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Intelligent Robotics

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L

see Tab. 1.1

Tab. 1.1

See Tab. 1.1.

See table ???.

see fig 1.1

Fig. 1.1

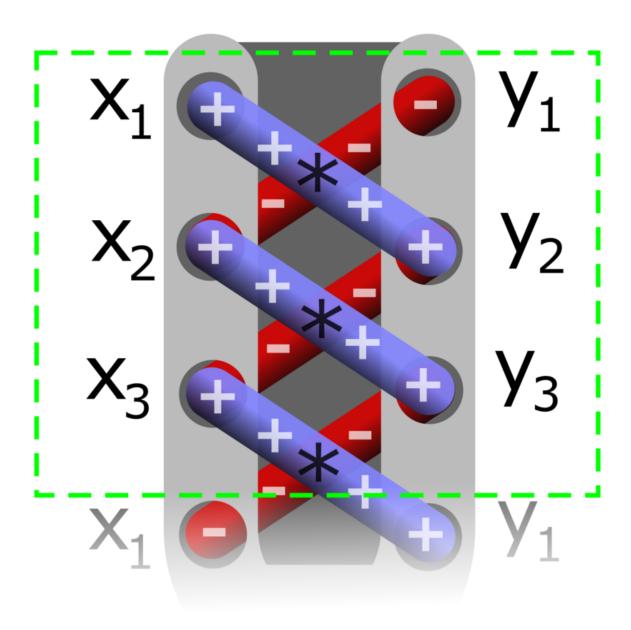


Figure 1.1: Shoelace

Table 1.2: Demonstration of a simple table.

Right	Left	Center	Default
12	12	12	12
123	123	123	123
1	1	1	1

Table 1.2 is from the Pandoc User's Guide. A simpler table is given by Tab. 1.3:

Table 1.3: Even simpler.

A	В
0	1

[1] M. S. Pini, F. Rossi, B. Venable, and T. Walsh, "Stable marriage problems with quantitative preferences," $arXiv\ preprint\ arXiv:1007.5120$, 2010.