

1 Hamiltonians and EOM

1.1 Toy Problem

Consider simplest spin Hamiltonian $H = -\vec{B} \cdot \vec{s}$. It's clear that if we set up initial conditions \vec{s} misaligned from \vec{B} , it will simply spin around \vec{B} , which is fixed. Thus, let $\vec{B} \cdot \hat{s} = \cos\theta$ the angle between the two, and let ϕ measure the azimuthal angle.

We claim that $\cos\theta, \phi$ are canonical variables. Since ϕ is ignorable, immediately $\frac{d\theta}{dt} = \frac{d\cos\theta}{dt} = -\frac{\partial H}{\partial \phi} = 0$, while $\frac{d\phi}{dt} = \frac{\partial H}{\partial(\cos\theta)} = Bs$ tells us the rate at which the spin precesses around \vec{B} .

1.2 Cassini State Hamiltonian

This Hamiltonian is Kassandras Eq. 13, in the co-rotating frame with the perturber's angular momentum:

$$\mathcal{H} = \frac{1}{2}(\hat{s} \cdot \hat{l})^2 - \eta(\hat{s} \cdot \hat{l}_p). \quad (1)$$

In this frame, we can choose $\hat{l} \equiv \hat{z}$ fixed, and $\hat{l}_p = \cos I \hat{z} + \sin I \hat{x}$ fixed as well. Then

$$\hat{s} = \cos\theta \hat{z} - \sin\theta(\sin\phi \hat{y} + \cos\phi \hat{x}).$$

We can choose the convention for $\phi = \phi$ azimuthal angle requiring $\phi = 0, \pi$ mean coplanarity between $\hat{s}, \hat{l}, \hat{l}_p$ in the \hat{x}, \hat{z} plane such that \hat{l}_p, \hat{s} lie on the same side of \hat{l} . Then we can evaluate in coordinates

$$\begin{aligned} \hat{s} \cdot \hat{l} &= \cos\theta, \\ \hat{s} \cdot \hat{l}_p &= \cos\theta \cos I - \sin I \sin\theta \cos\phi, \\ \mathcal{H} &= \frac{1}{2} \cos^2\theta - \eta(\cos\theta \cos I - \sin I \sin\theta \cos\phi). \end{aligned}$$

Note that if we take $\cos\theta$ to be our canonical variable, $\sin\theta = \sqrt{1 - \cos^2\theta}$ can be used.

1.3 Equation of Motion

The correct EOM comes from Kassandra's Eq. 12:

$$\begin{aligned} \frac{d\hat{s}}{dt} &= (\hat{s} \cdot \hat{l})(\hat{s} \times \hat{l}) - \eta(\hat{s} \times \hat{l}_p), \\ &= \cos\theta[\hat{x}(-\sin\theta \sin\phi) - \hat{y}(-\sin\theta \cos\phi)] \\ &\quad - \eta[\hat{x}(-\sin\theta \sin\phi \cos I) - \hat{y}(-\sin\theta \cos\phi \cos I - \cos\theta \sin I) + \hat{z}(+\sin\theta \sin\phi \sin I)], \\ &= [-\sin\theta \sin\phi \cos\theta + \eta \sin\theta \sin\phi \cos I]\hat{x} + [\cos\theta \sin\theta \cos\phi - \eta(\sin\theta \cos\phi \cos I + \cos\theta \sin I)]\hat{y} \\ &\quad + [-\eta \sin\theta \sin\phi \sin I]\hat{z}. \end{aligned}$$

Alternatively, consider Hamilton's equations applied to the Hamiltonian:

$$\frac{\partial \phi}{\partial t} = \frac{\partial \mathcal{H}}{\partial(\cos\theta)} = \cos\theta - \eta(\cos I + \sin I \cot\theta \cos\phi), \quad (2)$$

$$\frac{\partial(\cos\theta)}{\partial t} = -\frac{\partial \mathcal{H}}{\partial \phi} = +\eta \sin I \sin\theta \sin\phi. \quad (3)$$

This produces the same trajectories as the Cartesian EOM, so this is correct. However, since $\frac{\partial \phi}{\partial t} \propto 1/\sin\theta$, this is not a desirable system of equations to use, as they are very stiff near $\theta \approx 0$.

We can add a tidal dissipation term; this is just $\left(\frac{d\hat{s}}{dt}\right)_{\text{tide}} = \epsilon \hat{s} \times (\hat{l} \times \hat{s})$.

We can check the stability of each of the equilibria of the EOM, there should be four corresponding to the four Cassini states: