Introduction to Statistical Machine Learning Homework 3

Yota Toyama

November 17, 2016

- 1. A decision tree can classify linearly separable data. A boundary made by such a tree looks like stairs approximating $\mathbf{w}^T\mathbf{x} + w_0 = 0$. And, in the worst case, its depth is $\lceil \log \lceil \frac{N}{2} \rceil \rceil + 1$ because we can separate a space of \mathbf{x} into $\lceil \frac{N}{2} \rceil$ thin regions and balance the tree along \mathbf{x}_1 .
- 2. A decision tree can classify data points which are not linearly separable by separating a space of \mathbf{x} into N thin regions along \mathbf{x}_1 . And, in the worst case, its depth is $\lceil \log N \rceil$ when the tree is balanced in the same way as in the problem 1.

3.

$$\sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T+1)} = \sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} \frac{1}{Z} W_i^{(T)} e^{-\alpha_{T+1} y_i h_{T+1}(\mathbf{x}_i)}$$

$$= \frac{1}{Z} \sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T)} e^{\frac{1}{2} \log \frac{1 - \epsilon_{T+1}}{\epsilon_{T+1}}}$$

$$= \frac{1}{Z} \sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T)} \sqrt{\frac{1 - \epsilon_{T+1}}{\epsilon_{T+1}}}$$

$$= \frac{1}{Z} \sqrt{\frac{1 - \epsilon_{T+1}}{\epsilon_{T+1}}} \sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T)}$$

$$= \frac{\sqrt{\epsilon_{T+1}(1 - \epsilon_{T+1})}}{Z}$$

$$Z = e^{-\alpha_{T+1}} (1 - \epsilon_{T+1}) + e^{\alpha_T} \epsilon_{T+1}$$

$$= \sqrt{\frac{\epsilon_{T+1}}{1 - \epsilon_{T+1}}} (1 - \epsilon_{T+1}) + \sqrt{\frac{1 - \epsilon_{T+1}}{\epsilon_{T+1}}} \epsilon_{T+1}$$

$$= 2\sqrt{\epsilon_{T+1} (1 - \epsilon_{T+1})}$$

$$\therefore \sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T+1)} = \frac{1}{2}$$

Assume $h_{T+2} = h_{T+1}$.

$$\sum_{i \text{ s.t. } y_i \neq h_{T+1}(\mathbf{x}_i)} W_i^{(T+1)} = \frac{1}{2}$$

$$\sum_{i \text{ s.t. } y_i \neq h_{T+2}(\mathbf{x}_i)} W_i^{(T+1)} = \frac{1}{2}$$

$$\epsilon_{T+2} = \frac{1}{2}$$

$$\epsilon_{T+2} \geq \frac{1}{2}$$

 $\therefore h_{T+2} \neq h_{T+1}$

4.

$$\frac{\partial}{\partial \alpha_t} L(H_t, X) = 0$$

$$\frac{\partial}{\partial \alpha_t} \left(e^{-\alpha_t} (1 - \epsilon_t) + e^{\alpha_t} \epsilon_t \right) = 0$$

$$-e^{-\alpha_t} (1 - \epsilon_t) + e^{\alpha_t} \epsilon_t = 0$$

$$e^{2\alpha_t} = \frac{1 - \epsilon_t}{\epsilon_t}$$

$$\alpha_t = \frac{1}{2} \log \frac{1 - \epsilon_t}{\epsilon_t}$$

5.

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^{N} \max \left\{ 0, 1 - y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) \right\}$$

$$\max_{\mathbf{w}, \xi} -\frac{1}{2} \|\mathbf{w}\|^2 - C \sum_{i=1}^{N} \xi_i$$

$$\Leftrightarrow \begin{cases} y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) - 1 + \xi_i \ge 0 \\ \xi_i \ge 0 \end{cases}$$

Using Langrange multipliers,

$$\min_{\alpha,\mu} \max_{\mathbf{w},\xi} -\frac{1}{2} \|\mathbf{w}\|^2 - C \sum_{i=1}^N \xi_i + \sum_{i=1}^N \alpha_i \left(y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) - 1 + \xi_i \right) + \sum_{i=1} \mu_i \xi_i$$

$$\Leftrightarrow \begin{cases}
y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) - 1 + \xi_i \ge 0 \\
\xi_i \ge 0 \\
\alpha_i \ge 0 \\
\mu_i \ge 0 \\
\alpha_i (y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) - 1 + \xi_i) = 0 \\
\mu_i \xi_i = 0
\end{cases}$$
Let $L = -\frac{1}{2} \|\mathbf{w}\|^2 - C \sum_{i=1}^N \xi_i + \sum_{i=1}^N \alpha_i \left(y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + w_0) - 1 + \xi_i \right) + \sum_{i=1}^N \mu_i \xi_i.$

$$\frac{\partial L}{\partial \mathbf{w}} = -\mathbf{w} + \sum_{i=1}^N \alpha_i y_i \phi(\mathbf{x}_i) = 0$$

$$\frac{\partial L}{\partial w_0} = \sum_{i=1}^N \alpha_i y_i = 0$$

$$\begin{split} L &= -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) + \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{x}_{j}) - \sum_{i=1}^{N} \alpha_{i} \alpha_{i} \alpha_{i} \alpha_{j} y_{i} y_{j} \phi(\mathbf{x}_{i}) \phi(\mathbf{$$

 $\frac{\partial L}{\partial \xi} = -C + \alpha_i + \mu_i = 0$

 \therefore The resulting optimization problem is the below.

$$\min_{\alpha} \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j y_i y_j \phi(\mathbf{x}_i) \phi(\mathbf{x}_j) - \sum_{i=1}^{N} \alpha_i$$

$$\begin{cases} 0 \le \alpha_i \le C & \because \alpha_i = C - \mu_i \land \mu_i \ge 0 \\ \sum_{i=1}^{N} \alpha_i y_i = 0 \end{cases}$$

 \therefore The parameters $H, \mathbf{f}, A, \mathbf{a}, B, \mathbf{b}$ of an equivalent quadratic problem are

the below.

$$H = \begin{bmatrix} y_1 y_1 \phi(\mathbf{x}_1) \phi(\mathbf{x}_1) & \cdots & y_1 y_N \phi(\mathbf{x}_1) \phi(\mathbf{x}_N) \\ \vdots & \ddots & \vdots \\ y_N y_1 \phi(\mathbf{x}_N) \phi(\mathbf{x}_1) & \cdots & y_N y_N \phi(\mathbf{x}_N) \phi(\mathbf{x}_N) \end{bmatrix}$$

$$\mathbf{f} = -\begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \\ -1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & -1 \end{bmatrix}$$

$$\mathbf{a} = \begin{bmatrix} C \\ \vdots \\ C \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$B = \begin{bmatrix} y_1 & \cdots & y_N \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} 0 \end{bmatrix}$$

6. Please, see a Jupyter notebook file submitted together.

References

- [1] Christopher M. Bishop, Pattern Recognition and Machine Learning
- [2] Discussion with Tomoki Tsujimura and Bowen Shi