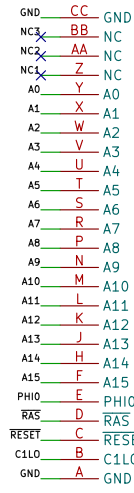
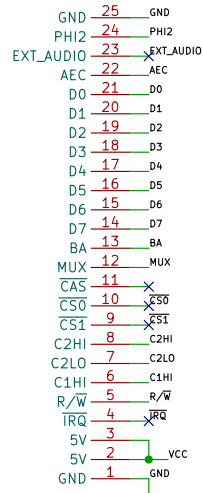


CC=bottom left

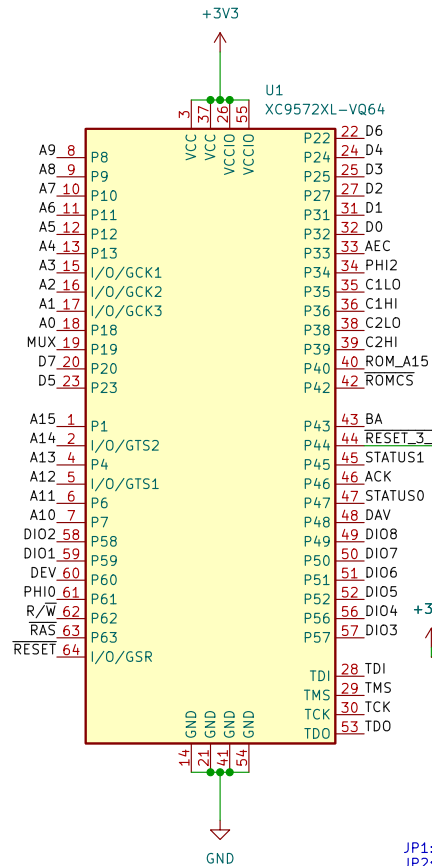
25=top left



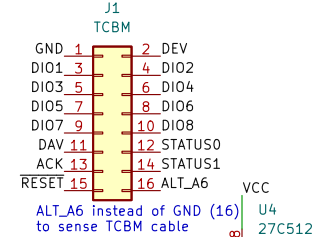
A=bottom right



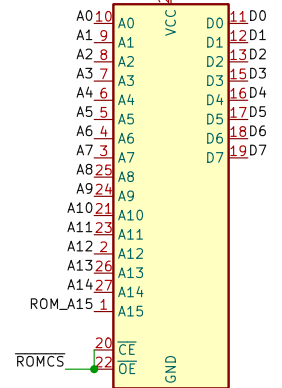
1=top right



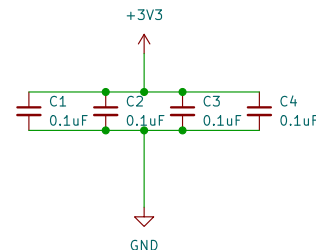
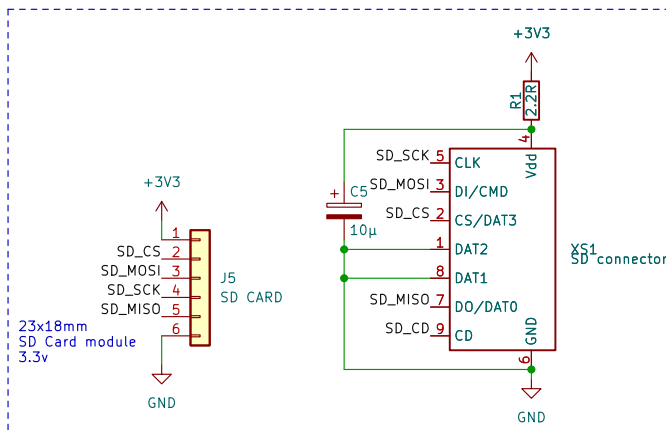
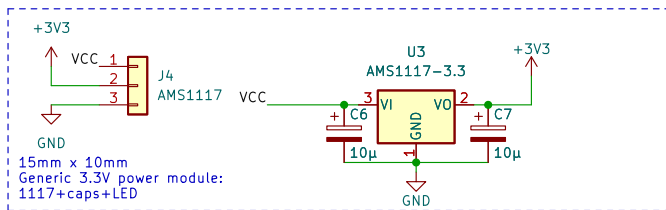
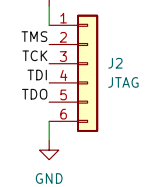
NOTE: ACK here is controller's ACK output and goes to cable pin 13 (drive's DAV input)
NOTE: DAV here is controller's DAV input and goes to cable pin 11 (drive's ACK output)



ALT_A6 instead of GND (16) to sense TCBM cable



64K: \$0000-\$7FFF = ROM C2
\$8000-\$FFFF = ROM C1
32K: \$0000-\$7FFF = ROM C1



JP1: pass computer reset to Arduino
JP2: select h/w DEV #9 (1-2) or #8 (2-3)
JP3: select s/w DEV from A4 (1-2) or D1 (2-3)
JP4: select s/w DEV (1-2) or h/w DEV (2-3)

A7 shorted to GND at RESET = disable buttons (A6 won't be checked)
else:
A6 shorted to GND at RESET = disable Arduino
A6 shorted to GND at RESET = enable TCBM conn
(A6 can be shorted by TCBM cable or by holding SW1)
SW1/SW2 option for next/previous disk image (autolist)

Maciej Witkowiak <ytm@elysium.pl>

YTM Enterprises

Sheet: /

File: tcbm2sd.kicad_sch

Title: tcbm2sd

Size: A4 Date: 2024-10-01

KiCad E.D.A. kicad (6.0.11)

Rev: 1.3

Id: 1/1