

Solutions to Math 51 Final Exam — August 19, 2023

1. (10 points) Consider the curve defined by the equation

$$(x+1)(x^2+y^2) = 4x^2.$$

Find the rightmost point(s) (i.e., the point(s) with the largest x -coordinate) on the curve.

Remark. This curve is called *conchoid of de Sluze*.

We are trying to maximize $f(x, y) = x$ subject to $g(x, y) = (x+1)(x^2+y^2) - 4x^2 = x^3 - 3x^2 + xy^2 + y^2 = 0$. We compute

$$\nabla f = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \nabla g = \begin{bmatrix} 3x^2 - 6x + y^2 \\ 2xy + 2y \end{bmatrix}.$$

We first check where ∇g vanishes. Setting $\nabla g = \mathbf{0}$, the second equation yields $2y(x+1) = 0$.

- $x = -1$ is impossible since the first equation becomes $y^2 = -9$ which has no solutions.
- If $y = 0$, we get $(0, 0)$ and $(2, 0)$; however $(2, 0)$ is not on the constraint.

Hence, $(0, 0)$ is the only point of interest from checking $\nabla g = \mathbf{0}$.

The Lagrange multiplier equation $\nabla f = \lambda \nabla g$ gives us

$$\begin{aligned} 1 &= \lambda(3x^2 - 6x + y^2) \\ 0 &= \lambda 2y(x+1) \end{aligned}$$

The first equation implies $\lambda \neq 0$. From the second equation, we get either $y = 0$ or $x = -1$.

- $x = -1$ is impossible since plugging this into the constraint gives us $-4 = 0$.
- $y = 0$ leads to $(0, 0)$ and $(3, 0)$. But $(0, 0)$ gives us $1 = 0$ for the first of the two equations, so the only point of interest here is $(3, 0)$.

Between the two points of interest $(0, 0)$ and $(3, 0)$, we see that $f(3, 0) = 3$ is the larger one, and so, $(3, 0)$ is the rightmost point on the curve.

2. (6 points) Find the line of best fit (that minimizes SSE (sum of square errors)) for the data

$$(0, 1), \quad (1, 0), \quad (2, 1), \quad (3, 1), \quad (4, -1).$$

Setting $\mathbf{X} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ and $\mathbf{Y} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ -1 \end{bmatrix}$, we get $\hat{\mathbf{X}} = \mathbf{X} - 2\mathbf{1} = \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$.

Now we compute

$$\mathbf{Proj}_{\mathcal{P}}(\mathbf{Y}) = -\frac{3}{10}\hat{\mathbf{X}} + \frac{2}{5}\mathbf{1} = -\frac{3}{10}(\mathbf{X} - 2\mathbf{1}) + \frac{2}{5}\mathbf{1} = -\frac{3}{10}\mathbf{X} + \mathbf{1}.$$

Thus, the line of best fit is

$$y = -\frac{3}{10}x + 1.$$

3. (10 points) Let $A = \begin{bmatrix} 1 & 1 & 4 \\ -1 & 3 & 2 \\ 0 & 1 & -3 \end{bmatrix}$.

(a) (6 points) Compute a QR -decomposition for A .

Remark. The only irrational entries will involve $\sqrt{2}$.

Let us label the columns of A \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

Setting $\mathbf{w}_1 = \mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$, we compute $\mathbf{Proj}_{\mathbf{w}_1}(\mathbf{v}_2) = \frac{-2}{2}\mathbf{w}_1$. Hence,

$$\mathbf{w}_2 = \mathbf{v}_2 + \mathbf{w}_1 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}.$$

Next, we compute $\mathbf{Proj}_{V_2}(\mathbf{v}_3) = \mathbf{Proj}_{\mathbf{w}_1}(\mathbf{v}_3) + \mathbf{Proj}_{\mathbf{w}_2}(\mathbf{v}_3) = \frac{2}{2}\mathbf{w}_1 + \frac{9}{9}\mathbf{w}_2$. Thus,

$$\mathbf{w}_3 = \mathbf{v}_3 - \mathbf{w}_1 - \mathbf{w}_2 = \begin{bmatrix} 1 \\ 1 \\ -4 \end{bmatrix}.$$

Taking $\mathbf{w}'_1 = \frac{1}{\sqrt{2}}\mathbf{w}_1$, $\mathbf{w}'_2 = \frac{1}{3}\mathbf{w}_2$, and $\mathbf{w}'_3 = \frac{1}{3\sqrt{2}}\mathbf{w}_3$, we get

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{w}_1 &= \sqrt{2}\mathbf{w}'_1 \\ \mathbf{v}_2 &= -\mathbf{w}_1 + \mathbf{w}_2 &= -\sqrt{2}\mathbf{w}'_1 + 3\mathbf{w}'_2 \\ \mathbf{v}_3 &= \mathbf{w}_1 + \mathbf{w}_2 + \mathbf{w}_3 &= \sqrt{2}\mathbf{w}'_1 + 3\mathbf{w}'_2 + 3\sqrt{2}\mathbf{w}'_3. \end{aligned}$$

Therefore, we get

$$A = QR = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{2}{3} & \frac{1}{3\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{2}{3} & \frac{1}{3\sqrt{2}} \\ 0 & \frac{1}{3} & -\frac{4}{3\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & -\sqrt{2} & \sqrt{2} \\ 0 & 3 & 3 \\ 0 & 0 & 3\sqrt{2} \end{bmatrix}.$$

(b) (4 points) Using your results from (a), write down an expression for A^{-1} . You may leave your answer as a product of two matrices.

We get $Q^{-1} = Q^T = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3\sqrt{2}} & \frac{1}{3\sqrt{2}} & -\frac{4}{3\sqrt{2}} \end{bmatrix}$, and R^{-1} must be of the form $\begin{bmatrix} \frac{1}{\sqrt{2}} & \alpha & \beta \\ 0 & \frac{1}{3} & \gamma \\ 0 & 0 & \frac{1}{3\sqrt{2}} \end{bmatrix}$.

$$I_3 = R^{-1}R = \begin{bmatrix} \frac{1}{\sqrt{2}} & \alpha & \beta \\ 0 & \frac{1}{3} & \gamma \\ 0 & 0 & \frac{1}{3\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & -\sqrt{2} & \sqrt{2} \\ 0 & 3 & 3 \\ 0 & 0 & 3\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1 & -1 + 3\alpha & 1 + 3\alpha + 3\sqrt{2}\beta \\ 0 & 1 & 1 + 3\sqrt{2}\gamma \\ 0 & 0 & 1 \end{bmatrix}$$

yields $\alpha = \frac{1}{3}$, $\beta = -\frac{2}{3\sqrt{2}}$, and $\gamma = -\frac{1}{3\sqrt{2}}$. Thus,

$$A^{-1} = R^{-1}Q^{-1} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{3} & -\frac{2}{3\sqrt{2}} \\ 0 & \frac{1}{3} & -\frac{1}{3\sqrt{2}} \\ 0 & 0 & \frac{1}{3\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3\sqrt{2}} & \frac{1}{3\sqrt{2}} & -\frac{4}{3\sqrt{2}} \end{bmatrix} = \frac{1}{18} \begin{bmatrix} 11 & -7 & 10 \\ 3 & 3 & 6 \\ 1 & 1 & -4 \end{bmatrix}.$$

4. (10 points) The kea are alpine parrots native to the South Island of New Zealand. The zoologists observe the following migratory patterns of the kea in three mountain ranges A , B , and C .

Every March,

- 20% of the kea in range A move to range B , 40% to range C , and the rest do not migrate;
- 50% of the kea in range B move to range C , and the rest do not migrate; and
- 30% of the kea in range C move to range A , 20% to range B , and the rest do not migrate.

Every September, for some fixed value of β ,

- 40% of the kea in range A move to range C , and the rest do not migrate;
- 30% of the kea in range B move to range A , and the rest do not migrate; and
- 40% of the kea in range C move to range A , $\beta\%$ to range B , and the rest do not migrate.

Suppose that, in **January 2020**, there are 20,000, 10,000, and 0 kea in ranges A , B , and C , respectively; suppose also that we can safely ignore population changes due to any other factors, including births and deaths.

- (a) (3 points) How many kea are there in range B in **June 2020**?

By analyzing the dynamics of the spring migration, we get the corresponding Markov matrix

$$S = \begin{bmatrix} 0.4 & 0 & 0.3 \\ 0.2 & 0.5 & 0.2 \\ 0.4 & 0.5 & 0.5 \end{bmatrix}.$$

Computing

$$\begin{bmatrix} 0.4 & 0 & 0.3 \\ 0.2 & 0.5 & 0.2 \\ 0.4 & 0.5 & 0.5 \end{bmatrix} \begin{bmatrix} 20000 \\ 10000 \\ 0 \end{bmatrix} = \begin{bmatrix} 8000 & 9000 & 13000 \end{bmatrix},$$

we see there are 9000 kea in range B in June 2020.

- (b) (3 points) If there are 4,500 kea in range C in **January 2021**, what is the value of β ?

By analyzing the dynamics of the fall migration, we get the corresponding Markov matrix

$$F = \begin{bmatrix} 0.6 & 0.3 & 0.4 \\ 0 & 0.7 & \frac{\beta}{100} \\ 0.4 & 0 & 0.6 - \frac{\beta}{100} \end{bmatrix}.$$

Computing

$$\begin{bmatrix} 0.6 & 0.3 & 0.4 \\ 0 & 0.7 & \frac{\beta}{100} \\ 0.4 & 0 & 0.6 - \frac{\beta}{100} \end{bmatrix} \begin{bmatrix} 8000 \\ 9000 \\ 13000 \end{bmatrix} = \begin{bmatrix} \dots \\ \dots \\ 11000 - 130\beta \end{bmatrix},$$

we get $\beta = 50$ from $11000 - 130\beta = 4500$.

- (c) (4 points) Let a_n , b_n , c_n represent the number of kea in mountain ranges A , B , C , respectively, in **June of the n th year after 2020**. (For example, a_1 is the number of kea in mountain range A in **June 2021**, and so on.) Write down a matrix M for which

$$M \begin{bmatrix} a_n \\ b_n \\ c_n \end{bmatrix} = \begin{bmatrix} a_{n+1} \\ b_{n+1} \\ c_{n+1} \end{bmatrix}.$$

If you wish, you may express your matrix M as a product of some fixed number of matrices (each of which contains specific numbers), but without carrying out the actual multiplication.

(Note: if you found the value of the constant β in part (b), you may use this value in your answer; if you did not, you may express one or more entries of your answer for M in terms of β .)

From June of a year to June of the next year, spring migration happens after fall migration. Hence,

$$M = SF = \begin{bmatrix} 0.4 & 0 & 0.3 \\ 0.2 & 0.5 & 0.2 \\ 0.4 & 0.5 & 0.5 \end{bmatrix} \begin{bmatrix} 0.6 & 0.3 & 0.4 \\ 0 & 0.7 & 0.5 \\ 0.4 & 0 & 0.1 \end{bmatrix} = \begin{bmatrix} 0.36 & 0.12 & 0.19 \\ 0.20 & 0.41 & 0.35 \\ 0.44 & 0.47 & 0.46 \end{bmatrix}.$$

Note that M is a Markov matrix, as expected.

5. (14 points) Consider the matrix $A = \begin{bmatrix} a & 0 & 0 \\ 0 & b & c \\ 0 & d & e \end{bmatrix}$, where a, b, c, d, e are real numbers. Define the matrix

$$B = \begin{bmatrix} b & c \\ d & e \end{bmatrix}.$$

- (a) (3 points) Suppose $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ is an eigenvector for B with eigenvalue λ . Show that $\mathbf{v}' = \begin{bmatrix} 0 \\ v_1 \\ v_2 \end{bmatrix}$ and \mathbf{e}_1 are eigenvectors for A , and find their respective eigenvalues.

Since $B\mathbf{v} = \lambda\mathbf{v}$, we get $v_1 \begin{bmatrix} b \\ d \end{bmatrix} + v_2 \begin{bmatrix} c \\ e \end{bmatrix} = \lambda \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$. Hence,

$$A\mathbf{v}' = A \begin{bmatrix} 0 \\ v_1 \\ v_2 \end{bmatrix} = v_1 \begin{bmatrix} 0 \\ b \\ d \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ c \\ e \end{bmatrix} = \begin{bmatrix} 0 \\ \lambda v_1 \\ \lambda v_2 \end{bmatrix} = \lambda \begin{bmatrix} 0 \\ v_1 \\ v_2 \end{bmatrix} = \lambda\mathbf{v}',$$

and $A\mathbf{e}_1 = a\mathbf{e}_1$. Thus, \mathbf{v}' and \mathbf{e}_1 are eigenvectors of A with eigenvalues λ and a , respectively.

For parts (b) – (d) of this problem, consider the matrix $A = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 3 & 2 \\ 0 & 2 & 0 \end{bmatrix}$.

- (b) (4 points) Using the results of part (a), find all the eigenvalues of A and give an eigenvector associated with each eigenvalue. Make sure to verify your answers.

For $B = \begin{bmatrix} 3 & 2 \\ 2 & 0 \end{bmatrix}$, we get $p_B(\lambda) = \lambda^2 - 3\lambda - 4$, and so $\lambda_1 = 4$, $\lambda_2 = -1$. We also find eigenvectors $\mathbf{w}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\mathbf{w}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$.

Using part (a), we see that $\begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}$, and $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ are eigenvectors of A with eigenvalues 4, -1 , and -2 , respectively.

- (c) (3 points) Find a matrix Q and a diagonal matrix D for which $A = QDQ^\top$.

By the spectral theorem,

$$A = QDQ^{-1} = QDQ^\top = \begin{bmatrix} 0 & 0 & 1 \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} & 0 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ 0 & \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ 1 & 0 & 0 \end{bmatrix}.$$

- (d) (4 points) Find a scalar α and a 3×3 matrix L , whose entries are all real numbers (i.e., no n in the entries), for which

$$A^n \approx \alpha^n L$$

for large n .

Using our results from part (c), we get

$$\begin{aligned} A^n &= QD^nQ^T = \begin{bmatrix} 0 & 0 & 1 \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} & 0 \end{bmatrix} \begin{bmatrix} 4^n & 0 & 0 \\ 0 & (-1)^n & 0 \\ 0 & 0 & (-2)^n \end{bmatrix} \begin{bmatrix} 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ 0 & \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ 1 & 0 & 0 \end{bmatrix} \\ &= 4^n \begin{bmatrix} 0 & 0 & 1 \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & (-\frac{1}{4})^n & 0 \\ 0 & 0 & (-\frac{2}{4})^n \end{bmatrix} \begin{bmatrix} 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ 0 & \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ 1 & 0 & 0 \end{bmatrix} \\ &\approx 4^n \begin{bmatrix} 0 & 0 & 1 \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ 0 & \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ 1 & 0 & 0 \end{bmatrix} \\ &= 4^n \begin{bmatrix} 0 \\ \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} \\ &= 4^n \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{4}{5} & \frac{2}{5} \\ 0 & \frac{2}{5} & \frac{1}{5} \end{bmatrix}. \end{aligned}$$

6. (10 points) Let $\mathbf{f}: \mathbf{R}^2 \rightarrow \mathbf{R}^3$ be given by

$$\mathbf{f}(u, v) = \begin{bmatrix} (7 + \cos v) \sin u \\ 2u + \sin v \\ (7 + \cos v) \cos u \end{bmatrix}.$$

The set $\mathbf{f}(\mathbf{R}^2)$ (i.e. image of \mathbf{R}^2 under \mathbf{f}) describes a surface in \mathbf{R}^3 and is in fact the level set of a function $g: \mathbf{R}^3 \rightarrow \mathbf{R}$ at level 13. In particular, this means that $g(\mathbf{f}(u, v)) = 13$ for all $(u, v) \in \mathbf{R}^2$.

- (a) (6 points) Given that

$$(\nabla g)(\mathbf{f}(\pi, \pi/2)) = \begin{bmatrix} 1 \\ \alpha \\ \beta \end{bmatrix},$$

find the values of α and β , using the Multivariate Chain Rule.

We are given that

$$(g \circ \mathbf{f})(u, v) = 13 \quad \text{for all } (u, v) \in \mathbf{R}^2.$$

The right-hand side is a constant independent of both u and v , so

$$(D(g \circ \mathbf{f}))(u, v) = \left[\frac{\partial}{\partial u}(13) \quad \frac{\partial}{\partial v}(13) \right] = [0 \quad 0].$$

In particular, $(D(g \circ \mathbf{f}))(\pi, \pi/2) = [0 \quad 0]$.

Remark: We must calculate $(D(g \circ \mathbf{f}))(u, v)$ first, before evaluating it at $(\pi, \pi/2)$. It is incorrect to evaluate $g \circ \mathbf{f}$ at $(\pi, \pi/2)$ first before taking the derivative.

We can also calculate $(D(g \circ \mathbf{f}))(\pi, \pi/2)$ using the chain rule:

$$(D(g \circ \mathbf{f}))(\pi, \pi/2) = (Dg)(\mathbf{f}(\pi, \pi/2))(D\mathbf{f})(\pi, \pi/2).$$

We have

$$(Dg)(\mathbf{f}(\pi, \pi/2)) = (\nabla g)(\mathbf{f}(\pi, \pi/2))^T = [1 \quad \alpha \quad \beta]$$

and

$$(D\mathbf{f})(\pi, \pi/2) = \left[\begin{array}{cc} (7 + \cos v) \cos u & -\sin v \sin u \\ 2 & \cos v \\ -(7 + \cos v) \sin u & -\sin v \cos u \end{array} \right] \bigg|_{(\pi, \pi/2)} = \left[\begin{array}{cc} -7 & 0 \\ 2 & 0 \\ 0 & 1 \end{array} \right],$$

so the chain rule says

$$(D(g \circ \mathbf{f}))(\pi, \pi/2) = [1 \quad \alpha \quad \beta] \begin{bmatrix} -7 & 0 \\ 2 & 0 \\ 0 & 1 \end{bmatrix} = [-7 + 2\alpha \quad \beta].$$

Equating the two expressions we obtained for $(D(g \circ \mathbf{f}))(\pi, \pi/2)$, we obtain

$$[-7 + 2\alpha \quad \beta] = [0 \quad 0].$$

The first entry tells us $-7 + 2\alpha = 0$, so $\alpha = 7/2$. The second entry tells us $\beta = 0$.

- (b) (2 points) Find the equation of the tangent plane to the surface $\mathbf{f}(\mathbf{R}^2)$ at the point $\mathbf{f}(\pi, \pi/2)$. You may leave your answer in terms of α and β if you have not found them in part (a).

Since

$$\mathbf{f}(\pi, \pi/2) = \begin{bmatrix} 0 \\ 2\pi + 1 \\ -7 \end{bmatrix} \quad \text{and} \quad (\nabla g)(\mathbf{f}(\pi, \pi/2)) = \begin{bmatrix} 1 \\ \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} 1 \\ 7/2 \\ 0 \end{bmatrix} \neq \mathbf{0},$$

then the equation of the tangent plane to $\mathbf{f}(\mathbf{R}^2)$ at the point $\mathbf{f}(\pi, \pi/2)$ is

$$\begin{bmatrix} 1 \\ 7/2 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x - 0 \\ y - (2\pi + 1) \\ z + 7 \end{bmatrix} = 0,$$

i.e.,

$$2x + 7y - 14\pi - 7 = 0,$$

or equivalently, $2x + 7y = 14\pi + 7$.

- (c) (2 points) Give, with justification, a unit vector $\mathbf{v} \in \mathbf{R}^3$ for which the *absolute value* of the change in g at the point $\mathbf{f}(\pi, \pi/2)$ in the direction of \mathbf{v} is minimized. You may leave your answer in terms of α and β if you have not found them in part (a).

When we move away from $\mathbf{f}(\pi, \pi/2)$ along $\mathbf{f}(\mathbf{R}^2)$ (which is the level set of g at level 13), the value taken by g stays at 13 and does not change. This means the absolute value of the change in g as we move away in any direction along $\mathbf{f}(\mathbf{R}^2)$ is zero (the smallest possible non-negative number). Therefore, we are seeking a unit vector parallel to the tangent plane to $\mathbf{f}(\mathbf{R}^2)$ at $\mathbf{f}(\pi, \pi/2)$, i.e. a unit vector orthogonal to

$$(\nabla g)(\mathbf{f}(\pi, \pi/2)) = \begin{bmatrix} 1 \\ 7/2 \\ 0 \end{bmatrix}.$$

One possible candidate for \mathbf{v} is

$$\mathbf{v} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

In general, any vector $\mathbf{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ satisfying $a^2 + b^2 + c^2 = 1$ and $2a = -7b$ would work.

We may also arrive at the same conclusion by seeking to minimize the absolute value of the directional derivative of g in the direction \mathbf{v} (a unit vector) at the point $\mathbf{f}(\pi, \pi/2)$, namely the absolute value of

$$(D_{\mathbf{v}}g)(\mathbf{f}(\pi, \pi/2)) = (\nabla g)(\mathbf{f}(\pi, \pi/2)) \cdot \mathbf{v} = \begin{bmatrix} 1 \\ 7/2 \\ 0 \end{bmatrix} \cdot \mathbf{v}.$$

The absolute value of this is minimized when $\begin{bmatrix} 1 \\ 7/2 \\ 0 \end{bmatrix} \cdot \mathbf{v} = 0$, and we proceed as above.

*Remark: The question asked for a **unit** vector \mathbf{v} , so your vector needs to have length 1.*

7. (10 points) Consider the function

$$f(x, y) = 17x^2 - 8xy + 2y^2 - 10x - 4y - 2.$$

(a) (2 points) Show that f has a unique critical point.

We compute $\nabla f = \begin{bmatrix} 34x - 8y - 10 \\ -8x + 4y - 4 \end{bmatrix}$ and setting $\nabla f = \mathbf{0}$, we get $x = 1$ and $y = 3$. Thus, the unique critical point is $(1, 3)$.

(b) (3 points) By analyzing the Hessian at the critical point, determine whether it is a local maximum, local minimum, or neither.

We compute $Hf(1, 3) = \begin{bmatrix} 34 & -8 \\ -8 & 4 \end{bmatrix}$ and

$$p_{Hf(1,3)}(\lambda) = \lambda^2 - 38\lambda + 72 = (\lambda - 36)(\lambda - 2).$$

Thus, $\lambda_1 = 36$ and $\lambda_2 = 2$, and so, $(1, 3)$ is a local minimum since $Hf(1, 3)$ is positive-definite.

(c) (5 points) Sketch an approximate contour plot of f at the critical point on the coordinate plane provided below.

Sketch qualitatively correct level sets, including justification in terms of the eigenvalues and eigenvectors.

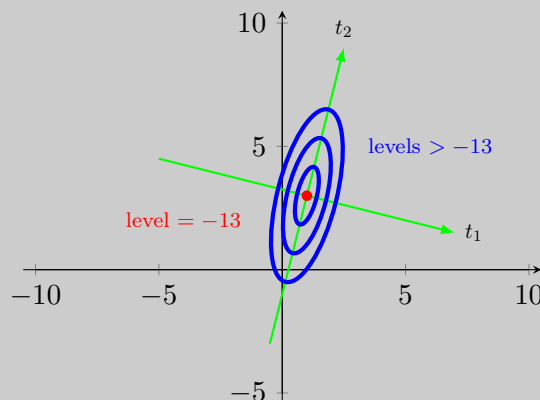
For $\lambda_1 = 36$, $Hf(1, 3) - 36I_2 = \begin{bmatrix} -2 & -8 \\ -8 & -32 \end{bmatrix}$, and so, $\mathbf{w}_1 = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$ is a 36-eigenvector.

For $\lambda_2 = 2$, $Hf(1, 3) - 2I_2 = \begin{bmatrix} 32 & -8 \\ -8 & 2 \end{bmatrix}$, and so, $\mathbf{w}_2 = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$ is a 2-eigenvector.

Taking $\mathbf{w}'_1 = \frac{1}{\sqrt{17}} \begin{bmatrix} 4 \\ -1 \end{bmatrix}$ and $\mathbf{w}'_2 = \frac{1}{\sqrt{17}} \begin{bmatrix} 1 \\ 4 \end{bmatrix}$, for $\mathbf{v} = t_1\mathbf{w}'_1 + t_2\mathbf{w}'_2$, we get

$$q_{Hf(1,3)}(\mathbf{v}) = 36t_1^2 + 4t_2^2,$$

which is positive-definite. The level curves will be ellipses longer in the t_2 direction. Putting all this together, we get the following approximate contour plot of f at $(1, 3)$:



The green level curve is at level $f(1, 3) = -13$, and the blue level curves are at levels greater than $f(1, 3) = -13$.

8. (10 points) For each of the following statements, circle either TRUE (meaning, “always true”) or FALSE (meaning, “not always true”), and briefly and convincingly justify your answer. 1 point for the correct choice, and the rest for convincing justification.

- (a) (5 points) Suppose A is an $m \times n$ matrix with the property $A^T A = 0$. Then, A must be the zero matrix.

Circle one, and justify below:

☒ TRUE

☐ FALSE

Denoting the columns of A by $\mathbf{v}_1, \dots, \mathbf{v}_n$, we have

$$0 = (A^T A)_{ii} = \mathbf{v}_i^T \mathbf{v}_i = \mathbf{v}_i \cdot \mathbf{v}_i = \|\mathbf{v}_i\|^2$$

for all i . Hence, $\|\mathbf{v}_i\| = 0$ for all i , and so, $\mathbf{v}_i = \mathbf{0}$ for all i . Thus, $A = 0$.

- (b) (5 points) If a 2×2 matrix A has characteristic polynomial $P_A(\lambda) = \lambda^2 - \lambda - 2$, then the characteristic polynomial $P_B(\lambda)$ of $B = A^3 - 4A^2 + 7I_2$ must also be $P_B(\lambda) = \lambda^2 - \lambda - 2$.

Circle one, and justify below:

☒ TRUE

☐ FALSE

Since $p_A(\lambda) = (\lambda - 2)(\lambda + 1)$, we get $\lambda_1 = 2$ and $\lambda_2 = -1$. Suppose \mathbf{w}_1 and \mathbf{w}_2 are the corresponding eigenvectors of λ_1 and λ_2 , respectively. Note that

$$B\mathbf{w}_1 = A^3\mathbf{w}_1 - 4A^2\mathbf{w}_1 + 7\mathbf{w}_1 = 8\mathbf{w}_1 - 16\mathbf{w}_1 + 7\mathbf{w}_1 = -\mathbf{w}_1$$

and

$$B\mathbf{w}_2 = A^3\mathbf{w}_2 - 4A^2\mathbf{w}_2 + 7\mathbf{w}_2 = -\mathbf{w}_2 - 4\mathbf{w}_2 + 7\mathbf{w}_2 = 2\mathbf{w}_2.$$

Hence, \mathbf{w}_1 and \mathbf{w}_2 are eigenvectors of B with eigenvalues -1 and 2 , respectively. In particular, -1 and 2 are the eigenvalues of B (which can have at most two eigenvalues, since it is 2×2), and so,

$$p_B(\lambda) = (\lambda + 1)(\lambda - 2) = \lambda^2 - \lambda - 2.$$