Yuchen Rao

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EDUCATION

Master of Science in Robotics	09/2016-12/2017
Northwestern University, Evanston, IL (GPA 3.90/4.00)	
Bachelor of Science in Mechanical and Electrical Engineering	09/2012-07/2016
China Agricultural University (CAU, which is a university in Project 985), Beijing, China	
GPA 3.88/4.00, Rank: 1/43	
ACADEMIC AWARDS	
Outstanding graduate of Beijing, China	05/2016
Outstanding graduate of CAU	05/2016
Excellent Student Award granted by the Ministry of Education with Scholarship, China, twice	09/2013-07/2014
Excellent Student Award with Scholarship, CAU	09/2015-07/2014
Excellent Student Award in Academics Grade 1 with Scholarship, CAU, three times	09/2013-07/2015
Excellent Student Award, CAU, twice	09/2013-07/2014

WORK EXPERIENCE

School Outstanding Members

Robotics Software Engineer, Otsaw Digital Inc, California, United State

The Honorable Mention for Mathematical Contest in Modeling (MCM) (America)

The 3rd place in NEAR Speak Out for Engineering Competition (Asian-Pacific region)

07/2018- present

09/2013-07/2012

03/2015

09/2014

- Tested move base navigation system on an ackermann drive robot
- Created a recovery method when robot gets stuck
- Designed a global path planner based on A* algorithm

Robotics Software Engineer Intern, Honda Research Institute USA, California, United State

02/2018-07/2018

- Simulated a Fetch robot decluttering a table of multiple cups in Gazebo, and implemented it on a real Fetch robot
- Detected centroid position of a cup based on pointcloud2 data by using Point Cloud Library(PCL)
- Designed arm movement by using MoveIt!, which considers obstacle avoidance and orientation constraints
- Retrained YOLO with custom data to classify specific bowls

Robotics Software Engineer Intern, Zoetic Inc., California, United State

09/2017-11/2017

- Developed a system for blob motion detection and tracking by using Lucas-Kanade optical flow in OpenCV
- Created a machine learning pipeline for classifying user's facial expression based on face features

PROJECTS

Robot Drawing Control Based on Detected Facial Emotion, Northwestern University

01/2017-04/2017

- Extracted facial features using OpenCV Haar Cascade and dense SIFT algorithm
- Developed machine learning pipeline capable of multi classification of user's real-time emotion (happy, sad, surprise, and disgust) using webcam
- Developed ROS software to control a Baxter Research Robot to draw images corresponding to result of emotion classification

Simulation Tool for Decentralized Multi-Robot Co-op Manipulation, Northwestern University 09/2017-12/2017

- Used a dynamic simulation library developed by Northwestern (trep) to develop kinematic and torque control strategies for the system, which allows the robots to manipulate the object through different desired trajectories
- Each robot consists of a four-mecanum wheeled mobile base and delta robot arm attachment

Autonomous Path-Following Car Controlled by Android Phone, Northwestern University

04/2017-06/2017

Designed and built a differential drive robot car using 3D printer and laser cutter

- Developed an image processing Android app for detecting the road with the phone's camera
- Motor controlled by PIC microcontroller on custom PCB communicating with Android over USB CDC protocol

Machine Learning Projects, Northwestern University

09/2016-07/2017

- Real time playing card recognition with OpenCV and Convolutional Neural Net in TensorFlow
- Developed a musical instrument classifier by using Mel-Frequency Cepstral Coefficients and SVM algorithm

Freescale Cup: Intelligent Car Racing (Electromagnetism Group), Beijing, China

05/2014-05/2015

Team Leader of Freescale Cup: Intelligent Car Racing of North China region (3rd place finish)

- Created software for controlling a car to follow a wire with PIC microcontroller
- Improved an adaptive PID algorithm to maintain steady velocity, and refined steering angle PD algorithm in greater stability and accuracy of turning angle
- Designed fuzzy controller and filtering scheme to determine set point for low-level steering angle controller

RESEARCH EXPERIENCE

Research Assistant, Tsinghua University, Beijing, China

10/2015-06/2016

Contributed into the research about Natural Language Processing (NLP): Extract emotions of online users based on the micro-blog article

 Developed software for emotion classification (happy, sad, surprise, disgust, angry and afraid) for online articles based on words and structure features of sentences using SVMPerf, and improved accuracy by 15% over previous solution that ignores sentence structure

Research Assistant, Renming University, Beijing, China

11/2014-09/2015

Contributed into the research about Music Information Retrieval (MIR): Music emotion classification for Erhu performance (Erhu is a traditional Chinese string instrument)

• Proposed and worked on a new researching direction: combines performer's actions (hand movement feature: velocity of the bow and move distance of the bow) and audio data as classification features, which improved the accuracy by 9.4% over previous solution that only considers audio data

SKILLS

- Proficient: C, C++, Python, ROS, Linux, Git/GitHub, Gazebo, MoveIt!, Mathematica, MATLAB, AutoCAD, SOLIDWORKS
- Experience: Eagle, V-REP, Weka, MPLAB, CodeWarrior, Android Studio
- Knowledge: PIC Microcontroller, PCB Design, Forward and Inverse Kinematics, Android Development, Optimal Control of Nonlinear System, Machine Learning, Computer Vision, Computational Geometry

EXTRACURRICULAR ACTIVITIES

Participated as an erhu performer in Stanford Chinese Music Chamber Orchestra, CA, United State

Volunteer in Community Animal Rescue Effort for cats caring, Chicago, United State

O7/2017-01/2018

Participated as an erhu performer in CAU Chinese Music Chamber Orchestra, Beijing, China

07/2012-09/2015

- The Solver Award of Chinese National Music Alliance's International Chinese Music Chamber Orchestra Competition (The world)
- The First Award of Beijing University Students Performance about Chinese Music Chamber Orchestra Competition (Beijing)

Volunteer of teaching, cleaning library and helping pupils, Beijing, China

O9/2012-09/2014

Investigated the promotion of democracy at the grass-roots level, Hebei, China

Member of Student Union of Engineering College, CAU, China

09/2012-09/2013

League Branch Secretary, CAU, China 09/2012-09/2013

HOBBIES

- Erhu
- Photograph
- Reading