Perturbation-Stable Maximum Cut

Yuchong Pan

UBC Beyond Worst-Case Analysis Reading Group (Based on Tim Roughgarden's Notes for Stanford CS264)

June 30, 2020

MAXIMUM CUT

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Input: An undirected graph G = (V, E) with edge weights $w_e > 0$ for each $e \in E$.

Goal: A cut (A, B) that maximizes the weight of the *crossing* edges.

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► MAXIMUM CUT is a type of 2-clustering problem (e.g. weights measure dissimilarities).

Problem (MAXIMUM CUT, Decision Version)

Input: An undirected graph G = (V, E) with edge weights

 $w_e > 0$ for each $e \in E$, and a positive integer W.

Output: Yes iff. there is a set $S \subseteq V$ such that the weight of the

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Proof Sketch (PARTITION \leq_P MAXIMUM CUT)

- $ightharpoonup G = K_n$.
- $ightharpoonup w_{ij} = c_i c_j$ for all $i, j \in V, i \neq j$.
- $W = \lceil \frac{1}{4} \sum_{i} c_i^2 \rceil.$



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- ► **Question:** Can't we negate the edge weights, yielding a MINIMUM CUT instance?
- ▶ No! Polynomial-time algorithms solving MINIMUM CUT require nonnegative edge weights.

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▶ **Theme:** To recover the optimal solution in polynomial time in γ -perturbation-stable instances, where γ is as small as possible.

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Definition (γ -Perturbation-Stability)

For $\gamma \geq 1$, an instance of MAXIMUM CUT is γ -perturbation-stable if a cut (A,B) is the *unique* optimal solution to all γ -perturbations, where each original edge weight w_e is replaced with an edge weight $w_e' \in \left[\frac{1}{\gamma}w_e, w_e\right]$.

▶ Question: Can we use an LP relaxation similar to the one for MINIMUM CUT, i.e.

$$\begin{array}{ll} \max & \sum_{e \in E} w_e x_e \\ \\ \text{s.t.} & x_e \geq |d_u - d_v| \,, \qquad \forall e = uv \in E, \\ & x_e \in [0,1], & \forall e \in E, \\ & d_v \in [0,1], & \forall v \in V. \end{array}$$

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- No! $x_e = 1$ for each $e \in E$ is a feasible solution and maximizes the objective value.
- ▶ **Question:** What about $x_e \le d_u d_v$ and $x_e \le d_v d_u$?
- ▶ This forces $x_e = 0$, instead of $x_e \le |d_u d_v|$.

Let $x_{ij} \in \{0,1\}$ denote whether or not i,j are on different sides of the cut, for all distinct $i,j \in V$. We denote by x_{ij} and x_{ij} the same variable.

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► Hence we obtain the LP relaxation (LP-MAXCUT):

$$\begin{aligned} \max & & \sum_{(i,j) \in E} w_{ij} x_{ij} \\ \text{s.t.} & & x_e \geq |d_u - d_v| \,, \quad \forall e = uv \in E, \\ & x_{ij} + x_{ik} + x_{jk} \leq 2, & \forall i,j,k \in V \text{ distinct}, \\ & x_{jk} \leq x_{ij} + x_{ik}, & \forall i,j,k \in V \text{ distinct}, \\ & x_{ij} \in [0,1], & \forall i,j \in V \text{ distinct}. \end{aligned}$$

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- ► MINIMUM MULTIWAY CUT: For each iteration, a group and a threshold are chosen uniformly randomly.



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 - **Exercise 2.** Show how to find (in polytime) a bfs with objective value within the range. You may use the LP oracle.
- ➤ Since all of the extreme points of the feasible region are integral and correspond to a cut, then LP algorithms always solve (LP-MaxCut) to an integral optimal solution.

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- ▶ Formally, we define $\Delta(C)$ to be the total cost of C that exceeds that of C^* and $\Delta(\hat{x})$ to be total cost of C^* that exceeds the objective function value of \hat{x} .

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- ▶ We show that $\mathbb{E}[\Delta(C)] \leq 0$ by the probability properties of the cut generated by the randomized rounding algorithm.
- Since $\Delta(C) \ge 0$ and since the equality holds iff. C is an optimal cut, it follows that the randomized rounding algorithm outputs an optimal cut w.p.1.

Randomized Rounding Algorithm

Lemma

Fix an instance of the MAXIMUM CUT problem, with F^* the edges in the optimal cut, and \hat{x} the optimal solution to (LP-MAXCUT). Then there exists a randomized algorithm that generates a random cut (A,B) and a scaling parameter $\sigma>0$ such that:

1. For every edge $e = ij \notin F^*$,

$$\mathbb{P}[e \ cut \ by \ (A,B)] \geq \sigma \cdot \frac{\hat{x}_{ij}}{\alpha},$$

where
$$\alpha = \Theta(\log n)$$
;

2. For every edge $e = ij \in F^*$,

$$\mathbb{P}[e \text{ not cut by } (A,B)] \leq \sigma \cdot (1-\hat{x}_{ij});$$

3. The rounding algorithm is deterministic iff. \hat{x} is integral.



► Exercise: Show that this lemma implies the main theorem (outlined above, Homework #4).

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Proposition

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$$\hat{y}_{ij} = \begin{cases} \hat{x}_{ij}, & \text{if } i, j \text{ are on the same side of } C, \\ 1 - \hat{x}_{ij}, & \text{if } i, j \text{ are on different sides of } C. \end{cases}$$

Then \hat{y} satisfies the triangle inequality:

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► That is, \hat{x} , \hat{y} are both **pseudometrics** (i.e. metrics except that distinct points may have zero distances).



Theorem (Bourgain's Theorem)

For every n-point pseudometric space (X,d), there exists a randomized algorithm that generates a random partition (A,B) of X and a scaling parameter $\sigma>0$ such that, for all distinct $i,j\in X$,

$$\mathbb{P}[i,j \text{ on different sides of } (A,B)] \in \sigma \cdot \left[\frac{d(i,j)}{\alpha},d(i,j)\right],$$

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- ▶ That is, every n-point metric space admits a randomized partitioning algorithm so that the sepration probabilities between pairs of points are *proportional* to the distances, up to a $\Theta(\log n)$ factor.
- ► The $\Theta(\log n)$ approximation factor is the best possible for **arbitrary** pseudometric spaces.



Proof (Proposition & Bourgain's Theorem ⇒ Lemma).

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- ▶ By Proposition, ŷ is a pseudometric.
- ▶ By Bourgain's Theorem, there is a randomized algorithm that outputs a partition (A, B) and $\sigma > 0$ such that

$$\mathbb{P}[i,j \text{ on different sides of } (A,B)] = \sigma \cdot \left[\frac{\hat{y}_{ij}}{\alpha},\hat{y}_{ij}\right],$$

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► Exercise: Prove Proposition and Bourgain's Theorem (Homework #4). For Bourgain's Theorem see e.g. CPSC 531F Tools for Modern Algorithm Analysis.



Definition (α -Embeddings)

Let $(X, d_X), (Y, d_Y)$ be metric spaces. We say that $\phi: X \to Y$ is an α -embedding if there exists r > 0 such that

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- ▶ **Dimensionality reduction** is the process of mapping a high dimensional dataset to a lower dimensional space, while preserving much of the important structure.
- ▶ For instance, let $X \subseteq \mathbb{R}^d$ and $Y = \mathbb{R}^t$ with t < d and d_X, d_Y being the Euclidean distance.

Theorem (Johnson-Lindenstrauss, 1984)

Let $x_1, \ldots, x_n \in \mathbb{R}^d$. Let $\epsilon \in (0,1)$. Then for some $t = O(\frac{\log(n)}{\epsilon^2})$, there exist $y_1, \ldots, y_n \in \mathbb{R}^t$ such that

$$\begin{array}{cccc} (1 - \epsilon) \|x_j\| & \leq & \|y_j\| & \leq & (1 + \epsilon) \|x_j\|, & \forall j \in [n], \\ (1 - \epsilon) \|x_j - x_{j'}\| & \leq & \|y_j - y_{j'}\| & \leq & (1 + \epsilon) \|x_j - x_{j'}\|, & \forall j, j' \in [n]. \end{array}$$

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Notation: $||v|| = \sqrt{\sum_{i=1}^n v_i^2}$.

Remark: There is a *random linear map* such that for any x_1, \ldots, x_n the above condition holds with probability at least $\frac{1}{2n}$. This linear map is *oblivious*: it does not depend on x_1, \ldots, x_n at all! In fact, the linear map is just a matrix whose entries are independent Gaussians.

Theorem (Bourgain's Metric Embedding Theorem)

For any metric space (V,d), there exists an $O(\log n)$ -embedding into $\mathbb{R}^{O(\log^2 n)}$ with the ℓ_1 -norm that is computable with high probability by a randomized polynomial-time algorithm.

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► This result is the best possible; i.e., there exists a metric that cannot be embedded into ℓ_1 with distortion less than $\Omega(\log n)$.

Definition (Cut Metrics)

A metric (X, d) is a *cut metric* if there exists $S \subseteq X$ such that d(x, y) = 0 whenever $x, y \in S$ or $x, y \notin S$, and d(x, y) = 1 otherwise.

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- **Exercise:** Prove Lemma.
- ► Lemma and Bourgain's Metric Embedding Theorem imply Bourgain's Theorem in the proof of the main theorem.

Problem (Sparsest Cut)

Input: An undirected graph G = (V, E) with edge weights $w_e > 0$ for each $e \in E$, and k pairs of vertices (s_i, t_i) each with demand d_i .

Goal: A set of vertices *S* that minimizes

$$\rho(S) \equiv \frac{\sum_{e \in \delta(S)} c_e}{\sum_{i:|S \cap \{s_i,t_i\}|=1} d_i}.$$

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Corollary

There is a randomized $O(\log n)$ -approximation algorithm for SPARSEST CUT.

Tree Metric Embedding

Definition (Tree Metrics)

A metric (X, d) is a *tree metric* if there exists a tree T = (V, E) with edge costs c_e for each $e \in E$ such that d(u, v) is the cost of the unique path from u to v in T.

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Theorem (Fakcharoenphol-Rao-Talwar)

For any metric (V,d) such that $d(u,v) \ge 1$ for all $u,v \in V$ with $u \ne v$, there exists a randomized, polynomial-time algorithm that produces a tree metric $(V',T), V \subseteq V'$ such that for all $u,v \in V$, we have $d(u,v) \le T_{uv}$ and $\mathbb{E}[T_{uv}] \le O(\log n)d(u,v)$.

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► The above result is obtained via the method of **hierarchical tree decomposition**.

Semidefinite Programming

Definition (Positive Semidefinite Matrices)

A matrix $X \in \mathbb{R}^{n \times n}$ is positive semidefinite (or psd), denoted $X \succeq 0$, if $y^T X y \ge 0$ for all $y \in \mathbb{R}^n$.

Fact

If $X \in \mathbb{R}^{n \times n}$ is a symmetric matrix, then the following statements are equivalent:

- 1. X is psd;
- 2. X has nonnegative eigenvalues;
- 3. $X = V^T V$ for some $V \in \mathbb{R}^{m \times n}$ where $m \leq n$;
- 4. $X = \sum_{i=1}^{n} \lambda_i w_i w_i^T$ for some $\lambda_i \geq 0$ and $w_i \in \mathbb{R}^n$ such that $w_i^T w_i = 1$ and $w_i^T w_j = 0$ for all $i \neq j$.

Semidefinite Programming

Definition (Semidefinite Programming, SDP)

A semidefinite program, or SDP, is a mathematical program with real-valued variables, a linear objective function, linear constraints, and a square symmetric matrix of variables constrained to be psd.

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▶ Below is an example of SDP with variables x_{ij} for $i, j \in [n]$:

max or min
$$\sum_{i,j\in[n]} c_{ij}x_{ij} \tag{1}$$
 s.t.
$$\sum_{i,j\in[n]} a_{ijk}x_{ij} = b_k, \qquad \forall k\in[n],$$

$$x_{ij} = x_{ji}, \qquad \forall i,j\in[n],$$

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SDP can be solved to within an additive error of ϵ in polynomial time in the size of the input and $\log(\frac{1}{\epsilon})$.



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A *vector program* is a mathematical program with variables $v_i \in \mathbb{R}^n$, where n is the number of vectors, and an objective function and constraints linear in the inner products of the vectors.

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max or min
$$\sum_{i,j\in[n]} c_{ij} (v_i \cdot v_j)$$
(2)
s.t.
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$$v_i \in \mathbb{R}^n, \qquad \forall i \in [n].$$

Theorem (Equivalence of SDP and Vector Programming)

The SDP (1) and the vector program (2) are equivalent.

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- ► Hence, $z_i z_j$ is 0 if i, j are on the same side of the cut, and ± 2 otherwise.
- ▶ Equivalently, $(z_i z_j)^2$ is 0 if i, j are on the same side of the cut, and 4 otherwise.

► Hence we obtain the **exact** quadratic programming formulation of MAXIMUM CUT:

max
$$\frac{1}{4}\sum_{ij\in E}w_{ij}(z_i-z_j)^2$$
 s.t. $z_i\in\{-1,+1\}, \quad \forall i\in V.$

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► This quadratic program is **equivalent** to MAXIMUM CUT. Hence optimizing this program is *NP*-hard.

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- ▶ Hence relaxing each $z_i \in \{-1,1\}$ to a **unit vector** $v_i \in \mathbb{R}^n$ and therefore replacing quadratic terms with inner products yield a vector program that is computationally tractable:

$$\max \qquad \frac{1}{4} \sum_{ij \in E} w_{ij} \left\| \mathsf{v}_i - \mathsf{v}_j \right\|^2$$

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- ▶ This vector program is a relaxation of the quadratic program by setting $v_i = (z_i, 0, ..., 0) \in \mathbb{R}^n$.

Goemans-Williamson Approximation Algorithm

► The above vector programming relaxation already leads to the best-known approximation algorithm for MAXIMUM CUT:

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Theorem (Goemans-Williamson Approximation Algorithm)

There is a randomized .878-approximation algorithm for $MAXIMUM\ CUT$.

Theorem

Given the unique game conjecture there is no α -approximation for MAXIMUM CUT with constant $\alpha > .878$ unless P = NP.

For our purposes we want the vector programming relaxation to generalize the LP relaxation. Hence we want the analogs of the following two sets of constraints:

$$x_{ij} + x_{ik} + x_{jk} \le 2,$$
 $\forall i, j, k \in V \text{ distinct},$
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► This implies the following two sets of constraints in the form of inner products:

$$\begin{split} \|\mathbf{v}_{i} - \mathbf{v}_{j}\|^{2} + \|\mathbf{v}_{i} - \mathbf{v}_{k}\|^{2} + \|\mathbf{v}_{j} - \mathbf{v}_{k}\|^{2} &\leq 8, \quad \forall i, j, k \in V \text{ distinct,} \\ \|\mathbf{v}_{j} - \mathbf{v}_{k}\|^{2} &\leq \|\mathbf{v}_{i} - \mathbf{v}_{j}\|^{2} + \|\mathbf{v}_{i} - \mathbf{v}_{k}\|^{2}, \qquad \forall i, j, k \in V \text{ distinct.} \end{split}$$

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▶ The extended vector program, which we call (VP-MAXCUT), is still a relaxation for MAXIMUM CUT by setting v_i to $\pm e_1$ according to i's side.

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- We first proved a proposition saying that if \hat{x} is a pseudometric, then \hat{y} defined below is also a pseudometric:

$$\hat{y}_{ij} = \begin{cases} \hat{x}_{ij}, & \text{if } i, j \text{ are on the same side of } C, \\ 1 - \hat{x}_{ij}, & \text{if } i, j \text{ are on different sides of } C. \end{cases}$$

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► This proposition and Bourgain's Theorem imply the lemma for the existence of randomized rounding algorithm that outputs a (random) cut such that the probability of an edge being cut is approximately the same as the value of the corresponding decision variable.

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- ➤ This proposition and Bourgain's Theorem imply the lemma for the existence of randomized rounding algorithm that outputs a (random) cut such that the probability of an edge being cut is approximately the same as the value of the corresponding decision variable.
- ► The lemma then implies the exact recovery theorem by a common pattern used in perturbation-stable MINIMUM CUT and MINIMUM MULTIWAY CUT.



► Fix an instance of MAXIMUM CUT. Let $\hat{\mathbf{v}}_i$'s be an optimal solution to the vector program. Let $\hat{\mathbf{x}}_{ij} = \frac{1}{4} \|\mathbf{v}_i - \mathbf{v}_j\|^2$ for any distinct $i, j \in V$.

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Definition (ℓ_2^2 Metrics)

A metric (X, d) is an ℓ_2^2 **metric** if it represents squared Euclidean distances between points in \mathbb{R}^k for some k.

That is, there exists an embedding from X to \mathbb{R}^k for some k such that $d(\cdot, \cdot)$'s are squared Euclidean distances between points in \mathbb{R}^k .

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Theorem (Arora, Lee, and Naor, 2005)

For every n-point ℓ_2^2 metric space (X,d), there exists a randomized algorithm that generates a random partition (A,B) of X and a scaling parameter $\sigma>0$ such that, for all distinct $i,j\in X$,

$$\mathbb{P}[i,j \text{ on different sides of } (A,B)] \in \sigma \cdot \left[\frac{d(i,j)}{\alpha},d(i,j)\right],$$

where $\alpha = O(\sqrt{\log n} \log \log n)$.

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- ▶ Hence we prove an analog of the proposition used in the exact recovery with $\gamma = \Theta(\log n)$. That is, if \hat{x} is an ℓ_2^2 metric, then so is the similarly defined \hat{y} .

Proposition

Fix an instance of MAXIMUM CUT, a cut C, and a feasible solution $\hat{\mathbf{v}}_i$'s to (VP-MAXCUT). Let $\hat{\mathbf{x}}$ be the induced ℓ_2^2 metric $\hat{\mathbf{x}}_{ij} = \frac{1}{4} \|\mathbf{v}_i - \mathbf{v}_j\|^2$. For distinct $i, j \in V$, define

$$\hat{y}_{ij} = \begin{cases} \hat{x}_{ij}, & \text{if } i, j \text{ are on the same side of } C, \\ 1 - \hat{x}_{ij}, & \text{if } i, j \text{ are on different sides of } C. \end{cases}$$

Then \hat{y} is also an ℓ_2^2 metric.

Proof.

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▶ Then $\hat{y}_{ij} = \frac{1}{4} ||\hat{u}_i - \hat{u}_j||^2$ for any distinct $i, j \in V$.



Lemma

Fix an instance of Maximum Cut, with F^* the edges in the optimal cut, and v_i 's the optimal solution to (VP-MaxCut). Then there exists a randomized algorithm that generates a random cut (A,B) and a scaling parameter $\sigma>0$ such that:

1. For every edge $e = ij \notin F^*$,

$$\mathbb{P}[e \ cut \ by \ (A,B)] \geq \sigma \cdot \frac{\frac{1}{4} \|v_i - v_j\|^2}{\alpha},$$

where $\alpha = \Theta(\sqrt{\log n} \log \log n)$;

2. For every edge $e = ij \in F^*$,

$$\mathbb{P}[e \text{ not cut by } (A, B)] \leq \sigma \cdot \left(1 - \frac{1}{4} \|\mathsf{v}_i - \mathsf{v}_j\|\right);$$

3. The rounding algorithm is deterministic iff. \hat{v}_i 's are integral.



▶ By $\hat{\mathbf{v}}_i$'s being **integral**, we mean that there exist antipodal unit vectors \mathbf{w} , $-\mathbf{w}$ such that $\hat{\mathbf{v}}_i \in \{\mathbf{w}, -\mathbf{w}\}$ for each $i \in V$.

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Theorem

There is a constant c>0 such that in every $(c\sqrt{\log n}\log\log n)$ -perturbation-stable instance of MAXIMUM CUT with n vertices, every optimal solution to (VP-MAXCUT) is integral.

Can We Do Better?

Theorem

There exist $O(\sqrt{\log n})$ -perturbation-stable instances of Maximum Cut for which the optimal solution to (VP-MaxCut) is not integral.

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Theorem

Assuming the Unique Game Conjecture, for every constant $\gamma \geq 1$, there is no polynomial-time algorithm for certifiable exact recovery in γ -perturbation-stable instances of Maximum Cut.

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Assuming the Unique Game Conjecture, for every constant $\gamma \geq 1$, there is no polynomial-time algorithm for certifiable exact recovery in γ -perturbation-stable instances of Maximum Cut.

▶ Both results are based upon a reduction from SPARSEST CUT to MAXIMUM CUT. See *Bilu–Linial Stable Instances of Max Cut and Minimum Multiway* by Makarychev, Makarychev, and Vijayaraghavan (2013) and Homework #4.