

Learning to Price Vehicle Service with Unknown Demand

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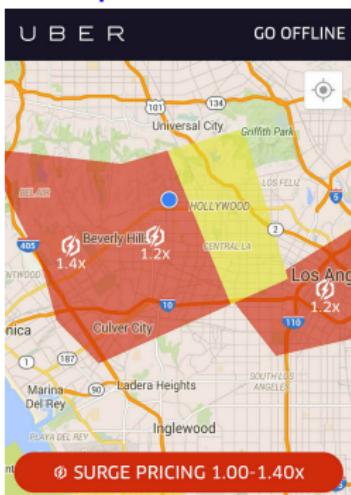
Problem

Location-Based Vehicle Service Pricing

- People use vehicle service offered by ride-sharing platforms.



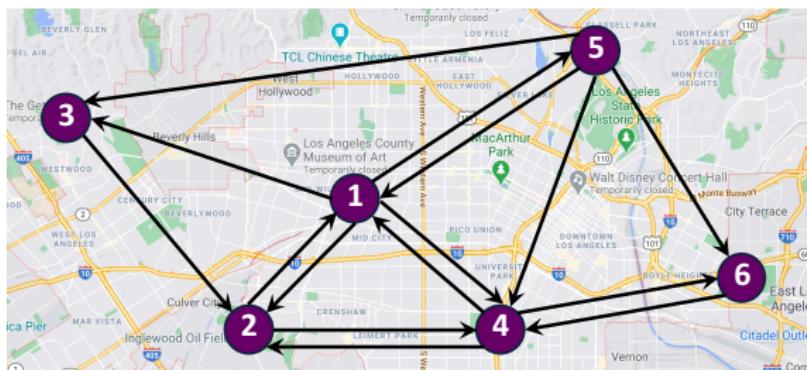
- **Location-based pricing:** It depends on origin-destination pairs.
 - **Purpose:** Balance demand and supply.



Example of origin-based charge:
price=standard price \times multiplier

Location-Based Vehicle Service Pricing

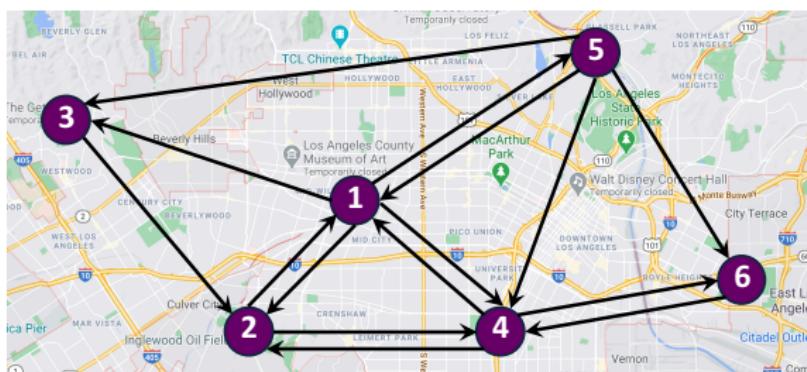
- We introduce a traffic graph to illustrate location-based pricing.
 - Node: location, link: traffic demand.



- Provider sets different vehicle service prices for different links. Let p_{ij} be the price for link (i, j) (i : origin; j : destination).
 - e.g., $p_{13} = \$1/\text{minute}$.
 - Can be converted to $\$/\text{mile}$ based on vehicle velocity.
- For each link (i, j) , actual demand changes with p_{ij} .

Location-Based Vehicle Service Pricing

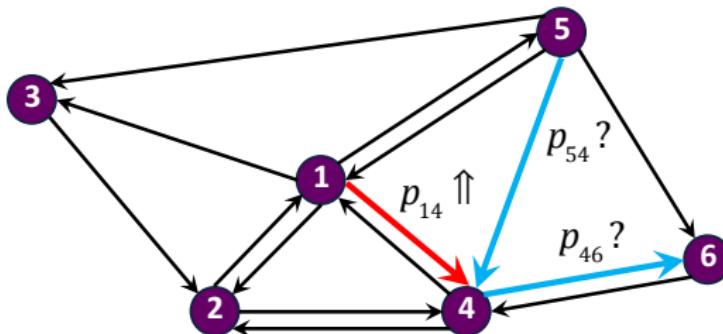
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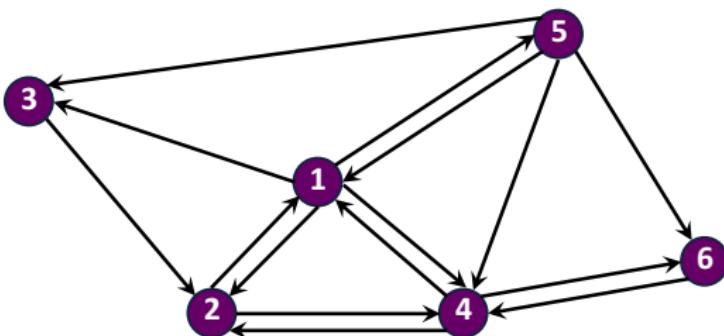
Location-Based Vehicle Service Pricing

- Optimal pricings for links are **coupled** due to vehicle flow balance.



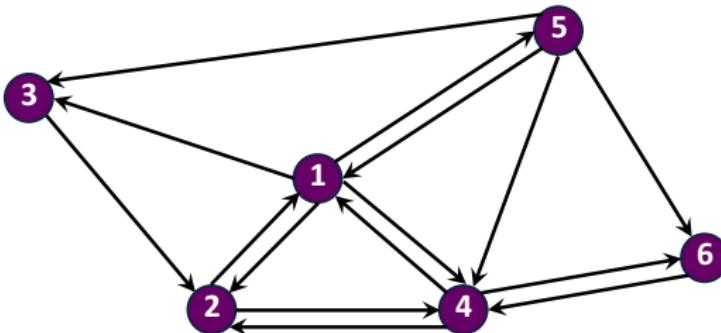
- Example:** Suppose p_{14} increases. How should provider change other prices?
 - Increase** p_{46} : to save supply at node 4.
 - Decrease** p_{54} : to increase supply at node 4.
- Provider needs to jointly optimize p_{ij} for different links.

Challenge of Unknown Demand



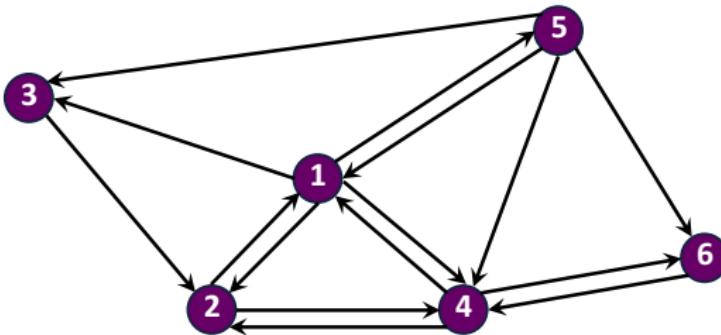
- If mapping from **price** to **demand** is **known**:
 - **Example:** If $p_{12} = 2$, demand = 100; If $p_{12} = 4$, demand = 50.
 - Given all parameters and topology, can calculate p_{ij}^* for all (i, j) .

Challenge of Unknown Demand



- If mapping from price to demand is unknown:
 - Example: If $p_{12} = 2$, demand =? If $p_{12} = 4$, demand =?
 - Intuitive solution: (i) test many prices $p_{ij}^1, p_{ij}^2, \dots$ to learn mapping; (ii) derive optimal prices based on learned mapping.
 - Challenge: If do not choose $p_{ij}^1, p_{ij}^2, \dots$ carefully, the provider's payoff at initial stage is low.

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Our Work

- Consider a **simplified** model with a **monopolistic** provider.
- Design an online pricing policy:
 - (i) Can **learn** accurate user demand for each (i, j) ;
 - (ii) Achieve **asymptotically-optimal** provider long-term payoff.

Related Work

- Prior work on **vehicle service pricing**: [Banerjee *et al.* 2015], [Banerjee *et al.* 2016], [Ma *et al.* 2018], [Bimpikis *et al.* 2019], [Yu *et al.* 2019] etc.
 - **Our work:** Consider **unknown** user demand.
- Prior work on **pricing with unknown demand**: [Besbes and Zeevi 2009], [Broder and Rusmevichientong 2012], [Den Boer and Zwart 2013] [Keskin and Zeevi 2014] [Khezeli and Bitar 2017] etc.
 - **Our work:** Consider **vehicle service**, where prices for links are coupled due to vehicle flow balance.
- Prior work on **multi-armed bandit problem**: [Berry and Fristedt 1985], [Kleinberg 2005], [Vermorel and Mohri 2005], [Wang and Huang 2018] etc.
 - **Our work:** Consider an **infinite decision space**.

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Model

User Demand

- A **monopolistic** provider offers service on day $d = 1, 2, \dots$
- Let p_{ij}^d be service price for (i, j) on d -th day (**\$ per time slot**).
- Realized user demand on (i, j) is

$$\Psi_{ij}^d \left(p_{ij}^d, \epsilon_{ij}^d \right) = \alpha_{ij} - \beta_{ij} p_{ij}^d + \epsilon_{ij}^d.$$

- α_{ij} and β_{ij} are positive parameters that are **unknown** to provider and need to be learned.
- ϵ_{ij}^d is a zero-mean i.i.d. random variable, capturing **demand shock**. Provider only knows its distribution.
- On each day, provider can **only observe** $\Psi_{ij}^d \left(p_{ij}^d, \epsilon_{ij}^d \right)$.
- **Assumptions:** **linear** and **time-invariant** demand.

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Provider Decisions and Constraints

- p_{ij}^d : service price for (i, j) (\$ per time slot).
 - Should satisfy $p_{ij}^d \leq p_{\max}$, e.g., due to government regulation.
- w_{ij}^d : vehicle supply for (i, j) , i.e., mass of vehicles departing from i to j per time slot.
 - Should satisfy $w_{ij}^d \geq 0$ and **vehicle flow balance**:

$$\underbrace{\sum_j w_{ij}^d}_{\text{departure rate}} = \underbrace{\sum_j w_{ji}^d}_{\text{arrival rate}}, \forall i.$$

- This couples the provider's decisions for different links.
- **Assumptions:** full control over vehicles and consideration of system's steady state.

Provider Payoff

- Provider's time-average payoff on day d in the steady state
= user payment per slot - operation cost per slot

$$\Pi(\mathbf{p}^d, \mathbf{w}^d, \epsilon^d) \triangleq \underbrace{\sum_{(i,j)} \xi_{ij} \min \left\{ \Psi_{ij}^d(p_{ij}^d, \epsilon_{ij}^d), w_{ij}^d \right\} p_{ij}^d}_{\text{number of users served on link in any slot}} - \sum_{(i,j)} \xi_{ij} w_{ij}^d c.$$

- ξ_{ij} : travel time from i to j (measured by number of slots).
- c : one vehicle's operation cost per slot.
- $\Psi_{ij}^d(p_{ij}^d, \epsilon_{ij}^d)$: realized demand given price and demand shock.

Provider Target

- Provider should choose \mathbf{p}^d and \mathbf{w}^d in real time to maximize
$$\lim_{D \rightarrow \infty} \mathbb{E} \left\{ \frac{1}{D} \sum_{d=1}^D \Pi(\mathbf{p}^d, \mathbf{w}^d, \epsilon^d) \right\}.$$
 - Expectation is taken with respect to $\epsilon^1, \dots, \epsilon^D$ and the possible randomness in the provider policy.

Performance Metric

- We design a policy under which provider's time-average payoff **converges to** the optimal objective value of following problem:

$$\max \mathbb{E}_{\epsilon^d} \left\{ \Pi \left(\mathbf{p}^d, \mathbf{w}^d, \epsilon^d \right) \right\}$$

$$\text{s.t. } \sum_j w_{ij}^d = \sum_j w_{ji}^d, \forall i,$$

$$w_{ij}^d = \mathbb{E}_{\epsilon_{ij}^d} \left\{ \Psi_{ij}^d \left(p_{ij}^d, \epsilon_{ij}^d \right) \right\}, \forall i, j$$

$$\text{var. } p_{ij}^d \leq p_{\max}, w_{ij}^d \geq 0, \forall i, j.$$

- Intuition:** Optimal payoff when provider **knows** all α_{ij} and β_{ij} .
- Assumption:** local supply-demand balance.

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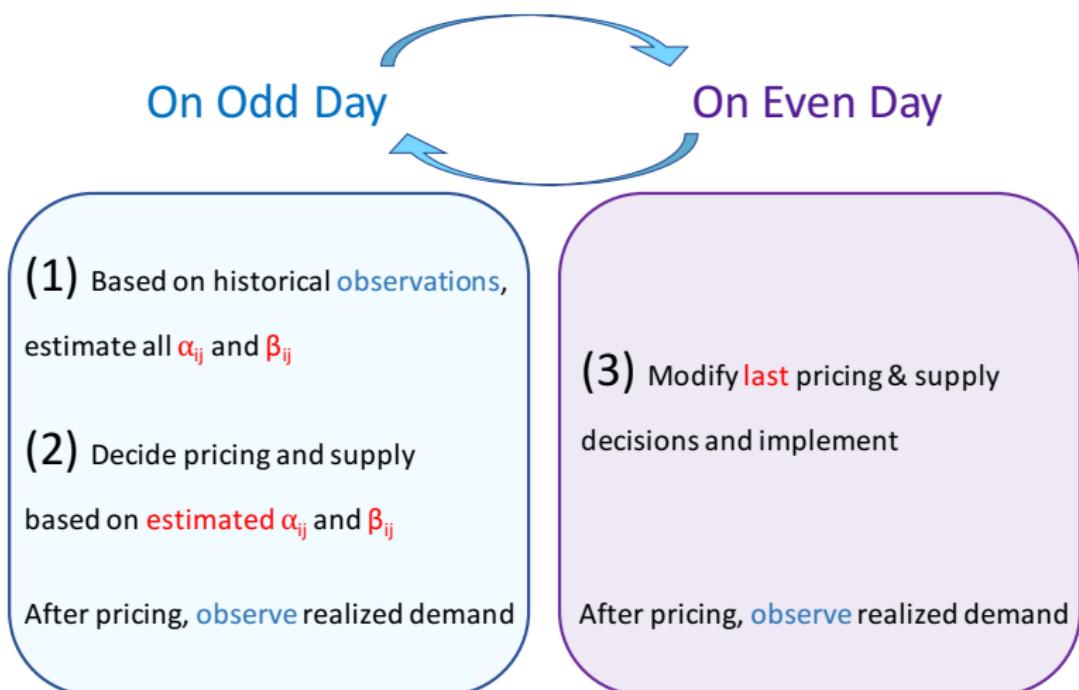
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Our Policy

Our Online Policy



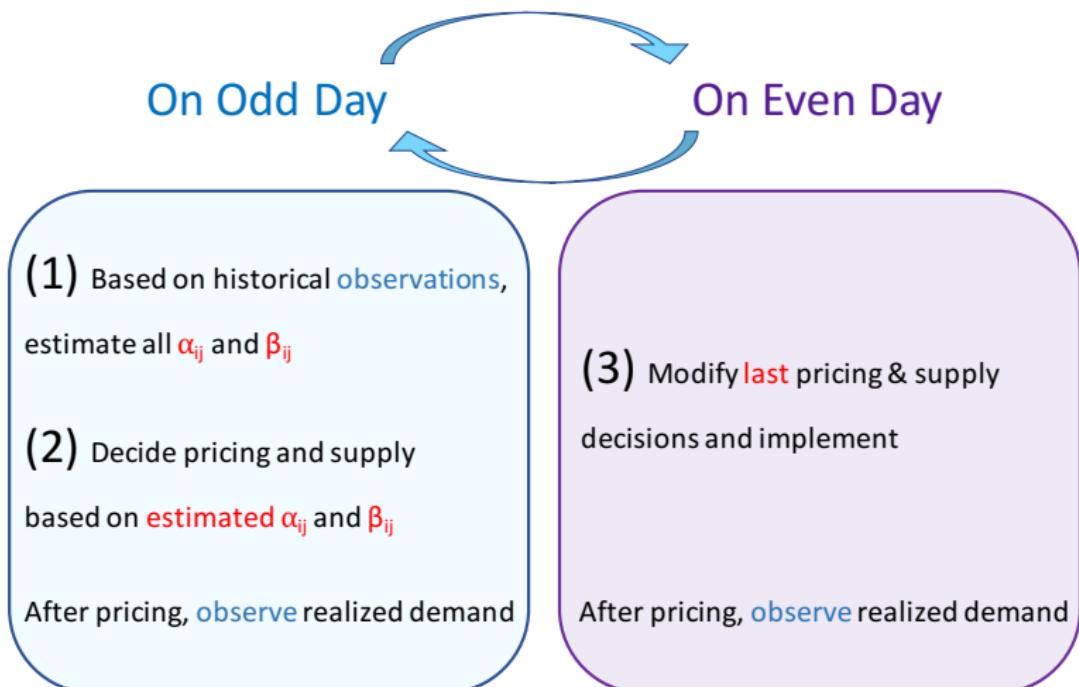
Intuition: balance **exploitation** and **exploration**.

Odd Day: Demand Parameter Estimation

- Given historical observations on demand and pricing, estimate α_{ij} and β_{ij} for each (i, j) by **least squares estimation**:

$$\left(\hat{\alpha}_{ij}^{d-1}, \hat{\beta}_{ij}^{d-1} \right) = \arg \min_{(\bar{\alpha}_{ij}, \bar{\beta}_{ij})} \sum_{\tau=1}^{d-1} \left(\underbrace{\Psi_{ij}^\tau(p_{ij}^\tau, \epsilon_{ij}^\tau)}_{\text{observed demand}} - \underbrace{(\bar{\alpha}_{ij} - \bar{\beta}_{ij} p_{ij}^\tau)}_{\text{demand under estimation}} \right)^2.$$

Odd Day: Pricing Under Estimated Parameters



Odd Day: Pricing Under Estimated Parameters

- Provider makes decisions based on estimated parameters $\hat{\alpha}_{ij}^{d-1}, \hat{\beta}_{ij}^{d-1}$:

$$\max \sum_{(i,j)} \xi_{ij} \mathbb{E}_{\epsilon_{ij}^d} \left\{ \min \left\{ \hat{\alpha}_{ij}^{d-1} - \hat{\beta}_{ij}^{d-1} p_{ij}^d + \epsilon_{ij}^d, w_{ij}^d \right\} \right\} p_{ij}^d - \sum_{(i,j)} \xi_{ij} w_{ij}^d c$$

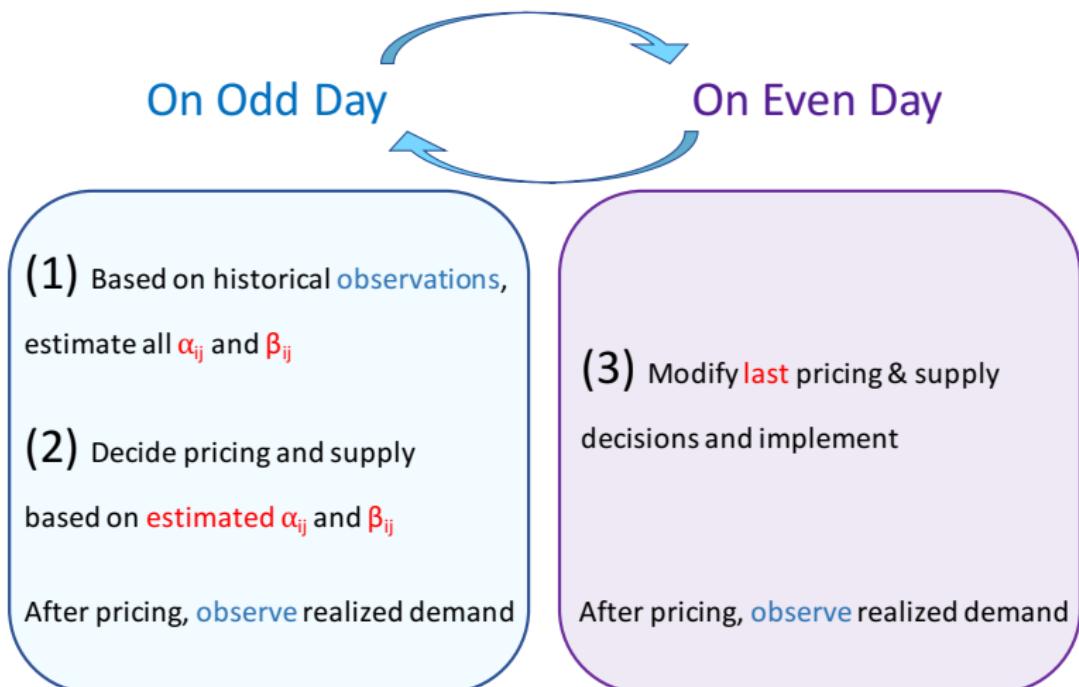
$$\text{s.t. } \sum_j w_{ij}^d = \sum_j w_{ji}^d, \forall i, \text{(vehicle flow balance)}$$

$$w_{ij}^d = \hat{\alpha}_{ij}^{d-1} - \hat{\beta}_{ij}^{d-1} p_{ij}^d, \forall i, j, \text{(local supply demand balance)}$$

$$\text{var. } p_{ij}^d \leq p_{\max}, w_{ij}^d \geq 0, \forall i, j.$$

- After rearrangement, can show problem is convex.

Even Day: Pricing Under Estimated Parameters



Even Day: Modify Odd Day's Decisions

- Let $p_{ij}^*(\hat{\alpha}^{d-2}, \hat{\beta}^{d-2})$ and $w_{ij}^*(\hat{\alpha}^{d-2}, \hat{\beta}^{d-2})$ be the decisions on odd day $d - 1$.
- On each even day d , for each (i, j) :
 - Implement $p_{ij}^*(\hat{\alpha}^{d-2}, \hat{\beta}^{d-2}) - \frac{\rho}{\hat{\beta}_{ij}^{d-2}} d^{-\eta}$ as the pricing decision.
 - Implement $w_{ij}^*(\hat{\alpha}^{d-2}, \hat{\beta}^{d-2}) + \rho d^{-\eta}$ as the supply decision.
- $\rho > 0$ and $0 < \eta < \frac{1}{2}$ are controllable parameters.
- Intuition:** Adding offset terms facilitates exploring different prices and learning demand parameters.
- The offset terms decay to zero as d increases.

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Performance

Theoretical Performance: Squared Estimation Error

Theorem

For all $d \geq 5$ and (i, j) :

$$\mathbb{E} \left\{ \| (\hat{\alpha}_{ij}^{d-1}, \hat{\beta}_{ij}^{d-1}) - (\alpha_{ij}, \beta_{ij}) \|_2^2 \right\} < \Phi_1(\rho, \eta) \frac{\ln(d-1)}{(d-1)^{1-2\eta}}.$$

The upper bound approaches zero as d goes to infinity.

Theoretical Performance: Time-Average Payoff

Theorem

For all $D > 4 + e^{\frac{1}{1-2\eta}}$:

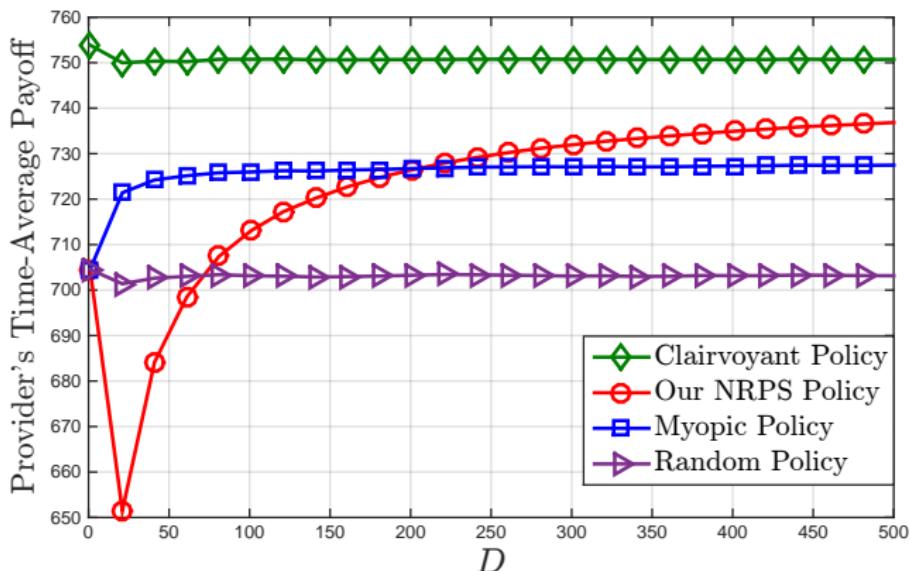
$$\begin{aligned} & \mathbb{E} \left\{ \frac{1}{D} \sum_{d=1}^D \left(\Pi \left(\mathbf{p}^*, \mathbf{w}^*, \epsilon^d \right) - \Pi \left(\mathbf{p}^d, \mathbf{w}^d, \epsilon^d \right) \right) \right\} \\ & < \Phi_2(\rho, \eta) D^{-1} + \Phi_3(\rho, \eta) (\ln D)^{\frac{1}{2}} D^{\eta - \frac{1}{2}} + \Phi_4(\rho, \eta) D^{-\eta}. \end{aligned}$$

The upper bound approaches zero as D goes to infinity.

Numerical Performance

- Real-world dataset (DiDi Chuxing GAIA Open Data Initiative).
- Compare our policy with:
 - **Clairvoyant policy:** make decisions with complete information;
 - **Myopic policy:** choose decisions **without** adding offset terms;
 - **Random policy:** choose decisions based on randomly guessed parameters.
- Can see our paper for comparison with more policies (e.g., perturbed myopic policy).

Numerical Performance



Controllable parameters in our policy: $\rho = 2$ and $\eta = 0.45$.

Conclusion

- Conclusion

- Propose an effective online pricing and supply policy that balances **exploitation** and **exploration**.

- Future directions

- Consider **driver side compensation** design and learn drivers' willingness to work.
- Use closed-queueing network to model users' **stochastic demand**.

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