



Week 4 Report

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Title:

1 Building the system for the second example

We have the second system of the following form:

$$x' = -x^3$$

Normally, we have the following quadratization, where $y=x^2$:

$$y' = -2xx' = -2x^4 = -2y^2$$

Then we have the following system:

$$\begin{cases} y' = -2y^2 \\ x' = -xy \end{cases}$$

However, we can find that **there is no linear part** in the system. Therefore, we try to add linear terms like ax or a. After computation, we find that ax can't produce eigenvalues for matrix F_1 . Therefore, we try with the term a. We can change $y = x^2 - a \Rightarrow a = x^2 - y$, then we have the following system:

$$x' = -x^{3} = -x(y+a) = -xy - ax$$

$$y' = 2xx' = 2x(-x^{3}) - 2x^{4}$$

$$= -2(y+a)^{2} = -2y^{2} - 4ay - 2a^{2}$$

$$= -2y^{2} - 4ay - 2a(x^{2} - y)$$

$$= -2y^{2} - 4ay - 2ax^{2} + 2ay$$

$$= -2y^{2} - 2ax^{2} - 2ay$$

Then we can finalize the system as following:

$$\begin{cases} y' = -2y^2 + 2ax^2 + 2ay \\ x' = -xy + ax \end{cases}$$

Then we have the $F_1 \in \mathbb{R}^{n \times n}$ matrix for linear part:

$$F_1 = \begin{cases} x & y \\ -a & 0 \\ 0 & -2a \end{cases}$$
 (1)

And for the nonlinear part we have $F_2 \in \mathbb{R}^{n \times n^2}$ matrix:

$$F_2 = \begin{cases} x^2 & xy & yx & y^2 \\ x' & 0 & -1 & 0 & 0 \\ -2a & 0 & 0 & -2 \end{cases}$$
 (2)

For matrix F_1 we have the eigenvalues $\lambda_1 = -a$ and $\lambda_2 = -2a$. Then we got $\Re(\lambda_1) = -1$ (the real part of λ_1). We cite the [paper] for reachability analysis, we have following part:

Definition 1. System is said to be weakly nonlinear if the ratio

$$R := \frac{\|X_0\| \|F_2\|}{|\Re(\lambda_1)|}$$



satisfies R < 1.

Definition 2. System (1) is said to be dissipative if $\Re(\lambda_1) < 0$ (i.e., the real part of all eigenvalues is negative).

The conditions $\Re(\lambda_1) < 0$ and R < 1 ensure arbitrary-time convergence.

Theorem 1 ([30, Corollary 1]) Assuming that (1) is weakly nonlinear and dissipative, the error bound associated with the linearized problem (2) truncated at order N satisfies

$$\|\eta_1(t)\| \le \varepsilon(t) := \|X_0\| R^N \left(1 - e^{\Re(\lambda_1)t}\right)^N$$

with R as defined in (5). This error bound holds for all $t \geq 0$.

2 Computation of the SVD decomposition of F_2

From above, we have the nonlinear system matrix that

$$F_2 = \begin{bmatrix} 0 & -1 & 0 & 0 \\ -2a & 0 & 0 & -2 \end{bmatrix}.$$

with a > 0. In the [paper], it mentioned that we apply the $l - \infty$ norm in the computation of $||F_2||$. However, when I look into the code of the function _error_bound_specabs_R(x0c, F1, F2; check=true), I have the following algorithms in Julia.

```
# See Definition (2.2) in [2]. These bounds use the spectral norm (p = 2) function _error_bound_specabs_R(x_0, F_1, F_2; check=true) nx_0 = norm(x_0, 2) nF_2 = opnorm(F_2, 2) # compute eigenvalues and sort them by increasing real part \lambda = eigvals(F_1, sortby=real) \lambda_1 = last(\lambda) Re_{\lambda_1} = real(\lambda_1) if check @assert Re_\lambda_1 <= 0 "expected Re(\lambda_1) \leq 0, got $Re_\lambda_1" end R = nx_0 * nF_2 / abs(Re_{\lambda_1}) return (R, Re_\lambda_1)
```

Figure 1: Code for function error bound specabs R(x0c, F1, F2; check=true)

Therefore, we can see that in the computation of $||F_2||$, we apply the l-2 norm. If we check the l-2 norm in **Julia**, we have the code as follows [link]:

```
function opnorm(A::AbstractMatrix, p::Real=2)
   F = factorize(Hermitian(A) |> Matrix)
   lambda = maximum(svdvals(F.U))
   return lambda^(1/p)
end
```

Therefore, in order to compute $||F_2||_2$, we need to apply **singular value decomposition (SVD)** to F_2 . We denote $A = F_2$ here and then compute $A^T A$ and AA^T . We have:

$$A^T A = \begin{bmatrix} 1 & 0 \\ 0 & 4a^2 \end{bmatrix}.$$



$$AA^T = \begin{bmatrix} 4a^2 & 0 & 0 & -4a \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -4a & 0 & 0 & 4 \end{bmatrix}.$$

For matrix $A^T A$, it's easy to find the eigenvalue $\lambda_1 = 1$ and $\lambda_2 = 4a^2$ with the eigenvector of $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

Then we try to compute the eigenvalue and eigenvector of AA^{T} , we first compute its **characteristic polynomial**, we have

$$\mathcal{X}_{AA^T} = \begin{vmatrix}
4a^2 - x & 0 & 0 & 4a \\
0 & 1 - x & 0 & 0 \\
0 & 0 & -x & 0 \\
4a & 0 & 0 & 4 - x
\end{vmatrix}$$

$$= (1 - x) \begin{vmatrix}
4a^2 - x & 0 & 4a \\
0 & -x & 0 \\
4a & 0 & 4 - x
\end{vmatrix}$$

$$= x^2(x - 1)(x - (4 + 4a^2))$$

Therefore, we have the eigenvalues that $\begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{bmatrix} = \begin{bmatrix} 4a^2 + 4 \\ 0 \\ 1 \\ 0 \end{bmatrix}.$ Then we got the eigenvectors that $\begin{bmatrix} u_1, u_2, u_3, u_4 \end{bmatrix} = \begin{bmatrix} u_1, u_2, u_3, u_4 \end{bmatrix} = \begin{bmatrix} u_1, u_2, u_3, u_4 \end{bmatrix}$

$$\begin{bmatrix} \sqrt{\frac{a^2}{a^2+1}} & \frac{1}{a}\sqrt{\frac{a^2}{a^2+1}} & 0 & 4a \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -\frac{1}{a}\sqrt{\frac{a^2}{a^2+1}} & \sqrt{\frac{a^2}{a^2+1}} & 0 & 4 \end{bmatrix}.$$
 Then we can compute the singular value, we have $\sigma_i = \sqrt{\lambda_i}$ formula to

compute the singular value that $\sigma_1 = \sqrt{4 + 4a^2}$ and $\sigma_2 = 1$. Finally, we have the SVD of F_2 that:

$$F_2 = \begin{bmatrix} \sqrt{\frac{a^2}{a^2+1}} & \frac{1}{a}\sqrt{\frac{a^2}{a^2+1}} & 0 & 4a \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -\frac{1}{a}\sqrt{\frac{a^2}{a^2+1}} & \sqrt{\frac{a^2}{a^2+1}} & 0 & 4 \end{bmatrix} \begin{bmatrix} \sqrt{4+4a^2} & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Therefore, since l-2 norm is the maximum of the absolute value of the singular value, we have $||F_2||_2 = \sqrt{4+4a^2}$.

3 Computation of the error bound function

We have the weakly nonlinear condition that

$$R := \frac{\|X_0\| \|F_2\|}{\|\Re(\lambda_1)\|}$$

$$= \frac{2\sqrt{a^2 + 1}\sqrt{x_0^4 + (1 - 2a)x_0^2 + a^2}}{a}$$

$$< 1$$

Then for the error bound function we have

$$\varepsilon(t) := \frac{\|X_0\|^{N+1} \|F_2\|^N}{a^N} \left(1 - e^{-at}\right)^N$$