

Design and Analysis of Algorithm

Basics of Complexity Theory

- 1 Decision Problem
- 2 Deterministic Computation
- 3 Several Important Complexity Classes
 - \mathcal{P} vs. \mathcal{NP}
 - \mathcal{NP} -complete
 - $\text{co-}\mathcal{NP}$
- 4 Randomized Computation
 - \mathcal{BPP}
 - PSPACE
- 5 Decision vs. Search
- 6 Impact on Cryptography

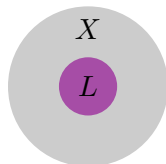
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Decision Problem

Decision Problem: recognition of a set of strings $L \subseteq X$

- X : a set of strings
- x : a string in X (each string corresponds to an instance)
- L : language (a subset of X satisfying some property)

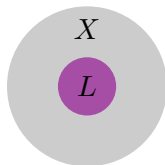


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Example

- $X = \mathbb{N}$
- L are Primes = $\{2, 3, 5, 7, 11, 13, \dots\}$
- decide if x is a prime.

Motivation for Complexity Theory

We always want to know if a given problem can be *efficiently* solved by an algorithm.

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We always want to know if a given problem can be *efficiently* solved by an algorithm.

- ① Precisely model algorithms
 - What is computation?
 - What is computable?
- ② Precisely define what does it means for efficient.

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Turing Machine

1936, London Mathematical Society: On computable numbers, with an application to the Entscheidungs Problem.

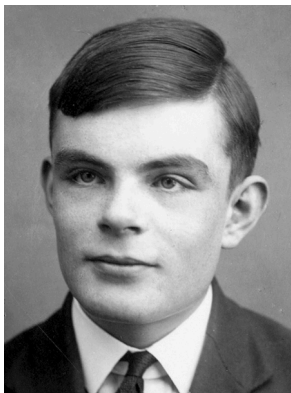
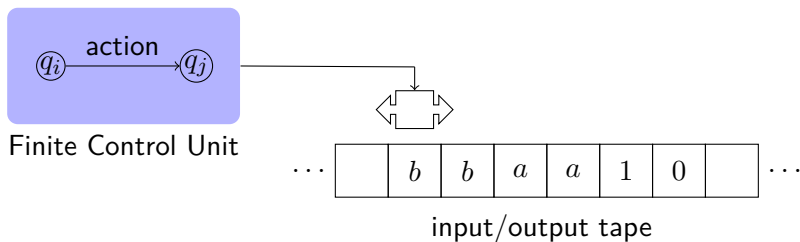


Figure: Alan Turing

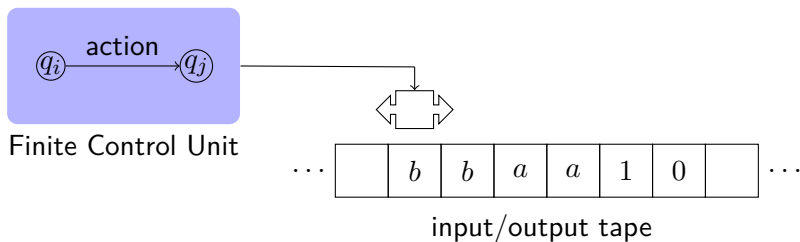
Turing Machine

Turing machine: automatic machine that has a tape (divided into infinite cells), a control unit and a read/write head.



Turing Machine

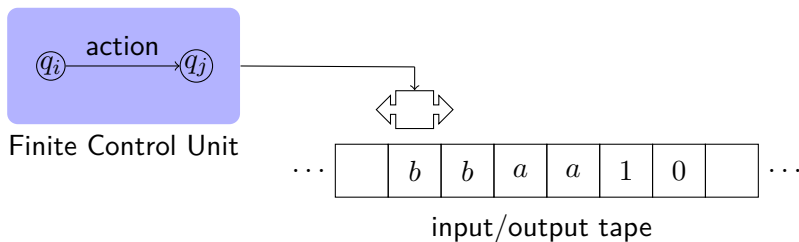
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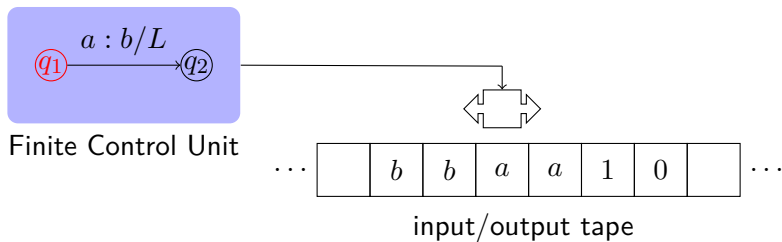
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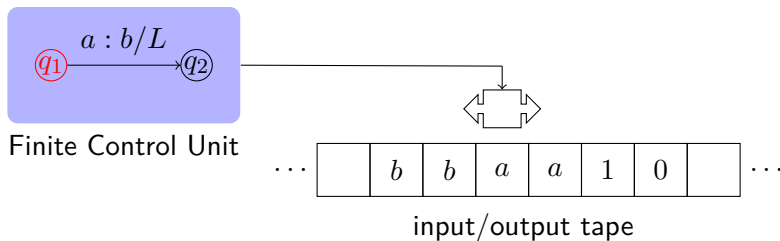


- At the beginning, the tape contains the input in several cells. Other places are empty.
- During computation, the control unit monitor current state and the head value, can do the following operations:
 - 1 wipe off old value and write new values
 - 2 change the current state
 - 3 move head left or right

An Example

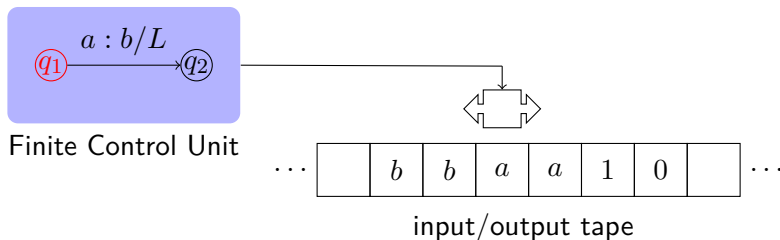


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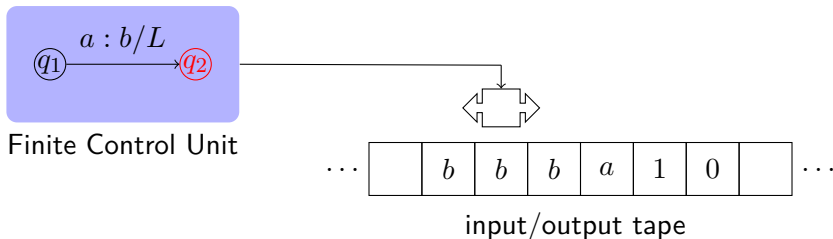


- $a \rightarrow b$; move left; current state $q_1 \rightarrow q_2$

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Intuition of Turing Machine

Mimic how human being solve a problem

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Mimic how human being solve a problem

- TM has a finite number of states (memory)
- TM is provided a tape, which contains infinite cells (paper)
- a symbol can be scanned from a cell or printed to a cell (reading and writing)

Definition 1 (Turing Machine)

TM consists $(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{acc}}, q_{\text{rej}})$

- Q : a finite set of states
- Σ : input alphabets
- Γ : working alphabets (including \perp , $\Sigma \subseteq \Gamma$)
- q_0 : the initial state of Q ;
- $q_{\text{acc}}, q_{\text{rej}}$: accept and reject state of Q
- δ : transition function

$$\delta : (Q \setminus \{q_{\text{acc}}, q_{\text{rej}}\}) \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

Running Time of TM

Definition 2

We denote the running time of TM by $t_M(n)$, which is the maximum steps that TM runs on all inputs of length n

Polynomial Time

$$\bigcup_{k \in \mathbb{N}} \text{TIME}(n^k)$$

The Extended Church-Turing Thesis

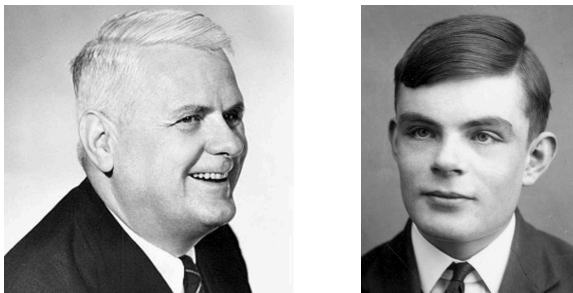


Figure: Alonzo Church & Alan Turing

Everyone's intuition of **Efficient** Algorithms = **Polynomial-Time**
deterministic TMs

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Non-determinism doesn't give TM any power to recognize more languages.

- Any NDTM can be simulated by a TM (with potentially exponential time overhead) by trying all branches of the NDTM machine “in parallel” by using BFS.

Notes

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Why TMs are so powerful?

- TM has a working tape (好记性不如烂笔头)
- TM itself can be treated as data! TM can take another TM as its input.

Universal TM



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Next, we introduce two important sets of problems, characterized by time complexity by DTM and NDTM:

$$\mathcal{P} \text{ and } \mathcal{NP}$$

Definition 3 (\mathcal{P} Language)

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Example of \mathcal{P} Languages

- $L = \{\text{even integers}\}$, M just need to check if the last bit is 0.
- $L = \text{PRIME}$, M is the AKS primality test algorithm.

Definition 4 (\mathcal{NP} Languages - Conventional)

$L \in \mathcal{NP}$ if there exists a non-deterministic poly-time TM M :

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Alert

\mathcal{NP} means non-deterministic poly-time, not **non-poly-time**!

Modern Definition

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$L \in \mathcal{NP}$ if there exists a deterministic poly-time TM M :

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Equivalence between traditional and modern definitions

- Even though M is a deterministic machine, its second argument w captures the nondeterminism in the definition.

Examples of \mathcal{NP} Language - Composites

$L = \text{COMPOSITE}$

- instance x is an integer
- a witness w for $x \in L$ is a non-trivial factor of x
- M just need to check if w divides x , which could be done in polynomial time.

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In fact, COMPOSITE also belong to \mathcal{P} (think why?)

Examples of \mathcal{NP} Language - SAT and 3-SAT

SAT: Given a CNF formula Φ , check if it has a satisfying truth assignment.

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Example of 3-SAT

- instance $\Phi = (\overline{x_1} \vee x_2 \vee x_3) \wedge (x_1 \vee \overline{x_2} \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_4)$
- witness: $x_1 = 1, x_2 = 1, x_3 = 0, x_4 = 0$

Examples of \mathcal{NP} Language - Hamilton Path

Hamilton Graph: Given an undirected graph $G = (V, E)$, does there exist a simple path that visits every node?

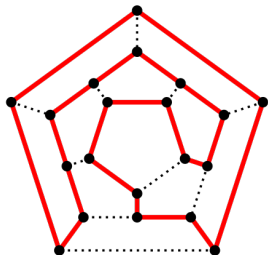


Figure: Hamiltonian Graph (a path traverses through each vertex exactly once)

witness: a path

M check if the path contains each node in V exactly once

\mathcal{P} vs. \mathcal{NP}

As per definition, $\mathcal{P} \subseteq \mathcal{NP}$. Because $L \in \mathcal{P} \Rightarrow L \in \mathcal{NP}$:

- $M'(x, w)$ can always sets $w = \perp$ and decide whether $x \in L$ using M .
- Alternatively, “short” M can be viewed as a witness for $x \in L$. Think about why the description of M is short?

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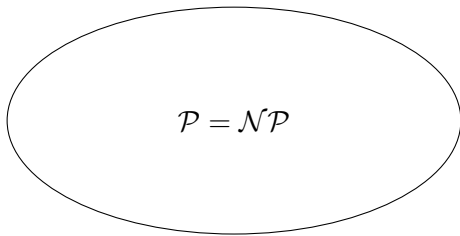
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1971: Cook, Edmonds, Levin, Yablonski, Gödel

Perhaps the most prominent question in TCS:

$$\mathcal{P} \stackrel{?}{=} \mathcal{NP}$$

$$\mathcal{P} = \mathcal{NP}$$



If $\mathcal{P} = \mathcal{NP}$

The foundation of modern cryptography collapse!



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Cryptography as we know it may be impossible. Cryptographic researchers are out of job.

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In principle, every aspect of life could be efficiently and globally optimized ...

... life as we know it would be different!

The Consequence of $\mathcal{P} = \mathcal{NP}$

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Let $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$. To efficiently find a pre-image x of y , the idea is to determine x bit-by-bit. $f(x_1 || \cdots || x_n) = y$.

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Define a collection of languages $L_i = \{(y, z) | \exists w \text{ s.t. } y = f(z || w)\}$, where $z \in \{0, 1\}^i$, $w \in \{0, 1\}^{n-i}$

- clearly $L_i \in \mathcal{NP}$ and thus also belong to \mathcal{P} by assumption, we define algorithm Invert as:

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Algorithm 4: Invert(y)

```
1:  $z = \epsilon$ ;  
2: for  $i \leftarrow 1$  to  $n$  do  
3:   if  $(y, z || 0) \in L_i$  then  $z = z || 0$ ;  
4:   else  $z = z || 1$ ;  
5: end  
6: return  $z$ 
```

The Reverse Direction

OWF exists $\Rightarrow \mathcal{P} \neq \mathcal{NP}$

- We have many candidates of OWFs, but they require assumptions.

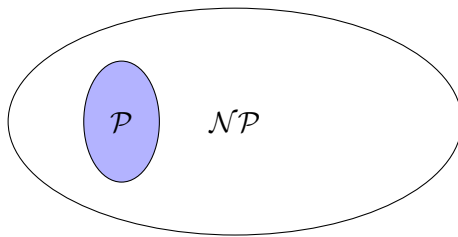
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Warning

OWFs do not exist *does not imply* $\mathcal{P} = \mathcal{NP}$



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Conjecture: $\underbrace{\text{No poly-time algorithm}}_{\text{intractable}} \text{ for 3-SAT}$

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Motivation of Reduction

\mathcal{NP} is the set of many problems.

How to figure out the relations among them?

A central approach is finding reductions

Polynomial Time Reducibility

Language L' is *poly-time reducible* or *reduces* to language L , written as $L' \leq_p L$, if there is a deterministic poly-time function $\mathcal{R} : L' \rightarrow L$ so that:

$$x \in L' \iff \mathcal{R}(x) \in L$$

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We should pay attention to:

- the direction of \mathcal{R}
- the time complexity of \mathcal{R}

Definition 6 (\mathcal{NP} -Hard)

L is said to be \mathcal{NP} -hard if for every \mathcal{NP} -language L' , there is a deterministic poly-time algorithm (a reduction) \mathcal{R} :

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Fact: languages in \mathcal{NP} -hard may **not** fall in \mathcal{NP} .

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- We can solve all problems in \mathcal{NP} if we find an efficient algorithm for any problems in \mathcal{NP} -complete.

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- This theorem essentially states that if $\mathcal{P} \cap \mathcal{NPC}$ is non-empty iff $\mathcal{P} = \mathcal{NP}$.

\mathcal{P} vs. \mathcal{NP} revisited

Overwhelming consensus (still): $\mathcal{P} \neq \mathcal{NP}$.

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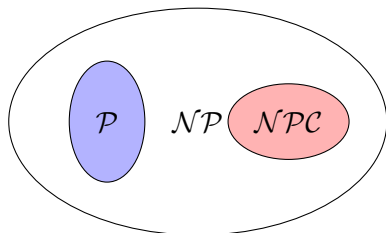


Figure: $\mathcal{P} \neq \mathcal{NP}$

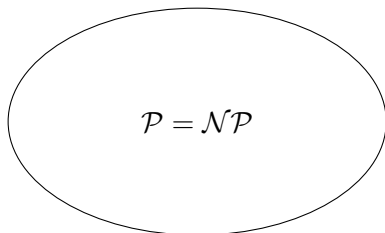


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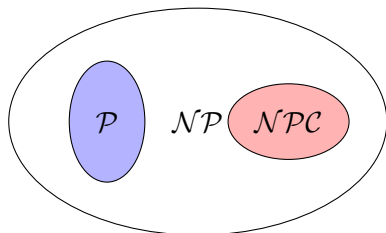


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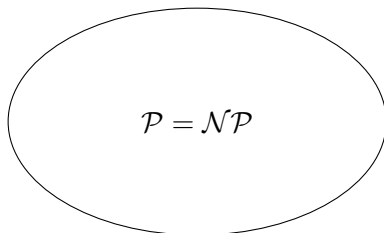
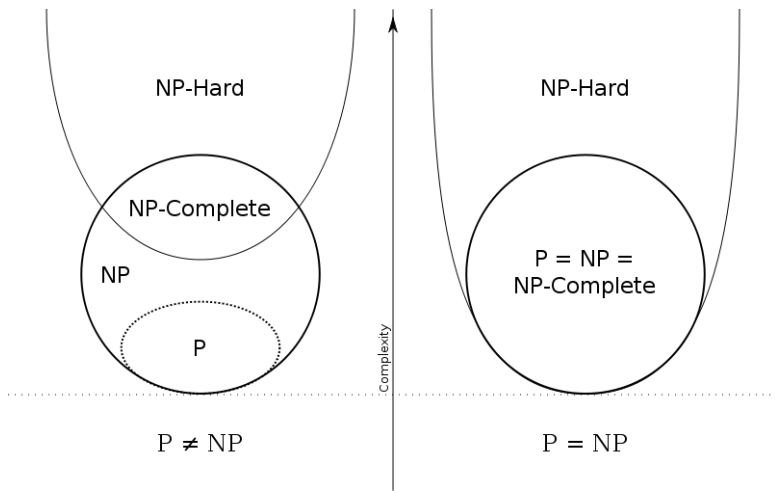


Figure: $\mathcal{P} = \mathcal{NP}$

Why we believe $\mathcal{P} \neq \mathcal{NP}$? Because some problems appear significantly harder.



Cook-Levin Theorem

Do there exist “natural” \mathcal{NP} -complete problems?

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- Other examples of \mathcal{NP} -complete including graph 3-colorability, graph Hamiltonicity, and so on.

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Motivation for co- \mathcal{NP}

Asymmetry of \mathcal{NP} : We need short certificates only for yes instances.

$$x \in L \iff \exists w \in \{0, 1\}^{\text{poly}(|x|)} \text{ s.t. } M(x, w) = 1$$

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Example 10 (HAM-CYCLE vs. NO-HAM-CYCLE)

- Can prove a graph is Hamiltonian by specifying a path.
- How could we prove that a graph is not Hamiltonian?

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Examples: UN-SAT, NO-HAM-CYCLE, and PRIMES.

\mathcal{NP} vs. $\text{co-}\mathcal{NP}$

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Proof idea.

- \mathcal{P} is closed under complementation.
- If $\mathcal{P} = \mathcal{NP}$, then \mathcal{NP} is closed under complementation. In other words, $\mathcal{NP} = \text{co-}\mathcal{NP}$.
- This is the contrapositive of the theorem.

$$\mathcal{NP} \cap \mathbf{co}\text{-}\mathcal{NP}$$

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Provides conceptual leverage for reasoning about a problem.

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Motivation of Randomized Algorithm

TM models deterministic algorithms.

TM does not seem to capture one aspect of reality — the ability to make random choices during computation

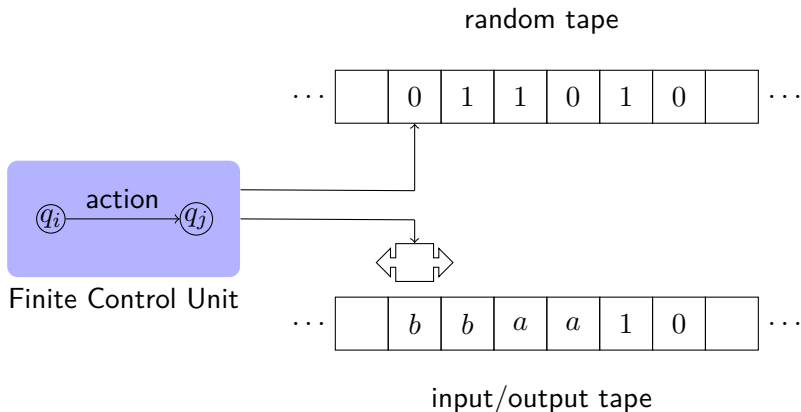
- Most programming languages provide a built-in RNG.

It makes sense to consider algorithms that can toss a coin, a.k.a. use a source of random bits. Such algorithms have been implicitly studied for a long time.

- estimate facts about a large sample by taking a small sample
- simulate real-world systems that are themselves probabilistic, such as nuclear fission and the stock market
- differential equations

Probabilistic Turing Machine

Probabilistic Polynomial-time TM models probabilistic algorithm.



PTM vs. NDTM

NDTM is a TM with two transition functions. PTM is syntactically similar.

The difference is in how we interpret the working of TM.

- In a PTM, each transition is taken with probability $1/2$, a computation that runs for time t gives rise 2^t branches in the graph of all computations, each of which is taken with probability $1/2^t$. $\Pr[M(x) = 1]$ is simply the *fraction* of branches that end with M outputting a 1.
- In a NDTM, $M(x) = 1$ iff there exists a branch that outputs 1

On a conceptual level, PTM and NDTM are very different

- PTM like TM and unlike NDTM, is intended to model realistic computation devices.

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Bounded-Error Probabilistic Polynomial Time

Definition 14 (\mathcal{BPP} Complexity)

$L \in \mathcal{BPP}$ iff there exists a probabilistic polynomial time TM M such that:

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Bounded-error Probabilistic Polynomial Time (weak version)

- A typical choices is $\alpha = 2/3$, $\beta = 1/3$. In this case, the class of decision problems solvable by a probabilistic TM in polynomial time with an error probability ϵ bounded away from $1/3$ for all instances

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- The idea is if the algorithm is run many times, the chance that the majority of the runs are wrong drops off exponentially as a consequence of the **Chernoff bound**.

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Chernoff Bounds (Lower Tail): Let $X = \sum_{i=1}^n X_i$, $\Pr[X_i] = p$, $\mu = \mathbb{E}(X) = np$.

$$\Pr[X \leq (1 - \delta)\mu] \leq e^{-\mu\delta^2/2} \text{ for all } 0 \leq \delta < 1$$

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Do the Majority Vote, i.e., set $(1 - \delta)\mu = n/2$ and thus $\delta = 1 - 1/2p$, we obtain:

$$\Pr[X \leq n/2] \leq e^{-n \frac{(1-2p)^2}{8p}}$$

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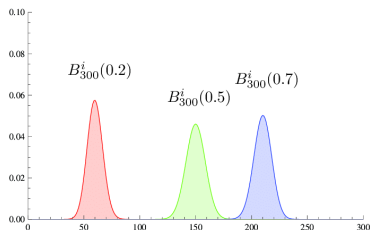
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- the threshold $1/2$ can be replaced by any fixed rational number in $(0, 1)$, without changing the class.

Why majority vote works?

Recall that X is a Binomial distribution. When α and β are not negligible close, after polynomial times of repetition, the two distributions induced by $x \in L$ and $x \notin L$ are largely detached. Otherwise, they are mingled together \leadsto hard to find a split line



- this is a theory reasoning of why majority vote works.

This also explain for \mathcal{PP} , the majority vote does not work if β is negligibly close to α . For example:

$$x \in L \Rightarrow \Pr[M(x) = 1] \geq 1 - 1/2^n$$

$$x \notin L \Rightarrow \Pr[M(x) = 1] \leq 1 - 1/2^n$$

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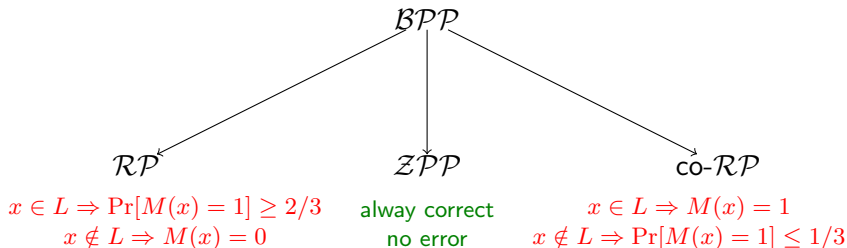
[AKS04] gave a deterministic polynomial-time algorithm for PRIME, thus showing that it is in \mathcal{P} .

Gödel Prize and Fulkerson Prize

One-sided and Zero-sided Error

\mathcal{ZPP} : probabilistic polynomial-time TM always returns correct YES or NO answer, or halts with low probability, a.k.a. running time is polynomial **in expectation** for every input

two-sided error

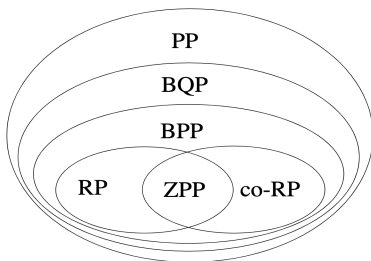


- BPP : Monte Carlo algorithms (probabilistic) likely to be correct in strict polynomial running time
- ZPP : Las Vegas algorithms (probabilistic) are always correct in expected polynomial running time

BPP in Relation to Other Probabilistic Complexity Classes

BQP (bounded-error quantum polynomial time): the class of decision problems solvable by a quantum TM in polynomial time with bounded error

- It is the quantum analogue of BPP



Limits of BPP

Consensus: $\mathcal{P} \subseteq \underline{\mathcal{ZPP} = \mathcal{RP} \cap \text{co-}\mathcal{RP}} \subseteq BPP \subseteq \mathcal{NP}$

$\mathcal{P} \subseteq BPP$

- An important example of a problem in BPP still not known to be in \mathcal{P} is **polynomial identity testing** — determining whether a polynomial is identically equal to the zero polynomial, when you have access to the value of the polynomial for any given input, but not to the coefficients.

$BPP \subseteq \mathcal{NP}$

- Adleman's theorem: $BPP \subseteq P/\text{poly}$ (polynomial-size Boolean circuits)
- Karp-Levin theorem: $\mathcal{NP} \subseteq P/\text{poly} \Rightarrow \text{PH} = \sum_2^P$

Thus, $\mathcal{NP} \subseteq BPP$ will imply collapse of PH, which is unlikely to be true. In other words, \nexists bounded-error probabilistic algorithms for \mathcal{NPC} problems.

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PSPACE

\mathcal{P} : Decision problems solvable by DTM in polynomial time.

PSPACE: Decision problems solvable by DTM in polynomial space.

Example 16

- Binary counter. Count from 0 to $2^n - 1$ in binary.
- Algorithm. Use n bit odometer.

Observation $\mathcal{P} \subseteq \text{PSPACE}$

- This is because poly-time algorithm can consume only polynomial space.

Relation Between NP and PSPACE

Claim: $3\text{-SAT} \in \text{PSPACE}$.

Proof of claim

- Enumerate all 2^n possible truth assignments using counter.
- Check each assignment to see if it satisfies all clauses.

Theorem: $\mathcal{NP} \subseteq \text{PSPACE}$

- Consider arbitrary problem $Y \in \mathcal{NP}$.
- Since $Y \leq_p 3\text{-SAT}$, there exists algorithm that solves Y in poly-time plus polynomial number of calls to 3-SAT black box.
- Thus, Y can be solved by DTM in poly-space.

It is easy to verify that $\text{co-}\mathcal{NP} \subseteq \text{PSPACE}$.

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But for 3-SAT, given an instance x , we know the exact length of its witness.

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A: For \mathcal{NP} languages. Yes!

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$$L = \{(\phi, r) : \exists w \text{ s.t. } \phi(w) = 1 \wedge w < r\}$$

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Conclusion: decision 3-SAT \approx_{hard} search 3-SAT

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Languages defined by Cryptographic Problems

Example based on DDH w.r.t. $(\mathbb{G}, p, g_1, g_2)$

- $X = \mathbb{G} \times \mathbb{G}$;
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Remark: Cryptographic problems assume average-case complexity (for $x \xleftarrow{\mathcal{R}} X$), while problems in computer science consider worst-case complexity.

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Remark

Proving the existence of hard-on-average problems in \mathcal{NP} using the $\mathcal{P} \neq \mathcal{NP}$ assumption is a major open problem.

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Leading candidate: Lattice problems (enjoy both)

Reference I



Manindra Agrawal, Neeraj Kayal, and Nitin Saxena.

Primes is in P .

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