

derive new features.

$$h_0(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$$

$x_1$  frontage  
 $x_2$  depth

$$\text{Area} = x_1 \times x_2$$

$$h_0(x) = \theta_0 + \theta_1 \text{Area}$$

might be a better feature.

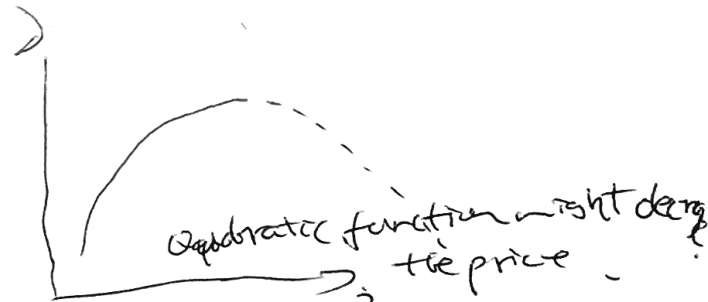
poly regression.

~~size~~

$$h_0(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3$$

$$= \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3$$

size = 1000<sup>2</sup>  
size = 1000<sup>3</sup>  
size = 1000<sup>3</sup>  
size feature !!!



$$\theta_0 + \theta_1 x + \theta_2 x^2$$

$$\theta_0 + \theta_1 x + \theta_2 \sqrt{x}$$

could be better.

Normal Equation.

$$J(\theta) = a\theta^2 + b\theta + c$$



$$\text{Set } \frac{dJ(\theta)}{d\theta} = 0$$

solve for  $\theta$ .

$$\frac{\partial J(\theta)}{\partial \theta_j} = 0 \text{ for every } j.$$

solve for  $\theta_0, \theta_1, \dots, \theta_n$ .

$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$y$

$$X = \begin{bmatrix} x_0^1 & x_1^1 & x_2^1 & x_3^1 & x_4^1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_0^m & x_1^m & x_2^m & x_3^m & x_4^m \end{bmatrix}$$

$$y = \begin{bmatrix} y_1^1 \\ y_2^1 \\ \vdots \\ y_m^1 \end{bmatrix} \begin{matrix} \text{not 1.} \\ m. \end{matrix}$$

$$\theta = (X^T X)^{-1} X^T y.$$

No need for feature scaling

\* compare AD & NE.

AD	NE
choose $\alpha$ . iterate a lot works when $n$ is large. $O(n^2)$	no $\alpha$ . no iteration slow when $n$ is large > 10,000

$$\uparrow$$

$$(X^T X)^{-1} \sim O(n^3)$$

Non invertible  $X^T X$  ?

(1) redundant feature.  
e.g. linearly dependant feature.

(2) ~~delete~~  $m$  is much less than  $n$ . (delete or regularize)