# Equipping Federated Graph Neural Networks with Structure-aware Group Fairness

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Abstract—Graph Neural Networks (GNNs) are used for graph data processing across various domains. Centralized training of GNNs often faces challenges due to privacy and regulatory issues, making federated learning (FL) a preferred solution in a distributed paradigm. However, GNNs may inherit biases from training data, causing these biases to propagate to the global model in distributed scenarios. Addressing this, we introduce F<sup>2</sup>GNN, a Fair Federated Graph Neural Network, to enhance group fairness. Recognizing that bias originates from both data and algorithms, F<sup>2</sup>GNN aims to mitigate both types of bias under federated settings. We offer insights into the relationship between data bias and statistical fairness metrics in GNNs. Building on this, F<sup>2</sup>GNN features a fairness-aware local model update scheme and a fairness-weighted global model update scheme, considering both data bias and local model fairness during aggregation. Empirical evaluations show  $F^2GNN$  outperforms baselines in fairness and accuracy.

Index Terms—Graph Neural Networks, Federated Learning, Group Fairness

#### I. Introduction

Graph neural networks (GNNs) have emerged as a formidable tool for generating meaningful node representations [14] and making accurate predictions on nodes by leveraging graph topology [29]. Despite its success in graph analytics, training GNNs over centralized graph data has been limited in practice due to privacy concerns. Federated learning, a trending distributed learning paradigm, has emerged as a promising solution. Several federated GNNs [26], [28] have been designed recently.

Recent studies have revealed that predictions of GNNs (over centralized data) can be unfair and have undesirable discrimination [3], [11]. Under the federated learning setting, the bias in the local GNN models can be easily propagated to the global model. While most of the prior works [5], [6] mainly consider the federated learning models trained over non-graph data, none of them have studied federated GNNs. How to enhance the fairness of GNNs under federated settings remains to be largely unexplored.

In general, the bias of GNNs can be stemmed from two different sources: (1) bias in graph data [11], [15], and (2) bias in learning algorithms (e.g., the message-passing procedure of GNNs) [2], [12]. In this paper, we aim to enhance the group fairness of federated GNNs by mitigating both types of bias. In particular, in terms of data bias, we group the nodes by their sensitive attribute (e.g., gender and race). Then we group the links between nodes based on the sensitive attribute values of the connecting nodes: (1) the *intra-group links* that

connect nodes belonging to the same node groups (i.e., the same sensitive attribute value), and (2) the *inter-group links* that connect nodes that belong to different node groups. Based on the link groups, we consider the data bias that takes the form of the *imbalanced distribution between inter-group and intra-group links*, which is a key factor to the disadvantage of minority groups by GNNs [11]. On the other hand, in terms of model fairness, we consider two well-established group fairness definitions: *statistical parity* (SP) [1], [2] and *equalized odds* (EO) [12], [24].

In this paper, we propose F<sup>2</sup>GNN, one of the first federated graph neural networks that enhance group fairness of both local and global GNN models. Our contributions are summarized as follows: 1) We provide theoretical insights on the connection between data bias (imbalanced distributions between inter-group and intra-group links) and model fairness (SP and EO); 2) Based on the theoretical findings, we design F<sup>2</sup>GNN that enhances group fairness of both local and global GNN models by taking both the data bias of local graphs and statistical fairness metrics of local models into consideration during the training of both local and global models; 3) Through experiments on two real-world datasets, we demonstrate that F<sup>2</sup>GNN outperforms the baseline methods in terms of both fairness and model accuracy.

#### II. FEDERATED GRAPH LEARNING

**Notations.** We consider an undirected graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E}, \mathbf{X})$ , comprising nodes  $\mathcal{V}$ , edges  $\mathcal{E}$ , and node features  $\mathbf{X}$ , with  $\mathbf{A}$  as its adjacency matrix.  $\mathbf{Z}$  represents the node representations (embedding) learned by a GNN model. This paper focuses on node classification, using y and  $\hat{y}$  to represent the ground truth and predicted labels, respectively.

**Federated Graph Learning.** This study explores *horizontal* federated learning (HFL) setting [4], involving K clients  $\{C_1, \ldots, C_K\}$  and a server S. Each client  $C_i$  possesses a unique private graph  $G_i$ , with different  $V_i$  and  $A_i$ , while sharing the same set of node features.

In HFL, clients retain their local graphs, avoiding sharing with the server S for reasons such as privacy. The goal of HFL is to optimize the global objective function while maintaining the privacy of local graphs:

$$\arg\min_{\omega} \sum_{i=1}^{K} \mathcal{L}_i(\omega) = \arg\min_{\omega} \sum_{i=1}^{K} \sum_{j=1}^{N_i} \ell_i(v_j, \mathcal{G}_i; \omega).$$

Here,  $\mathcal{L}_i(\omega)$  is the loss function for client  $C_i$ , parameterized by  $\omega$ ,  $N_i$  is the number of nodes in the local graph  $\mathcal{G}_i$ , and  $\ell_i(v_j, \mathcal{G}_i; \omega)$  denotes the average loss over the local graph of client  $C_i$ .

In this work, we adapt the SOTA FedAvg framework [18] to our context. In FedAvg, only model parameters are exchanged between  $\mathcal S$  and each client  $C_i$ . Specifically, in each round t,  $\mathcal S$  sends the current global model parameters  $\omega_t$  to a selected subset of clients for local training. Each selected client  $C_i$  refines  $\omega_t^i$  locally and returns the updated parameters to  $\mathcal S$ , which then aggregates them to form the new global model  $\omega_{t+1}$ , subsequently broadcasted for the next round of training. The process continues until convergence is achieved.

#### III. GROUP FAIRNESS AND DATA BIAS

This paper emphasizes group fairness, where the model output should not discriminate between *protected groups* (e.g., female) and *un-protected groups* (e.g., male) based on a sensitive attribute like gender [1].

**Node groups.** Adapting conventional group fairness, we assume each graph node has a *sensitive attribute* s (e.g., gender) [19]. Nodes are grouped by this attribute's values. Considering a binary attribute, we use s=0 and s=1 for protected and un-protected node groups.

**Edge categorization.** Edges are categorized based on node groups into: (1) *inter-group edges* connecting nodes from different groups (e.g., the edges between female and male nodes); (2) *intra-group edges* connecting nodes within the same group (e.g., the edges between male and male nodes).

**Data bias in edge distribution.** Recent studies indicate that GNN unfairness can arise from imbalanced edge distributions in training graphs [11]. We focus on this imbalance between inter-group and intra-group edges. In particular, we define *group balance score* (GBS) to quantify this bias.

**Definition 1.** For a graph  $\mathcal{G}$ , with  $|\mathcal{E}_{inter}|$  as inter-group edges and  $|\mathcal{E}_{intra}|$  as intra-group edges, and  $|\mathcal{E}| = |\mathcal{E}_{intra}| + |\mathcal{E}_{inter}|$  as total edges, GBS (denoted as B) is defined as follows:

$$B = 1 - (|H_{intra}| - |H_{inter}|),$$
where  $H_{intra} = \frac{|\mathcal{E}_{intra}|}{|\mathcal{E}|}$  and  $H_{inter} = \frac{|\mathcal{E}_{inter}|}{|\mathcal{E}|}$ . (1)

A higher B indicates a better balance between different edge types. Maximum balance (B=1) occurs when both edge groups are equal (i.e.,  $|H_{\text{intra}}|=|H_{\text{inter}}|$ ).

Group fairness of models. To assess the group fairness of the GNN model, we employ two established fairness definitions: statistical parity (SP) [1], [2], [15] and equalized odds (EO) [12], [24]. SP measures the difference in positive outcome probabilities between node groups as:  $\Delta_{\rm SP} = |P(\hat{y}=1|s=0)-P(\hat{y}=1|s=1)|$  reflecting the positive rate difference between two node groups. EO gauges the difference in true positive rates of node groups as:  $\Delta_{\rm EO} = |P(\hat{y}=1|y=1,s=0)-P(\hat{y}=1|y=1,s=1)|$  indicating the true positive rate difference for these groups.

In this paper, we adapt both fairness definitions to node classification tasks. Both SP and EO provide complementary insights into fairness in node classification. While other accuracy measurements exist, they are topics for future exploration. We also consider both *local fairness* and *global fairness*. Previous research [22] suggests that while local and global fairness don't necessarily imply each other, global fairness is influenced by local fairness under IID distribution. Our empirical studies (Section VI) show that F<sup>2</sup>GNN achieves both local and global fairness, even for non-IID distributions.

# IV. CONNECTION BETWEEN DATA BIAS AND MODEL FAIRNESS

Data bias has been identified as a significant source of model unfairness. In this section, we investigate how the imbalanced distribution between intra-group and inter-group links affects the model fairness, specifically in terms of SP and EO.

Given the complexity of directly examining the impact of data bias on SP and EO, we approach model fairness through graph representations. Intuitively, group fairness requires that model outputs should not differ based on sensitive attributes. If graph representations are invariant to these attributes, group fairness can be achieved [15]. To measure the correlation between the graph representation and the sensitive attribute, we utilize the *Point-Biserial Correlation* [9].

**Definition 2** (Point-Biserial Correlation Coefficient). The point-biserial correlation coefficient quantifies the degree of association between a continuous variable and a dichotomous variable. Given a dichotomous variable s ( $s \in \{0,1\}$ ) and a continuous variable X, the point-biserial correlation coefficient  $\rho_{X,s}$  is defined as:

$$\rho_{X,s} = \frac{\mu_0 - \mu_1}{\sigma_X} \sqrt{\frac{N_0 N_1}{N^2}},$$

where  $\mu_0$  ( $\mu_1$ ) is the mean value of X that are associated with s=0 (s=1),  $N_0$  ( $N_1$ ) is the number of samples in the class s=0 (s=1),  $N=N_0+N_1$ , and  $\sigma_X$  is the standard deviation of X.

The traditional point-biserial correlation is defined with a 1-dimensional variable, X. Consistent with prior work [15], we expand this to accommodate higher-dimensional data via a node feature matrix  $\mathbf{X}$ , represented as  $\mathbf{X} \in \mathbb{R}^{N \times d}$ , with N as the node number and d the feature dimension. Here,  $\mu_0$  ( $\mu_1$ ) is the mean of the j-th dimension of node features for nodes with a sensitive attribute s=0 (s=1), where  $j\in 1,...,d$ . We will use  $\mu_0$  ( $\mu_1$ ) and  $\mu_j^{s=0}$  ( $\mu_j^{s=1}$ ) interchangeably. After computing the means  $\mu_0$  and  $\mu_1$  for a specific column j, the point-biserial correlation is calculated as traditionally defined.

Given a graph  $\mathcal{G}$ , with s as its sensitive attribute and  $\mathbf{Z}$  as its representation (node embeddings), we analyze the relationship between data bias (group balance score) and the correlation  $\rho_{\mathbf{Z},s}$  between s and  $\mathbf{Z}$ . Our theoretical analysis is grounded on two assumptions:

- Model assumption: We assume the GNN model contains a linear activation function [25].
- **Data assumption**: Let  $\mathbf{X}_{j}^{s=0}$  and  $\mathbf{X}_{j}^{s=1}$  be the *j*-th feature of those data samples associated with the sensitive attribute s=0 and s=1 respectively. Following prior

works [12], [17], we assume the data values of  $\mathbf{X}_{j}^{s}$  follow a Gaussian distribution  $\mathcal{N}(\mu_{j}^{s}, \sigma_{j}^{s})$ , where  $\mu_{j}^{s}$  and  $\sigma_{j}^{s}$  are the mean and variance of  $\mathbf{X}_{i}^{s}$ .

Based on these assumptions, we derive the following:

**Lemma 3.** Given a graph G and a GNN model that satisfies the data and model assumptions respectively, the Point-biserial correlation (denoted as  $\rho_{\mathbf{Z},s}$ ) between the graph representation  $\mathbf{Z}$  and the sensitive attribute s is measured as the following:

$$\rho_{\mathbf{Z},s} = (N_0\mu_0 - N_1\mu_1)(H_{intra} - H_{inter}) \cdot \frac{\sqrt{N_0\,N_1}}{\sigma_{\mathbf{Z}}N^2},$$
 where  $H_{intra}$  and  $H_{inter}$  are defined by Definition 1,  $N_0$  ( $N_1$ ) is the number of nodes associated with  $s=0$  ( $s=1$ ),  $\sigma_{\mathbf{Z}}$  is the standard deviation of  $\mathbf{Z}$ ,  $N$  is the total number of nodes of  $\mathcal{G}$ , and  $\mu_0$  ( $\mu_1$ ) is the mean value of nodes that are associated with  $s=0$  ( $s=1$ ).

When  $\rho_{\mathbf{Z},s}=0$  (indicating graph representation's independence from the sensitive attribute), it implies  $N_0\mu_0=N_1\mu_1$  or  $H_{\text{intra}}=H_{\text{inter}}$ . Given that  $N_0$  and  $N_1$  are constants for a graph, we present the subsequent theorem:

**Theorem 4.** Let  $\mathcal{G}$  be a graph that satisfies the given data assumption, and  $\mathbf{Z}$  be the representation of  $\mathcal{G}$  learned by a GNN model that satisfies the given model assumption. Then, the Point-biserial correlation  $\rho_{\mathbf{Z},s}$  between the graph representation  $\mathbf{Z}$  and the sensitive attribute s is positively correlated/monotonically increasing with  $|H_{intra} - H_{inter}|$ . In particular,  $\rho_{\mathbf{Z},s} = 0$  when  $H_{intra} = H_{inter}$ .

The Theorem 4 suggests that the balance between intergroup and intra-group links is crucial for the correlation between graph representations and the sensitive attribute. A balanced distribution should lead to a fairer model. This insight guides the design of our method.

# V. DETAILS OF F<sup>2</sup>GNN ALGORITHM

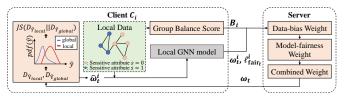


Fig. 1: The overview of F<sup>2</sup>GNN. In each iteration, client  $C_i$  receives the global model, calculates the Jensen-Shannon (JS) divergence  $\mathrm{js}_t^i$ , and updates its local model  $\hat{\omega}_t^i$  using a 2-layer GCN over several epochs. The updated model  $\omega_t^i$  and the group balance score  $B_i$  are sent to the server. The server then computes the data-bias and model-fairness weights, integrates them, and updates the global model  $\omega_t$  using the combined weight.

In a nutshell,  $F^2GNN$  follows the principles of FedAvg [18]: in each round t, the server  $\mathcal{S}$  uniformly samples a set of clients. Each selected client  $C_i$  receives the current global parameters  $\omega_t$ , and updates its local model  $\omega_t^i$  by learning over its local graph  $\mathcal{G}_i$  with  $\omega_t$  as the initialized model parameters. Then, each client  $C_i$  sends  $\omega_t^i$  back to  $\mathcal{S}$ . The server aggregates all received local model updates on  $\omega_t$  to obtain  $\omega_{t+1}$ . To ensure

both local and global fairness within the federated learning framework, F<sup>2</sup>GNN comprises two main components:

- Client-side fairness-aware local model update scheme: Each client  $C_i$  determines  $\omega_t^i$  by incorporating local fairness into the loss function of its local model as a penalty term.
- Server-side fairness-weighted global model update scheme: When S aggregates all local model updates from the clients, it considers both the fairness metrics of local models (like SP or EO) and the data bias of local graphs as aggregation weights.

Figure 1 illustrates the framework of F<sup>2</sup>GNN. Next, we present the details of each component.

# A. Client-side Fairness-aware Local Model Update

Intuitively, the local model update scheme pursues two objectives: 1) Ensuring convergence of both the local models on clients and the global model on the server, particularly when client data is non-iid, and 2) Integrating fairness (both SP and EO) into local models by seamlessly adding the fairness constraint during training. To meet these goals, we employ two techniques: (i) model interpolation using the Jensen-Shannon (JS) divergence [20], and (ii) introducing fairness as a penalty in the local models' loss function. Next, we discuss the details of each technique.

JS divergence between global and local models. In federated GNN training, a challenge arises when local client data is not IID [16]. This data distribution variance can hinder the global model's convergence due to conflicting goals of minimizing local and global empirical losses. To address this, F<sup>2</sup>GNN, inspired by Zheng *et al.* [30], evaluates the disparity between local and global models, incorporating this difference during local model parameter updates.

Specifically, consider  $\omega_t$  as the global model parameters at epoch t and  $\omega_{t-1}^i$  as the local parameters for client  $C_i$  at epoch t-1. The distributions of node labels in  $C_i$ 's local graph, predicted by the global and local models, are represented as  $D_{\hat{\mathbf{Y}}_{\text{global}}}$  and  $D_{\hat{\mathbf{Y}}_{\text{local}}}$  respectively. When client  $C_i$  receives  $\omega_t$ , it computes the Jensen-Shannon (JS) divergence,  $\mathrm{js}_t^i$ , between these distributions:  $\mathrm{js}_t^i = \mathrm{JS}(D_{\hat{\mathbf{Y}}_{\mathrm{global}}}||D_{\hat{\mathbf{Y}}_{\mathrm{local}}})$ .

A higher  $js_t^i$  suggests a significant difference between the global and local models. Using this, client  $C_i$  determines its initial local model update,  $\hat{\omega}_t^i$ , as:

$$\hat{\omega}_t^i \leftarrow (1 - j s_t^i) \cdot \omega_{t-1}^i + j s_t^i \cdot \omega_t. \tag{2}$$

From Eqn. (2), if the global model diverges considerably from the local one,  $\omega_t$  gains prominence over  $\omega_t^i$ . As a result,  $\omega_t^i$  aligns more with  $\omega_t$ , aiding the global model's convergence to a stationary point.

**Fairness penalty term.** To instill fairness in local models, we adopt an in-process approach, integrating fairness during training. This is commonly done by adding a fairness constraint or penalty to the objective function [27]. Instead of using sensitive features as GNN inputs, they're incorporated during training as a disparity penalty. The fairness penalty for

client  $C_i$  at epoch t (denoted as  $\ell_{fair_t}^i$ ) is the sum of the norm-1 of both SP and EO fairness types over  $C_i$ 's local graph  $G_i$ :

$$\ell_{\text{fair}_t}^i = ||\Delta_{\text{SP}_t}^i||_1 + ||\Delta_{\text{EO}_t}^i||_1.$$

The fairness penalty is incorporated into the local model's loss function as:

$$\ell(\omega_t^i; \mathbf{Z}_i) = \ell_{\text{util}_t}^i + \alpha \, \ell_{\text{fair}_t}^i, \tag{3}$$

with  $\ell_{\mathrm{util}}^i$  representing the utility loss (like entropy loss for node classification) and  $\alpha$  being an adjustable hyper-parameter.

Local model parameter updates. To finalize the local model update, client  $C_i$  performs several SGD steps:

$$\omega_t^i \leftarrow \hat{\omega}_t^i - \eta \cdot \nabla \ell(\omega_t^i; \mathbf{Z}_i),$$

where  $\hat{\omega}_{t}^{i}$  is the initialized local model update,  $\eta$  is the learning rate, and  $\nabla \ell(\omega_t^i; \mathbf{Z}_i)$  is the gradient of the loss function.

Upon concluding local training, client  $C_i$  transmits its local model parameters  $\omega_t^i$ , the local fairness loss  $\ell_{\mathrm{fair}_t}^i$ , and a group balance score  $B^i$  to the server S. We remark that sharing aggregated information of the local graphs such as  $\ell_{\text{fair},}^i$  and  $B^i$  with the server will make attacking individual information harder and thus protect their privacy.

## B. Server-side Fairness-weighted Global Model Update

The server-side model update scheme in each iteration consists of four steps:

- Step 1. Calculate the data-bias weight  $\gamma_{\mathcal{E}_t}$  based on the group balance scores provided by each client;
- Step 2. Derive the model-fairness weight  $\gamma_{\mathcal{F}_t}$  using the fairness loss metrics uploaded by the clients, ensuring fairness metrics are integrated into the global model aggregation process;
- Step 3. Combine the data-bias weight and model-fairness weight into a combined weight  $(\gamma_t)$ ; and
- Step 4. Aggregate the local model updates with the global model utilizing the combined weight.

The following elaboration provides a detailed description of each step.

Data-bias weight. Upon obtaining local parameters from the selected subset of clients at epoch t-1, the server first constructs a data-bias weight  $\gamma_{\mathcal{E}_t} \in \mathbb{R}^{K'}$ , where K' represents the number of clients in the subset:

$$\gamma_{\mathcal{E}_t} = \operatorname{softmax} \left( B^1, ..., B^{K'} \right).$$

Each element in  $\gamma_{\mathcal{E}_t}$  corresponds to the group balance score  $B^i$  for each client  $C_i$ . Given that each client  $C_i$  maintains a graph  $\mathcal{G}_i$ , the data-bias weight  $\gamma_{\mathcal{E}_t}$  effectively gauges the equilibrium between inter- and intra-edges within each client

Model-fairness weight. While the group balance score provides a useful measure of the balance between inter- and intra-edges within each client graph, it is static and unable to capture the model's evolving learning process regarding fairness. To address this, we also consider a dynamic fairness metric weight  $\gamma_{\mathcal{F}} \in \mathbb{R}^{K'}$  that evaluates the statistical parity  $\Delta_{\mathrm{SP}_t}^i$  and equalized odds  $\Delta_{\mathrm{EO}_t}^i$  of each client's local model at each iteration:

$$\gamma_{\mathcal{F}_t} = \exp\left(\operatorname{softmax}\left(\gamma_{\mathcal{F}_t}'\right)\right).$$

To calculate  $\gamma_{\mathcal{F}_t}$ , we start by a weight vector  $\gamma'_{\mathcal{F}_t}$ , which takes each client's sum of two types of group fairness metrics as the element. Therefore,  $\gamma'_{\mathcal{F}_t}$  can be illustrated as:

$$\gamma_{\mathcal{F}_t}' = \left[\Delta_{\mathrm{SP}_t}^1 + \Delta_{\mathrm{EO}_t}^1, ..., \Delta_{\mathrm{SP}_t}^{K'} + \Delta_{\mathrm{EO}_t}^{K'}\right]$$

 $\gamma_{\mathcal{F}t}' = \left[\Delta_{\mathrm{SP}_t}^1 + \Delta_{\mathrm{EO}_t}^1, ..., \Delta_{\mathrm{SP}_t}^{K'} + \Delta_{\mathrm{EO}_t}^{K'}\right].$  To magnify the effect of this dynamic model-fairness weight  $\gamma'_{\mathcal{F}_t}$ , we use an exponential function to rescale it after passing through a softmax function. This expands its range while maintaining its relative proportions as exponential functions grow faster than linear ones.

The softmax function is crucial for normalizing the two weight vectors, ensuring their comparability. Given the unique nature of the group balance score B, confined to the interval [0, 1], every component of  $\gamma_{\mathcal{E}_t}$  respects these boundaries. In contrast, each element in  $\gamma'_{\mathcal{F}_t}$  merges two statistical fairness metrics for each client, resulting in a value within the [0, 2]range. Through the softmax function, we align the scales of these weights, streamlining their integration and subsequent hyperparameter adjustments.

**Combined weight.** After deriving  $\gamma_{\mathcal{E}_t}$  and  $\gamma_{\mathcal{F}_t}$ , they are merged into a single weight vector  $\gamma_t \in \mathbb{R}^{K'}$  as:

$$\gamma_t = \operatorname{softmax} \left( (\lambda \cdot \gamma_{\mathcal{E}_t} + \gamma_{\mathcal{F}_t}) / \tau \right), \tag{4}$$

where  $\lambda$  is a hyperparameter, and  $\tau$  denotes the temperature parameter of the softmax function. This formula transforms the weights  $\gamma_{\mathcal{E}_t}$  and  $\gamma_{\mathcal{F}_t}$  into probability distributions that total one, resulting in the weight vector  $\gamma_t$ . The temperature parameter modulates the distribution's smoothness, and  $\lambda$  finetunes the emphasis on data bias in the final combination.

Global model updating. Utilizing the consolidated weights, the global model  $\omega_t$  is updated by aggregating the local models  $\omega_t^i$   $(i \in 1, ..., K')$  from K' clients, weighted by the vector  $\gamma_t$ :

$$\omega_t \leftarrow \sum_{i=1}^{K'} \gamma_t^i \cdot \omega_t^i, \tag{5}$$

where  $\gamma_t^i$  represents the *i*-th element of the combined weight vector. The server then disseminates the refreshed global model  $\omega_t$  to all clients.

#### VI. EXPERIMENTAL EVALUATION

In this section, we present the results of our experiments on two real-world datasets for node classification. Our proposed approach, F<sup>2</sup>GNN; is evaluated and compared against several baseline schemes in terms of both utility and fairness metrics.

#### A. Experimental Setup

Datasets. We employ two real-world datasets, Pokec-z and Pokec-n, that are widely used for GNN training [2], [3], [12], [15]. Both Pokec-z and Pokec-n graphs are social network data collected from two regions in Slovakia [21]. We pick the region attribute as the sensitive attribute and working fields as the label for both Pokec-z and Pokec-n graphs. We binarize the sensitive attributes and prediction labels for all the two datasets.

Evaluation metrics. In terms of GNN performance, we measure Accuracy and AUC score for node classification. Regarding fairness, we measure  $\Delta_{EO}$  and  $\Delta_{SP}$  of the predictions. Intuitively, smaller  $\Delta_{EO}$  and  $\Delta_{SP}$  indicate better fairness.

TABLE I: Node classification and fairness evaluation on the test sets of the Pokec-z and Pokec-n datasets.

	Global test set								
Method	Pokec-z				Pokec-n				
	Accuracy(%) ↑	AUC(%) ↑	$\Delta_{\mathrm{SP}}$ (%) $\downarrow$	$\Delta_{\rm EO}(\%)\downarrow$	Accuracy(%) ↑	AUC(%) ↑	$\Delta_{\text{SP}}$ (%) $\downarrow$	$\Delta_{\rm EO}(\%)\downarrow$	
FairAug <sub>+FL</sub> FairFed	$64.62 \pm 0.65$ $65.48 \pm 2.63$	$64.73 \pm 0.67$ $69.72 \pm 2.7$	$4.01 \pm 0.28$ $2.92 \pm 1.28$	$3.98 \pm 0.51$ $3.08 \pm 1.21$	$64.38 \pm 0.38 61.16 \pm 2.46$	$62.45 \pm 0.47$ $61.97 \pm 1.93$	$4.31 \pm 1.32$ $2.66 \pm 1.20$	$5.98 \pm 1.96$ $3.69 \pm 2.95$	
F <sup>2</sup> GNN	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$								
Method	Local Acc(%) ↑	Local AUC(%) ↑	Local $\Delta_{SP}$ (%) $\downarrow$	Local $\Delta_{EO}(\%) \downarrow$	Local Acc(%) ↑	Local AUC(%) ↑	Local $\Delta_{SP}$ (%) $\downarrow$	Local $\Delta_{EO}(\%)$	
FairAug <sub>+FL</sub> FairFed F <sup>2</sup> GNN	$63.33 \pm 4.91$ $59.44 \pm 3.60$ $68.43 \pm 1.99$	$57.8 \pm 3.76$ $63.7 \pm 12.13$ $75.74 \pm 2.13$	$8.54 \pm 0.53$ $8.12 \pm 3.32$ $7.24 \pm 0.99$	$8.54 \pm 0.53$ $7.69 \pm 1.96$ $7.35 \pm 1.58$	$61.03 \pm 5.89$ $56.26 \pm 2.42$ $68.19 \pm 2.40$	$52.50 \pm 4.23$ $58.41 \pm 1.75$ $\mathbf{69.49 \pm 3.81}$	$21.12 \pm 0.65$ $8.38 \pm 4.93$ $8.38 \pm 2.27$	$28.11 \pm 0.71$ $7.79 \pm 4.36$ $7.23 \pm 5.11$	

Furthermore, we measure two kinds of trade-offs between fairness and model accuracy as follows:

$$\begin{split} \operatorname{Trade-off}_{ACC} &= \operatorname{Accuracy} / \left( \Delta_{EO} + \Delta_{SP} \right), \\ \operatorname{Trade-off}_{AUC} &= \operatorname{AUC} / \left( \Delta_{EO} + \Delta_{SP} \right). \end{split}$$

Intuitively, a model that delivers higher accuracy and lower EO and SP values will lead to a better trade-off.

**Baselines.** To the best of our knowledge, there is no existing work on fairness issues in federated GNNs. Thus we adapt existing methods of fair federated learning and fair GNNs. We consider two baseline methods specifically:

- We deploy GNNs under an existing fairness-enhancing federated learning framework named **FairFed** [6].
- We deploy the fairness-aware GNN model FairAug [15] in the federated framework (denoted as FairAug<sub>+FL</sub>), replacing local models with it.

To ensure a fair comparison between different models on each dataset, we remove all the isolated nodes in the datasets.

**GNN Setup.** We deploy a 2-layer graph convolutional networks (GCNs), tailoring neuron configurations to each dataset. Specifically, the GCNs are set up with 64 neurons for the Pokec-n dataset, whereas 128 neurons per layer for the Pokec-z dataset. We utilize the Rectified Linear Unit (ReLU) [8] and the Adam optimizer [13]. Our F<sup>2</sup>GNN implementation is developed using the Deep Graph Library (DGL) [23], PyTorch Geometric [7], and NetworkX [10].

**Federated learning setup.** In the federated learning setting, we randomly select a set of nodes from each graph data set to serve as the centers of egocentric networks, which also determine the number of clients, and we specify a certain number of hops to grow the networks. Each network (or subgraph) is considered as a client. We evaluate our proposed approach on the Pokec datasets in a setting with 30 clients, each holding a 3-hop ego-network.

## B. Performance Evaluation

Tables I provide a comprehensive performance comparison of various models on the Pokec datasets, with a particular focus on their fairness attributes, specifically  $\Delta_{SP}$  and  $\Delta_{EO}$ .

Specifically, we evaluate the models on a global test set as well as local test sets. Each local client has its corresponding test set. After we get the metrics from all clients, we report the median value of these clients for each metric. Among the evaluated methods, our proposed framework,  $F^2GNN$  consistently outperforms other methods across two datasets in both global and local sets. In particular,  $F^2GNN$  achieves the lowest  $\Delta_{SP}$  and  $\Delta_{EO}$  values, indicating the effectiveness of the proposed scheme in federated settings.

The trade-off performance of each model on the two datasets is illustrated in Table II. The proposed method achieves the highest trade-off values for all datasets, respectively, demonstrating its exceptional ability to balance accuracy and fairness.

TABLE II: Trade-offs of F<sup>2</sup>GNN and baselines.

	Pok	ec-z	Pokec-n		
Method	$\overline{\text{Trade-off}}_{\text{ACC}}\uparrow$	$\operatorname{Trade-off}_{\operatorname{AUC}} \uparrow$	Trade-off <sub>ACC</sub> $\uparrow$	Trade-off_AUC $\uparrow$	
FairAug <sub>+FL</sub> FairFed F <sup>2</sup> GNN	$   \begin{array}{r}     11.129 \\     5.6581 \\     21.6445   \end{array} $	12.0854 5.6598 23.3264	8.2651 5.6581 36.2460	8.235 $12.5286$ $37.6649$	

In summary, our proposed  $F^2GNN$  framework outperforms other baselines in terms of  $\Delta_{SP}$ ,  $\Delta_{EO}$ , and trade-off values across all datasets. These results validate the effectiveness and robustness of  $F^2GNN$  in achieving competitive performance while maintaining group fairness in node classification tasks. These findings also highlight the broad applicability of our approach in the field of federated learning, suggesting its potential for adaptation to other domains.

#### C. Ablation Study

In the ablation study illustrated in Figure 2, we assess the impact of client-side fairness-aware and server-side fairness-weighted updates in our model on the Pokec datasets. Excluding either client-side or server-side updates results in decreased accuracy and increased disparity in  $\Delta_{\rm SP}$  and  $\Delta_{\rm EO}$ , emphasizing their role in balancing performance and fairness. Also, neglecting the server-side fair aggregation adversely affects fairness metrics, underscoring its crucial role in fairness enhancement. The complete model, F<sup>2</sup>GNN, optimally balances performance and fairness, proving the efficacy of all components in federated graph learning.

#### VII. CONCLUSION

In this study, we explore data bias in federated learning with a focus on graph neural networks. We highlight the need to account for the relationship between sensitive attributes

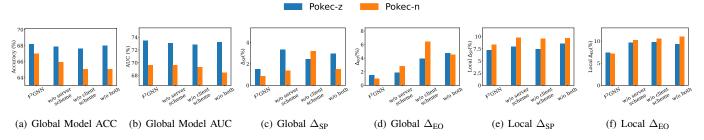


Fig. 2: Ablation Study

and graph structures to achieve model fairness. Introducing  $F^2GNN$ , we integrate fairness into both local and global training phases. Our tests on real datasets show our method effectively balances fairness and performance. As a future direction, we recognize the value of enhancing privacy, possibly through methods like homomorphic encryption, ensuring secure data aggregation.

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