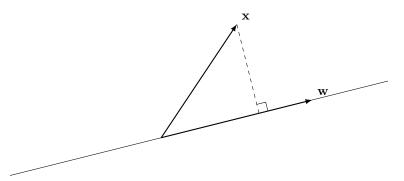
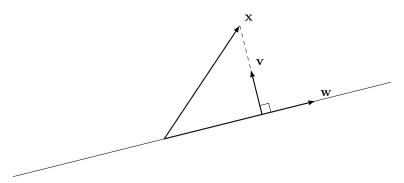
## Goal: projections!

Consider the subspace generated by  $\mathbf{w}$  in  $\mathbb{R}^n$ . The subspace will be the line in direction of  $\mathbf{w}$  and is of dimension 1. Now consider an arbitrary vector  $\mathbf{x} \in \mathbb{R}^n$ .



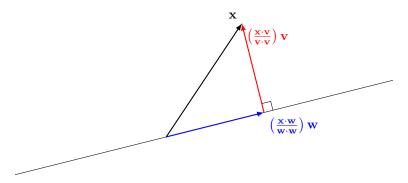
From the picture above, we can see that if we take a vector along the dashed line, say  $\mathbf{v}$ , then  $\mathbf{v} \perp \mathbf{w}$ . So,  $\{\mathbf{v}, \mathbf{w}\}$  is an orthogonal basis for the plane containing  $\mathbf{x}$  and  $\mathbf{w}$ .



This means we can write  $\mathbf{x}$  as a linear combination of  $\mathbf{v}$  and  $\mathbf{w}$  by using Fourier formula:

$$\mathbf{x} = \left(\frac{\mathbf{x} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w} + \left(\frac{\mathbf{x} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}}\right) \mathbf{v}.$$

We can actually visualize what  $\left(\frac{\mathbf{x} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w}$  and  $\left(\frac{\mathbf{x} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}}\right) \mathbf{v}$  should look like.



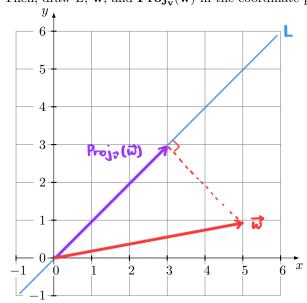
**Proposition 6.1.1.** Let  $L = \text{span}(\mathbf{w}) = \{c\mathbf{w} : c \in \mathbb{R}\}$  be a 1-dimensional linear subspace of  $\mathbb{R}^n$ , a "line". Choose any point  $\mathbf{x} \in \mathbb{R}^n$ . There is exactly one point in L closest to  $\mathbf{x}$ , and it is

$$\left(\frac{\mathbf{x}\cdot\mathbf{w}}{\mathbf{w}\cdot\mathbf{w}}\right)\mathbf{w}.$$

This is denoted by  $\mathbf{Proj}_{\mathbf{w}}(\mathbf{x})$  and is read "the projection of  $\mathbf{x}$  onto  $\mathrm{span}(\mathbf{w})$ ".

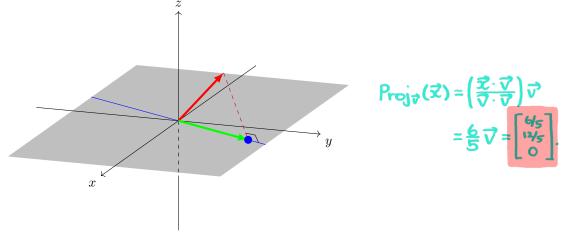
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**Example 1**. Let L be the line represented by y = x in  $\mathbb{R}^2$ . For  $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\mathbf{w} = \begin{bmatrix} 5 \\ 1 \end{bmatrix}$ , compute  $\mathbf{Proj_v}(\mathbf{w})$ . Then, draw L,  $\mathbf{w}$ , and  $\mathbf{Proj_v}(\mathbf{w})$  in the coordinate plane below.



Proj<sub>$$\vec{v}$$</sub> ( $\vec{\omega}$ ) =  $\left(\frac{\vec{\omega} \cdot \vec{v}}{\vec{\nabla} \cdot \vec{v}}\right) \vec{v}$   
=  $\frac{6}{2} \vec{v} = 3 \vec{v} = \begin{bmatrix} 3\\3 \end{bmatrix}$ .

**Example 2.** Find the closest point to 
$$\mathbf{x} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$
 on the line  $\mathrm{span}(\mathbf{v})$  for  $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ 



There is a very useful algebraic property of projections onto lines L through  $\mathbf{0}$  that is difficult to see directly in purely geometric terms but is quite convenient when one needs to compute  $\mathbf{Proj}_L(\mathbf{v})$  for many different points  $\mathbf{v}$ . If we calculate the vectors  $\mathbf{Proj}_L(\mathbf{e}_i)$  ahead of time, then we can calculate  $\mathbf{Proj}_L(\mathbf{v})$  very quickly. We need the following key property of projections of linear combinations:

$$\mathbf{Proj_{w}}(a\mathbf{u} + b\mathbf{v}) = \left(\frac{(a\mathbf{u} + b\mathbf{v}) \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w}$$

$$= \left(\frac{a(\mathbf{u} \cdot \mathbf{w})}{\mathbf{w} \cdot \mathbf{w}} + \frac{b(\mathbf{v} \cdot \mathbf{w})}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w}$$

$$= a\left(\frac{\mathbf{u} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w} + b\left(\frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}\right) \mathbf{w}$$

$$= a\mathbf{Proj_{w}}(\mathbf{u}) + b\mathbf{Proj_{w}}(\mathbf{v}).$$

Generalizing this to multiple vectors gives us

$$\mathbf{Proj}_{\mathbf{w}}(c_1\mathbf{x}_1 + \dots + c_k\mathbf{x}_k) = c_1\mathbf{Proj}_{\mathbf{w}}(\mathbf{x}_1) + \dots + c_k\mathbf{Proj}_{\mathbf{w}}(\mathbf{x}_k).$$

Example 3. Let 
$$\mathbf{w} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$
. Compute  $\mathbf{Proj_w}(\mathbf{e}_1)$ ,  $\mathbf{Proj_w}(\mathbf{e}_2)$ , and  $\mathbf{Proj_w}(\mathbf{e}_3)$ .

Proj 
$$\vec{u}(\vec{e}_1) = \frac{1}{5}\vec{w} = \begin{bmatrix} \frac{1}{5} \\ \frac{2}{5} \\ 0 \end{bmatrix}$$
, Proj  $\vec{u}(\vec{e}_2) = \frac{2}{5}\vec{w} = \begin{bmatrix} \frac{2}{5} \\ \frac{2}{5} \\ 0 \end{bmatrix}$ , Proj  $\vec{u}(\vec{e}_3) = \frac{0}{5}\vec{w} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ .

Example 4. Use your answers from Example 3 to compute:

• 
$$\operatorname{Proj}_{\mathbf{w}}\left(\begin{bmatrix} 2\\2\\2\\2\end{bmatrix}\right) = 2\operatorname{Proj}_{\vec{w}}(\vec{e}_{i}) + 2\operatorname{Proj}_{\vec{w}}(\vec{e}_{s}) + 2\operatorname{Proj}_{\vec{w}}(\vec{e}_{s}) = \frac{6}{5}\vec{w} = \begin{bmatrix} \frac{4}{5}\\\frac{12}{5}\\0\end{bmatrix}$$

• 
$$\operatorname{Proj}_{\mathbf{w}}\left(\begin{bmatrix}2\\4\\2\end{bmatrix}\right) = 2\left(\frac{1}{5}\vec{\mathbf{w}}\right) + 4\left(\frac{2}{5}\vec{\mathbf{w}}\right) + 2\left(0\vec{\mathbf{w}}\right) = 2\vec{\mathbf{w}} = \begin{bmatrix}2\\4\\0\end{bmatrix}.$$

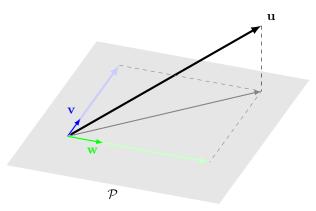
• 
$$\operatorname{Proj}_{\mathbf{w}}\left(\begin{bmatrix} -2\\-4\\0 \end{bmatrix}\right) = -2\left(\frac{1}{5}\vec{w}\right) - 4\left(\frac{2}{5}\vec{w}\right) + O(0\vec{w}) = -2\vec{w} = \begin{bmatrix} -2\\-4\\0 \end{bmatrix}$$

• 
$$\operatorname{Proj}_{\mathbf{w}}\left(\begin{bmatrix} -3\\1\\-2\end{bmatrix}\right) = -3\left(\frac{1}{5}\vec{\mathbf{w}}\right) + \left(\frac{2}{5}\vec{\mathbf{w}}\right) - 2\left(0\vec{\mathbf{w}}\right) = -\frac{1}{5}\vec{\mathbf{w}} = \begin{bmatrix} -\frac{1}{5}\vec{\mathbf{w}}\\-\frac{1}{5}\vec{\mathbf{w}}\end{bmatrix}$$

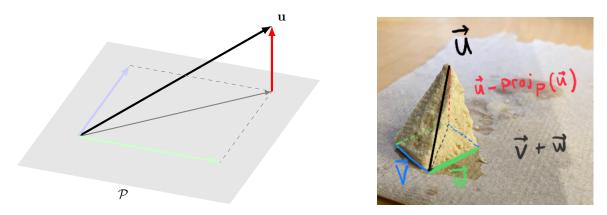
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We can also use the same method to find the closest point on a linear subspace to a given point. In other words, let V be a linear subspace of  $\mathbb{R}^n$ . For  $\mathbf{v} \in \mathbb{R}^n$ , what is the closest point in V to  $\mathbf{v}$ ?

Let us consider the problem of, given a plane  $\mathcal{P}$  in  $\mathbb{R}^3$  and  $\mathbf{u} \in \mathbb{R}^3$ , finding the closest point on  $\mathcal{P}$  to  $\mathbf{u}$ . Suppose  $\{\mathbf{v}, \mathbf{w}\}$  is an orthogonal basis for  $\mathcal{P}$ . In the diagram below, the light blue vector is  $\mathbf{Proj}_{\mathbf{v}}(\mathbf{u})$ , the light green vector is  $\mathbf{Proj}_{\mathbf{w}}(\mathbf{u})$ , and the gray vector is the sum of the two vectors.

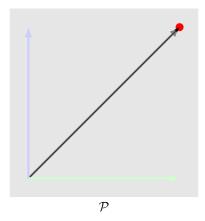


We can think of the gray vector as the "projection of  $\mathbf{u}$  onto the plane  $\mathcal{P}$ ," or  $\mathbf{Proj}_{\mathcal{P}}(\mathbf{u})$ . The red vector, shown below, is  $\mathbf{u} - \mathbf{Proj}_{\mathcal{P}}(\mathbf{u})$  and is perpendicular to  $\mathcal{P}$ .



The picture on the right is a physical model of the picture on the left, made with tofu by Aristotle Marangu '25.

The point at the base of the red vector,  $\mathbf{Proj}_{\mathcal{P}}(u)$  is the closest point on  $\mathcal{P}$  to  $\mathbf{u}$ . A bird's eye view is provided in hopes of better visual understanding (the red vector is coming straight out towards you).



Orthogonal projection theorem, version 1 (Theorem 6.2.1). For any  $\mathbf{x} \in \mathbb{R}^n$  and linear subspace V of  $\mathbb{R}^n$ , there is a unique  $\mathbf{v} \in V$  that is closest to  $\mathbf{x}$ . This  $\mathbf{v}$  is called the **projection of**  $\mathbf{x}$  onto V, and is denoted  $\mathbf{Proj}_V(\mathbf{x})$ .

The projection  $\operatorname{\mathbf{Proj}}_V(\mathbf{x})$  is the *ONLY* vector  $\mathbf{v} \in V$  such that  $\mathbf{x} - \mathbf{v}$  is perpendicular to V ( $\mathbf{x} - \mathbf{v}$  is perpendicular to V).

If V is nonzero, then for any orthogonal basis  $\{\mathbf{v}_1,\ldots,\mathbf{v}_k\}$  of V, we have

$$\mathbf{Proj}_V(\mathbf{x}) = \mathbf{Proj}_{\mathbf{v}_1}(\mathbf{x}) + \dots + \mathbf{Proj}_{\mathbf{v}_k}(\mathbf{x}).$$

For  $\mathbf{x} \in V$ ,  $\mathbf{Proj}_V(\mathbf{x}) = \mathbf{x}$ , which is the Fourier formula!

**Example 5.** Let U be the subspace of  $\mathbb{R}^4$  spanned by  $\mathbf{u}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$  and  $\mathbf{u}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}$ . If  $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ , find the point  $\mathbf{u} \in U$  that is closest to  $\mathbf{v}$ .

Since  $\vec{u_1} \perp \vec{u_2}$ ,  $\{\vec{u_1}, \vec{u_2}\}$  is an orthogonal basis for U. By the orthogonal projection theorem,

$$\vec{\mathcal{U}} = \text{Proj}_{\mathcal{U}}(\vec{\mathcal{V}}) = \text{Proj}_{\vec{\mathcal{U}}_1}(\vec{\mathcal{V}}) + \text{Proj}_{\vec{\mathcal{U}}_2}(\vec{\mathcal{V}}) = -\frac{1}{2}\vec{\mathcal{U}}_1 + 2\vec{\mathcal{U}}_2 = \begin{bmatrix} \frac{3}{2} \\ \frac{7}{2} \\ 4 \end{bmatrix}$$

is the point in U closest to V.

Orthogonal projection theorem, version 2 (Theorem 6.2.4). If V is a linear subspace of  $\mathbb{R}^n$ , then every vector  $\mathbf{x} \in \mathbb{R}^n$  can be uniquely expressed as a sum

$$\mathbf{x} = \mathbf{v} + \mathbf{v}',$$

where  $\mathbf{v} \in V$  and  $\mathbf{v}'$  is orthogonal to every vector in V. Explicitly,  $\mathbf{v} = \mathbf{Proj}_V(\mathbf{x})$ .

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**Example 6.** Let 
$$U$$
 be the subspace of  $\mathbb{R}^4$  spanned by  $\mathbf{u}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{u}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}$ , and  $\mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}$ . If  $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ , find the point  $\mathbf{u} \in U$  that is closest to  $\mathbf{v}$ .

Note that { \vec{u}\_1, \vec{u}\_2, \vec{u}\_3 } is an orthogonal basis for U. Hence,

$$Proj_{u}(\vec{v}) = Proj_{\vec{u}_{1}}(\vec{v}) + Proj_{\vec{u}_{2}}(\vec{v}) + Proj_{\vec{u}_{3}}(\vec{v}) = -\frac{1}{2}\vec{u}_{1} + 2\vec{u}_{2} - \frac{2}{5}\vec{u}_{3}$$

$$= \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ \frac$$

**Example 7.** Let  $\{\mathbf{v}_1, \mathbf{v}_2\}$  be an orthogonal basis for a plane  $\mathcal{P}$  in  $\mathbb{R}^n$  with  $\|\mathbf{v}_1\| = 3$  and  $\|\mathbf{v}_2\| = 1$ . Let  $\mathbf{w}$  be an n-vector lying outside  $\mathcal{P}$  for which  $\mathbf{Proj}_{\mathcal{P}}(\mathbf{w}) = 2\mathbf{v}_1 + \mathbf{v}_2$ .

(a) Explain why the span of the nonzero vectors  $\mathbf{v}_1$  and  $\mathbf{w}$  is a plane  $\mathcal{P}'$ , and that this plane cannot contain  $\mathbf{v}_2$ ; the visualization is that the planes  $\mathcal{P}$  and  $\mathcal{P}'$  meet along the line  $\mathrm{span}(\mathbf{v}_1)$ .

If  $\vec{V_2} \in \mathcal{P}' = \operatorname{span}(\vec{V_1}, \vec{W})$ , then  $\vec{V_2} = d\vec{V_1} + \beta \vec{W}$  for some scalars of and  $\beta$ . Note that  $\beta \neq 0$  (if  $\beta = 0$ , then  $\vec{V_2}$  is a scalar multiple of  $\vec{V_1}$ , which is impossible). Then,  $\vec{W} = -\frac{d}{\beta}\vec{V_1} + \frac{1}{\beta}\vec{V_2} \in \operatorname{span}(\vec{V_1}, \vec{V_2}) = \mathcal{P}$ , which is impossible. Hence,  $\vec{V_2} \notin \mathcal{P}'$ .

(b) For any linear subspace V of  $\mathbb{R}^n$  and vector  $\mathbf{v} \in V$ , show that  $\mathbf{x} \cdot \mathbf{v} = \mathbf{Proj}_V(\mathbf{x}) \cdot \mathbf{v}$  for every n-vector  $\mathbf{x}$ .

Let  $\vec{z}$  be arbitrary. By the orthogonal projection theorem,

where  $\vec{V}'$  is orthogonal to every vector in V. Thus, for any  $\vec{v} \in V$ ,

$$\vec{z} \cdot \vec{v} = (\text{Proj}_{\vec{v}}(\vec{z}) + \vec{v}') \cdot \vec{v} = \text{Proj}_{\vec{v}}(\vec{x}) \cdot \vec{v} + \vec{v}' \cdot \vec{v} = \text{Proj}_{\vec{v}}(\vec{z}) \cdot \vec{v}.$$

(c) Show that  $\mathbf{w} \cdot \mathbf{v}_1 = 18$  and  $\mathbf{w} \cdot \mathbf{v}_2 = 1$ , and use this to compute  $\mathbf{Proj}_{\mathbf{v}_1}(\mathbf{w})$  and  $\mathbf{Proj}_{\mathbf{v}_2}(\mathbf{w})$  as explicit scalar multiples of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ , respectively.

By (b), 
$$\vec{W} \cdot \vec{V_1} = Proj_p(\vec{W}) \cdot \vec{V_1} = (2\vec{V_1} + \vec{V_2}) \cdot \vec{V_1} = 2||\vec{V_1}||^2 + \vec{V_2} \cdot \vec{V_1} = 18$$
. Similarly,  $\vec{W} \cdot \vec{V_2} = (2\vec{V_1} + \vec{V_2}) \cdot \vec{V_2} = 2\vec{V_1} \cdot \vec{V_2} + ||\vec{V_2}||^2 = 1$ . Hence,

$$\mathsf{Proj}_{\vec{v}_i}(\vec{\omega}) = \left(\frac{\vec{w} \cdot \vec{v}_i}{\vec{v}_i \cdot \vec{v}_i}\right) \vec{v}_i = 2\vec{v}_i \quad \text{and} \quad \mathsf{Proj}_{\vec{v}_i}(\vec{\omega}) = \left(\frac{\vec{w} \cdot \vec{v}_i}{\vec{v}_i \cdot \vec{v}_i}\right) \vec{v}_i = \vec{v}_i.$$