

A Nonlinear PID-Incorporated Adaptive Stochastic Gradient Descent Algorithm for Latent Factor Analysis: Supplementary File

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This is the supplementary file for the paper entitled *A Nonlinear PID-Incorporated Adaptive Stochastic Gradient Descent Algorithm for Latent Factor Analysis*. It mainly contains the convergence analysis of an ANPS-based LFA model.

SUPPLEMENTARY CONVERGENCE ANALYSIS

1) Proof of Lemma 1

By replacing x_m in $\mathcal{E}_{m,n}$ with arbitrary vectors x_g and x_h which are independent of each other, we have:

$$\begin{aligned} & \nabla \mathcal{E}_{m,n} x_g - \nabla \mathcal{E}_{m,n} x_h \\ &= x_g - x_h y_n^T y_n + \lambda I_f, \\ & \Rightarrow \left\| \nabla \mathcal{E}_{m,n} x_g - \nabla \mathcal{E}_{m,n} x_h \right\|_2 \leq \left\| x_g - x_h \right\|_2 \left\| y_n^T y_n + \lambda I_f \right\|_2. \end{aligned} \quad (S1)$$

Note that $\left\| y_n^T y_n + \lambda I_f \right\|$ is $y_n^T y_n + \lambda I_f$'s largest singular value according to L_2 -norm's property. So **Lemma 1** holds. \square

Lemma 2. $\mathcal{E}_{m,n}$ is strongly convex if δ is the minimum singular value of $y_n^T y_n + \lambda I_f$.

2) Proof of Lemma 2

Given arbitrary vectors x_g and x_h , we consider the state of $\mathcal{E}_{m,n}$ at x_h following the principle of Taylor-series as:

$$\begin{aligned} \mathcal{E}_{m,n} x_g &\approx \mathcal{E}_{m,n} x_h + \nabla \mathcal{E}_{m,n} x_h x_g - x_h^T \\ &\quad + \frac{1}{2} x_g - x_h \nabla^2 \mathcal{E}_{m,n} x_h x_g - x_h^T, \\ &\Rightarrow \mathcal{E}_{m,n} x_g - \mathcal{E}_{m,n} x_h = \nabla \mathcal{E}_{m,n} x_h x_g - x_h^T \\ &\quad + \frac{1}{2} x_g - x_h \nabla^2 \mathcal{E}_{m,n} x_h x_g - x_h^T. \end{aligned} \quad (S2)$$

Recall **Definition 4**, the instant objective $\mathcal{E}_{m,n}$'s strong-convexity satisfies the following condition:

$$\mathcal{E}_{m,n} x_g - \mathcal{E}_{m,n} x_h \geq \nabla \mathcal{E}_{m,n} x_h x_g - x_h^T + \frac{1}{2} \delta \left\| x_g - x_h \right\|_2^2. \quad (S3)$$

Hence, δ is desired to make the following condition hold:

$$x_g - x_h \nabla^2 \mathcal{E}_{m,n} x_h x_g - x_h^T \geq \delta \left\| x_g - x_h \right\|_2^2. \quad (S4)$$

From the expression of $\mathcal{E}_{m,n}$, we achieve:

$$\nabla^2 \mathcal{E}_{m,n} x_h = y_n^T y_n + \lambda I_f. \quad (S5)$$

Thus, we achieve the following equation:

$$\underbrace{x_g - x_h}_a \underbrace{y_n^T y_n + \lambda I_f - \delta I_f}_b \underbrace{x_g - x_h^T}_c \geq 0, \quad (S6)$$

which is equivalent to prove that part (b) of (S6) is a positive semi-definite matrix. As unveiled by [50, 51], part (b) is a positive semi-definite matrix if δ is the minimum singular value of matrix $y_n^T y_n + \lambda I_f$. Thus, **Lemma 2** holds. \square

3) Proof of Theorem 1

Considering the ι -th training iteration, $\forall r_{m,n} \in \Lambda$ and $j \in \{1, \dots, J\}$, x_m is updated with the following scheme:

$$x_{j\ m}^\kappa \leftarrow x_{j\ m}^{\kappa-1} - \eta \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1}, \quad (S7)$$

where $x_{j\ m}^\kappa$ denotes $x_{(j)m}$'s state after its κ -th update point.

Assume that x_m^* is the local optimal state of x_m , then we have:

$$\begin{aligned} \left\| x_{j\ m}^\kappa - x_m^* \right\|_2^2 &= \left\| x_{j\ m}^{\kappa-1} - \eta \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1} - x_m^* \right\|_2^2 \\ &= \left\| x_{j\ m}^{\kappa-1} - x_m^* \right\|_2^2 + \eta^2 \left\| \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1} \right\|_2^2 \\ &\quad - 2\eta \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1} x_{j\ m}^{\kappa-1} - x_m^*{}^T. \end{aligned} \quad (S8)$$

According to **Definition 4** and **Lemma 2**, we have:

$$\begin{aligned} \mathcal{E}_{m,n} x_m^* &\geq \mathcal{E}_{m,n} x_{j\ m}^\kappa + \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1} x_m^* - x_{j\ m}^{\kappa-1}{}^T \\ &\quad + \frac{1}{2} \delta \left\| x_m^* - x_{j\ m}^{\kappa-1} \right\|_2^2. \end{aligned} \quad (S9)$$

Since x_m^* is the optimal state of x_m , we achieve that:

$$\begin{cases} \mathcal{E}_{m,n} x_m^* < \mathcal{E}_{m,n} x_{j\ m}^\kappa, \\ \nabla \mathcal{E}_{m,n} x_m^* = 0. \end{cases} \quad (S10)$$

Based on (S9)-(S10), the following inequality is achieved:

$$\nabla \mathcal{E}_{m,n} (x_{(j)m}^{(\kappa-1)}) (x_{(j)m}^{(\kappa-1)} - x_m^*)^T \geq \frac{1}{2} \delta \left\| x_{(j)m}^{(\kappa-1)} - x_m^* \right\|_2^2. \quad (S11)$$

By combining (S8) and (S11), we infer that:

$$\left\| x_{j\ m}^\kappa - x_m^* \right\|_2^2 < 1 - \eta \delta \left\| x_{j\ m}^{\kappa-1} - x_m^* \right\|_2^2 + \eta^2 \left\| \nabla \mathcal{E}_{m,n} x_{j\ m}^{\kappa-1} \right\|_2^2.$$

(S12)

By taking the expectation of (S12), we further have:

$$\begin{aligned} \mathbb{E} \left[\|x_{j,m}^\kappa - x_m^*\|_2^2 \right] &< 1 - \eta\delta \mathbb{E} \left[\|x_{j,m}^{\kappa-1} - x_m^*\|_2^2 \right] \\ &+ \eta^2 \mathbb{E} \left[\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2^2 \right]. \end{aligned} \quad (\text{S13})$$

Following [49], assume that a positive number p fulfills:

$$\mathbb{E} \left[\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2^2 \right] \leq p^2, \quad (\text{S14})$$

then (S13) is equivalent to:

$$\mathbb{E} \left[\|x_{j,m}^\kappa - x_m^*\|_2^2 \right] < 1 - \eta\delta \mathbb{E} \left[\|x_{j,m}^{\kappa-1} - x_m^*\|_2^2 \right] + \eta p^2. \quad (\text{S15})$$

By making $\eta = \alpha / \delta t$ with $\alpha > 1$, (S15) is reformulated as:

$$\mathbb{E} \left[\|x_{j,m}^\kappa - x_m^*\|_2^2 \right] < \left(1 - \frac{\alpha}{t} \right) \mathbb{E} \left[\|x_{j,m}^{\kappa-1} - x_m^*\|_2^2 \right] + \left(\frac{\alpha}{\delta t} p \right)^2. \quad (\text{S16})$$

By expanding (S16), we achieve the following condition:

$$\mathbb{E} \left[\|x_{j,m}^\kappa - x_m^*\|_2^2 \right] \leq \frac{1}{t} \max \left\{ \|x_{j,m}^1 - x_m^*\|_2^2, \frac{\alpha^2 p^2}{\delta \alpha - 1} \right\}. \quad (\text{S17})$$

where $x_{j,m}^1$ is the initial state of $x_{(j)m}$ at the t -th training iteration.

Since **Lemma 1** indicates that $\varepsilon_{m,n}$ is L -smooth, we achieve the following inference:

$$\begin{aligned} \varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* &\leq \frac{L}{2} \|x_{j,m}^\kappa - x_m^*\|_2^2 \\ \Rightarrow \mathbb{E} \left[\varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* \right] &\leq \frac{L}{2} \mathbb{E} \left[\|x_{j,m}^\kappa - x_m^*\|_2^2 \right]. \end{aligned} \quad (\text{S18})$$

By substituting (S17) into (S18), we achieve that:

$$\mathbb{E} \left[\varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* \right] \leq \frac{LQ}{2t} \alpha, \quad (\text{S19})$$

which satisfies the following condition:

$$Q \alpha = \max \left\{ \|x_{j,m}^1 - x_m^*\|_2^2, \frac{\alpha^2 p^2}{\delta \alpha - 1} \right\}. \quad (\text{S20})$$

Let $\Lambda(m)$ be the subset of Λ related to $m \in M$, then (S19) can be expanded into:

$$\mathbb{E} \left[\sum_{r_{m,n} \in \Lambda(m)} \varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* \right] \leq \frac{|\Lambda(m)| LQ}{2t} \alpha. \quad (\text{S21})$$

Note that we have $\sum_{m \in M} |\Lambda(m)| = |\Lambda|$. So (S21) can be further expanded into:

$$\begin{aligned} &\mathbb{E} \left[\sum_{m \in M} \sum_{r_{m,n} \in \Lambda(m)} \varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* \right] \\ &= \mathbb{E} \left[\sum_{r_{m,n} \in \Lambda} \varepsilon_{m,n} x_{j,m}^\kappa - \varepsilon_{m,n} x_m^* \right] \leq \frac{|\Lambda| LW}{2t} \alpha. \end{aligned} \quad (\text{S22})$$

With (S22) we have $\frac{|\Lambda| LW}{2t} \alpha \rightarrow 0$ when $t \rightarrow \infty$, indicating

the convergence with x_m . Note that the convergence with y_n can be achieved in the same way. Thus, **Theorem 1** holds. \square

4) Proof of Theorem 2

Considering (8), we infer the following expression:

$$\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1} = \lambda \cdot x_{j,m}^{\kappa-1} - e_{m,n}^t \cdot y_{j,n}. \quad (\text{S23})$$

According to the L_2 -norm's properties, we have the following inequality:

$$\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2 \leq \lambda \|x_{j,m}^{\kappa-1}\|_2 + \|e_{m,n}^t \cdot y_{j,n}\|_2. \quad (\text{S24})$$

Since $y_{(j)n}$ is considered as a constant when $x_{(j)m}$ is the active optimization parameter, we can reformulate (S24) as:

$$\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2 \leq \lambda \|x_{j,m}^{\kappa-1}\|_2 + y_{j,n} \|e_{m,n}^t\|_2. \quad (\text{S25})$$

From (S25), we evidently infer that an ANPS-based LFA model converges with the SGD-based learning scheme if

$\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2$ has an upper bound. Hence, to prove **Aspect 2**

is equivalent to prove that $\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2$ has an upper bound after refining the estimation learning error by NPID.

Based on (S14) and (S25), we have the following inference

$$\|x_{j,m}^{\kappa-1}\|_2 \leq \alpha, \quad \|e_{m,n}^t\|_2 \leq \beta; \quad (\text{S26})$$

where α and β are both finite positive numbers. Following (15), after refining the estimation learning error by an NPID controller, (S23) can be reformulated as:

$$\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1} = \lambda \cdot x_{j,m}^{\kappa-1} - \tilde{e}_{j,m,n}^t \cdot y_{j,n}. \quad (\text{S27})$$

And based on the L_2 -norm's properties, (S25) naturally satisfies the following condition:

$$\|\nabla \varepsilon_{m,n} x_{j,m}^{\kappa-1}\|_2 \leq \lambda \|x_{j,m}^{\kappa-1}\|_2 + y_{j,n} \cdot \|\tilde{e}_{j,m,n}^t\|_2. \quad (\text{S28})$$

On the other hand, for conveniently analyzing the convergence of an ANPS-based LFA model, we simplify the NPID-based learning error refinement (15) as:

$$\begin{aligned} \tilde{e}_{j,m,n}^t &= K_{j,p} \cdot e_{j,m,n}^t + K_{j,l} \cdot \sum_{k=0}^t e_{j,m,n}^k \\ &+ K_{j,d} \cdot e_{j,m,n}^t - e_{j,m,n}^{t-1}, \end{aligned} \quad (\text{S29})$$

$$\begin{cases} K_{j,p} = K_{j,p1}^{t-1} + K_{j,p2}^{t-1} (1 - \text{sech } K_{j,p3}^{t-1} e_{j,m,n}^t), \\ K_{j,l} = K_{j,l1}^{t-1} \text{sech } K_{j,l2}^{t-1} e_{j,m,n}^t, \\ K_{j,d} = K_{j,d1}^{t-1} + K_{j,d2}^{t-1} / (1 + K_{j,d3}^{t-1} \exp K_{j,d4}^{t-1} e_{j,m,n}^t). \end{cases} \quad (\text{S30})$$

Note that the value range of $\text{sech}(\cdot)$ lies in $(0, 1)$. Hence, K_p , K_l , and K_d are all finite positive numbers. Considering the L_2 -norm of (S29), we have:

$$\begin{aligned} \|\tilde{e}_{j,m,n}^t\|_2 &= \|K_{j,p} e_{j,m,n}^t \cdot e_{j,m,n}^t\|_2 + \|K_{j,l} e_{j,m,n}^t \cdot \sum_{k=0}^t e_{j,m,n}^k\|_2 \\ &+ \|K_{j,d} e_{j,m,n}^t \cdot e_{j,m,n}^t - e_{j,m,n}^{t-1}\|_2. \end{aligned} \quad (\text{S31})$$

And based on the L_2 -norm's properties, (S31) satisfies the following condition:

$$\begin{aligned} \|\tilde{e}_{j,m,n}^t\|_2 &\leq K_{j,p} \|e_{j,m,n}^t\|_2 \|e_{j,m,n}^t\|_2 + K_{j,l} \|e_{j,m,n}^t\|_2 \left\| \sum_{k=0}^t e_{j,m,n}^k \right\|_2 \\ &+ K_{j,d} \|e_{j,m,n}^t\|_2 \|e_{j,m,n}^t - e_{j,m,n}^{t-1}\|_2, \end{aligned}$$

(S32)

With (S26), we can reformulate (S32) into:

$$\begin{aligned} \left\| \tilde{e}_{j\ m,n}^t \right\|_2 &\leq K_{j\ p} \cdot e_{j\ m,n}^t \cdot \beta + \iota \cdot K_i \cdot e_{j\ m,n}^t \cdot \beta \\ &\quad + 2 \cdot K_d \cdot e_{j\ m,n}^t \cdot \beta. \end{aligned} \quad (\text{S33})$$

Hence, $\left\| \tilde{e}_{j\ m,n}^t \right\|_2$ has an upper bound as:

$$\left\| \tilde{e}_{j\ m,n}^t \right\|_2 \leq \chi, \quad (\text{S34})$$

where χ is a finite positive number. By substituting (S26) and (S34) into (S28), we deduce that:

$$\left\| \nabla_{\mathcal{E}_{m,n}} x_{j\ m}^{\kappa-1} \right\|_2 \leq \lambda \cdot \alpha + y_{j\ n} \cdot \chi. \quad (\text{S35})$$

Hence, there always exists a positive number θ to fulfill:

$$\left\| \nabla_{\mathcal{E}_{m,n}} x_{j\ m}^{\kappa-1} \right\|_2 \leq \theta. \quad (\text{S36})$$

Thus, **Theorem 2** holds. \square