic regression improves when augmenting collision data with VAE.
  - ▶ VAE with predicted loss function: Development of a VAE model that increases predictive performance by adding a predictive loss function in addition to two existing VAE loss functions.



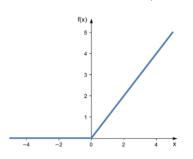
- input: $x_i \to q_\phi(x) \to \mu_i, \sigma_i$
- $\bullet$   $\mu_i, \sigma_i, \epsilon_i \rightarrow z_i$
- $z_i \to g_{\theta}(z) \to p_i$ : output



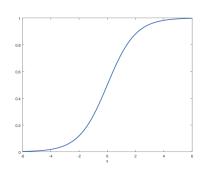


- $z^{i,l} \sim N(\mu_i, \sigma_i^2 I) \Rightarrow z^{i,l} = \mu_i + \sigma_i^2 \odot \epsilon$
- $\epsilon \sim N(0, I)$  same distribution! but it makes backpropagation possible

- RELU:  $R(x) = \max(0, x)$
- sigmoid:  $\sigma(x) = \frac{1}{1+e^{-x}}$



Relu



Sigmoid

#### Loss Function

- Data likelihood:  $p_{\theta}(x) = \int p_{\theta}(z)p_{\theta}(x|z)dz$  (intractable)
- Posterior density also intractable:  $p_{\theta}(z|x) = \frac{p_{\theta}(x|z)p_{\theta}(z)}{p_{\theta}(x)}$

• 
$$\log p_{\theta}(x^{(i)}) = E_{z \sim q_{\phi}(z|x^{(i)})} \left[ \log p_{\theta}(x^{(i)}) \right]$$
  

$$= E_{Z} \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right]$$

$$= E_{z} \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \frac{q_{\phi}(z|x^{(i)})}{q_{\phi}(z|x^{(i)})} \right]$$

$$= E_{z} \left[ \log p_{\theta}(x^{(i)}|z) \right] - E_{z} \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] + E_{z} \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right]$$

$$= E_{z} \left[ \log p_{\theta}(x^{(i)}|z) \right] - D_{KL} \left( q_{\phi}(z|x^{(i)}) ||p_{\theta}(z)) + D_{KL} \left( q_{\phi}(z|x^{(i)}) ||p_{\theta}(z) + D_{KL} \left( q_{\phi}(z|x^{(i)}) ||p_{\theta}($$

• 
$$E_z \left[ \log p_\theta(x^{(i)}|z) \right] - D_{KL} \left( q_\phi(z|x^{(i)}) || p_\theta(z) \right) = \pounds(x^i, \theta, \phi)$$

• 
$$D_{KL}(q_{\phi}(z|x^{(i)})||p_{\theta}(z|x^{(i)}) \ge 0$$

$$log p_{\theta}(x^{i}|z) >= \pounds(x^{i}, \theta, \phi)$$

variational lower bound("ELBO")

$$\Rightarrow$$

$$\theta^*, \phi^* = \underset{\theta, \phi}{argmax} \sum_{i=1}^{N} \mathcal{L}(x^{(i)}, \theta, \phi)$$

Training: Maximize lower bound

#### Loss Function

•  $argmin_{\theta,\phi} \sum_{i} -E_{q_{\phi}(z|x_{i})} \left[ log(p(x_{i}|g_{\theta}(z))) \right] + \frac{KL(q_{\phi}(z|x_{i})||p(z))}{kL(q_{\phi}(z|x_{i})||p(z))}$ 

#### reference

$$D_{KL}(N_0||N_1) = \frac{1}{2} \left( tr(\sum_{1}^{-1} \sum_{0}^{-1}) + (\mu_1 - \mu_0) - k + ln\left(\frac{\det \sum_{1}^{-1}}{\det \sum_{0}^{-1}}\right) \right)$$

## $\mathbf{KL}(\mathbf{q}_{\phi}(z|x_i)||p(z))$

$$\begin{split} &\frac{1}{2} \left\{ tr(\sigma_i^2) + \mu_i^T \mu_i - J + ln \frac{1}{\prod_{j=1}^J \sigma_{i,j}^2} \right\} = \\ &\frac{1}{2} \left\{ \sum_{j=1}^J \sigma_{i,j}^2 + \sum_{j=1}^J \mu_{i,j}^2 - J - \sum_{j=1}^J ln(\sigma_{i,j}^2) \right\} = \\ &\frac{1}{2} \sum_{j=1}^J (\mu_{i,j}^2 + \sigma_{i,j}^2 - ln(\sigma_{i,j}^2) - 1) \end{split}$$

$$\begin{split} E_{q_{\phi}(z|x_i)}\left[\log(p_{\theta}(x_i|z))q_{\phi}(z|x_i)dz\right] &= \int \log(p_{\theta}(x_i|z))q_{\phi}(z|x_i)dz \rightarrow \\ \text{monte-carlo technique} &\approx \frac{1}{L}\sum_{z^{i,l}}\log(p_{\theta}\rightarrow(x_i|z^{i,l})) \rightarrow \\ \log(p_{\theta}(x_i|z^i)) & & \end{split}$$

- L is the number of samples for latent vector.
- Usually, L is set to 1 for convenience.

#### [Decoder, likelihood] (gaussian distribution

$$\log(p_{\theta}(x_{i}|z^{i})) = \log(N(x_{i}; \mu_{i}, \sigma_{i}^{2})) = -\sum_{j=1}^{D} \frac{1}{2}log(\sigma_{i,j}^{2}) + \frac{(x_{i,j} - \mu_{i,j})^{2}}{2\sigma_{i,j}^{2}}$$

### For gaussian distribution with identity covariance

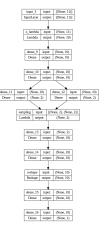
$$\log(p_{\theta}(x_i|z^i)) \propto \sum_{j=1}^{D} (x_{i,j} - \mu_{i,j})^2 (SquaredError)$$



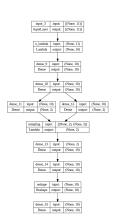


- Reconstruction error:  $-\sum_{i=1}^{D}(x_{i,j}-\mu_{i,j})^2$
- Regularization:  $\frac{1}{2} \sum_{i=1}^{J} (\mu_{i,i}^2 + \sigma_{i,j}^2 \ln(\sigma_{i,j}) 1)$
- Binary cross entropy:  $-\frac{1}{N}\sum_{i=0}^{N} y_i \cdot \log(\hat{y}) + (1-y_i) \cdot \log(1-\hat{y_i})$

#### Variational Autoencoder



(VAE)Prediction



(VAE1)Image Generation



Layer (type)	Output Shape	Param #	Activation function
input_1 (InputLayer)	[(None, 11)]	0	
lambda	(None, 10)	0	
dense	(None, 10)	110	relu
dense_1	(None, 10)	110	relu
dense_2	(None, 2)	22	
dense_3	(None, 2)	22	
concatenate	(None, 4)	0	
lambda_2	(None, 2)	0	
dense_4	(None, 10)	30	relu
dense_5	(None, 10)	110	relu
reshape	(None, 10)	0	
dense_6	(None, 10)	110	sigmoid
dense_7	(None, 1)	11	sigmoid

•0000000000000000

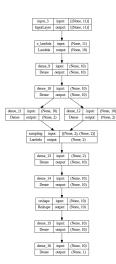
- train data=80000, test data=20000
- $x_1, x_2, x, \cdots, x_{10} \sim U(0, 1)$
- $y = \frac{e^{x_1 + 1.5x_2 + 2x_3 + 2.5x_4 + 0x_5 1x_6 1.5x_7 2x_8 2.5x_9 + 0x_{10}}{1 + e^{x_1 + 1.5x_2 + 2x_3 + 2.5x_4 + 0x_5 1x_6 1.5x_7 2x_8 2.5x_9 + 0x_{10}}$

 data→downsampling data with category 1 at 0.01 ratio→oversampling data with category 1

#### Feed forward neural network

dense_10_input		input:		[(None, 10)]	
InputLayer		output:		[(None, 10)]	
	dense_10	input:		(	None, 10)
	Dense	c	output:		(None, 1)

- set.seed(1)
- data: Oversampling data
- batch size:128, epochs=5
- optimizer:rmsprop, loss='binary crossentropy
- test data [loss:0.5572421] [accuracy: 0.71055]



- 1. Fit the oversampling data to the VAE model.(epochs=1,batch size=160)
- 60 data with category 1 + 20 data generated by VAE1 out of
   60 data + 80 data with category
   0 → 107200 total data
- 3. Fitting the entire data to the FFN.(epochs=10,batch size=160)
- 4. Repeat the above process for the number of epochs

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.1)

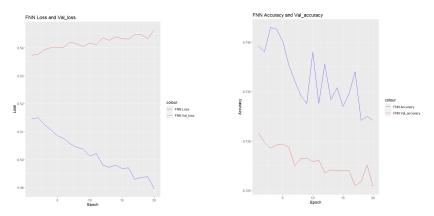


Figure: FNN loss and accuracy

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.1)

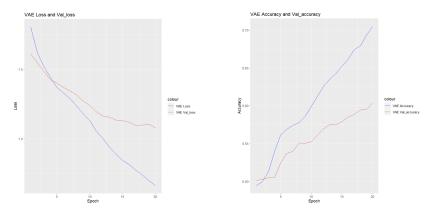


Figure: VAE loss and accuracy

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.0)

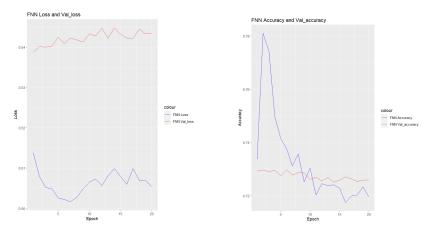


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• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.0)

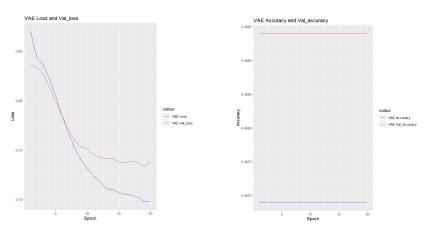


Figure: VAE loss and accuracy



• loss function weight: (xent loss:0),(kl loss:0.),(p loss:1.0)

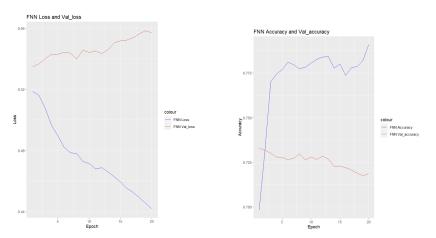


Figure: FNN loss and accuracy



• loss function weight: (xent loss:0),(kl loss:0.0),(p loss:1.0)

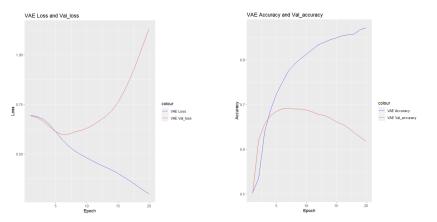
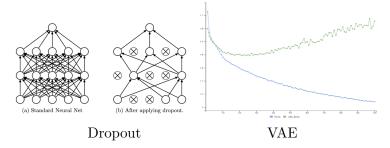


Figure: VAE loss and accuracy



### Dropout

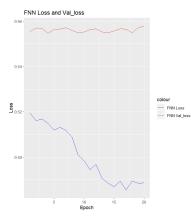
• Nitish Srivastava(2014) suggested that randomly drop units (along with their connections) from the neural reduces overfitting and gives major improvements over other regularization methods. network during training.



input\_9 input: [(None, 11)] InputLeyer output: [(None, 11)] lambda\_24 input: (None, 11) Lambda output (Now, 9) dense\_32 input: (Nose, 9)
Dense output: (Nose, 20) dropost\_16 input (None, 20)
Dropost output (None, 20) deuse\_33 input (Norse, 20) Deuse output (Norse, 20) dropout\_17 lopu: (Nose, 20) Dropout cutput: (Nose, 20) desse 34 | Igost | (Nose, 20) | desse 35 | Igost | (Nose, 20) Dense curput: (Nose, 36) Dense curput: (Nose, 36) Lambda output (None, 30) dense\_36 input (None, 30) Dense output (None, 20) dense\_37 input (None, 20)
Dense output (None, 20) reshape input: (None, 20) Beshape susput: (None, 20) dense\_38 input (None, 20) Dense output (None, 16) | dense\_38 | input: (None, 16) | Dense | output: (None, 1

- 1. Fit the oversampling data to the VAE model(Models with drop out added)(epochs=2,batch size=160).
- 2. Category 1 data + Category 0 data + Data generation from VAE1: (Data with VAE predictive probability close to 0.5) + Data with category 0 matched categories of 1.
  - 3. Fit the entire data to the FFN.(epochs=7,batch size=160)
  - 4. Repeat the above process for the number of epochs.

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:1.0)



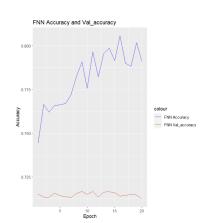


Figure: FNN loss and accuracy

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:1.0)

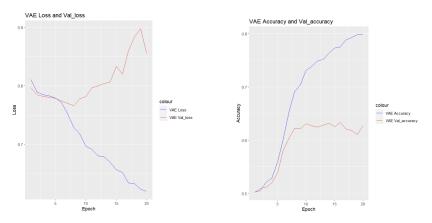
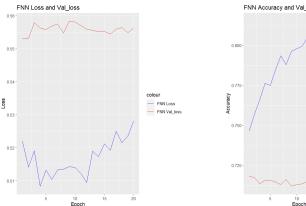


Figure: VAE loss and accuracy

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.0)



FNN Accuracy and Val accuracy colour FNN Accuracy ENN Val. accuracy

Figure: FNN loss and accuracy

• loss function weight: (xent loss:1),(kl loss:-0.5),(p loss:0.0)

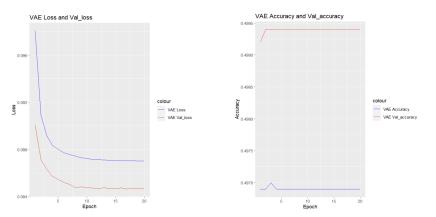


Figure: VAE loss and accuracy

• loss function weight: (xent loss:0),(kl loss:0.0),(p loss:1.0)

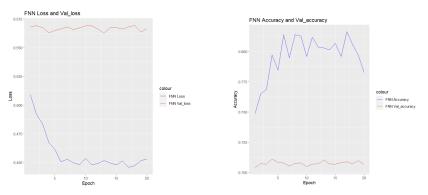


Figure: FNN loss and accuracy

• loss function weight: (xent loss:0),(kl loss:0.),(p loss:1.0)

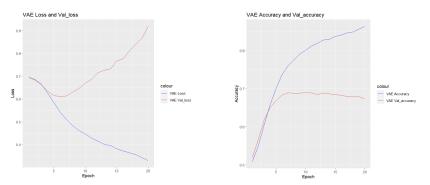


Figure: VAE loss and accuracy

# Future study

- Finding a way to improve the model by adjusting various factors in the vae model.
- When the performance of the model improves, the model is applied to bankrupcy data or credit card data.
- applying the model not only to two-dimensional data but also to three-dimensional data.
- Checking performance by fitting models that determine multiple categories instead of two categories

#### References

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